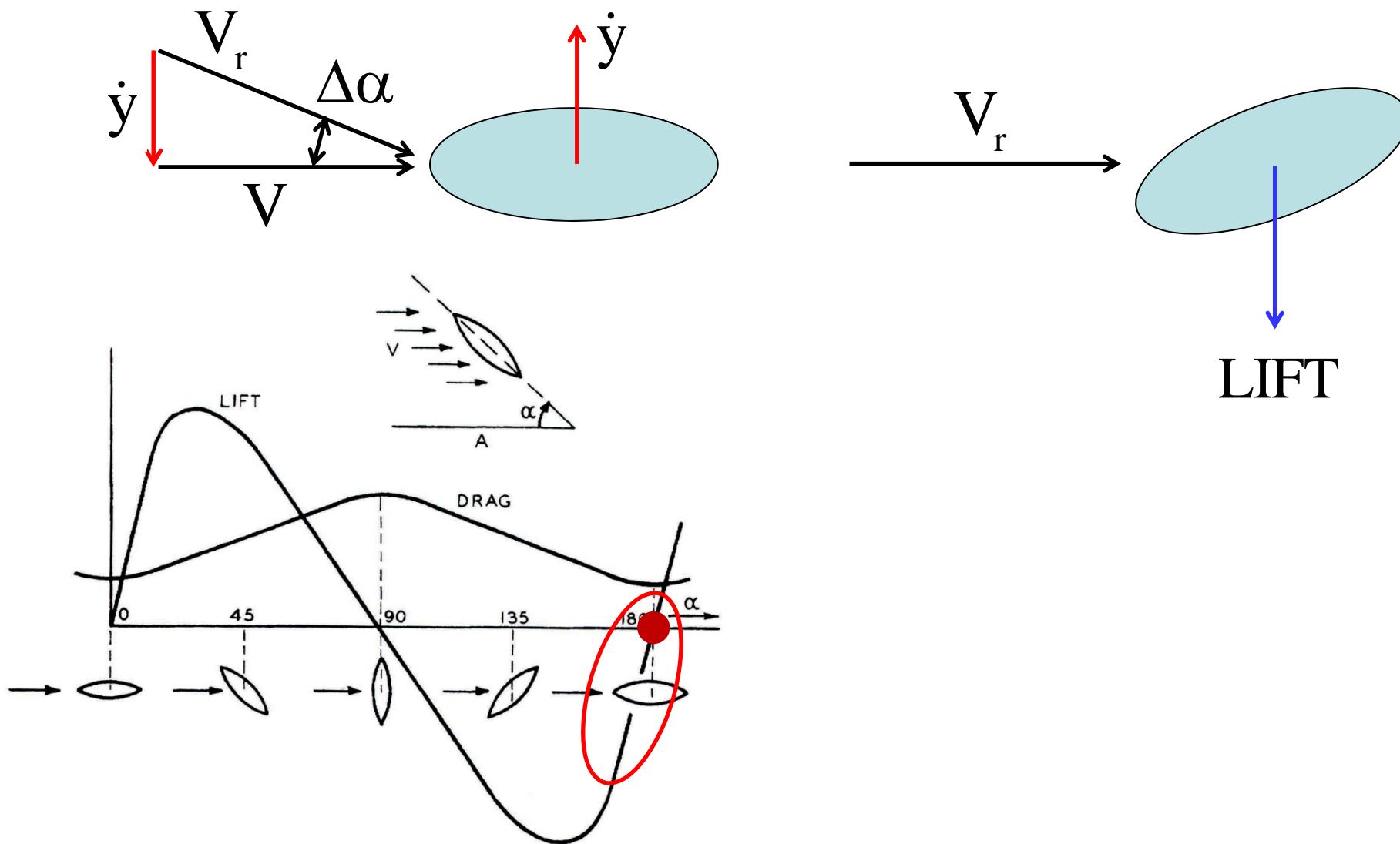
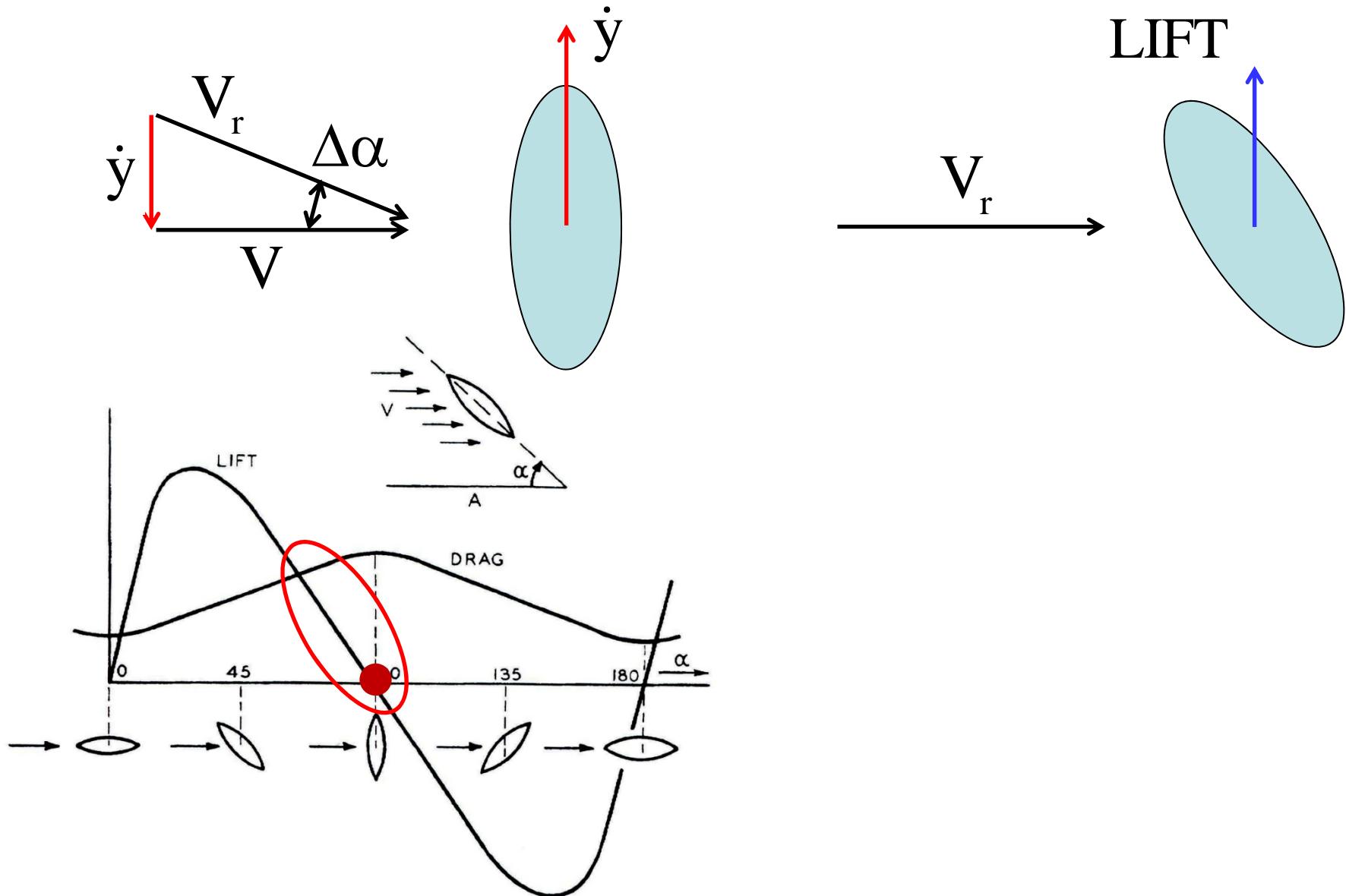


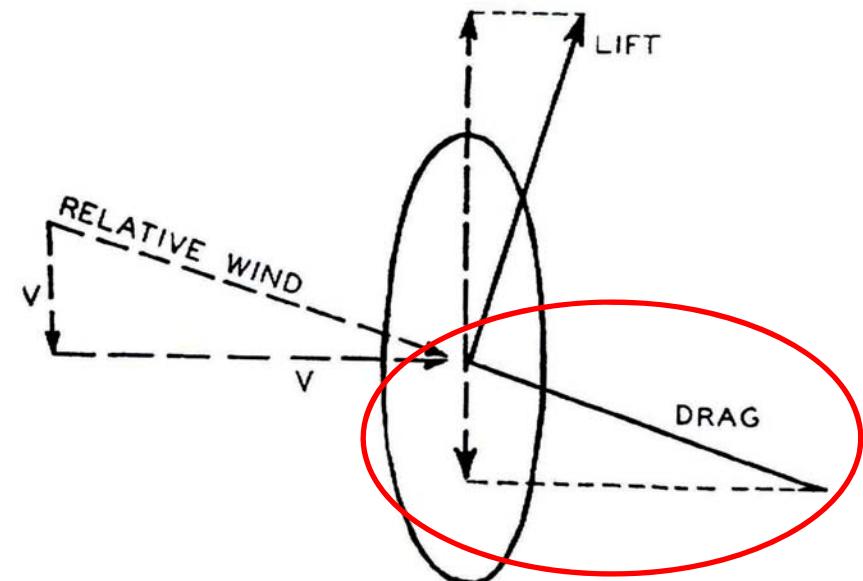
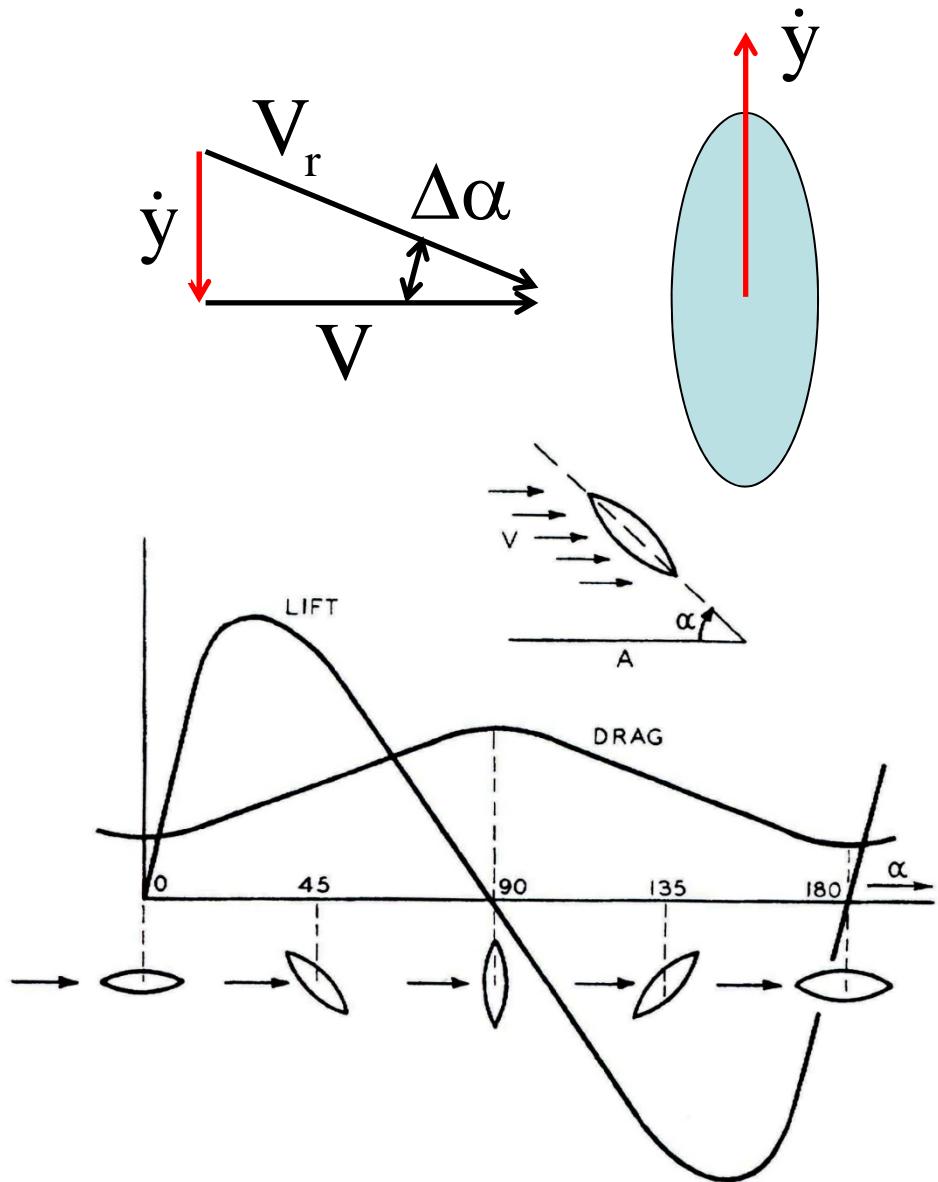
Crosswind galloping



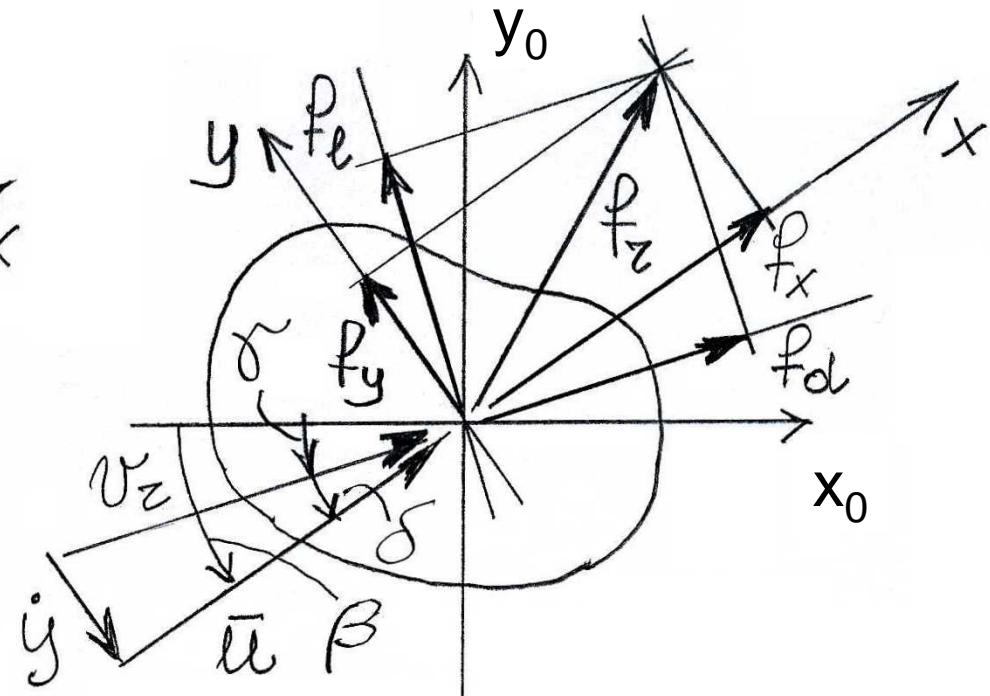
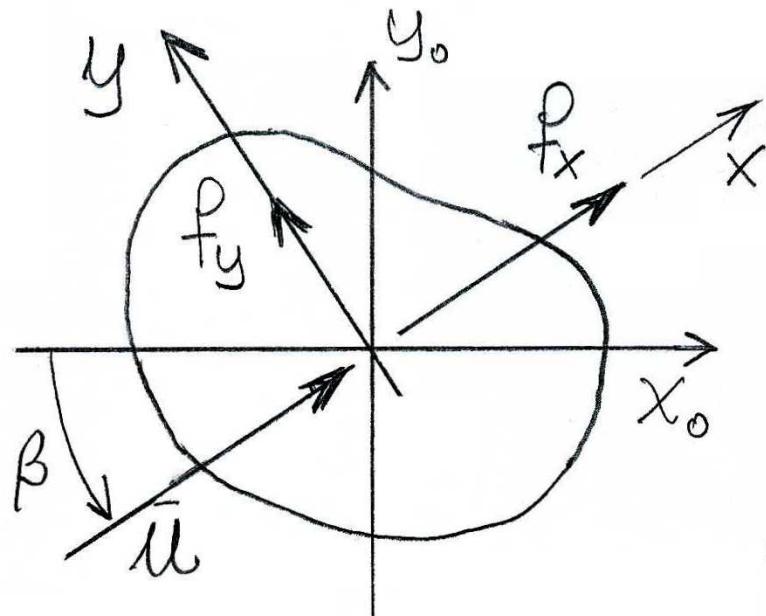
Crosswind galloping



