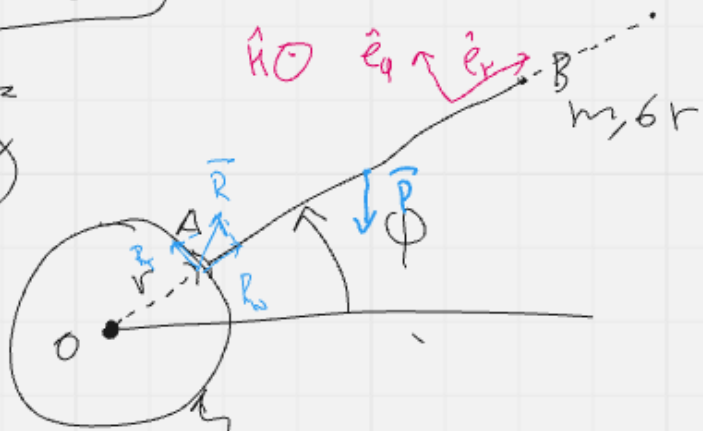
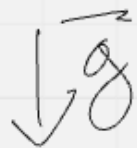


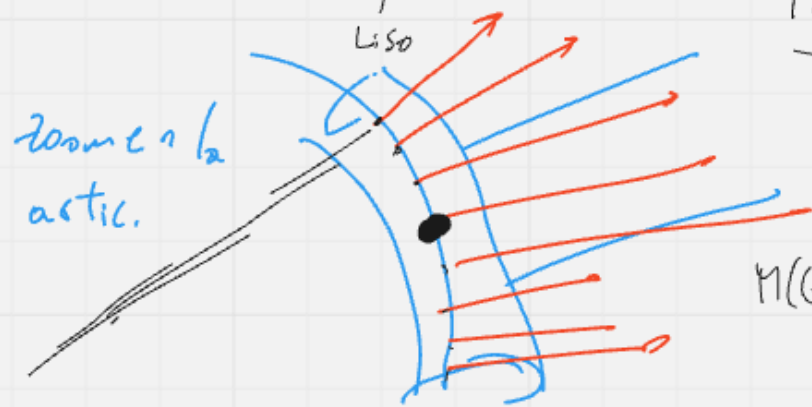
Ejercicio 7



a) E de mov.

1ª Cond + 2ª Cond } Fuerzas?
Energía

1ª C: $m\vec{a}_C = \vec{R} + \vec{N} - m\vec{g}(\cos\phi\vec{e}_r + \sin\phi\vec{e}_\theta)$



2ª C: ¿Dónde me paro? } Si me paro en O, los torques en A dan cero!

$M(g-Q) \times \vec{a}_Q + \frac{d(\Pi_Q \vec{\omega})}{dt} = \vec{M}_O^{Ext}$

O es parte de la extensión rígida de la barra.

↳ Todas las fuerzas son radiales.

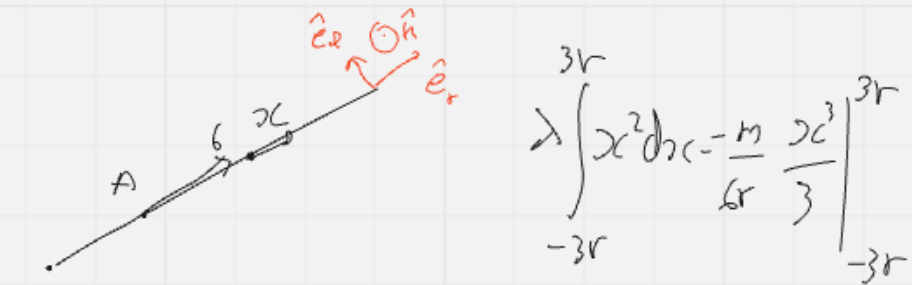
Camino 1: 2ª Cond: $\frac{d\Pi_O \vec{\omega}}{dt} = \vec{M}_O^{Ext}$

Hallo Π_O y después lo muevo a O con Steiner $\Pi_O = \frac{1}{6} + \int_0^l \dots$

Hallo \mathbb{I}_G y después lo muevo a 0 con Steiner $\mathbb{I}_0 = \mathbb{I}_G + \int_0^r \dots$

$$\begin{pmatrix} \int \lambda dx(y^2+z^2) & -\int \lambda dxxy & -\int \lambda dxxz \\ 0 & \int \lambda dx(z^2+x^2) & -\int \lambda dxyz \\ 0 & 0 & \int \lambda dx(y^2+z^2) \end{pmatrix} dm = \lambda dx$$

