

Aprendizaje automático



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Componentes del aprendizaje



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Components of learning

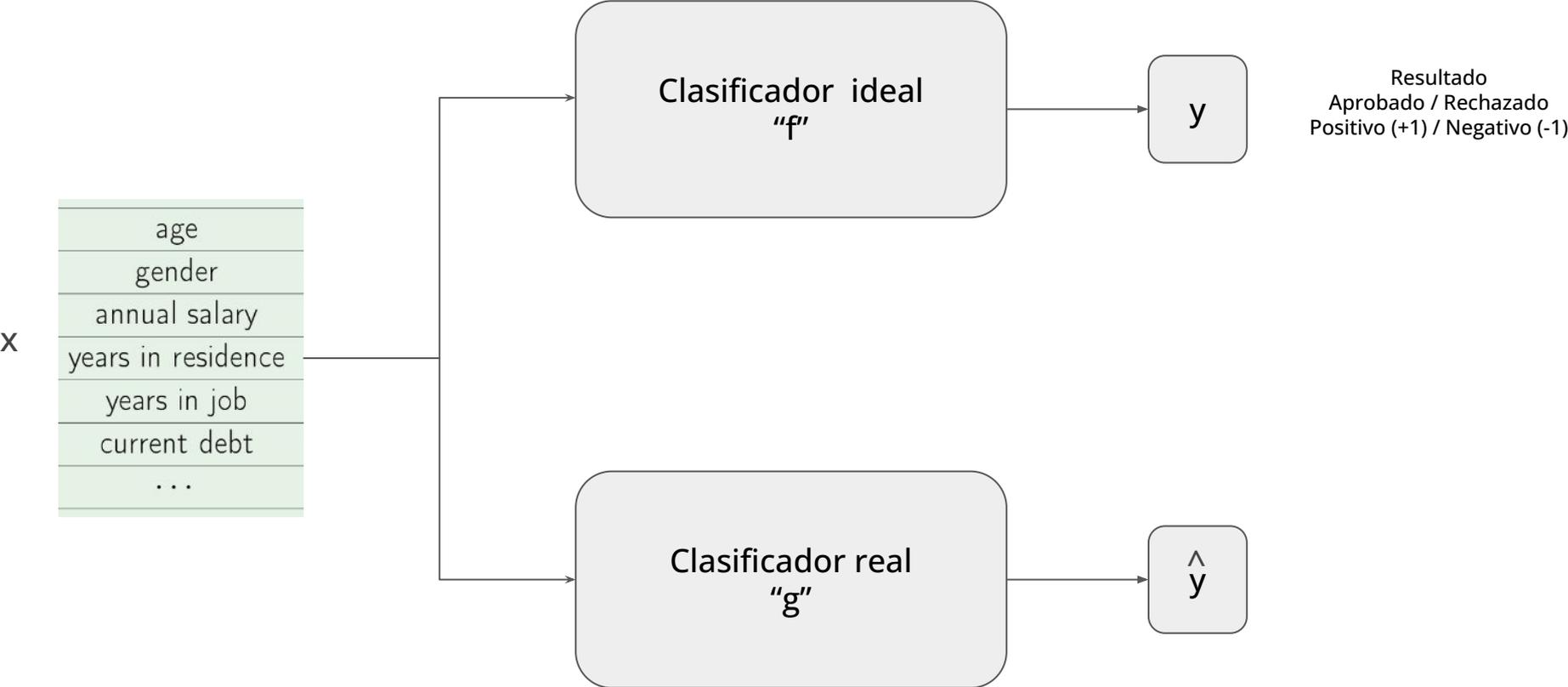
Metaphor: Credit approval

Applicant information:

age	23 years
gender	male
annual salary	\$30,000
years in residence	1 year
years in job	1 year
current debt	\$15,000
...	...

Approve credit?

