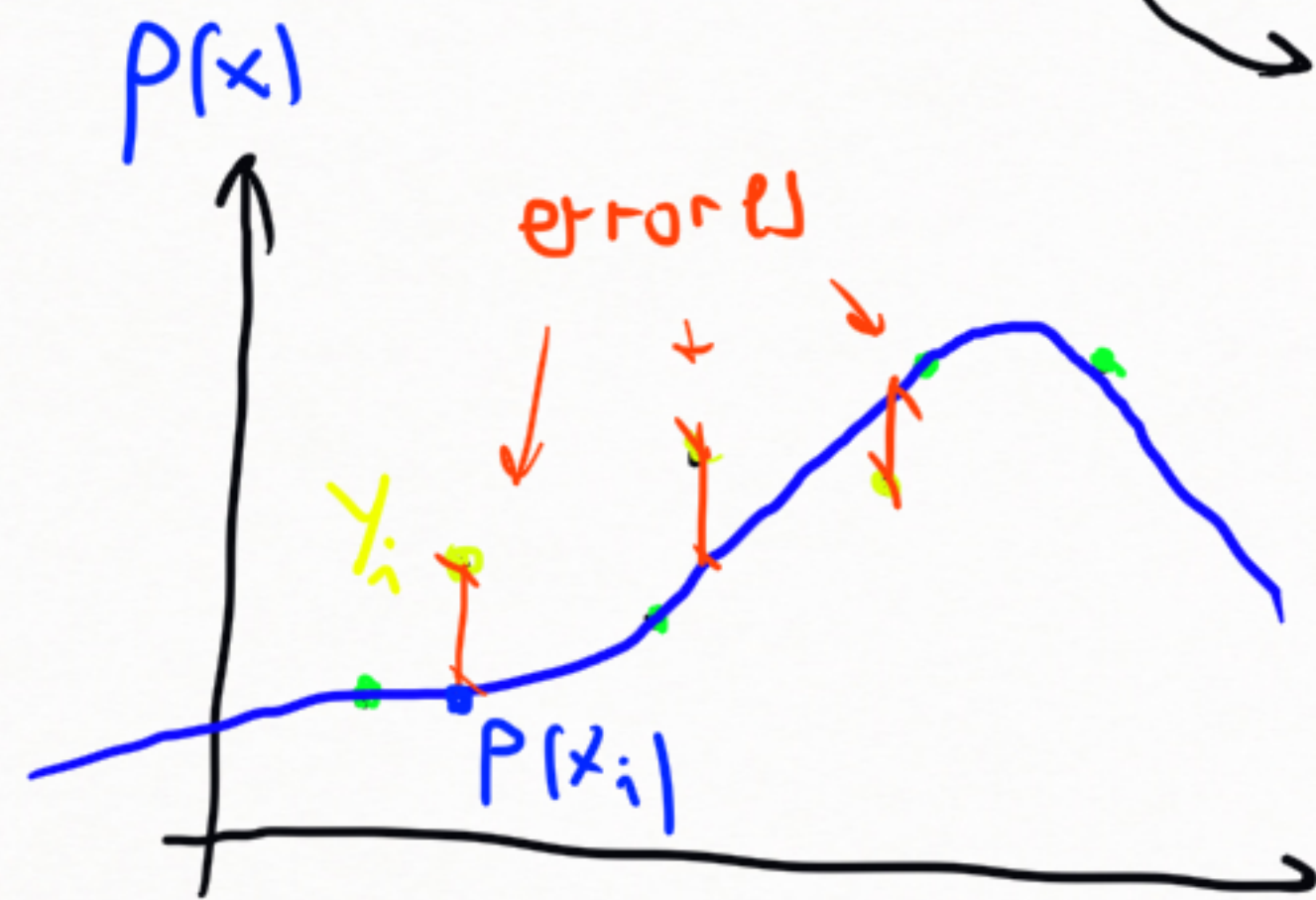


$\{(x_i, y_i) \mid i=1 \dots n\}$

→ "Entrenamiento"

→ "Verificación"



$x_i$  error  $|P(x_i) - y_i|$

Interpolación polinomial

Error de interpolación

Interpolación a trozos.