$\hookrightarrow \lambda = \frac{m}{6r}$



$$\lambda \int_{-3r}^{3r} x^2 dx = \frac{m}{6r} \frac{x^3}{3} \Big|_{-3r}^{3r}$$

$$= \frac{m}{6r} \cdot \frac{54r^3}{3} = 3mr^2$$

$$3mr^2 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\left(\mathbb{I}_0 \right)_{\alpha\beta} = m(6-0)^2 \delta_{\alpha\beta} - m(6-0)(6-0)_{\alpha\beta}$$

$\begin{cases} 1 \text{ si } \alpha = \beta \\ 0 \text{ si } \alpha \neq \beta \end{cases}$

$$\begin{aligned} (6-0) &= (4r, 0, 0) \\ (6-0)^2 &= 16r^2 \end{aligned}$$

$$\mathbb{I}_0 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 16mr^2 & 0 \\ 0 & 0 & 16mr^2 \end{pmatrix}$$

$$\mathbb{I}_0 = \mathbb{I}_G + \mathbb{I}_A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} 19mr^2$$

Valores de la 2ª coord:

$$\vec{\omega} = \dot{\varphi} \hat{n} = \begin{pmatrix} 0 \\ 0 \\ \dot{\varphi} \end{pmatrix}$$

$$\frac{d}{dt} \left(\mathbb{I}_0 \vec{\omega} \right) = \vec{\tau}_g = 4r \hat{e}_r \times mg (-\cos\varphi \hat{e}_\varphi - \sin\varphi \hat{e}_r)$$

$$= -4mg r \cos\varphi \hat{n}$$

$$\mathbb{I}_O \vec{\omega} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} 19mr^2 \begin{pmatrix} 0 \\ 0 \\ \dot{\varphi} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 19mr^2 \dot{\varphi} \end{pmatrix} = 19mr^2 \dot{\varphi} \hat{k} \implies \frac{d}{dt} (\mathbb{I}_O \vec{\omega}) = 19mr^2 \ddot{\varphi} \hat{k}$$

$$\stackrel{ZC}{\implies} 19mr^2 \ddot{\varphi} + 4mgR \cos \varphi = 0 \implies \boxed{\ddot{\varphi} = -\frac{4g}{19r} \cos \varphi}$$

Lagrange 2 (Energy): $P^{res} = 0 \implies \frac{dE}{dt} = 0 \quad \left| \quad E = T + U \right.$

$$T = \frac{1}{2} m \dot{\vec{v}}^2 + \underbrace{\left(\frac{1}{2} \vec{\omega} \cdot \mathbb{I}_O \vec{\omega} + r \vec{\omega} \cdot [\vec{\omega} \times (R_0 - \vec{r}_0)] \right)}_{E_{rot}} = \frac{1}{2} \vec{\omega} \cdot \mathbb{I}_O \vec{\omega} = \frac{19 \dot{\varphi}^2 m r^2}{2}$$

$\hookrightarrow 19 \dot{\varphi}^2 m r^2 \hat{k}$

$$U = mg 4R \sin \varphi$$

$$E = T + U = \frac{19}{2} \dot{\varphi}^2 m r^2 + mg 4R \sin \varphi \implies \frac{dE}{dt} = 0 \implies 19 \dot{\varphi} \ddot{\varphi} m r^2 + mg 4R \dot{\varphi} \cos \varphi = 0$$

$$\implies \boxed{19 \ddot{\varphi} m r^2 + mg 4R \cos \varphi = 0}$$

b) Los momentos de las reacciones desde O son 0 : Son todas variables.

Resultantes en A y Momento desde A

Vuelvo a la 1ª Coord: $m\vec{a}_G = R_N \hat{e}_r + R_T \hat{e}_\varphi - mg(\cos\varphi \hat{e}_\varphi + \sin\varphi \hat{e}_r)$

$$\vec{r}_G = 4r \hat{e}_r$$

$$\vec{v}_G = 4r\dot{\varphi} \hat{e}_\varphi$$

$$\vec{a}_G = 4r\ddot{\varphi} \hat{e}_\varphi - 4r\dot{\varphi}^2 \hat{e}_r$$

$$m4r\ddot{\varphi} \hat{e}_\varphi - m4r\dot{\varphi}^2 \hat{e}_r = R_N \hat{e}_r + R_T \hat{e}_\varphi - mg(\cos\varphi \hat{e}_\varphi + \sin\varphi \hat{e}_r)$$

$$\begin{cases} R_N = mg\sin\varphi - m4r\dot{\varphi}^2 \\ R_T = mg\cos\varphi + m4r\ddot{\varphi} \end{cases}$$

$$\ddot{\varphi} = -\frac{4g}{19r} \cos\varphi$$

$$R_T = mg\cos\varphi - \frac{16mg}{19} \cos\varphi = \boxed{\frac{3}{19} mg\cos\varphi}$$