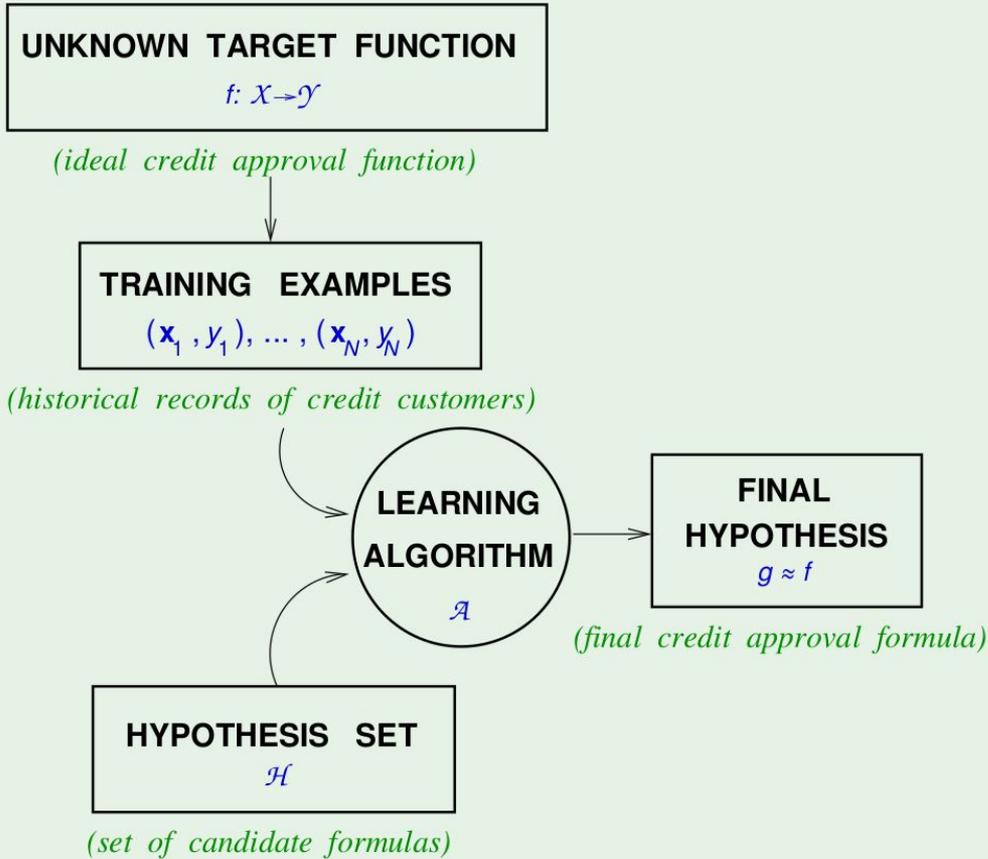
Aprobación de crédito como un problema de clasificación



Components of learning

Formalization:

- Input: \mathbf{x} (*customer application*)
 - Output: y (*good/bad customer?*)
 - Target function: $f : \mathcal{X} \rightarrow \mathcal{Y}$ (*ideal credit approval formula*)
 - Data: $(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)$ (*historical records*)
- ↓ ↓ ↓
- Hypothesis: $g : \mathcal{X} \rightarrow \mathcal{Y}$ (*formula to be used*)