Prop.:  $n+1$  puntos  $(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$   
 $x_i \neq x_j$  si  $i \neq j$

$\Rightarrow \exists!$   $p(x)$  polinomio de grado  $\leq n$  que  $*$  interpola

$$\forall i=0, \dots, n \quad p(x_i) = y_i$$

3 métodos para hallarlo

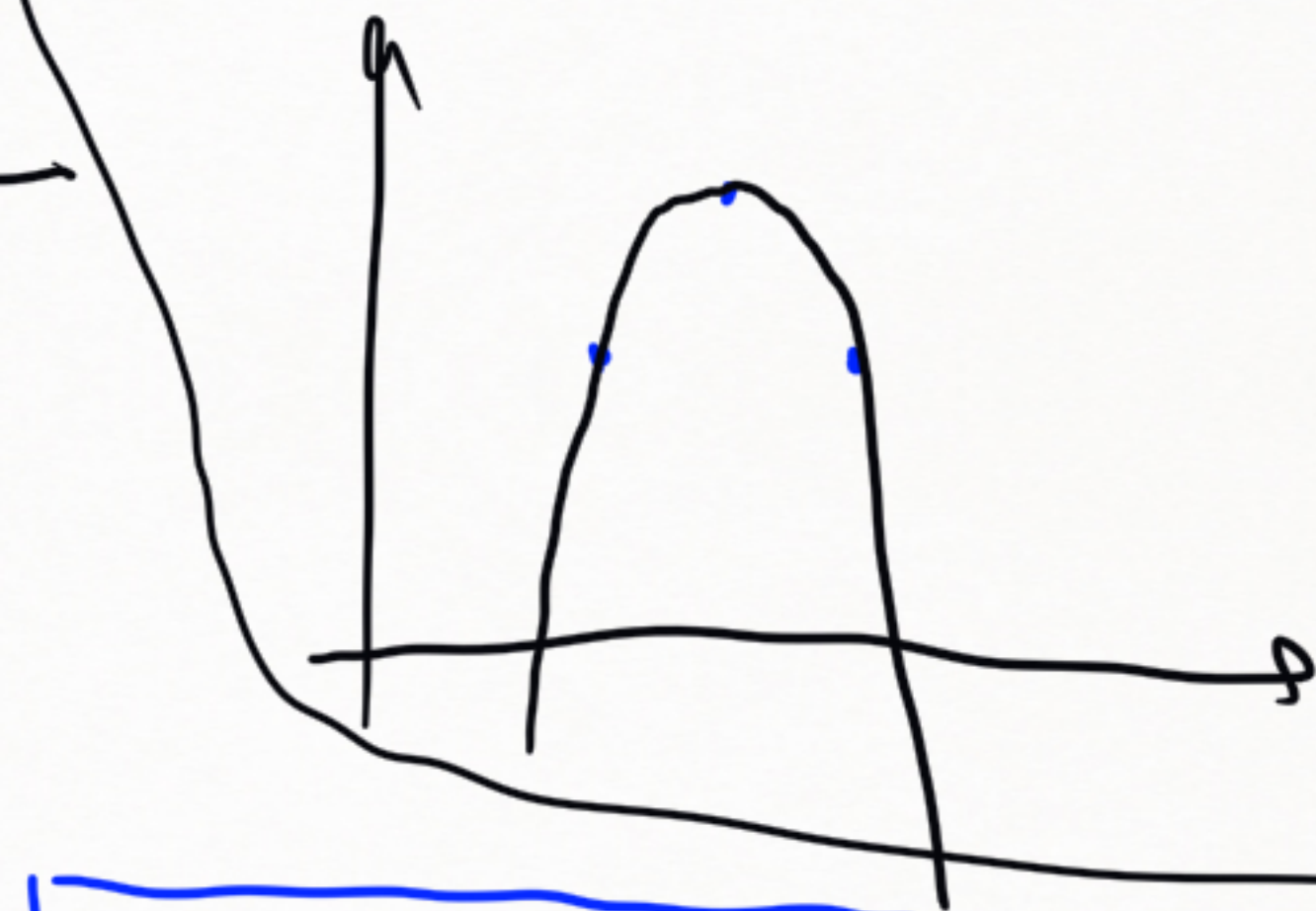
- Vandermonde
- Lagrange
- Newton.