Crosswind galloping



Crosswind galloping

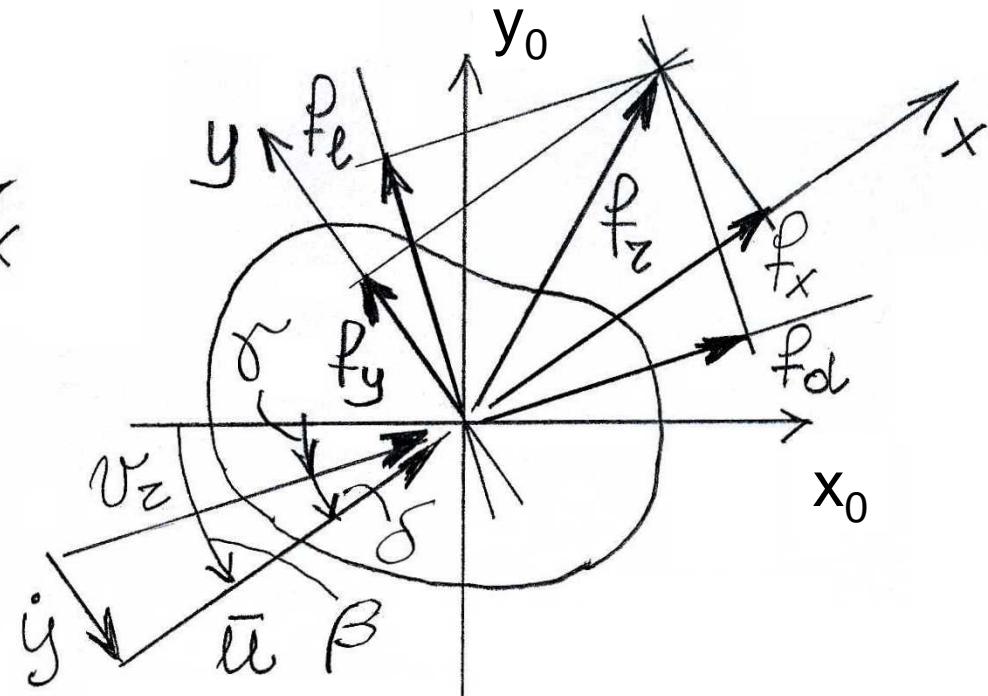
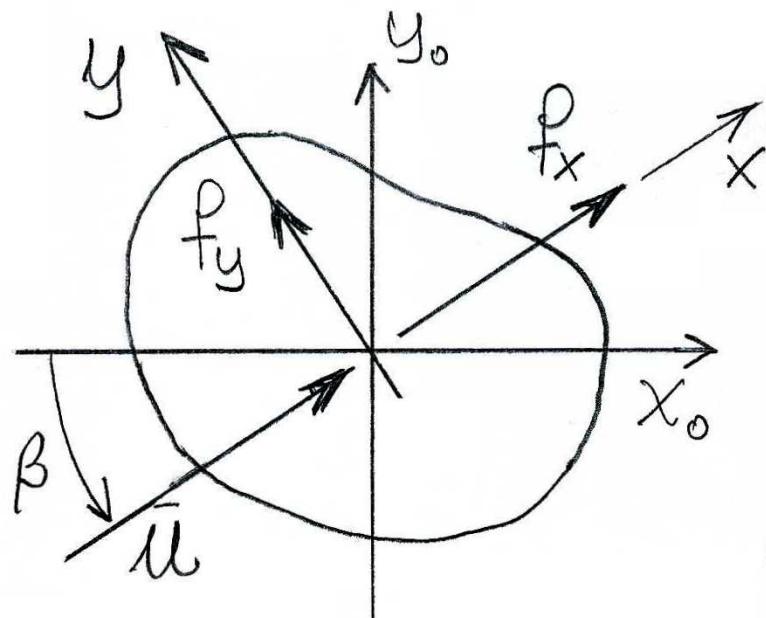


$$f_x = \frac{1}{2} \rho \bar{u}^2 b c_d(\beta); \quad f_y = \frac{1}{2} \rho \bar{u}^2 b c_l(\beta)$$

Quasi – steady theory

$$f_d = \frac{1}{2} \rho v_r^2 b c_d(\gamma); \quad f_l = \frac{1}{2} \rho v_r^2 b c_l(\gamma) \Rightarrow$$

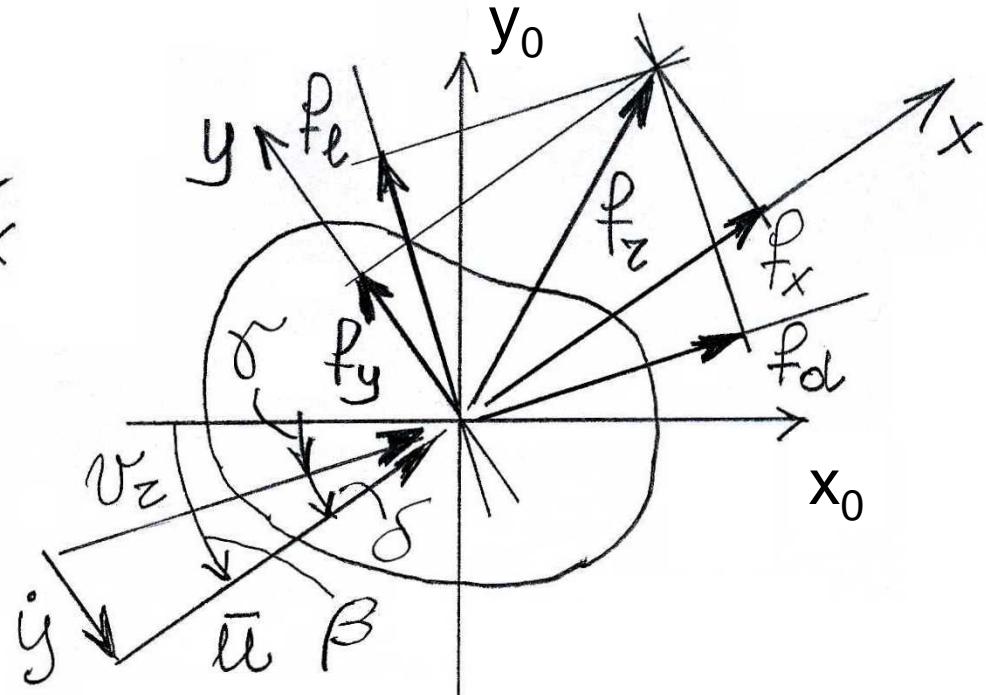
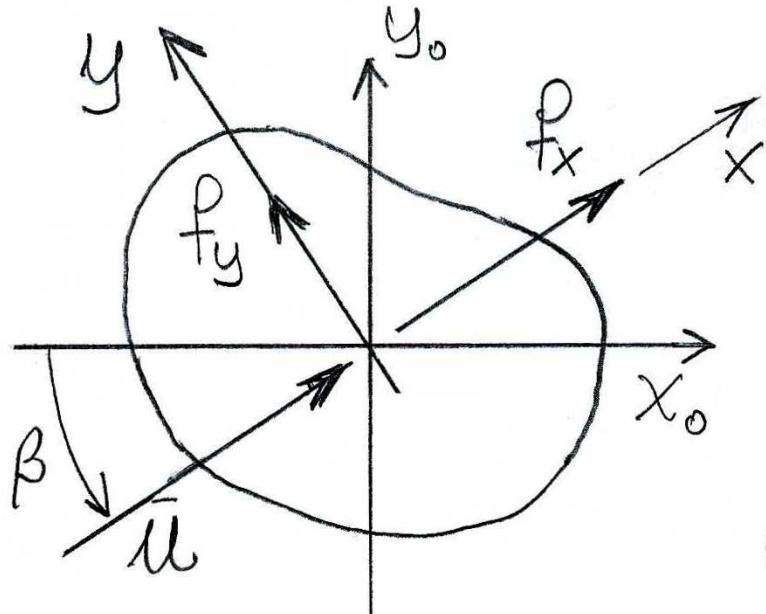
$$f_y = -f_d \sin \delta + f_l \cos \delta = \frac{1}{2} \rho v_r^2 b [-c_d(\gamma) \sin \delta + c_l(\gamma) \cos \delta]$$



$$f_y = -f_d \sin \delta + f_l \cos \delta = \frac{1}{2} \rho v_r^2 b [-c_d(\gamma) \sin \delta + c_l(\gamma) \cos \delta]$$

$$\gamma = \beta - \delta; \quad \delta = \operatorname{arctg} \frac{\dot{y}}{\bar{u}}; \quad v_r = \frac{\bar{u}}{\cos \delta} \Rightarrow$$

$$f_y = \frac{1}{2} \rho \bar{u}^2 b \frac{1}{\cos^2 \delta} [-c_d(\beta - \delta) \sin \delta + c_l(\beta - \delta) \cos \delta]$$

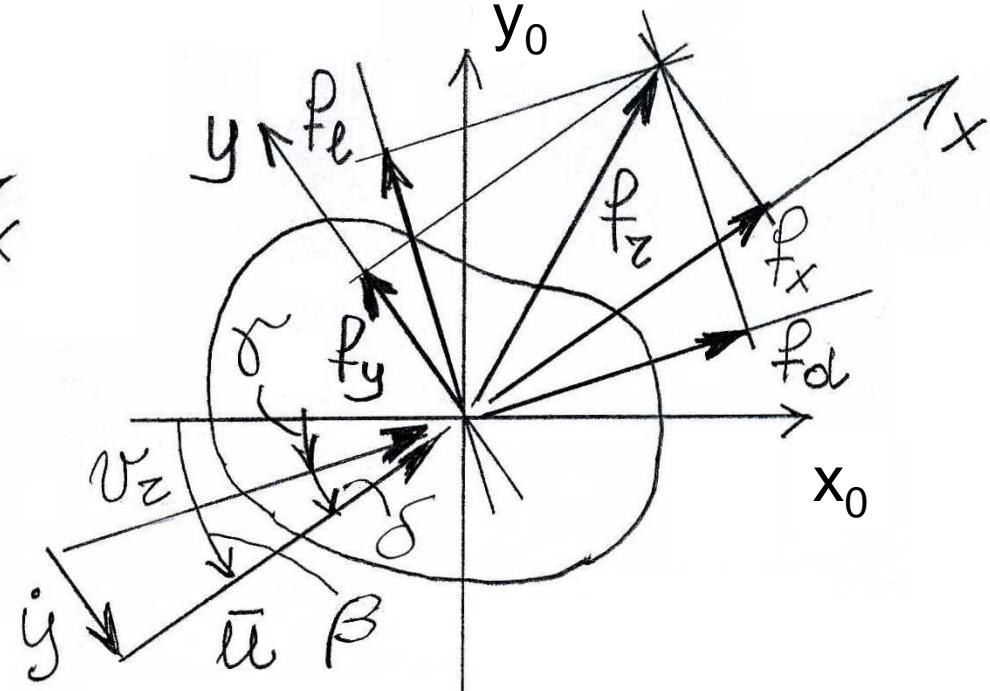
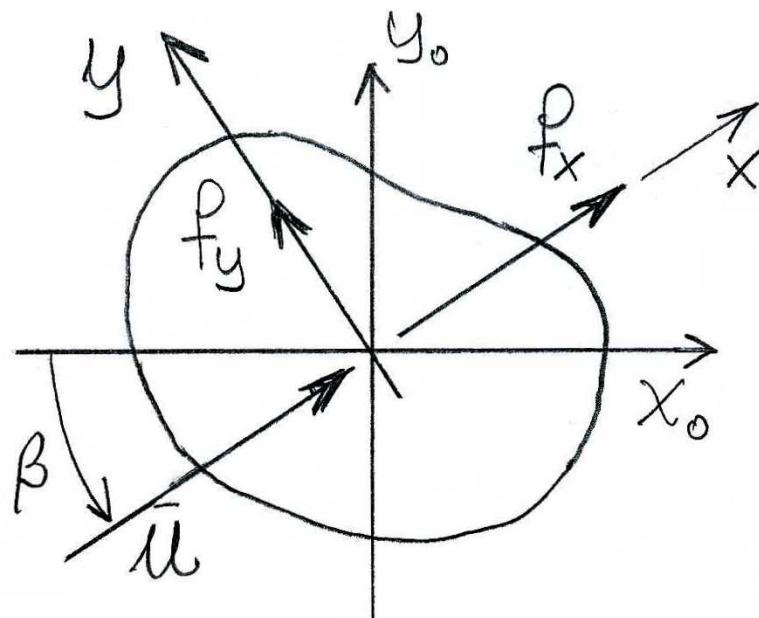


$$f_y = \frac{1}{2} \rho \bar{u}^2 b \frac{1}{\cos^2 \delta} [-c_d(\beta - \delta) \sin \delta + c_l(\beta - \delta) \cos \delta]$$

Rotation of reference axis : $\beta = 0 \Rightarrow$

$$f_y = \frac{1}{2} \rho \bar{u}^2 b \frac{1}{\cos \delta} [-c_d(-\delta) \operatorname{tg} \delta + c_l(-\delta)] = \frac{1}{2} \delta \bar{u}^2 b c_{fy}$$

$$c_{fy} = \frac{1}{\cos \delta} [-c_d(-\delta) \operatorname{tg} \delta + c_l(-\delta)] = \sum_k \left. \frac{1}{k!} \frac{\partial^k c_{fy}(\delta)}{\partial \delta^k} \right|_{\delta=0} \cdot \delta^k$$



$$f_y = \frac{1}{2} \delta \bar{u}^2 b c_{fy}; \quad c_{fy} = \sum_k \left. \frac{1}{k!} \frac{\partial^k c_{fy}(\delta)}{\partial \delta^k} \right|_{\delta=0} \cdot \delta^k$$

Linearized analysis ($k = 0, 1$) \Rightarrow Incipient instability

$$c_{fy} = c_l - (c_d + c'_l) \frac{\dot{y}}{\bar{u}} \quad (c_d = c_d|_{\delta=0}; c_l = c_l|_{\delta=0})$$

Galloping coefficient

$$a_G = -(c_d + c'_l) \Rightarrow c_{fy} = c_l + a_G \frac{\dot{y}}{\bar{u}}$$

$$f_y = \frac{1}{2} \delta \bar{u}^2 b c_{fy}; \quad c_{fy} = c_l + a_G \frac{\dot{y}}{\bar{u}}$$

SDOF Equation of motion (per unit length)

$$\ddot{y} + 2\xi_s \omega_0 \dot{y} + \omega_0^2 y = \frac{1}{m} f_y = \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b c_{fy} = \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b c_l + \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b a_G \frac{\dot{y}}{\bar{u}} \Rightarrow$$

$$\ddot{y} + \left(2\xi_s \omega_0 - \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b a_G \frac{1}{\bar{u}} \right) \dot{y} + \omega_0^2 y = \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b c_l \Rightarrow$$

$$\ddot{y} + 2(\xi_s + \xi_a) \omega_0 \dot{y} + \omega_0^2 y = \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b c_l$$

Crosswind aerodynamic damping

$$\xi_a = -\frac{\rho \bar{u} b a_G}{4m\omega_0} = \frac{\rho \bar{u} b (c_d + c'_l)}{4m\omega_0}$$

Total crosswind damping

$$\xi_t = \xi_s + \xi_a = \xi_s - \frac{\rho \bar{u} b a_G}{4m\omega_0} = \xi_s + \frac{\rho \bar{u} b (c_d + c'_l)}{4m\omega_0}$$

$$\ddot{y} + 2\xi_t \omega_0 \dot{y} + \omega_0^2 y = \frac{1}{m} \frac{1}{2} \rho \bar{u}^2 b c_l$$

$$\xi_t = \xi_s + \xi_a = \xi_s - \frac{\rho \bar{u} b a_G}{4m\omega_0} = \xi_s + \frac{\rho \bar{u} b (c_d + c'_l)}{4m\omega_0}$$

GALLOPING necessary condition

Glauert – Den Hartog criterion

$$\xi_a < 0 \Rightarrow a_G > 0 \text{ or } (c_d + c'_l) < 0$$

GALLOPING necessary and sufficient condition

$$\xi_t \leq 0 \Rightarrow \xi_s - \frac{\rho \bar{u} b a_G}{4m\omega_0} = \xi_s + \frac{\rho \bar{u} b (c_d + c'_l)}{4m\omega_0} \leq 0$$

GALLOPING necessary and sufficient condition

$$\xi_t \leq 0 \Rightarrow \xi_s - \frac{\rho \bar{u} b a_G}{4m\omega_0} = \xi_s + \frac{\rho \bar{u} b (c_d + c'_l)}{4m\omega_0} \leq 0 \Rightarrow$$

$$\bar{u} \geq \frac{4m\omega_0 \xi_s}{\rho b a_G} = -\frac{4m\omega_0 \xi_s}{\rho b (c_d + c'_l)}$$

being $a_G > 0, (c_d + c'_l) < 0$

GALLOPING critical velocity

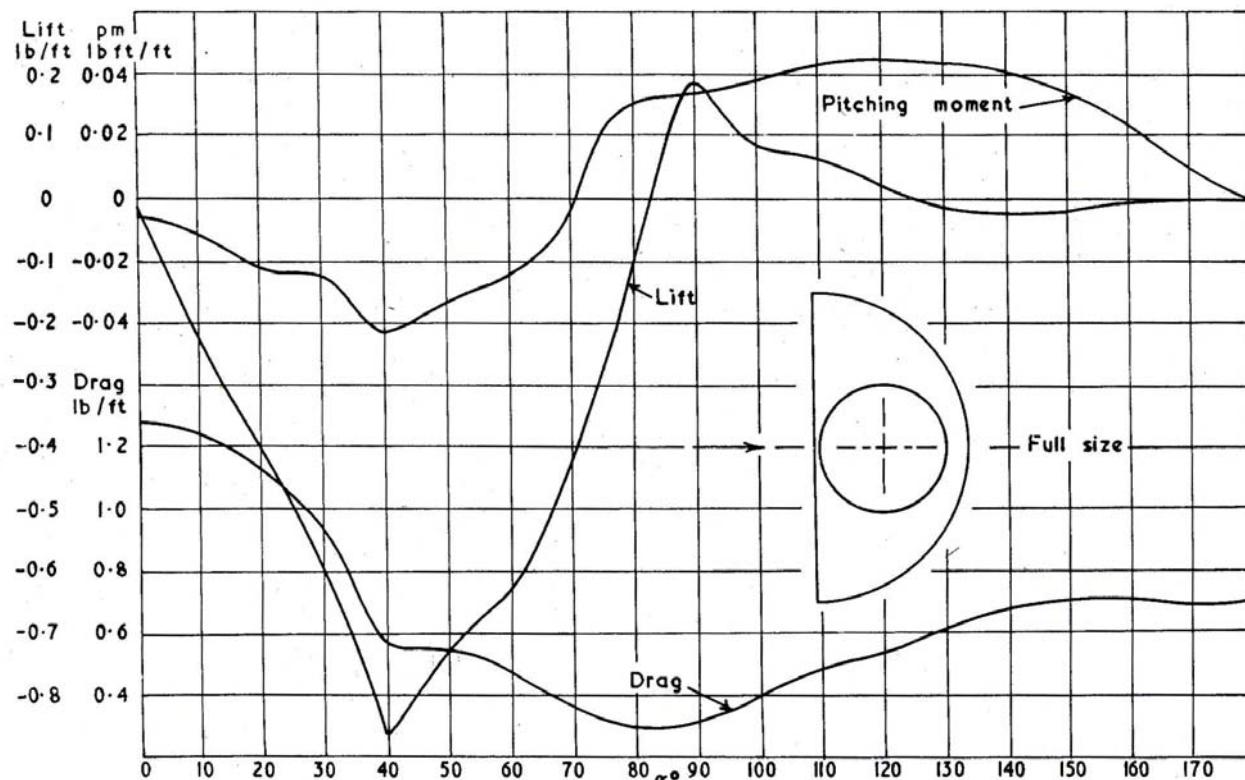
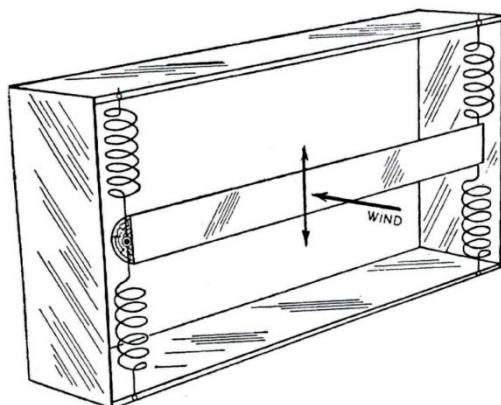
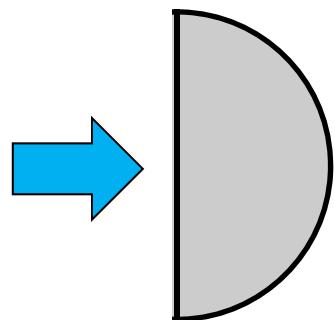
$$\bar{u}_{cr} = \frac{4m\omega_0 \xi_s}{\rho b a_G} = -\frac{4m\omega_0 \xi_s}{\rho b (c_d + c'_l)} \Rightarrow$$

