

Problema 1

a)



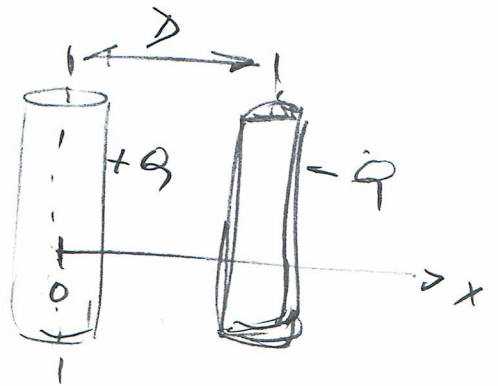
Interior: $2\pi r L E = \frac{q_{encerrada}}{\epsilon_0}$

$$\frac{q_{encerrada}}{\text{Volumen encerrado}} = \frac{Q}{\text{Vol. total}} \Rightarrow \frac{q_{enc}}{\pi r^2 L} = \frac{Q}{\pi R^2 L}$$

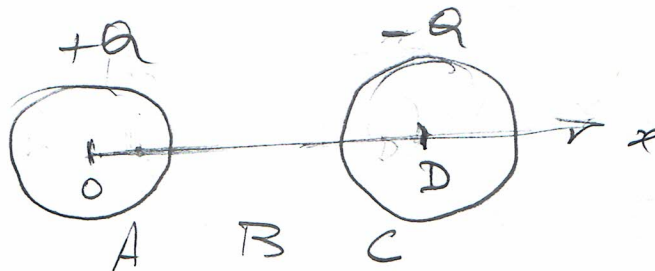
$$q_{enc} = Q \frac{r^2}{R^2} \Rightarrow 2\pi r L E = \frac{Q r^2}{\epsilon_0 R^2} \Rightarrow$$

$$\Rightarrow \boxed{E = \frac{Q \cdot r}{2\pi \epsilon_0 R^2 L}} \quad (0 \leq r \leq R)$$

Exterior: $2\pi r L E = \frac{Q}{\epsilon_0} \Rightarrow \boxed{E = \frac{Q}{2\pi \epsilon_0 L r}} \quad (R \leq r < \infty)$



b)



Zona A: $0 \leq x \leq R$

Zona B: $R \leq x \leq D - R$

Zona C: $D - R \leq x \leq D$

Zona A:

$$\vec{E}_+ \quad \vec{E}_- \quad E_A = E_+ + E_- = \frac{Qx}{2\pi \epsilon_0 R^2 L} + \frac{Q}{2\pi \epsilon_0 L(D-x)}$$

$$\boxed{E_A = \frac{Q}{2\pi \epsilon_0 L} \left(\frac{x}{R^2} + \frac{1}{D-x} \right)}$$

Zona B:

$$\vec{E}_+ \quad \vec{E}_- \quad E_B = E_+ + E_- = \frac{Q}{2\pi \epsilon_0 L x} + \frac{Q}{2\pi \epsilon_0 L(D-x)}$$

$$\boxed{E_B = \frac{Q}{2\pi \epsilon_0 L} \left(\frac{1}{x} + \frac{1}{D-x} \right)}$$

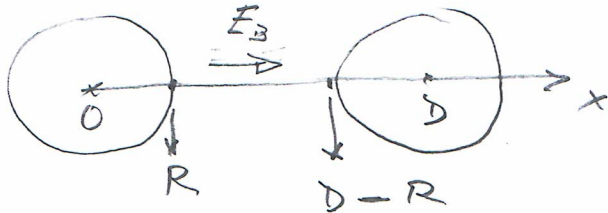
(continuación Problema 1)