①  $(-1, 0)$   $(0, 3)$   $(1, 2)$

independientes

$$a) \quad p(x) = \overline{a_2}x^2 + \overline{a_1}x + \overline{a_0}$$

$$\begin{aligned} (-1, 0) \xrightarrow{*} p(-1) = 0 &\rightarrow \begin{cases} a_2 - a_1 + a_0 = 0 \\ a_0 = 3 \\ a_2 + a_1 + a_0 = 2 \end{cases} & \text{sol.} \quad \begin{aligned} a_2 &= -2 \\ a_1 &= 1 \\ a_0 &= 3 \end{aligned} \\ (0, 3) \rightarrow p(0) = 3 &\rightarrow \\ (1, 2) \rightarrow p(1) = 2 &\rightarrow \end{aligned}$$



$$p(x) = -2x^2 + x + 3$$

$$b) \quad \underline{(-1, 0)} \quad \underline{(0, 3)} \quad \underline{(1, 2)} \quad (x_0, y_0) \quad (x_1, y_1) \quad (x_2, y_2)$$

Pol. de base de Lagrange:  $L_2^0(x)$ ,  $L_2^1(x)$ ,  $L_2^2(x)$ . El pol. interpolante es una combinación lineal de esos polinomios.

$$P(x) = \underline{0} L_2^0(x) + \underline{3} L_2^1(x) + \underline{2} L_2^2(x)$$

Propiedades:

$L_2^0(-1) = 1$	$L_2^1(-1) = 0$	$L_2^2(-1) = 0$	$x_0$ $x_1$ $x_2$	De esas propiedades se deduce la fórmula
$L_2^0(0) = 0$	$L_2^1(0) = 1$	$L_2^2(0) = 0$		
$L_2^0(1) = 0$	$L_2^1(1) = 0$	$L_2^2(1) = 1$		

$L_2^1(x)$ :  $L_2^1(x) = \kappa \underbrace{(x+1)}_{L_2^1(-1)=0} \underbrace{(x-1)}_{L_2^1(1)=0}$

$L_2^1(-1) = 0$     $L_2^1(1) = 0$

$L_2^2(x) = \kappa (x+1)x$

$L_2^2(1) = 1 \Leftrightarrow \kappa \cdot 2 \cdot 1 = 1 \Leftrightarrow \kappa = \frac{1}{2}$

$$L_2^2(x) = \frac{(x+1)x}{2}$$

Hallamos  $\kappa$  con la otra propiedad.

$L_2^1(0) = 1 \Leftrightarrow \kappa \cdot 1 \cdot (-1) = 1$   
 $\Leftrightarrow \kappa = -1$

$$L_2^1(x) = -(x+1)(x-1)$$

$$P(x) = -3(x+1)(x-1) + (x+1)x$$

- $\lambda$ ) Paso 1:  $P_0(x)$  interpola  $(-1, 0)$   
 Paso 2:  $P_1(x)$  interpola  $(-1, 0), (0, 3)$   
 Paso 3:  $P_2(x)$  interpola  $(-1, 0), (0, 3), (1, 2)$

En cada paso agregamos un punto más de interpolación.

Paso 1:  $P_0(x)$  interpola  $(-1, 0)$

$$P_0(x) = 0$$

Paso 2:  $P_1(x)$  interpola  $(-1, 0), (0, 3)$

$$P_1(x) = P_0(x) + \underbrace{q(x)}_{\text{hallar}} = P_0(x) + \underbrace{\lambda(x+1)}_{\text{ya interpola en } x=-1}$$

Al definirlo de esa forma, interpola  $(-1, 0)$

$$P_1(-1) = P_0(-1) + 0 = P_0(-1) = 0$$

Buscamos  $\lambda$  para que además interpole  $(0, 3)$

$$P_1(0) = P_0(0) + \lambda = \lambda \Rightarrow \lambda = 3$$

$$P_1(x) = 3(x+1)$$

Paso 3: Tenemos  $P_1(x)$  que interpola  $(-1, 0)$  y  $(0, 3)$   
Queremos  $P_2(x)$  que además interpole  $(1, 2)$ .

$$P_2(x) := P_1(x) + \underbrace{\lambda(x+1)x}_{\substack{\text{se anula en} \\ -1, 0}}$$