$$\bar{u}_{cr} = \frac{4m\omega_0 \xi_s}{\rho b a_G} \cdot \frac{\pi b}{\pi b} = \frac{\omega_0 b}{\pi a_G} \cdot \frac{4\pi m \xi_s}{\rho b^2} = \frac{\omega_0 b}{\pi a_G} \cdot Sc = \frac{2n_0 b}{a_G} \cdot Sc$$

$$Sc = \frac{4\pi m \xi_s}{\rho b^2}$$

Necessary condition

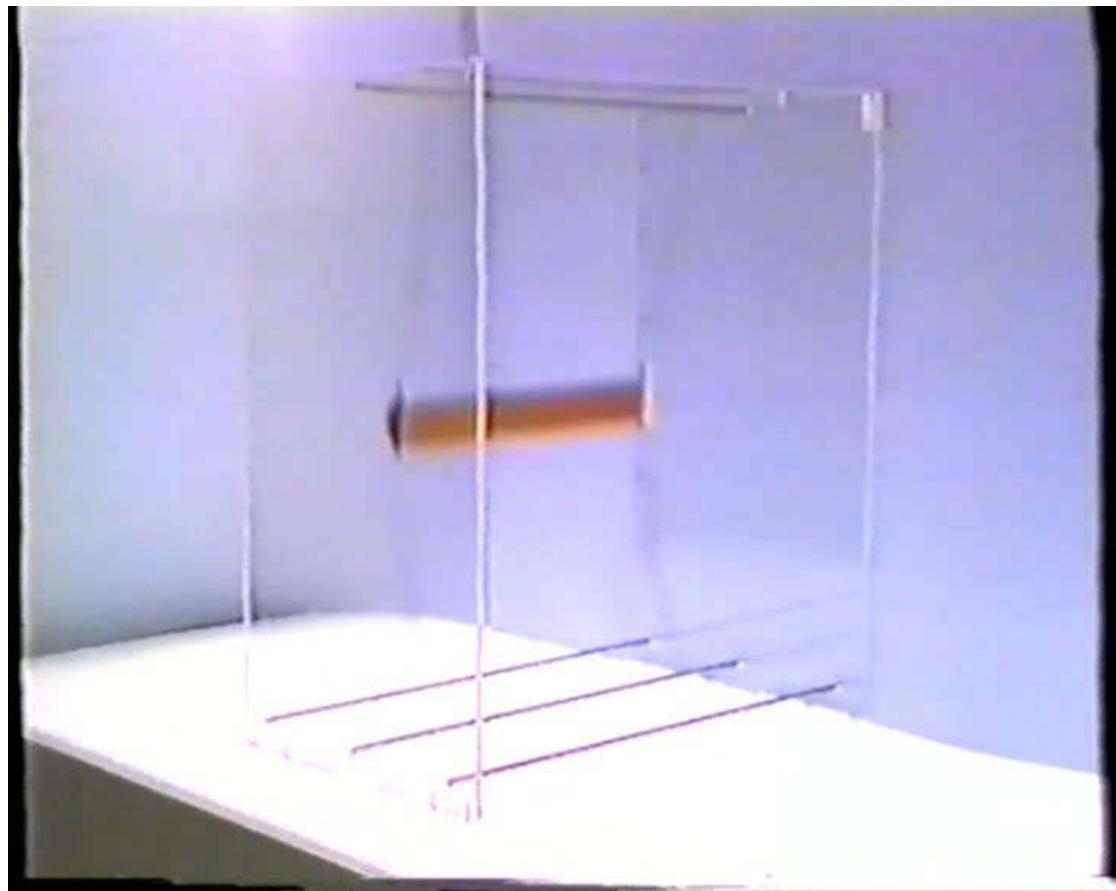
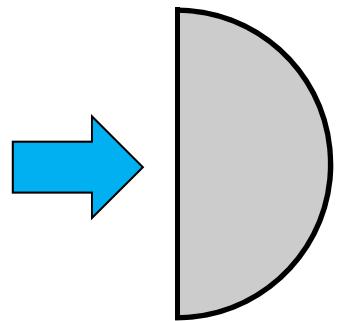
$$c_d + c'_l < 0$$



D-shaped section

Necessary condition

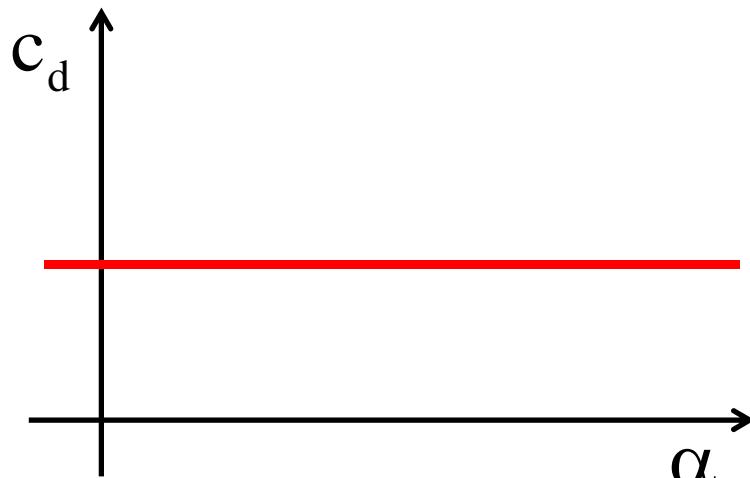
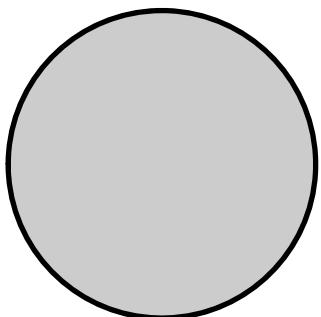
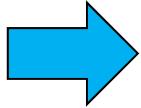
$$c_d + c'_l < 0$$



D-shaped section

Necessary condition

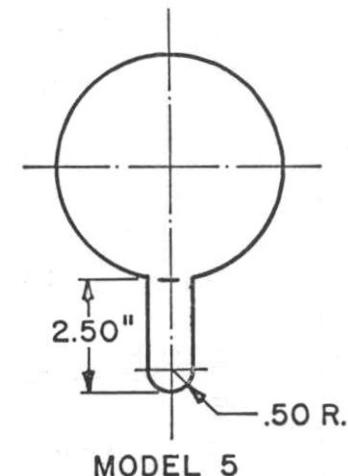
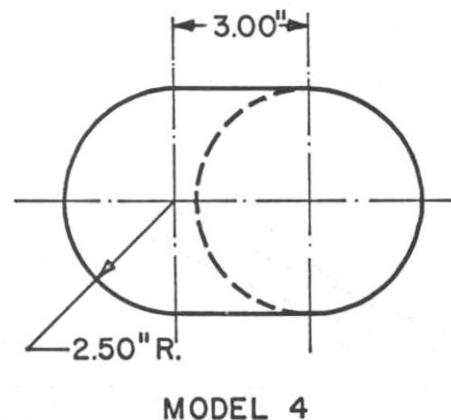
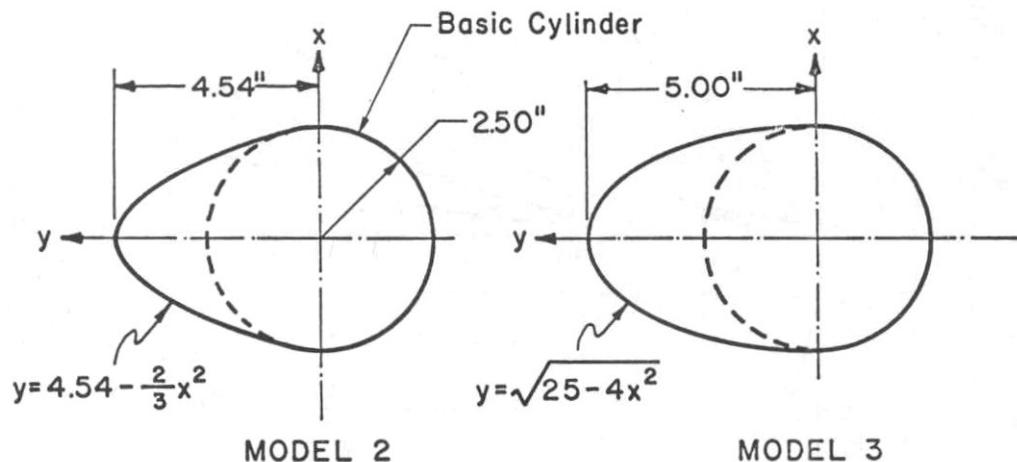
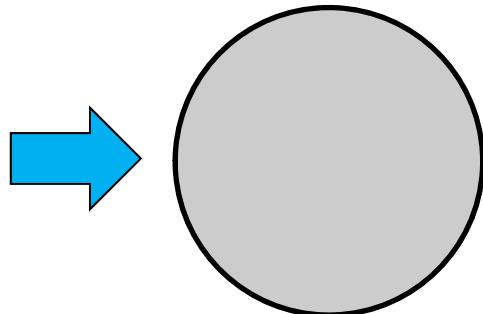
$$c_d + c'_l < 0$$