Para R_N preciso $\dot{\varphi} \rightarrow$ Pre integra la ecu de mov.

$$\int \ddot{\varphi} \dot{\varphi} dt = -\frac{4g}{19r} \int \cos \varphi \dot{\varphi} dt$$

$$\left(\begin{array}{l} \dot{\varphi} = \frac{d\varphi}{dt} \rightarrow \dot{\varphi} dt = d\varphi \\ \ddot{\varphi} = \frac{d\dot{\varphi}}{dt} \rightarrow \ddot{\varphi} dt = d\dot{\varphi} \end{array} \right)$$

$$\int_{\dot{\varphi}_0}^{\dot{\varphi}} \dot{\varphi} d\dot{\varphi} = -\frac{4g}{19r} \int_{\varphi_0}^{\varphi} \cos \varphi d\varphi$$

$$\frac{\dot{\varphi}^2}{2} - \frac{\dot{\varphi}_0^2}{2} = -\frac{4g}{19r} (\sin \varphi - \sin \varphi_0)$$

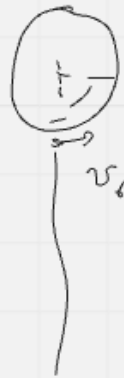
$\begin{array}{c} \text{---} \pi/2 \\ \uparrow \\ \sin \varphi_0 \end{array}$

$$\boxed{\dot{\varphi}^2 = \frac{\dot{\varphi}_0^2}{r^2} - \frac{8g}{19r} (\sin \varphi + 1)}$$

$$R_N = mg \sin \varphi - 4m r \dot{\varphi}^2$$

$$= mg \sin \varphi + \frac{32mg}{19} (\sin \varphi + 1) - \frac{4m v_0^2}{r}$$

$$v_A(\varphi = -\pi/2) = v_0 \Rightarrow \dot{\varphi}_0 = \frac{v_0}{r}$$



$$\begin{array}{l} \vec{r}_A = r \vec{e}_r \\ \vec{v}_A = r \dot{\varphi} \vec{e}_\varphi \\ v_A(\varphi = -\pi/2) = r \dot{\varphi}(\varphi = -\pi/2) \vec{e}_\varphi \\ = v_0 \vec{e}_\varphi \end{array}$$

$$R_N = mg \sin \varphi - 4mrv \dot{\varphi}^2$$

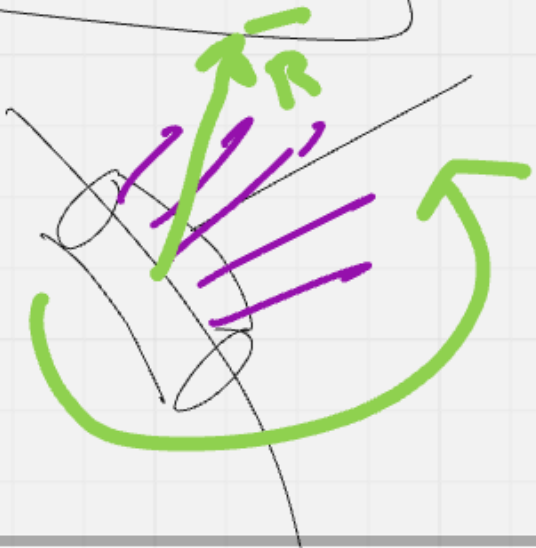
$$= mg \sin \varphi + \frac{32mg}{19} (\sin \varphi + 1) - \frac{4mrv \dot{\varphi}^2}{r}$$

$$R_N = \frac{51mg \sin \varphi}{19} + \frac{32mg}{19} - \frac{4mrv \dot{\varphi}^2}{r}$$

$$\vec{R} = \left(\frac{51mg \sin \varphi}{19} + \frac{32mg}{19} - \frac{4mrv \dot{\varphi}^2}{r} \right) \vec{e}_r + \frac{3}{19} mg \cos \varphi \vec{e}_\varphi$$

$$R_T = \frac{3}{19} mg \cos \varphi$$

$$\vec{M}_{Q_1}^{Ext} = \vec{M}_{Q_2}^{Ext} + \vec{R}^{Ext} \times (Q_1 - Q_2)$$



$$\vec{M}_O^R = 0$$

$$\vec{M}_A^R = \vec{M}_O^R + \vec{R} \times (r \hat{e}_r) = -\frac{3}{19} mgr \cos \varphi \hat{k}$$