Automáticamente interpola  $(-1, 0)$  y  $(0, 3)$

$$P_2(-1) = P_1(-1) + 0 = P_1(-1) = 0 \checkmark$$

$$P_2(0) = P_1(0) + 0 = P_1(0) = 3 \checkmark$$

Vamos a hallar  $\lambda$  para que interpole  $(1, 2)$

$$P_2(x) = 3(x+1) + \lambda(x+1)x$$

$$P_2(1) = 6 + 2\lambda = 2 \Leftrightarrow \lambda = -2$$

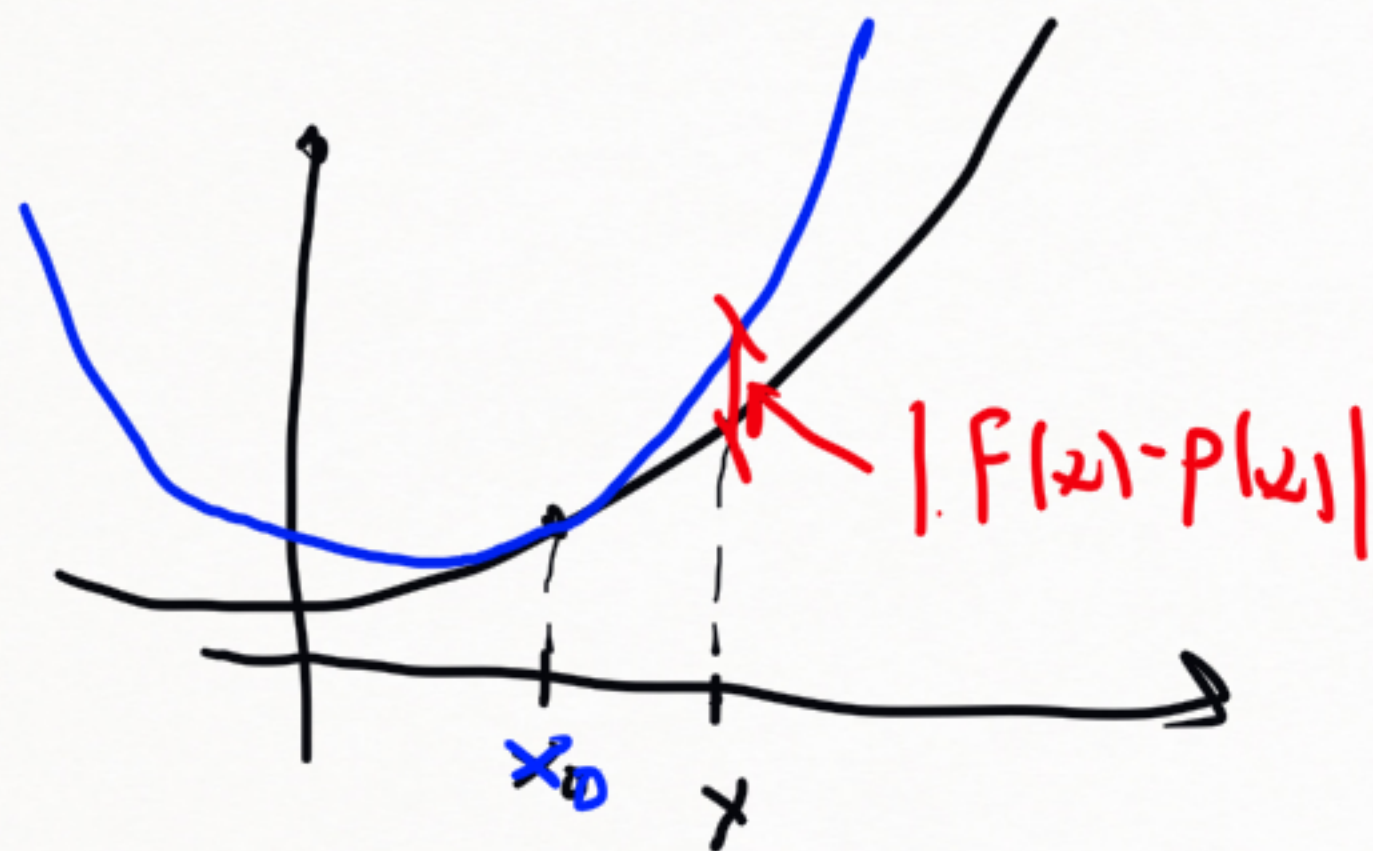
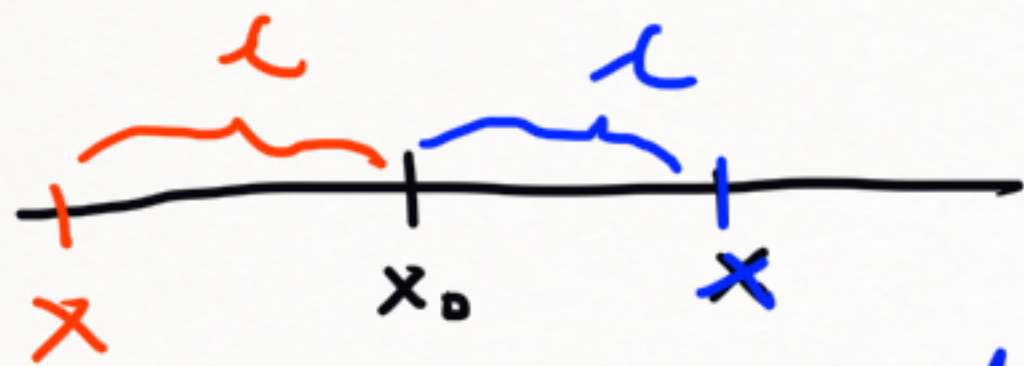
$$P_2(x) = 3(x+1) - 2(x+1)x$$