Circular section

Necessary condition

$$c_d + c'_1 < 0$$



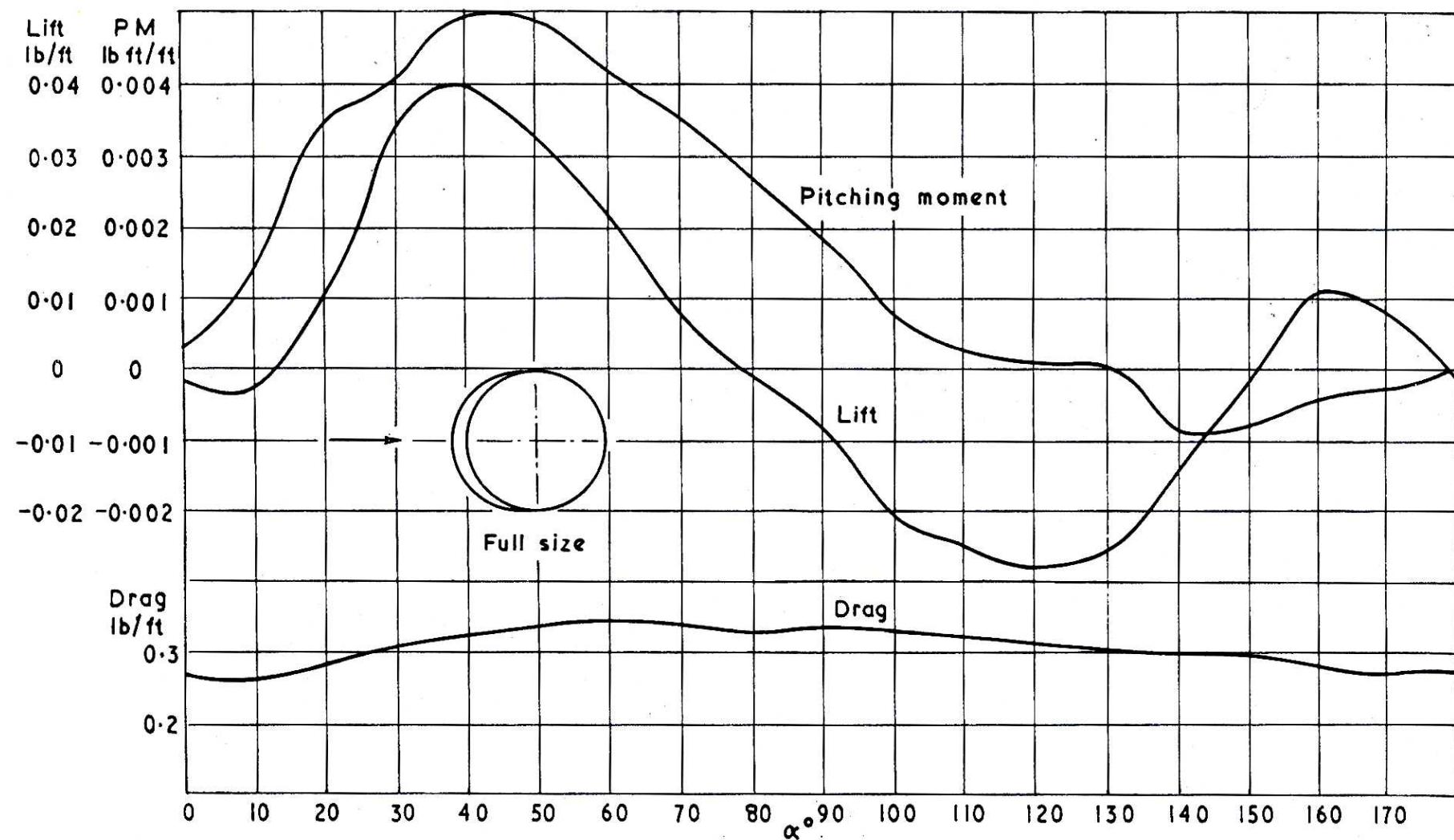
Iced cable section



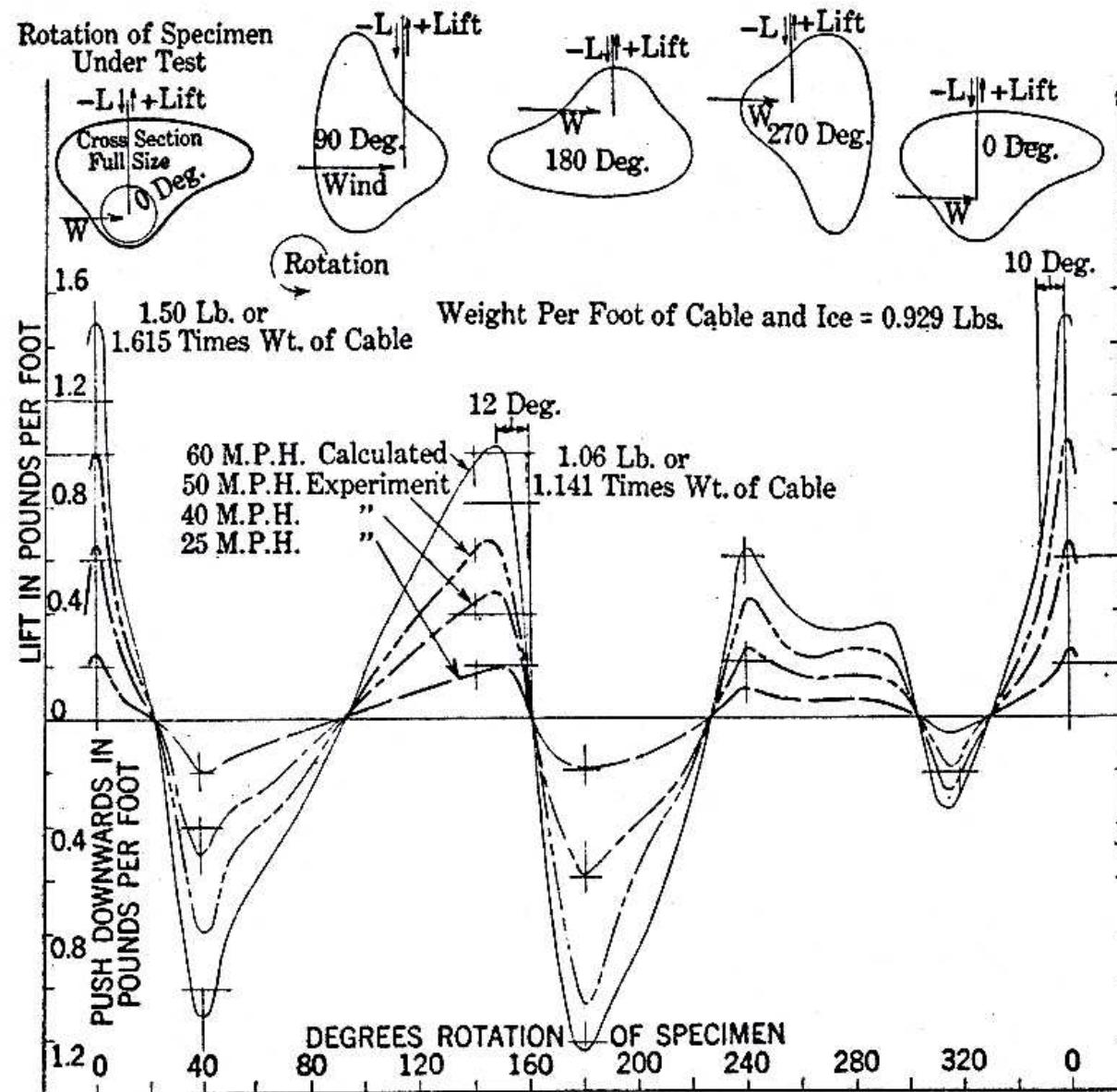
Iced cables



Iced cables



Iced cables



Iced cables



Conductor galloping



Conductor galloping



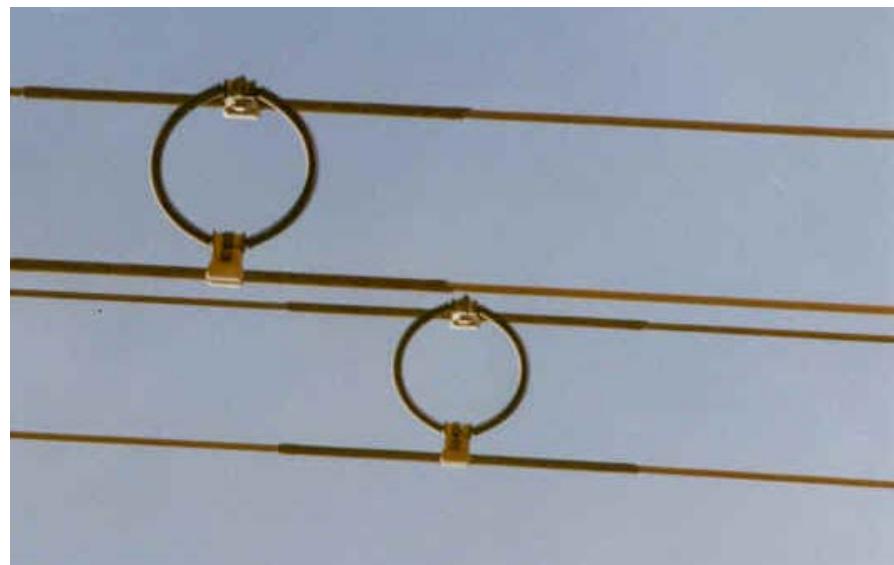
Fatigue collapse of conductors



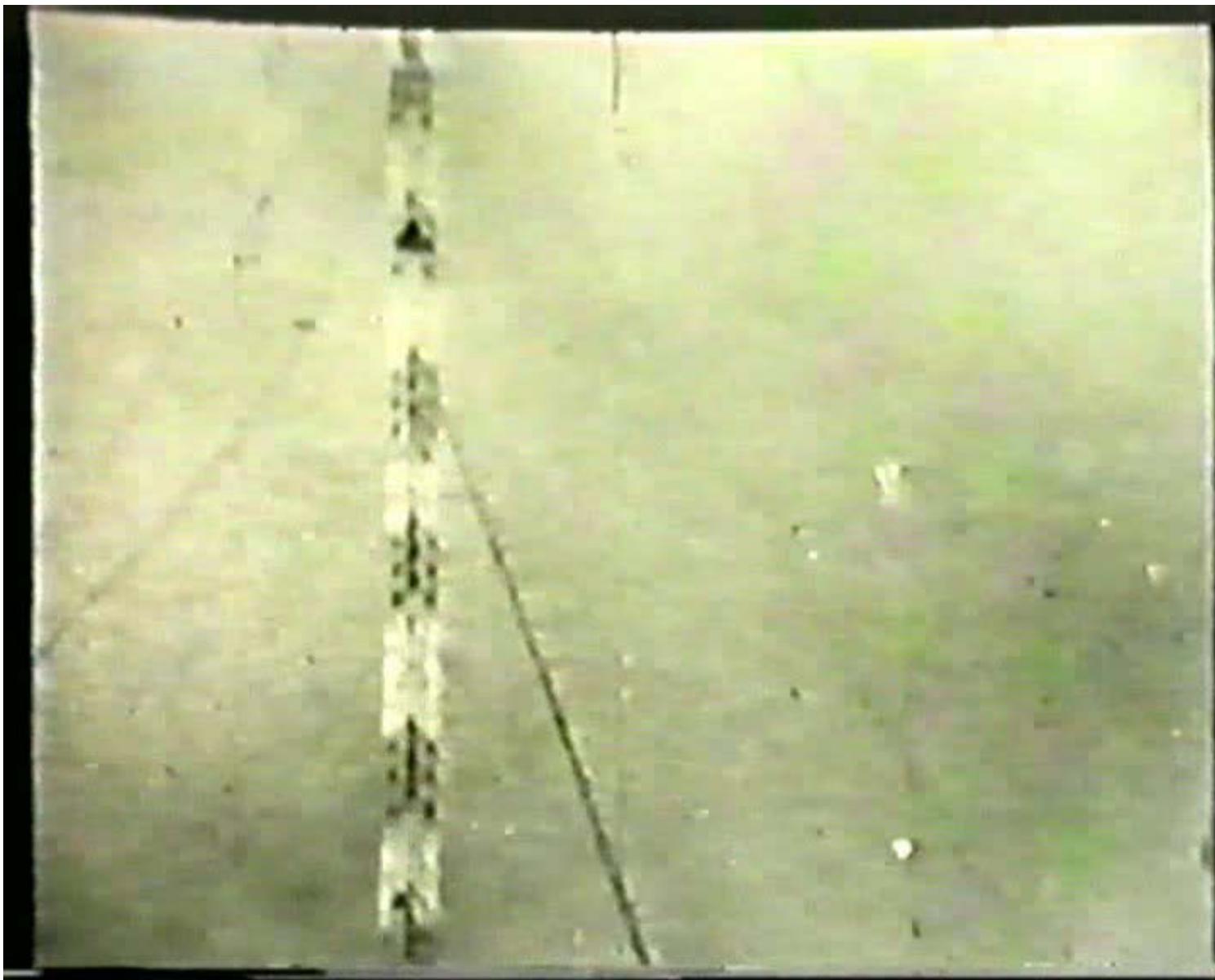
Collapse of towers for transmission lines



Collapse of towers for transmission lines



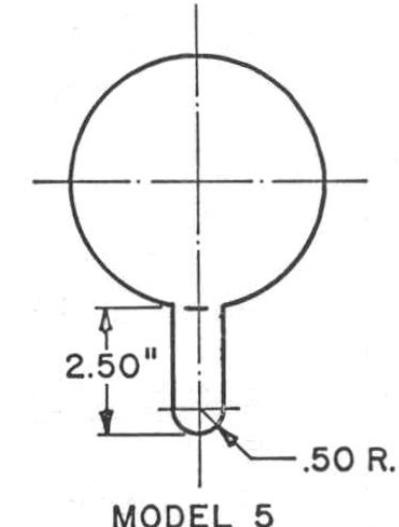
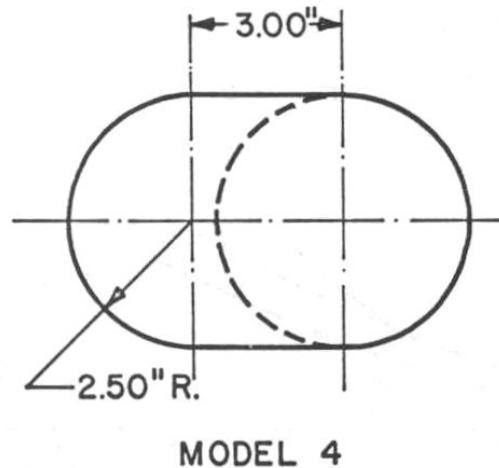
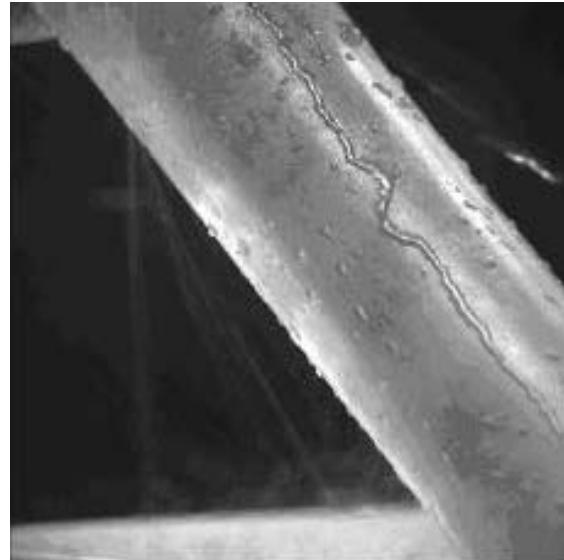
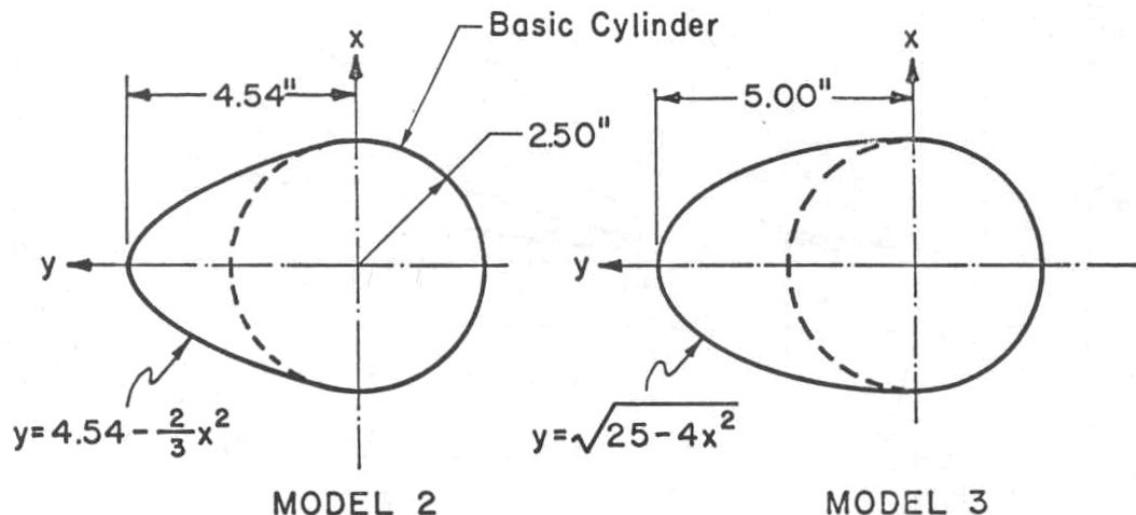
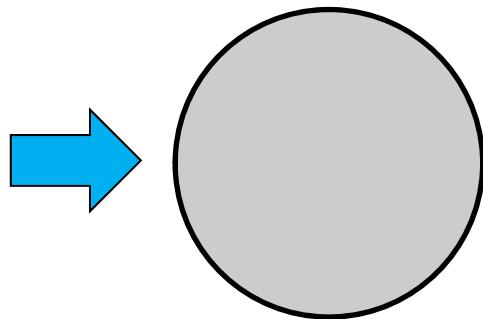
Devises to contrats galloping vibrations of transmission lines