Zona C $\Rightarrow \vec{E}_+$
 $\Rightarrow \vec{E}_-$

$$\vec{E}_C = \vec{E}_+ + \vec{E}_- = \frac{Q}{2\pi\epsilon_0 L x} + \frac{Q(D-x)}{2\pi\epsilon_0 L R^2}$$

$$\vec{E}_C = \frac{Q}{2\pi\epsilon_0 L} \left(\frac{1}{x} + \frac{D-x}{R^2} \right)$$

e)



$$V = \int_R^{D-R} E_B dx$$

$$E_B = \frac{Q}{2\pi\epsilon_0 L} \left(\frac{1}{x} + \frac{1}{D-x} \right) \Rightarrow V = \frac{Q}{2\pi\epsilon_0 L} \int_R^{D-R} \left(\frac{1}{x} + \frac{1}{D-x} \right) dx$$

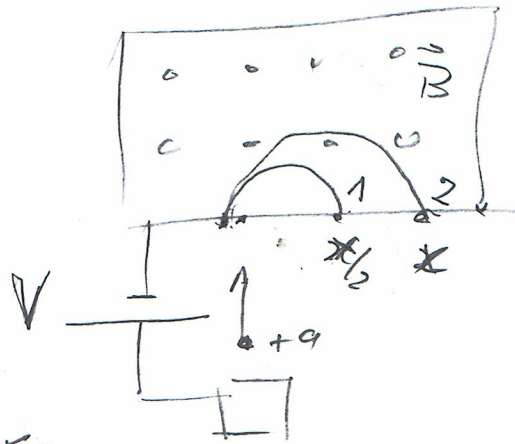
$$V = \frac{Q}{2\pi\epsilon_0 L} \left[\ln(x) - \ln(D-x) \right]_R^{D-R}$$

$$V = \frac{Q}{\pi\epsilon_0 L} \ln\left(\frac{D-R}{R}\right)$$

Problema 2

a) $\frac{m v^2}{2} = V_a q \Rightarrow$

$$V_a = \frac{m v^2}{2q}$$



b) $q N_b B = \frac{m v_b^2}{r} = \frac{m v_b^2}{(x/2)} \Rightarrow N_b = \frac{q B x}{2m} \rightarrow \text{cámara 2}$

$$\Rightarrow V_b = \frac{m v_b^2}{2q} = \frac{m}{2q} \left(\frac{q B x}{2m} \right)^2 = \frac{q B^2 x^2}{8m} = V_b$$

c) Cámara 1: $\frac{m_c v_c^2}{x/4} = q N_c B \Rightarrow N_c = \frac{q B x}{4m_c}, V_b q = \frac{m_c v_c^2}{2} \Rightarrow$

$$\Rightarrow V_b q = \frac{m_c}{2} \left(\frac{q B x}{4m_c} \right)^2 = \frac{m_c}{32m_c^2} q^2 B^2 x^2 \Rightarrow$$

$$\frac{32 V_b}{q B^2 x^2} = \frac{m_c}{m_c^2} \Rightarrow \text{sustituyendo } V_b \text{ de b)}$$