## Resto de Lagrange

$f: [a, b] \rightarrow \mathbb{R}, x_0 \in (a, b)$   
 $p(x)$  Taylor de orden  $n$ .

$$f(x) - p(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)^{n+1}$$

donde  $\xi$  depende de  $x$

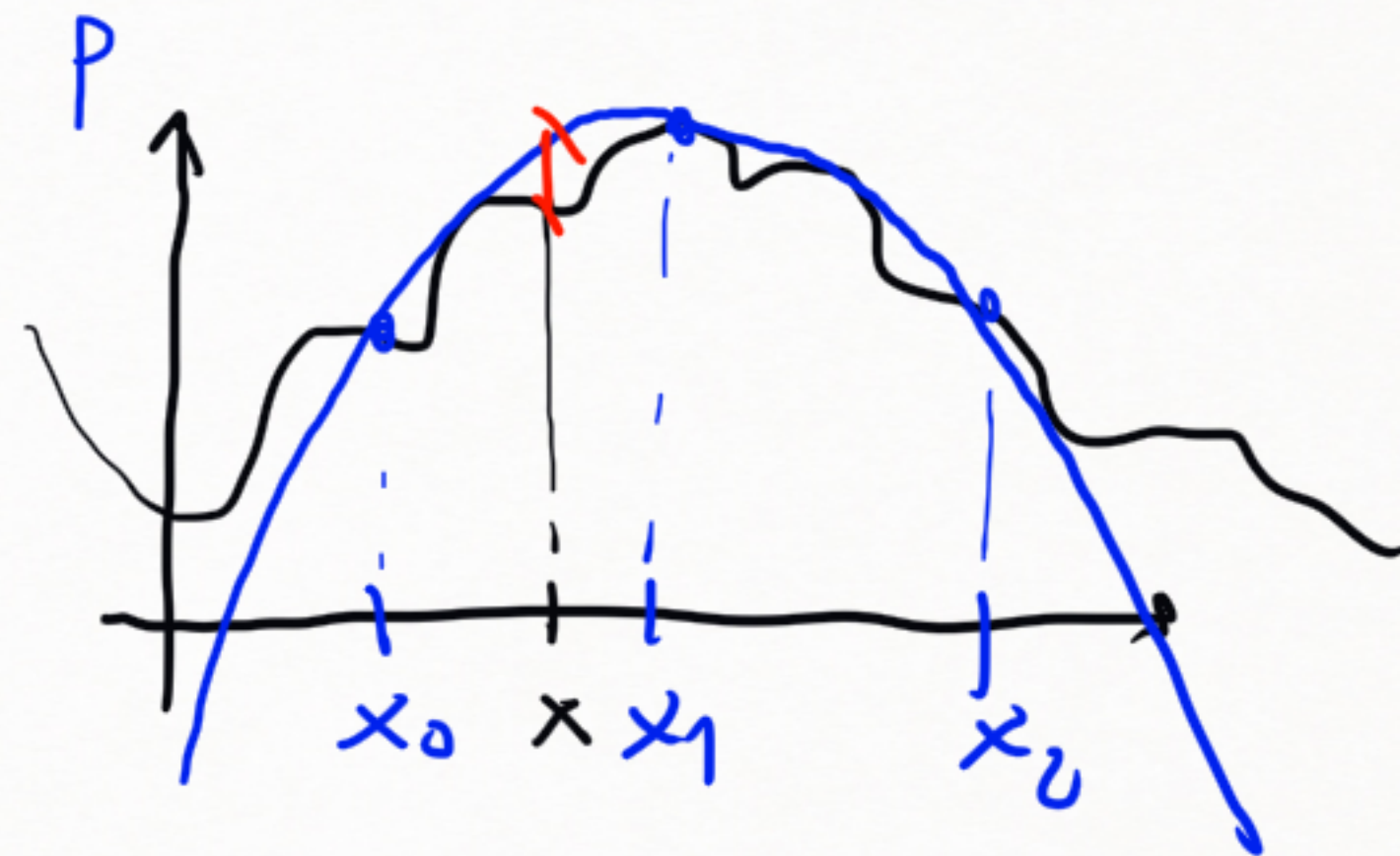


## Error de interpolación

$f: [a, b] \rightarrow \mathbb{R}, x_0, x_1, \dots, x_n \in [a, b]$   
 $p(x)$  pol. interpolante de  $f$  por  $x_0, \dots, x_n$

$$f(x) - p(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)(x - x_1) \dots (x - x_n)$$

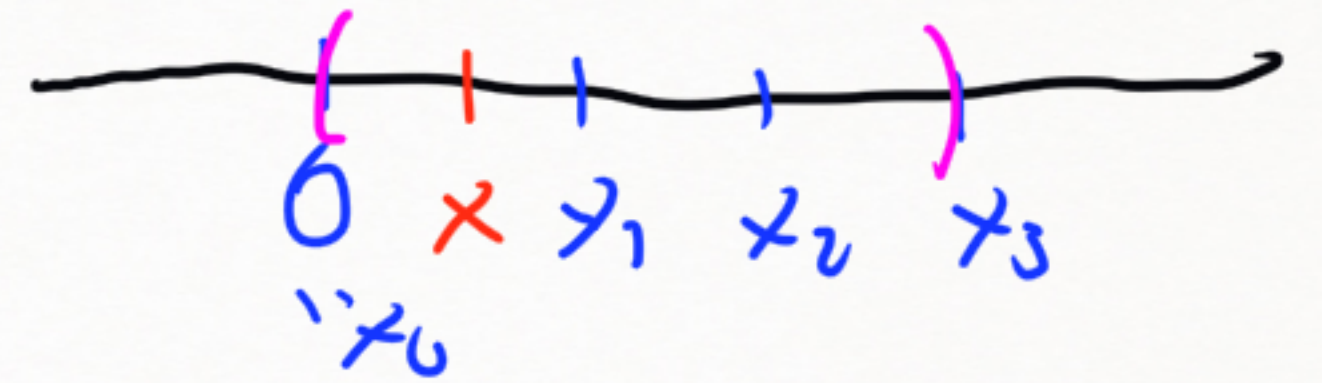
$\xi \in (a, b)$



⑥  $f(x) = \sin(x)$      $x_0 = 0$      $x_1 = \frac{\pi}{6}$      $x_2 = \frac{\pi}{4}$      $x_3 = \frac{\pi}{3}$

y ver qué pasa con el error en  $x = \pi/8$