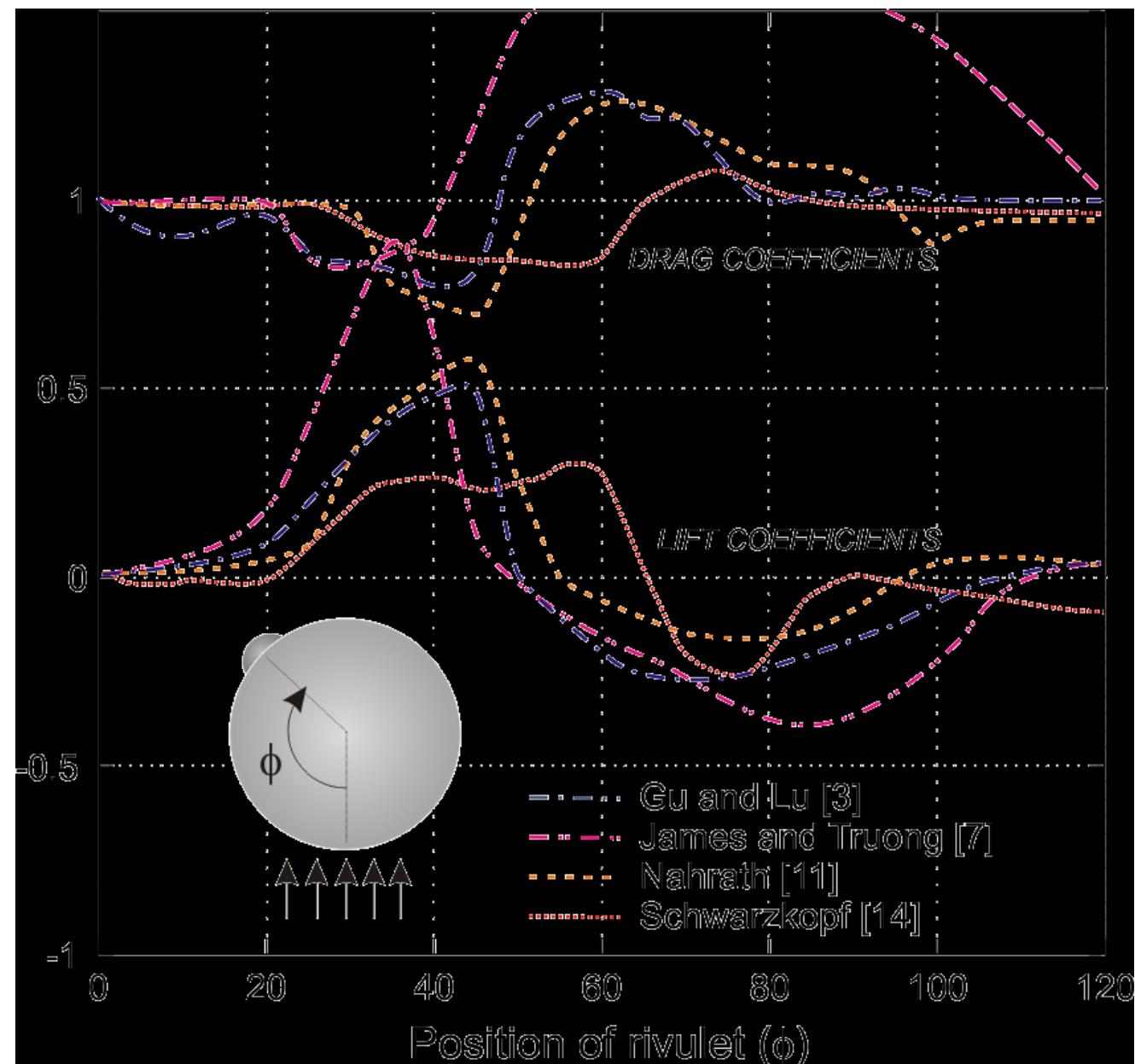
Cable galloping

Necessary condition

$$c_d + c'_1 < 0$$



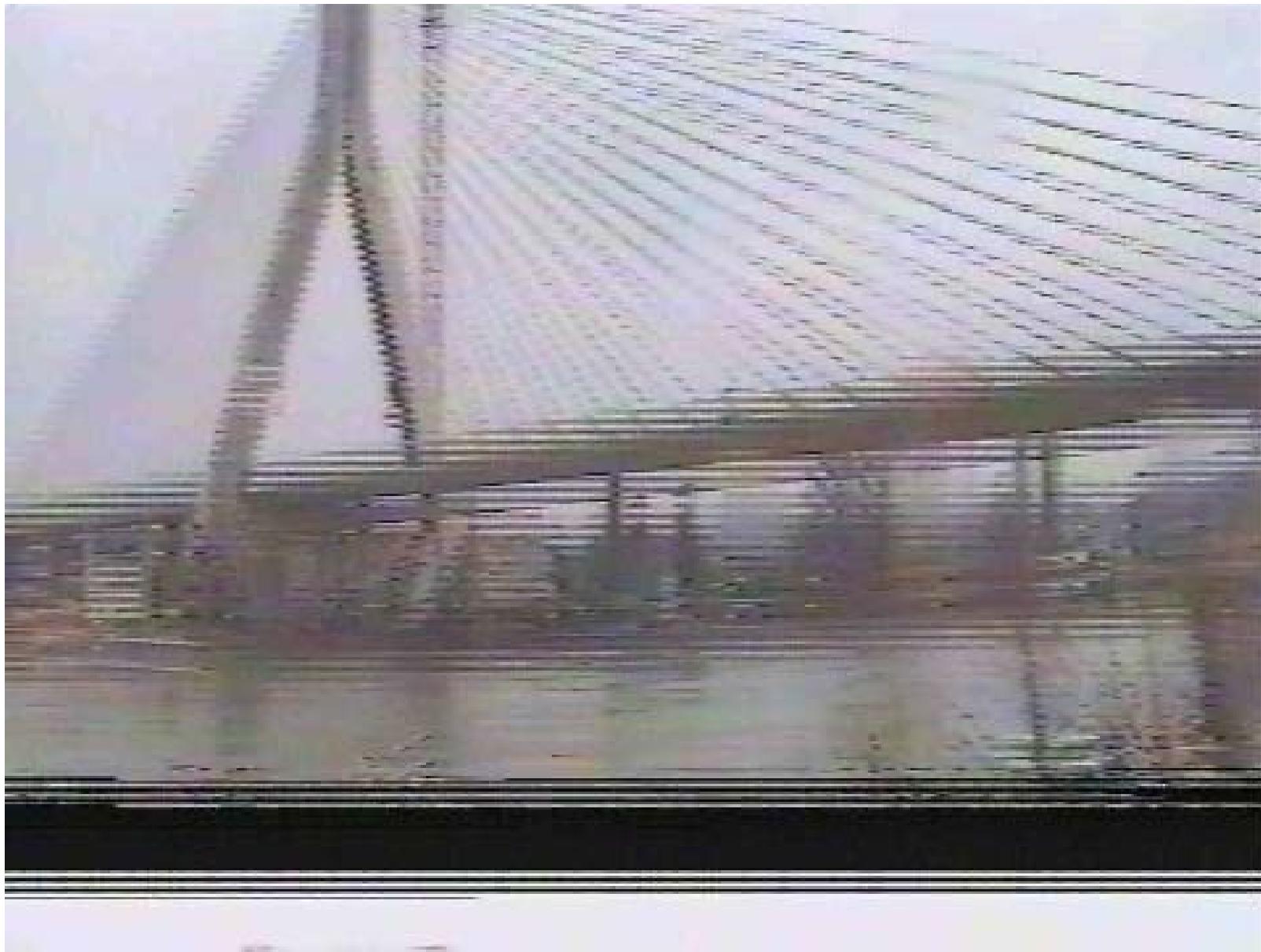
Water rivulet over cables



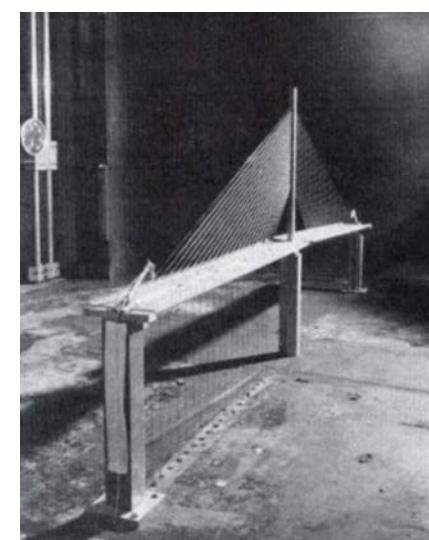
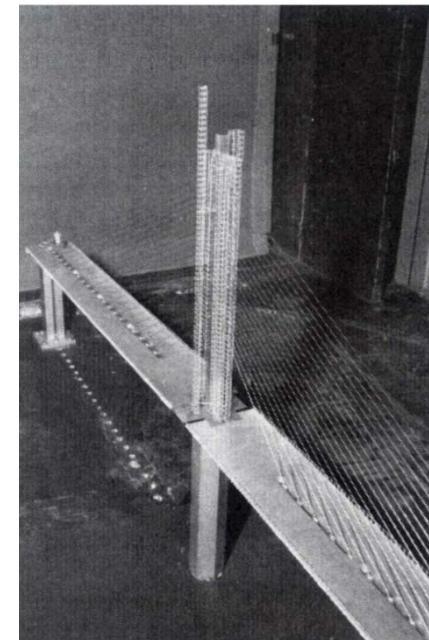
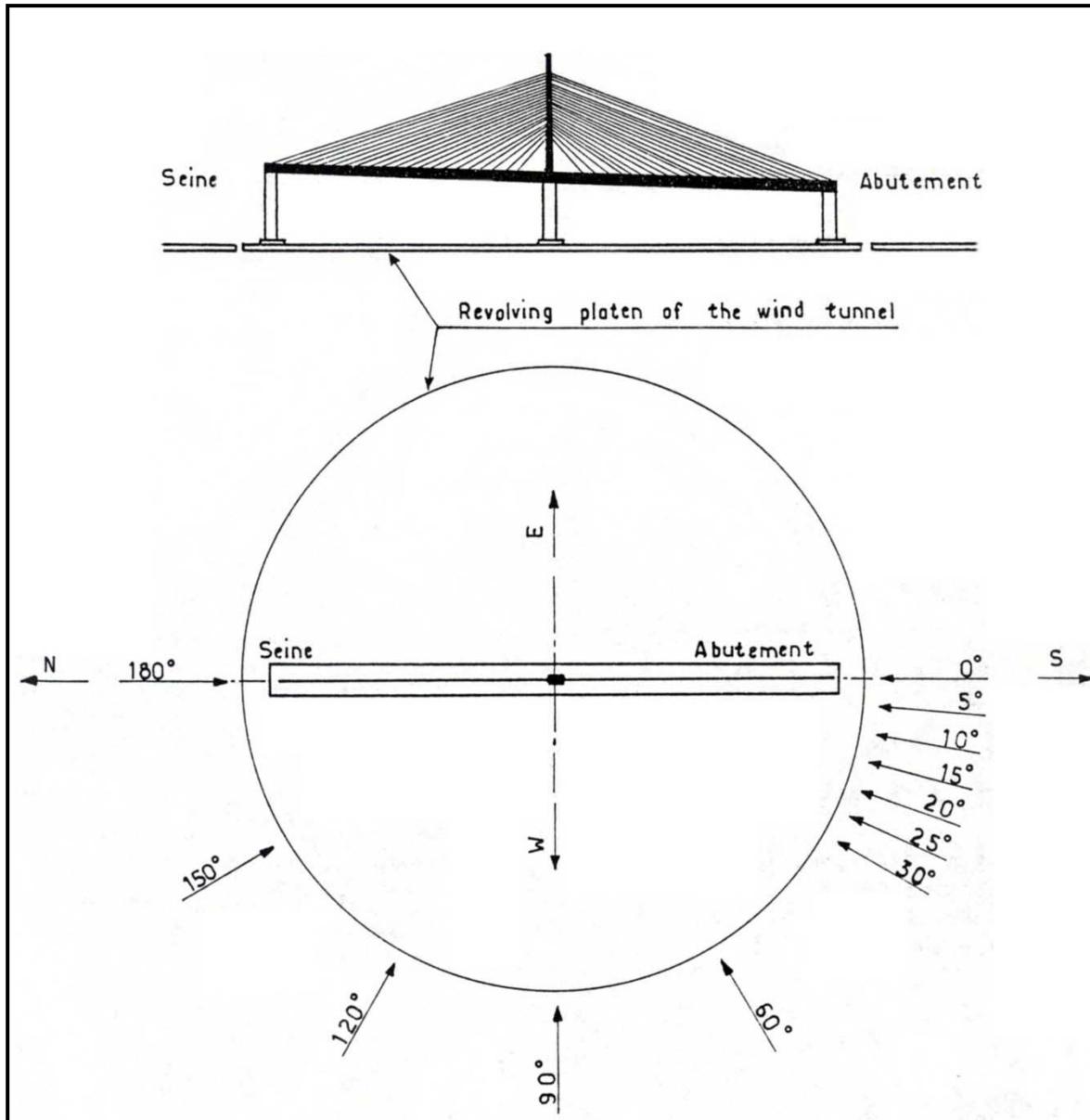
Water rivulet over cables



Brotonne Bridge, France, 1977



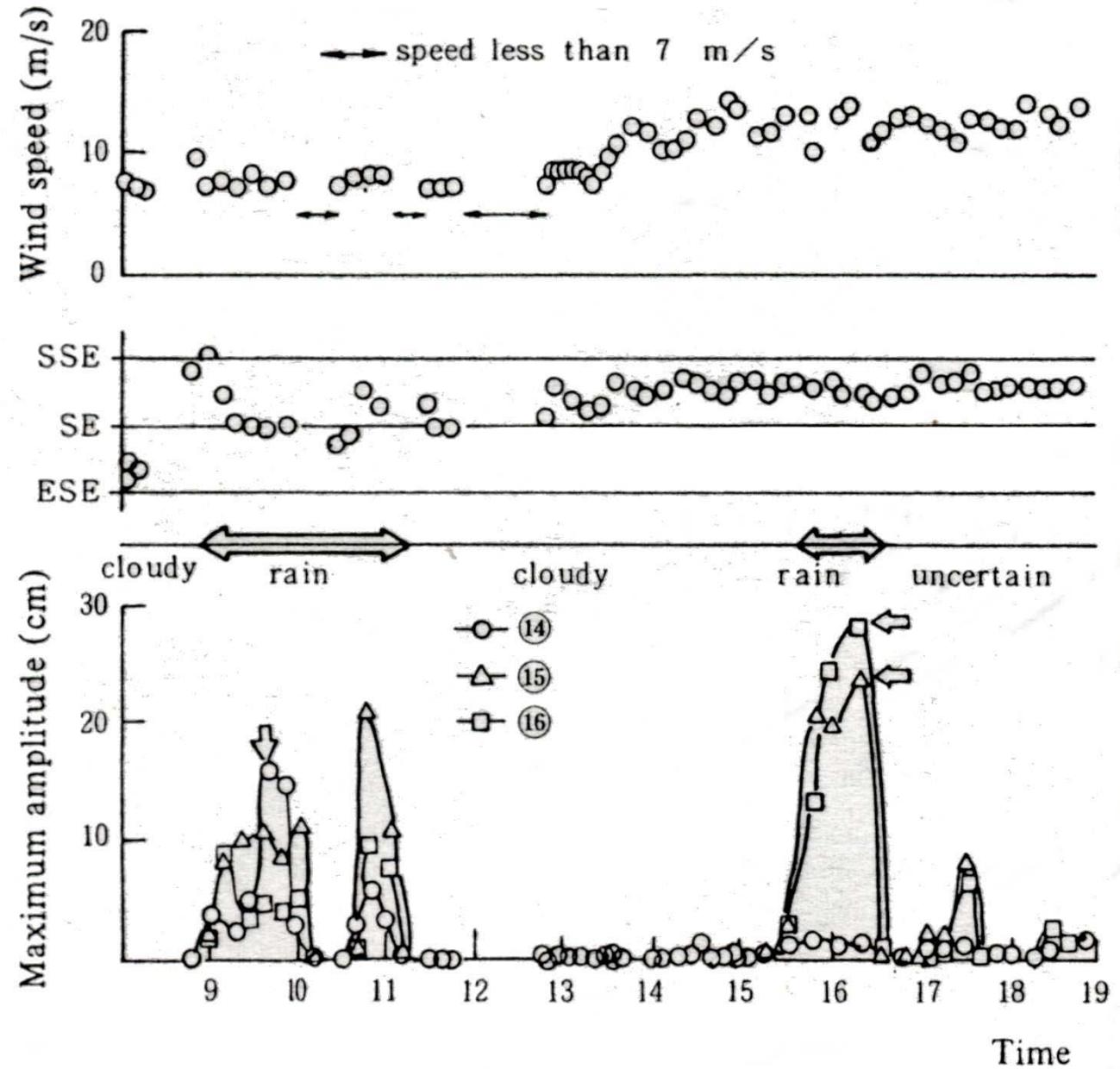
Brotonne Bridge, France, 1977



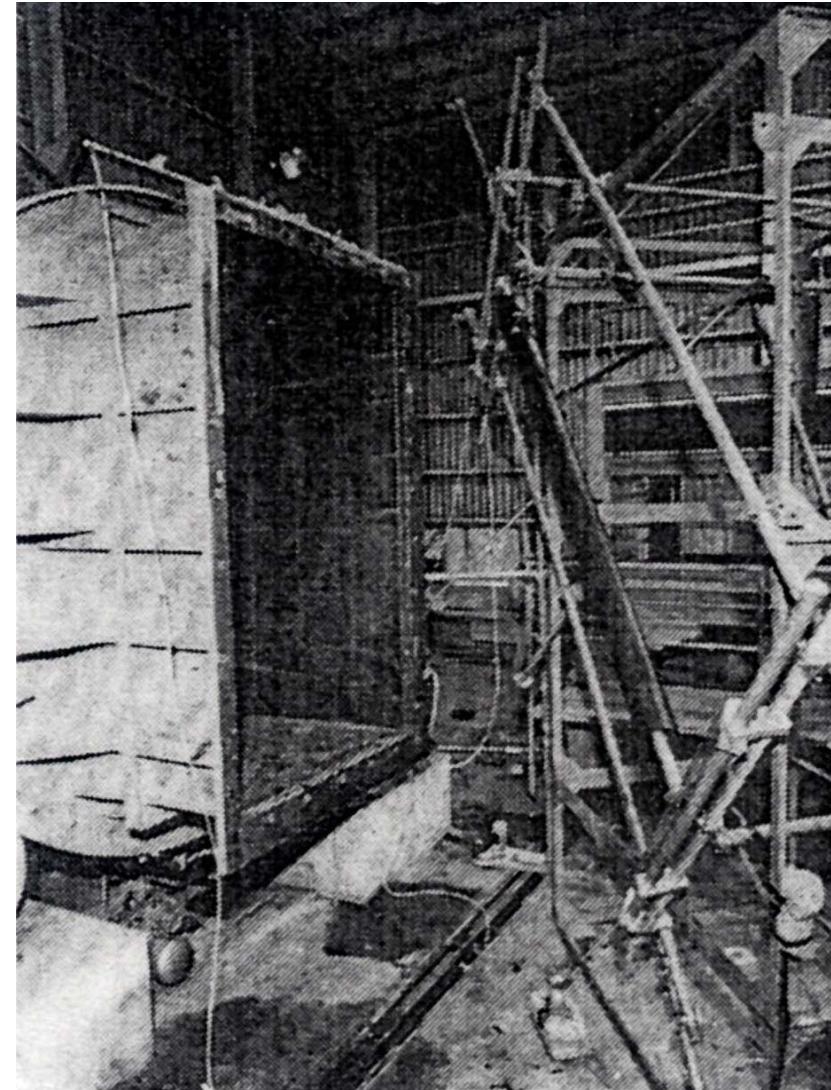
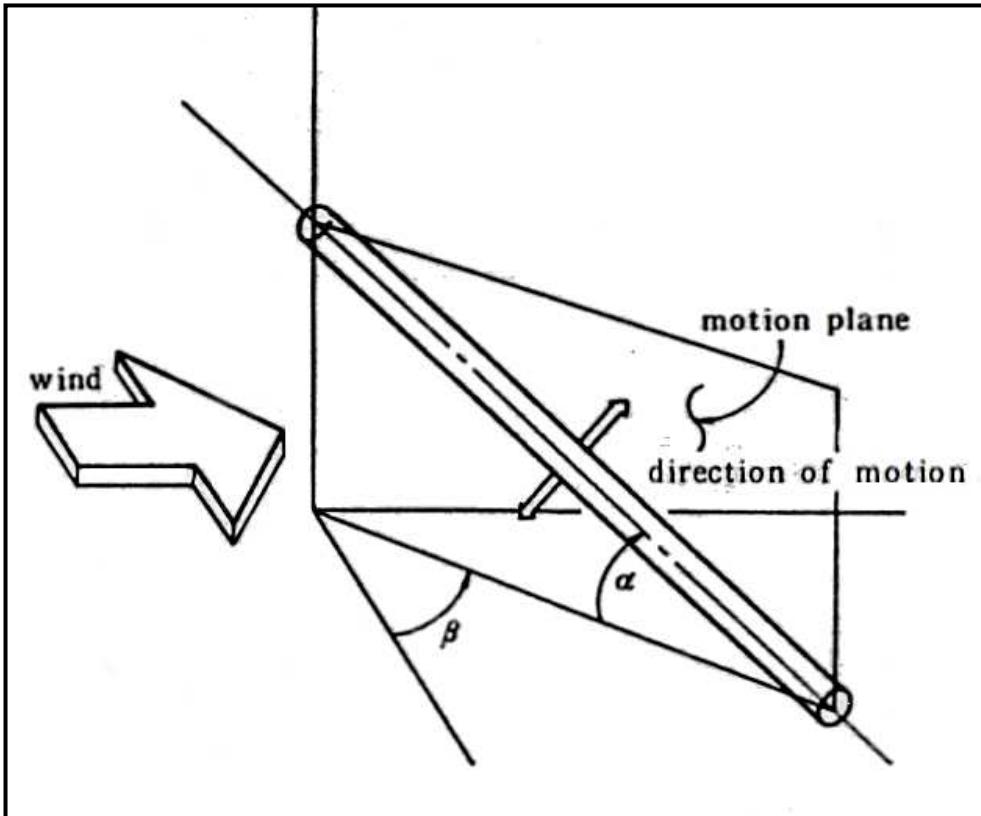
Brotonne Bridge, France, 1977



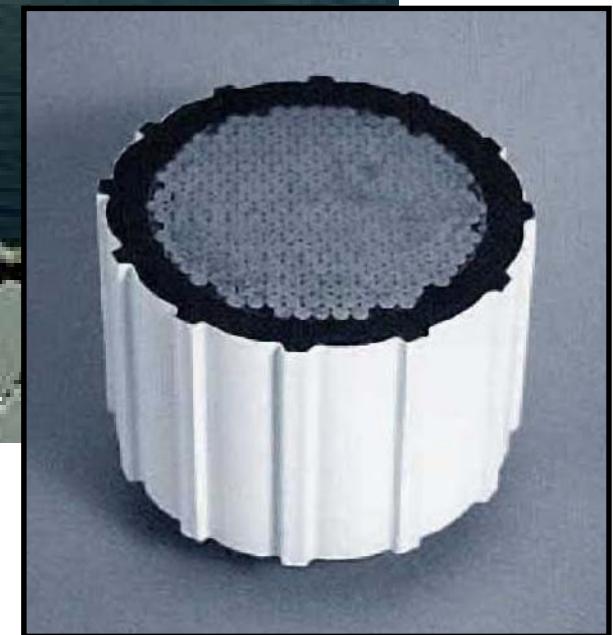
Meiko Nishi Bridge, Nagoya, Japan, 1985



Meiko Nishi Bridge, Nagoya, Japan, 1985



Meiko Nishi Bridge, Nagoya, Japan, 1985



Higashi-Kobe Bridge, Japan, 1992



Tsurumi-Tsubasa Bridge, Yokohama, Japan, 1994



Fred Hartman Bridge, U.S.A., 1995

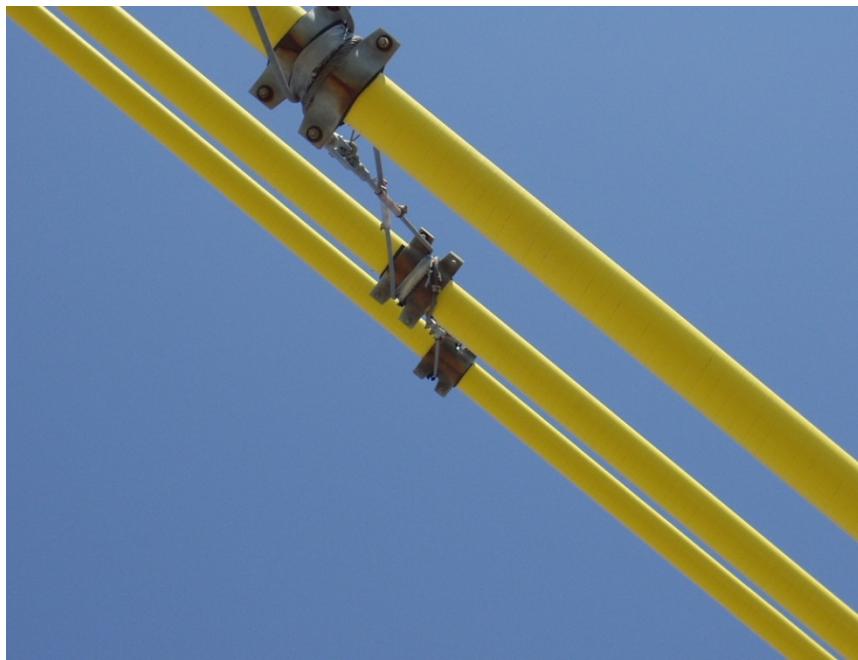


6:54 AM
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Fred Hatman Bridge, U.S.A., 1995