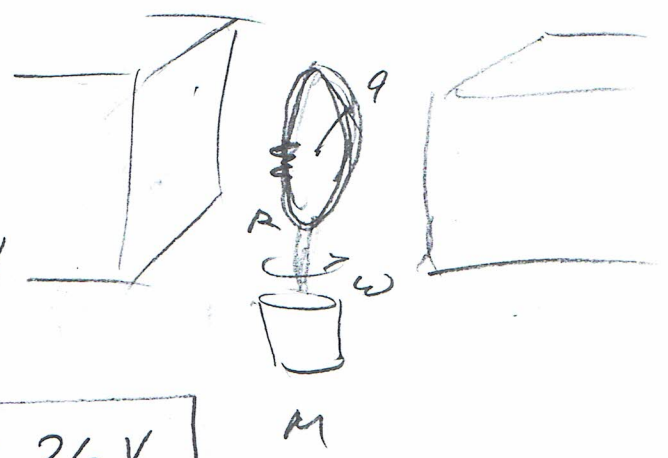
$$4 = \frac{m_c}{m_b}$$

Problema 3

a) $\phi_B(t) = B \cdot S \cdot \cos \omega t$

$\phi_B(t) = \pi a^2 B \cos \omega t$

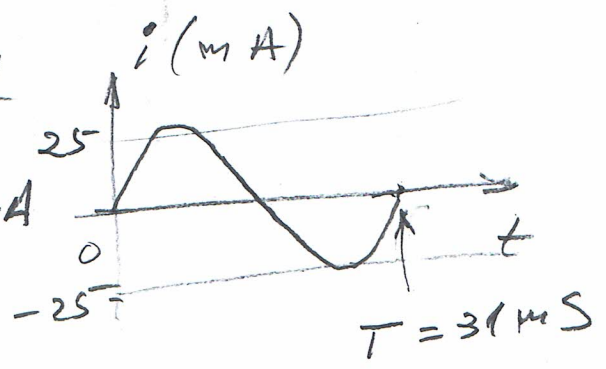
$\mathcal{E} = - \frac{d\phi_B}{dt} = \underbrace{\pi a^2 \omega B}_{\mathcal{E}_0} \sin \omega t$



$\mathcal{E}_{\text{max}} = \mathcal{E}_0 = \pi a^2 \omega B \approx 1,26 \text{ V}$

b) $i(t) = \frac{\mathcal{E}}{R} = \frac{\mathcal{E}_0}{R} \sin \omega t$

$i(t) = i_0 \sin \omega t \quad i_0 = 25 \text{ mA}$

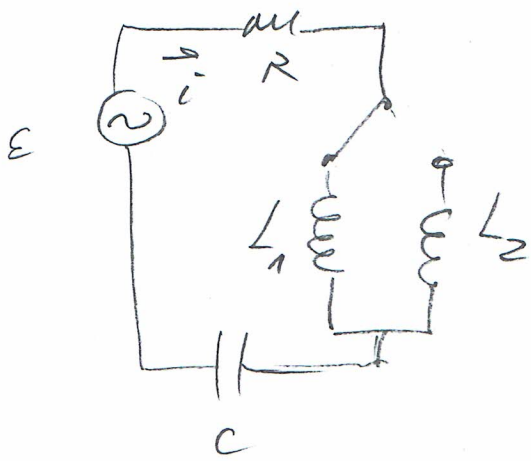


$T = \frac{2\pi}{\omega} = 31 \text{ ms}$

e) $P = i_{\text{rms}}^2 R \quad i_{\text{rms}} = \frac{i_0}{\sqrt{2}} \Rightarrow P = \frac{i_0^2 R}{2}$

$P = 15,6 \text{ mW}$

PROBLEMA 4

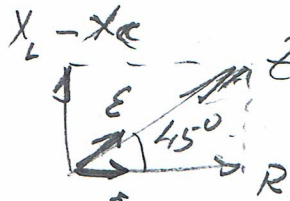


a) Con L_1 $\phi = 0 \Rightarrow$ resonancia

$$\Rightarrow \omega = \frac{1}{\sqrt{LC}} = 1000 \frac{\text{rad}}{\text{s}}$$

$$f \approx 159 \text{ Hz}$$

b) Con L_2 :



$$\Rightarrow X_L - X_C = R \Rightarrow$$

$$X_L = X_C + R = \frac{1}{\omega C} + R = 300 \Omega = \omega L_2$$

$$\Rightarrow L_2 = \frac{300}{\omega} = 0,30 \text{ H} = L_2$$

c) $E_{\text{rms}} = 220 \text{ V}$ $P = E_{\text{rms}} i_{\text{rms}} \cos \varphi = \frac{E_{\text{rms}}^2}{Z} \cos \varphi$

$$\varphi = 45^\circ \quad Z = \sqrt{(X_L - X_C)^2 + R^2} = \sqrt{(300 - 200)^2 + 100^2} = 141,4$$

$$\Rightarrow P = \frac{220^2}{141,4} \cos 45^\circ \quad P = 242 \text{ W}$$