$\mathcal{L}$ )  $\sin(\frac{\pi}{8}) - P(\frac{\pi}{8}) = \frac{\overbrace{\sin^{(4)}(\mathcal{L})}^{\text{negativo}}}{4!} (\frac{\pi}{8} - 0) (\frac{\pi}{8} - \frac{\pi}{6}) (\frac{\pi}{8} - \frac{\pi}{4}) (\frac{\pi}{8} - \frac{\pi}{3})$



$|\sin(\frac{\pi}{8}) - P(\frac{\pi}{8})| = \frac{|\sin(\mathcal{L})|}{4!} \frac{\pi}{8} (\frac{\pi}{6} - \frac{\pi}{8}) (\frac{\pi}{4} - \frac{\pi}{8}) (\frac{\pi}{3} - \frac{\pi}{8}) < \frac{1}{4!} \frac{\pi}{8} (\frac{\pi}{6} - \frac{\pi}{8}) (\frac{\pi}{4} - \frac{\pi}{8}) (\frac{\pi}{3} - \frac{\pi}{8})$   
 $\approx 5,5 \times 10^{-4}$

$\sin(\frac{\pi}{8}) = \sqrt{\frac{1 - \cos(\frac{\pi}{4})}{2}} = \sqrt{\frac{1 - \frac{1}{\sqrt{2}}}{2}} = \sqrt{\frac{\sqrt{2} - 1}{2\sqrt{2}}}$

$\mathcal{L} \in (0, \frac{\pi}{3})$      $\sin(\mathcal{L}) > 0$