Fred Hatman Bridge, U.S.A., 1995



Fred Hatman Bridge, U.S.A., 1995



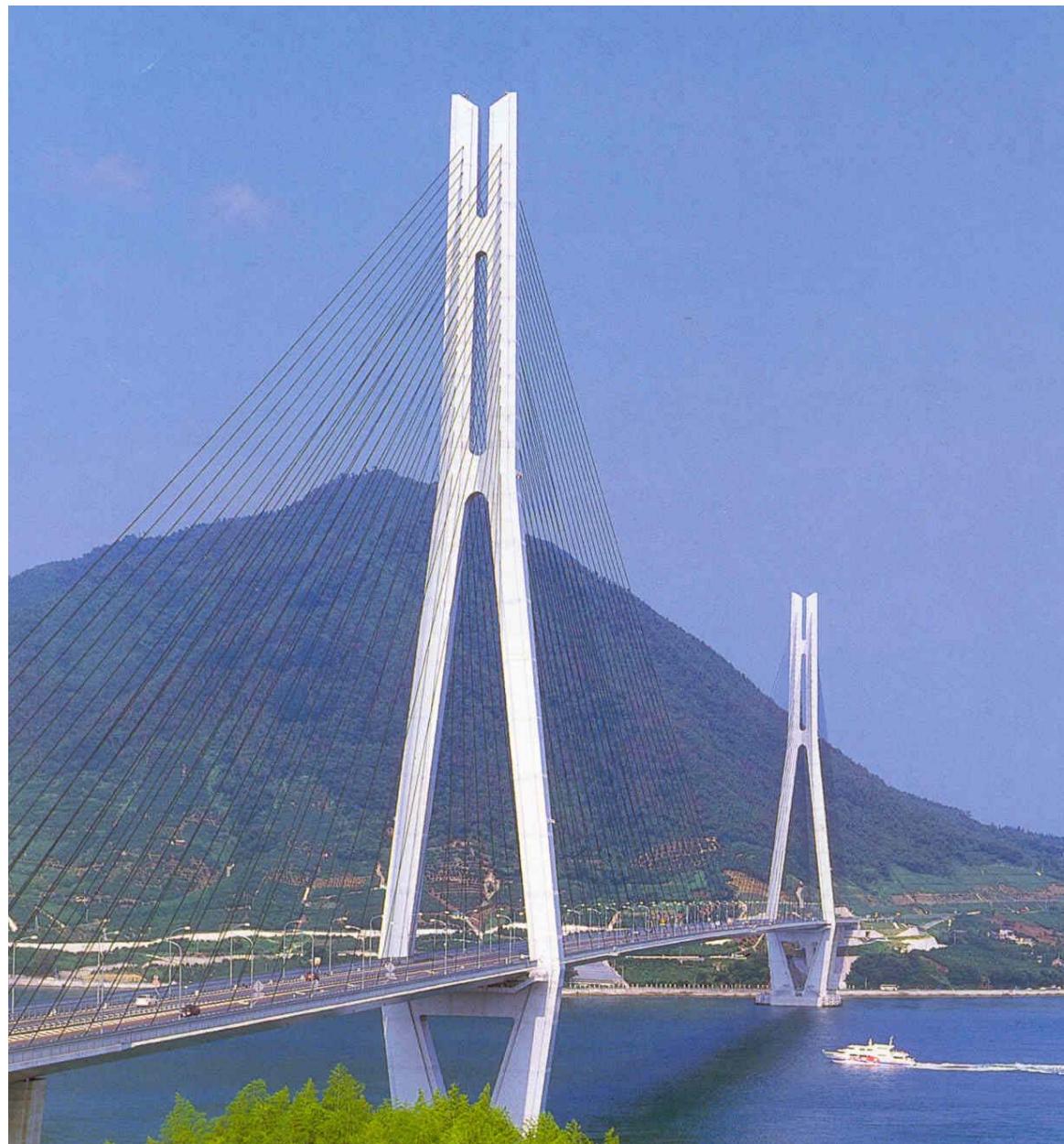
Øresund Cable Stayed Bridge, 1999



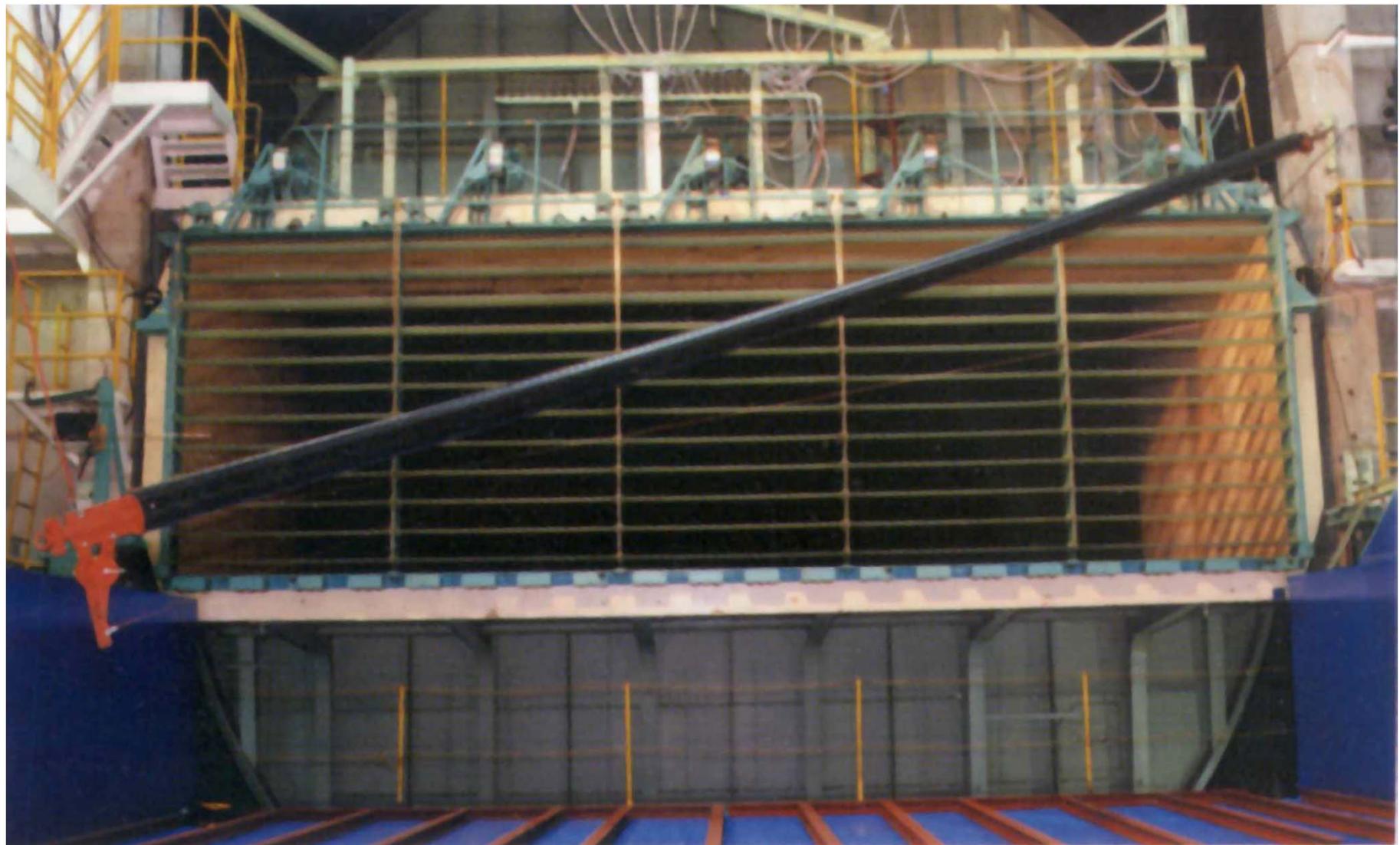
Øresund Cable Stayed Bridge, 1999



Dong Ting Bridge, China



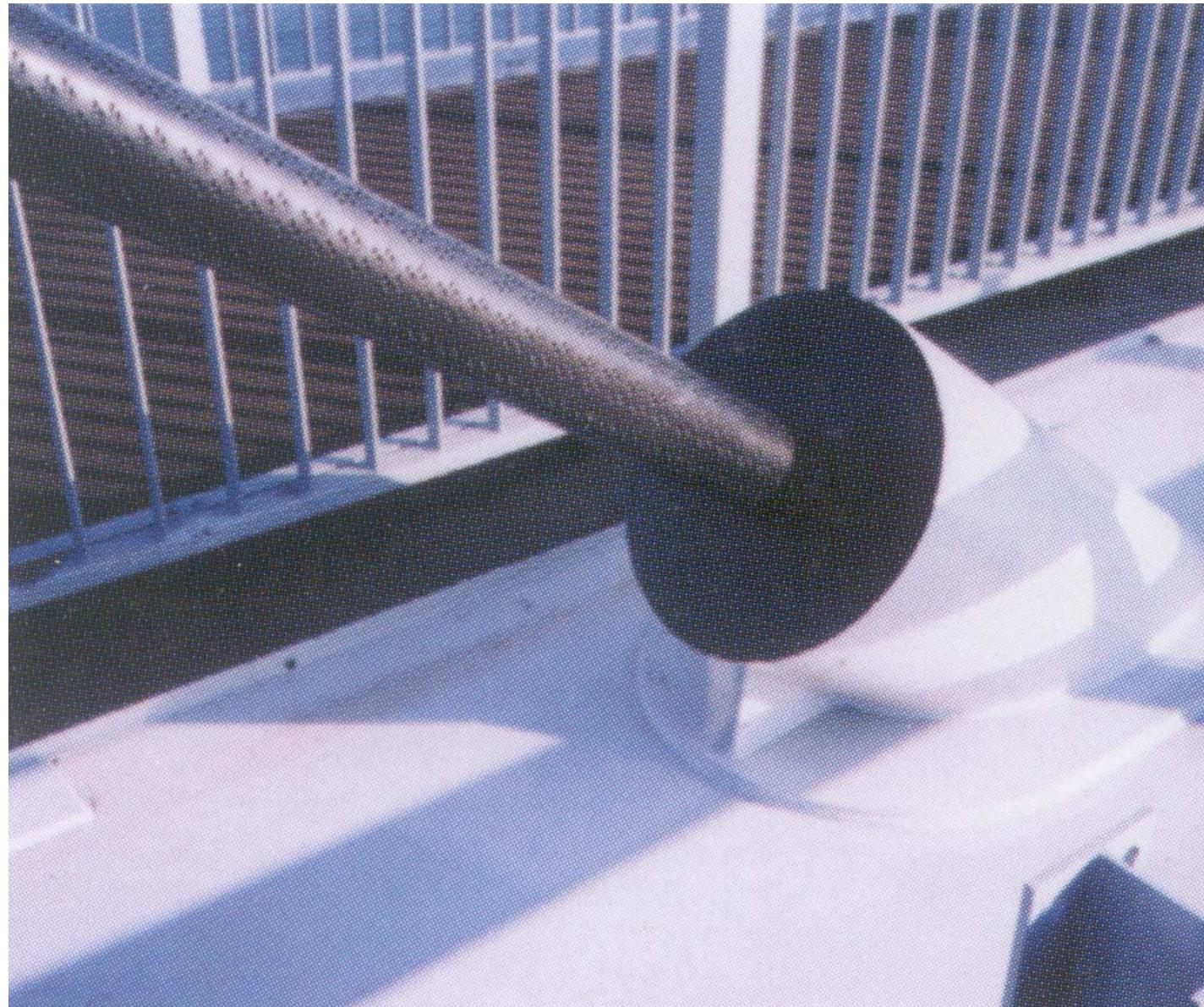
Tatara Bridge, Japan, 1999



Tatara Bridge, Japan, 1999



Tatara Bridge, Japan, 1999



Tatara Bridge, Japan, 1999



Sutong Bridge, Yangtze River, China, 2007



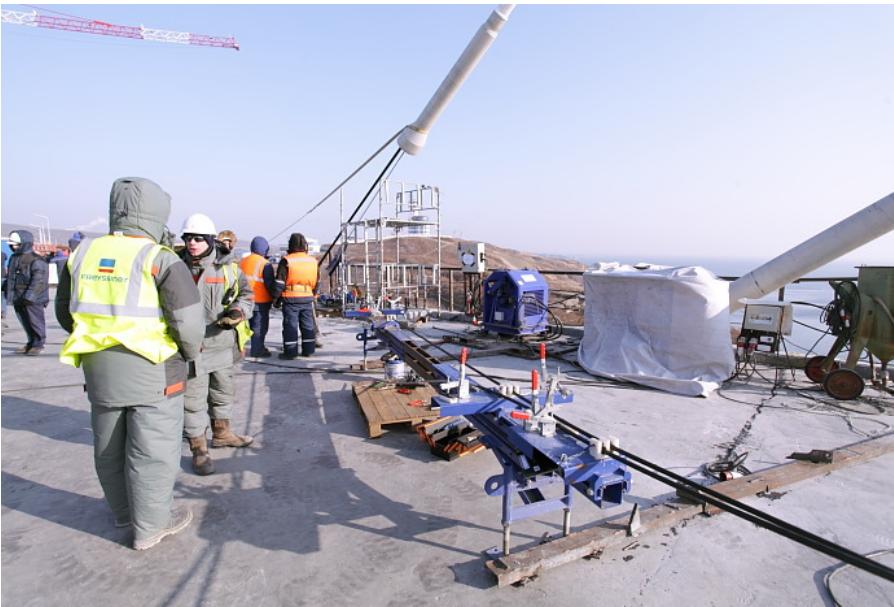
Sutong Bridge, Yangtze River, China, 2007



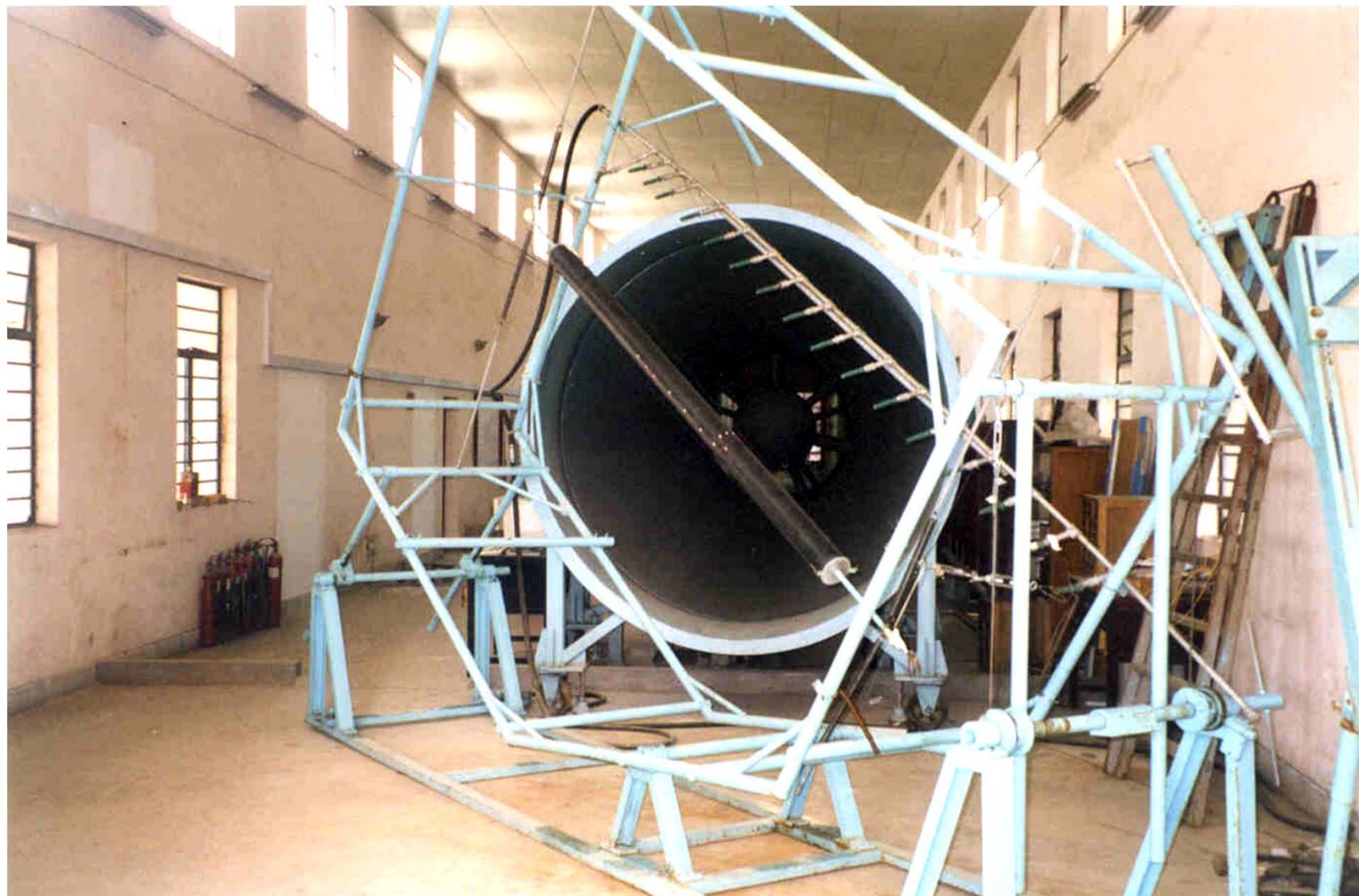
Russky Island Bridge, Vladivostok, Siberia, 2012



Russky Island Bridge, Vladivostok, Siberia, 2012



Russky Island Bridge, Vladivostok, Siberia, 2012



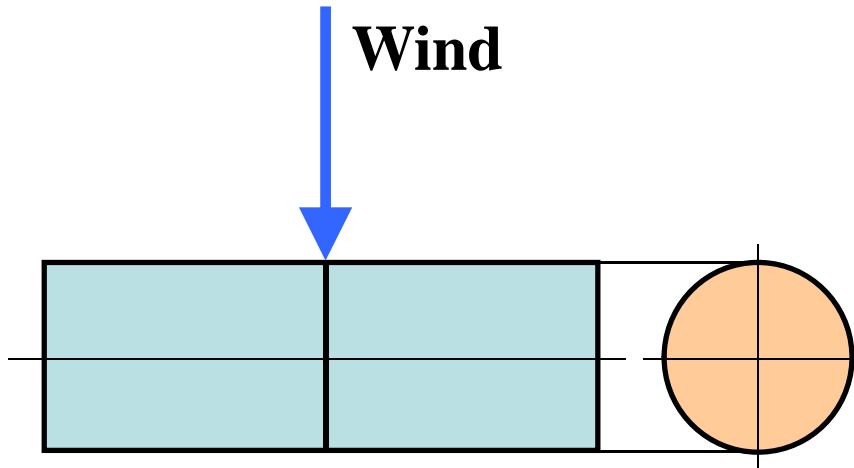
Rain-wind-induced vibrations



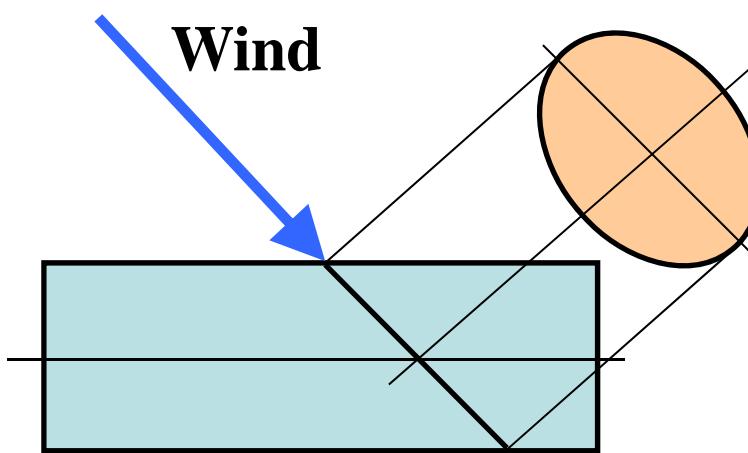
Rain-wind-induced vibrations



Rain-wind-induced vibrations

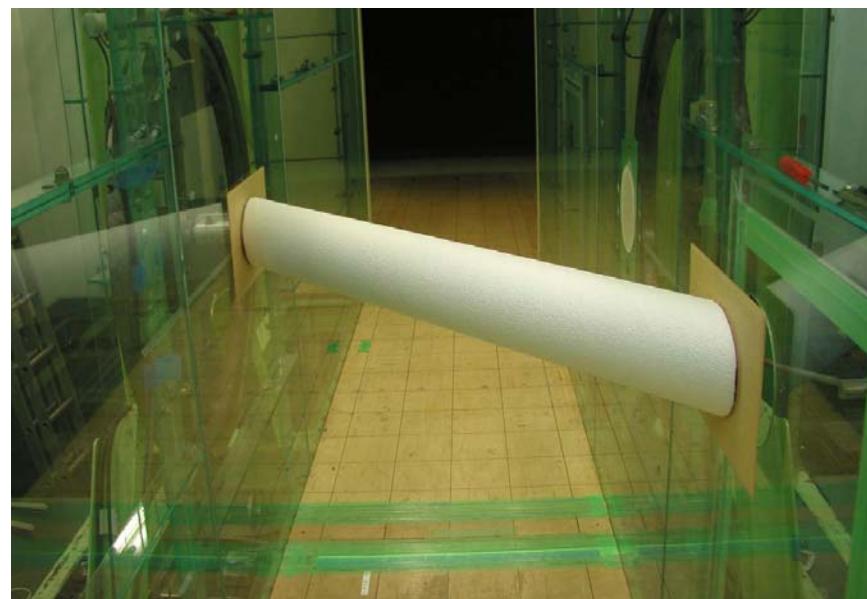
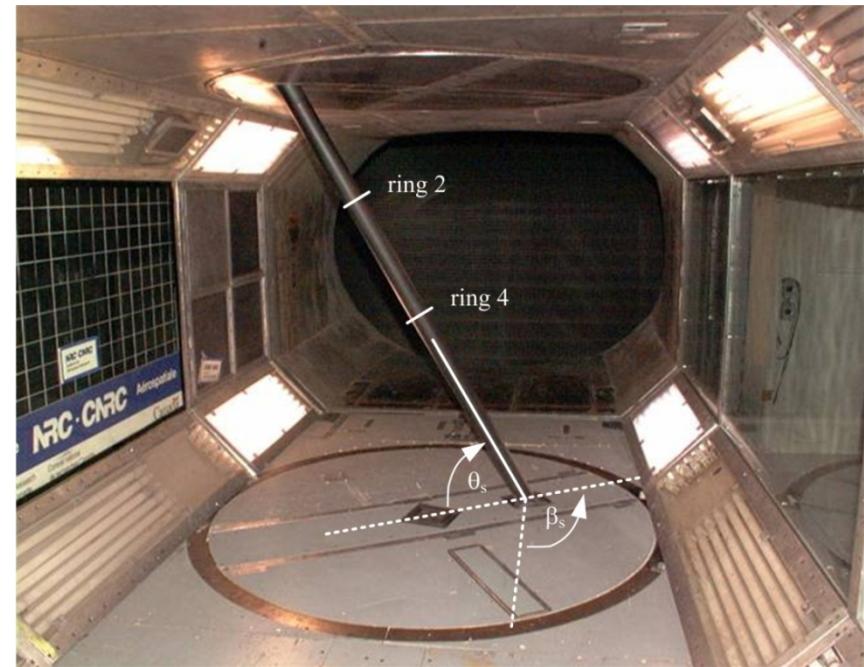
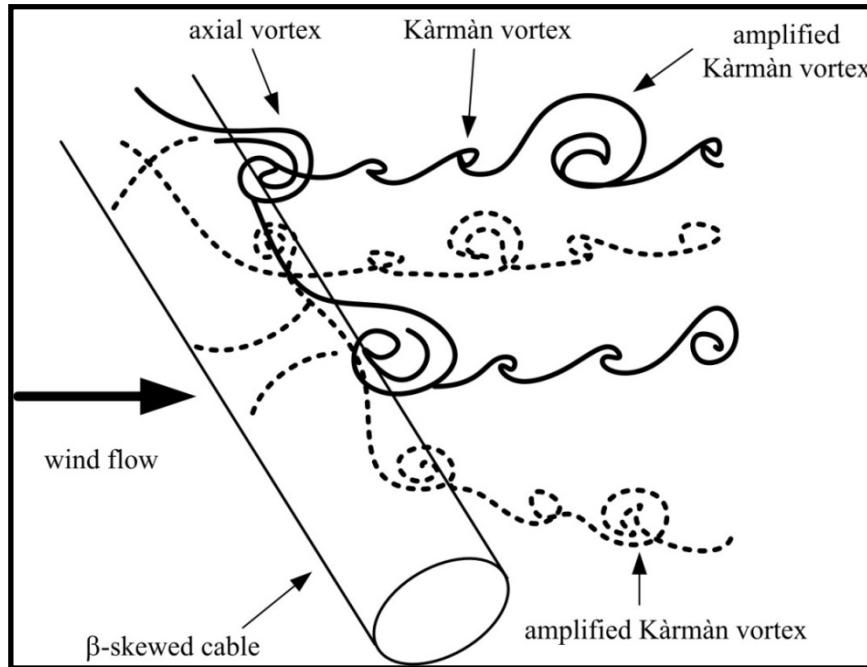


Circular cylinder



Circular cylinder

Aeroelastic instability of yawed dry circular cylinder



Aeroelastic instability of yawed dry circular cylinder

Galloping coefficient

$$a_G = -(c_d + c'_l)$$

Cross-section	Factor of galloping instability a_G	Cross-section	Factor of galloping instability a_G
<p>ICE (ice on cables)</p>	1,0	<p>b</p>	1,0
<p>linear interpolation</p>	$d/b=2$ 2 $d/b=1,5$ 1,7 $d/b=1$ 1,2	<p>$d/b=2$ 2 $d/b=1,5$ 1,7 $d/b=1$ 1,2</p>	$d/b=2,7$ 5 $d/b=5$ 7
<p>linear interpolation</p>	$d/b=2/3$ 1 $d/b=1/2$ 0,7 $d/b=1/3$ 0,4	<p>$d/b=3$ 7,5 $d/b=3/4$ 3,2 $d/b=2$ 1</p>	$d/b=3/4$ 3,2 $d/b=2$ 1

Crosswind galloping

Megaframe beams

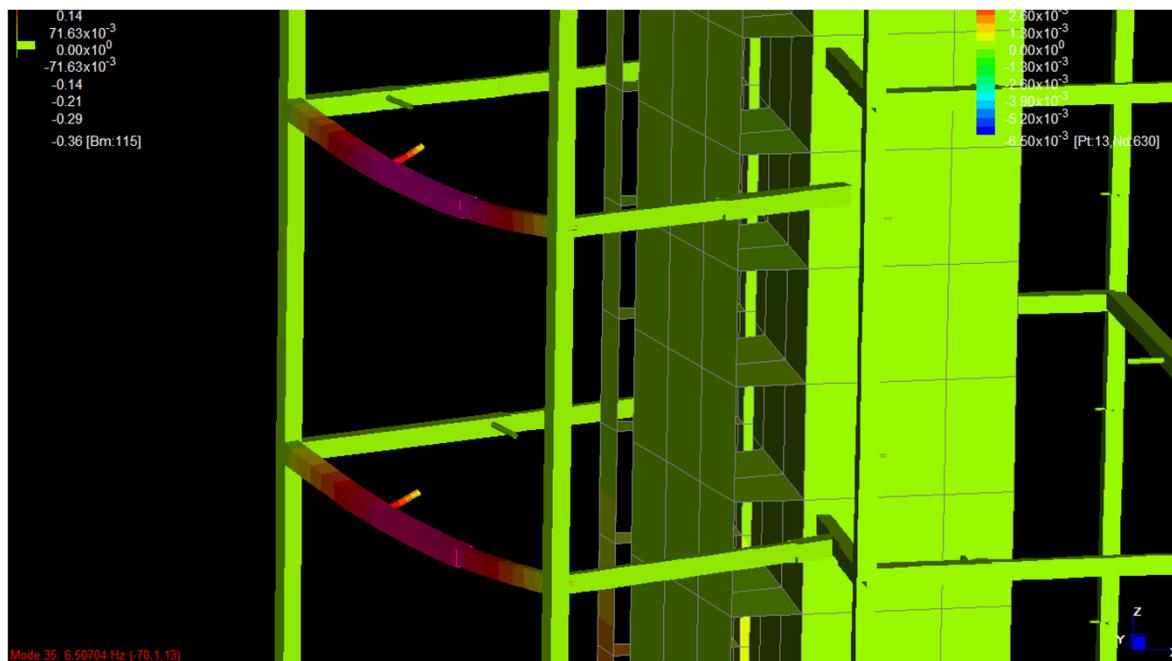
Length L = 11,2 m

Square side b = 600 mm

Mass per unit length m = 148,7 kg/m

Fundamental frequency n = 6,51 Hz

Damping coefficient ζ = 0,002



Megaframe beams

Length L = 11,2 m

Square side b = 600 mm

Mass per unit length m = 148,7 kg/m

Fundamental frequency n = 6,51 Hz

Damping coefficient ζ = 0,002

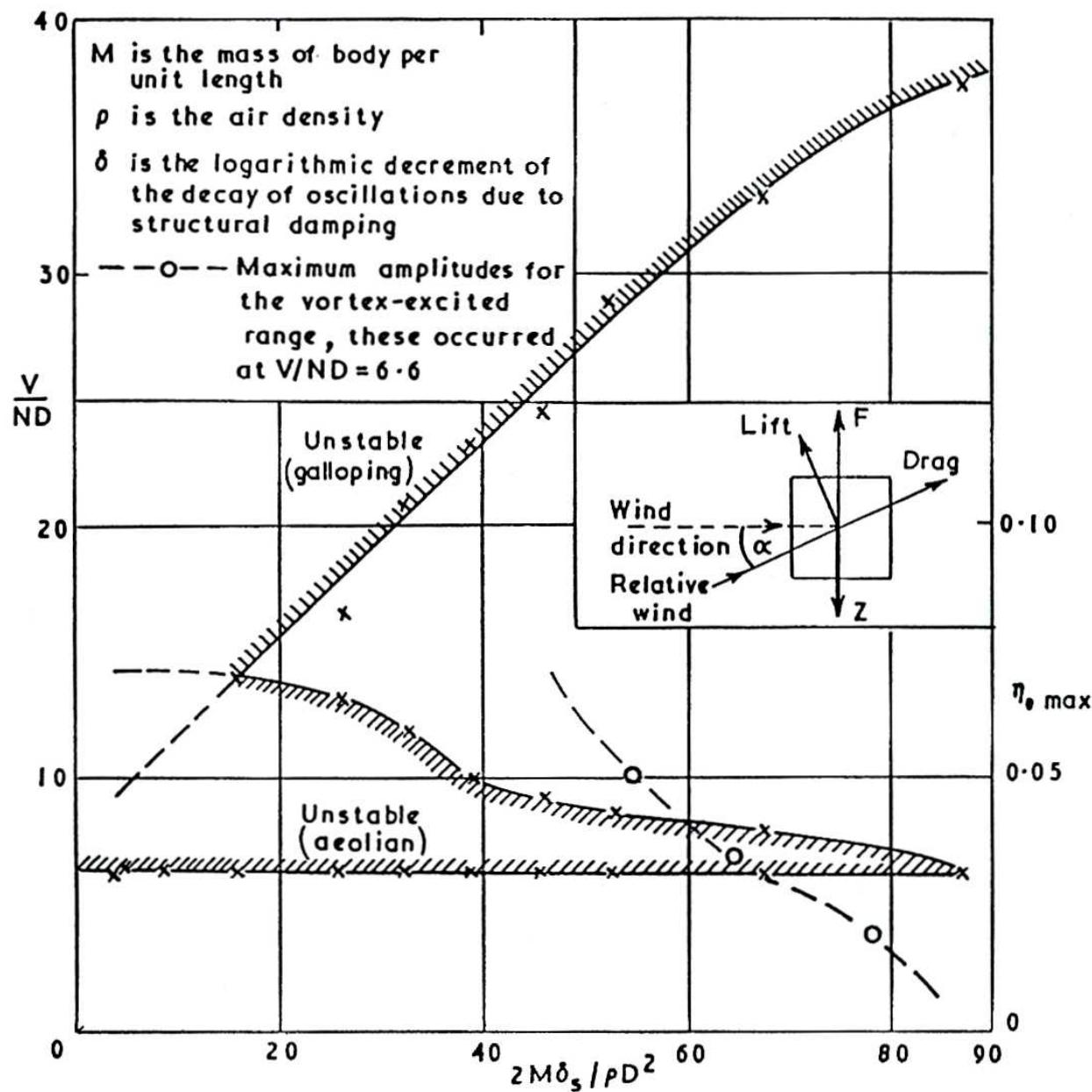
Scruton number

$$Sc = \frac{4\pi m \xi_s}{\rho b^2} = \frac{4\pi \times 148,7 \times 0,002}{1,25 \times 0,60^2} = 8,30$$

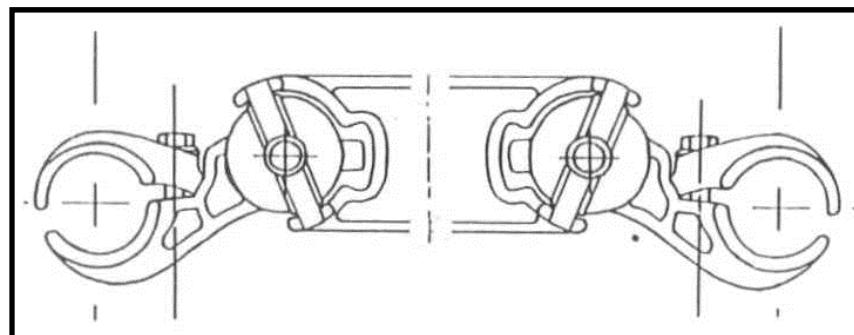
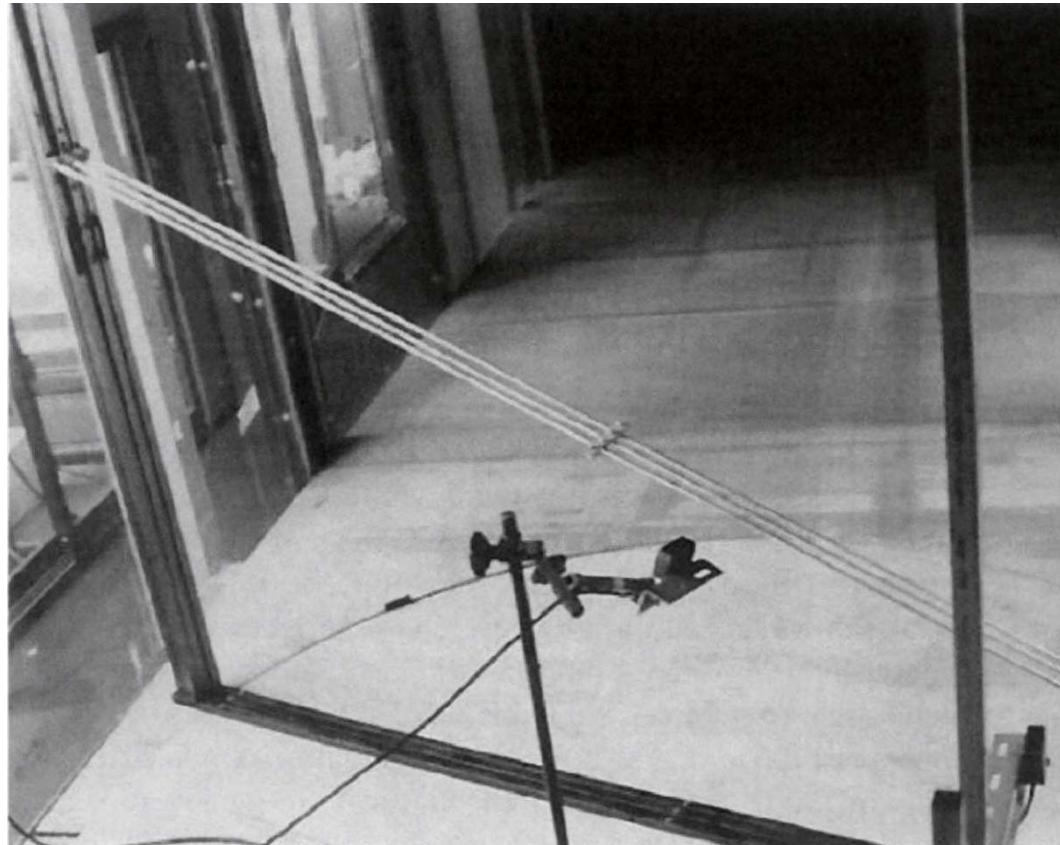
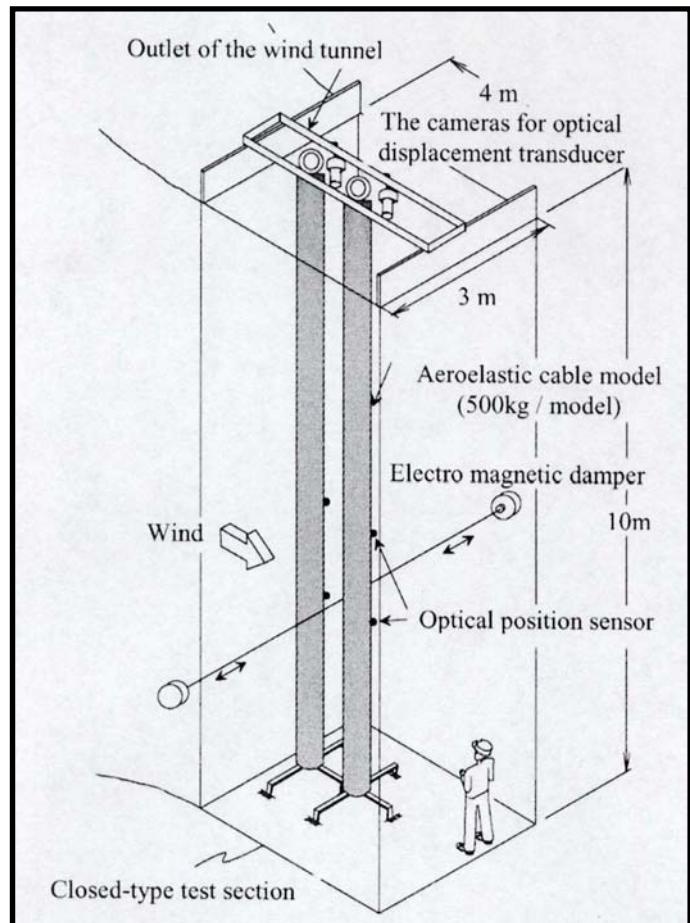
Galloping coefficient $a_G = 1,2$

Galloping critical velocity

$$\bar{u}_{cr} = \frac{2nb}{a_G} \cdot Sc = \frac{2 \times 6,51 \times 0,60}{1,2} \cdot 8,30 = 54,0 \text{ m / s}$$



Galloping and vortex shedding critical interaction domains



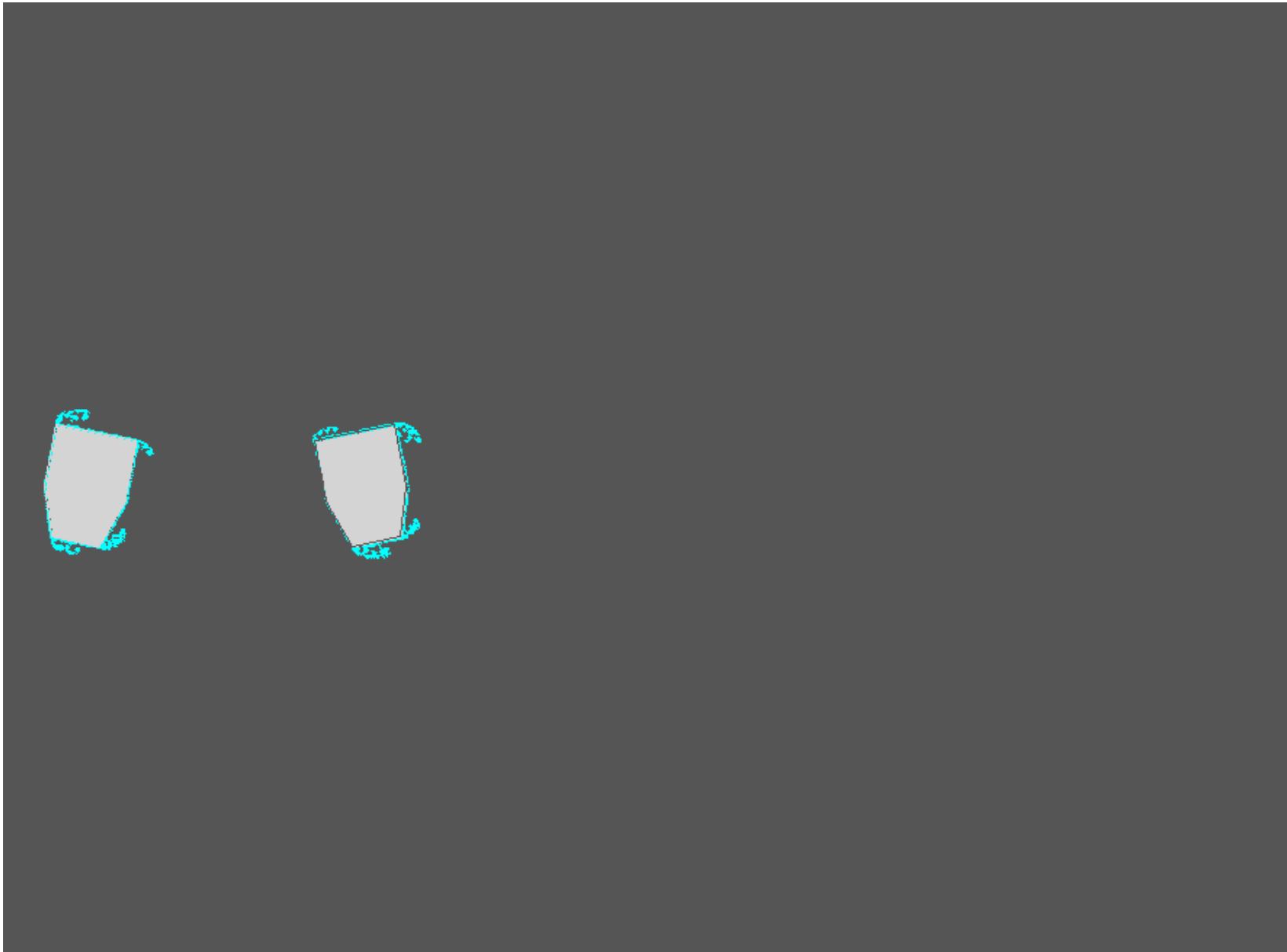
Wake galloping



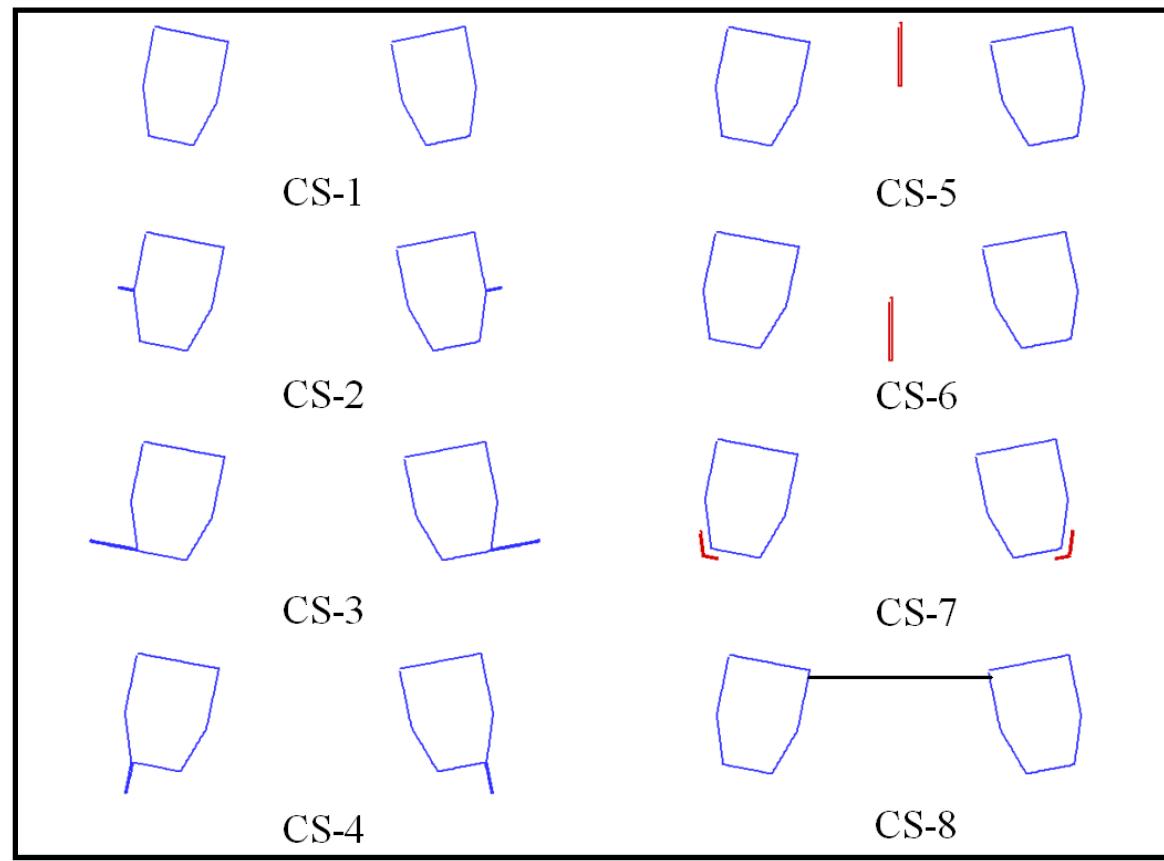
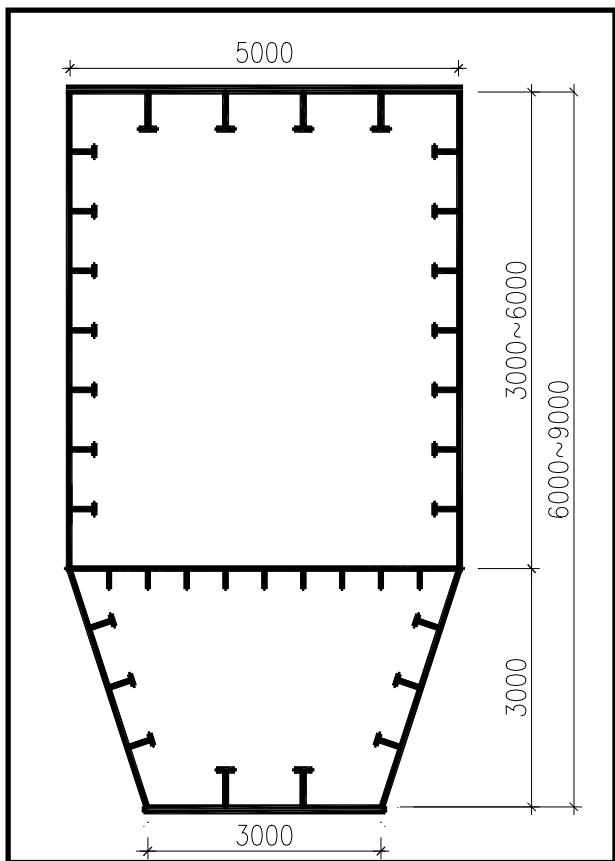
Dong Ping Bridge, China



Lupu Bridge, Shanghai, China, 2003



Lupu Bridge, Shanghai, China, 2003



Lupu Bridge, Shanghai, China, 2003

Lupu Bridge Section



*the State Key Laboratory
for Disaster reduction in Civil Engineering*



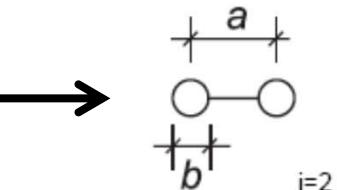
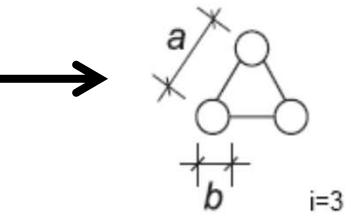
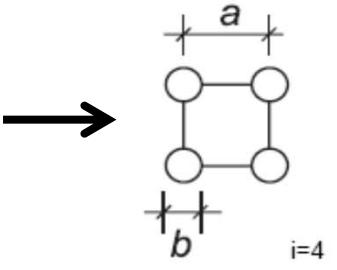
Lupu Bridge, Shanghai, China, 2003

Necessary condition

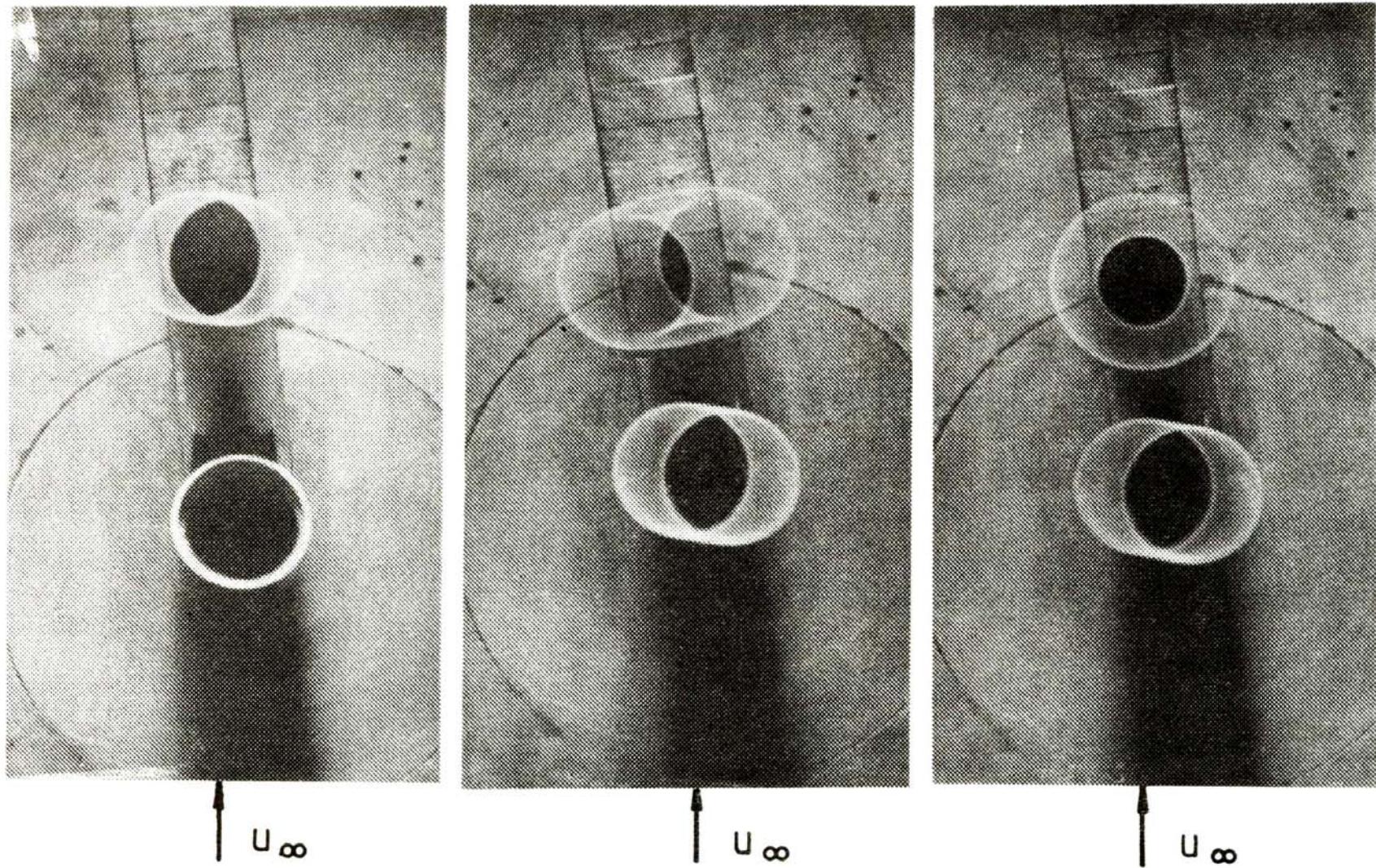
$$a_G > 0$$

Critical velocity

$$\bar{u}_{cr} = \frac{4m\omega_0\xi_s}{\rho ba_G} = \frac{2n_0 b}{a_G} \cdot Sc$$

Number of coupled cylinders	a_G	
	$a/b \leq 1,5$	$a/b \geq 2,5$
	1,5	3,0
	6,0	3,0
	1,0	2,0

Classical galloping for structurally connected circular cylinder



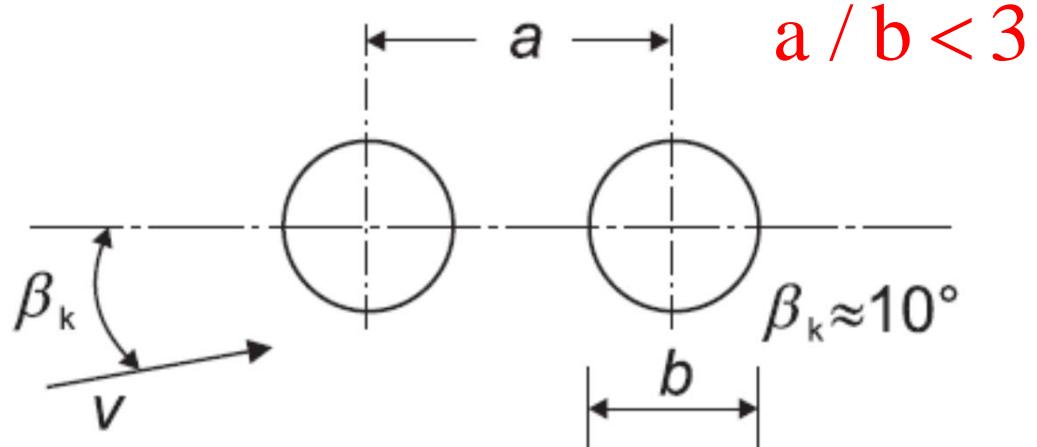
Interference galloping for non-structurally connected
circular cylinder

Necessary condition

$$a_{IG} > 0$$

Critical velocity

$$v_{IG} = 3,5 \cdot n_1 \cdot \sqrt{\frac{a \cdot b}{a_{IG}} \cdot Sc}$$



a_{IG} = Interference Galloping factor

In the lack of more accurate assessments,

a_{IG} can be taken as equal to 3

Interference galloping for non-structurally connected
circular cylinder



Thermoelectric Power Plant, Priolo Gargallo, Siracusa

Coupled chimneys with Tuned Mass Damper (TMD)

$$h = 90 \text{ m}; d = 6,4 \text{ m}; a = 8,4 \text{ m} \Rightarrow a / d = 1,31$$

$$n_1 = 0,80 \text{ Hz}; \xi = 0,08; m = 1.683 \text{ kg / m}$$

$$Sc = \frac{4\pi \cdot m \cdot \xi}{\rho \cdot d^2} = \frac{4\pi \cdot 1.683 \cdot 0,08}{1,25 \cdot 6,4^2} = 33,05$$

Classical galloping for structurally connected chimneys

$$a / d = 1,31 < 1,5 \Rightarrow a_G = 1,5$$

$$\bar{u}_{cr} = \frac{2n_1 b}{a_G} \cdot Sc = \frac{2 \times 0,80 \times 6,4}{1,5} \cdot 33,05 = 226 \text{ m / s}$$

Interference galloping for non – structurally connected chimneys

$$v_{IG} = 3,5 \cdot n_1 \cdot \sqrt{\frac{a \cdot b}{a_{IG}} \cdot Sc} = 3,5 \cdot 0,8 \cdot \sqrt{\frac{8,4 \cdot 6,4}{3} \cdot 33,05} = 68 \text{ m / s}$$