Solution components

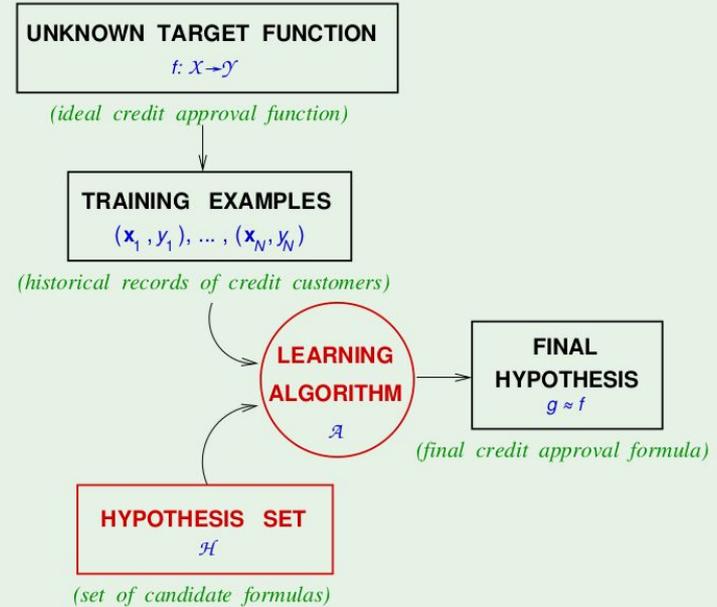
The 2 solution components of the learning problem:

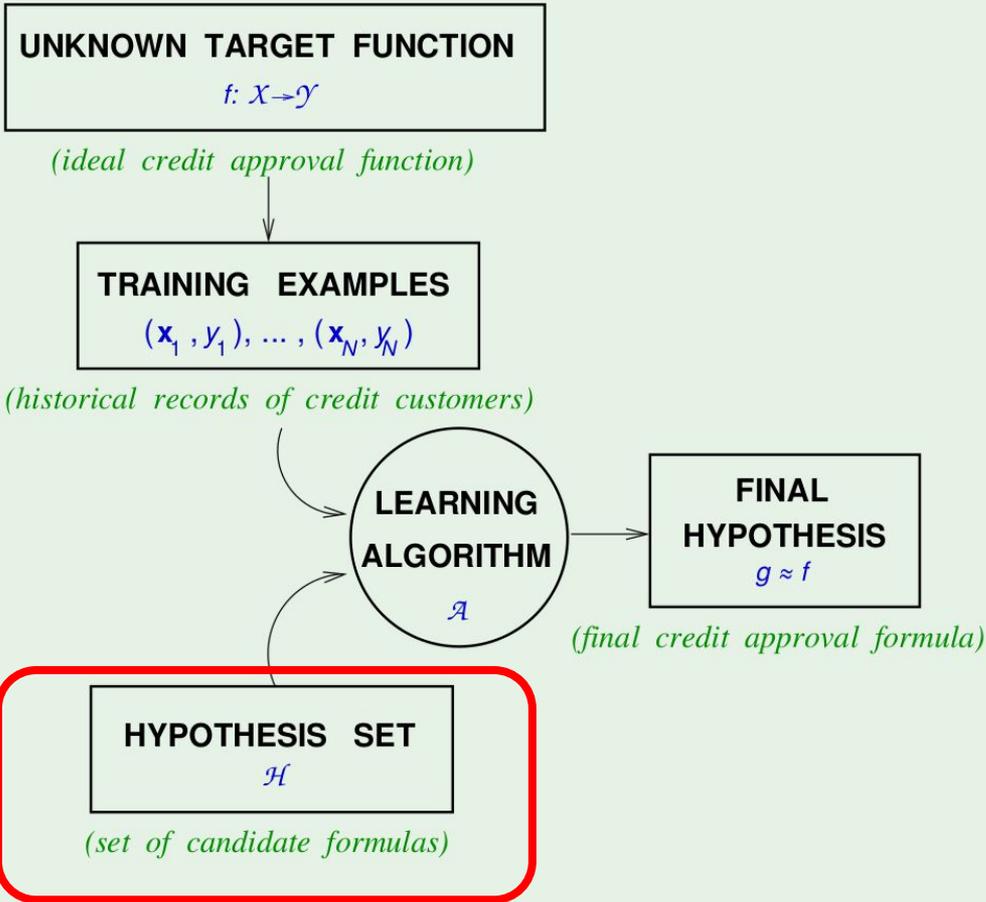
- The Hypothesis Set

$$\mathcal{H} = \{h\} \quad g \in \mathcal{H}$$

- The Learning Algorithm

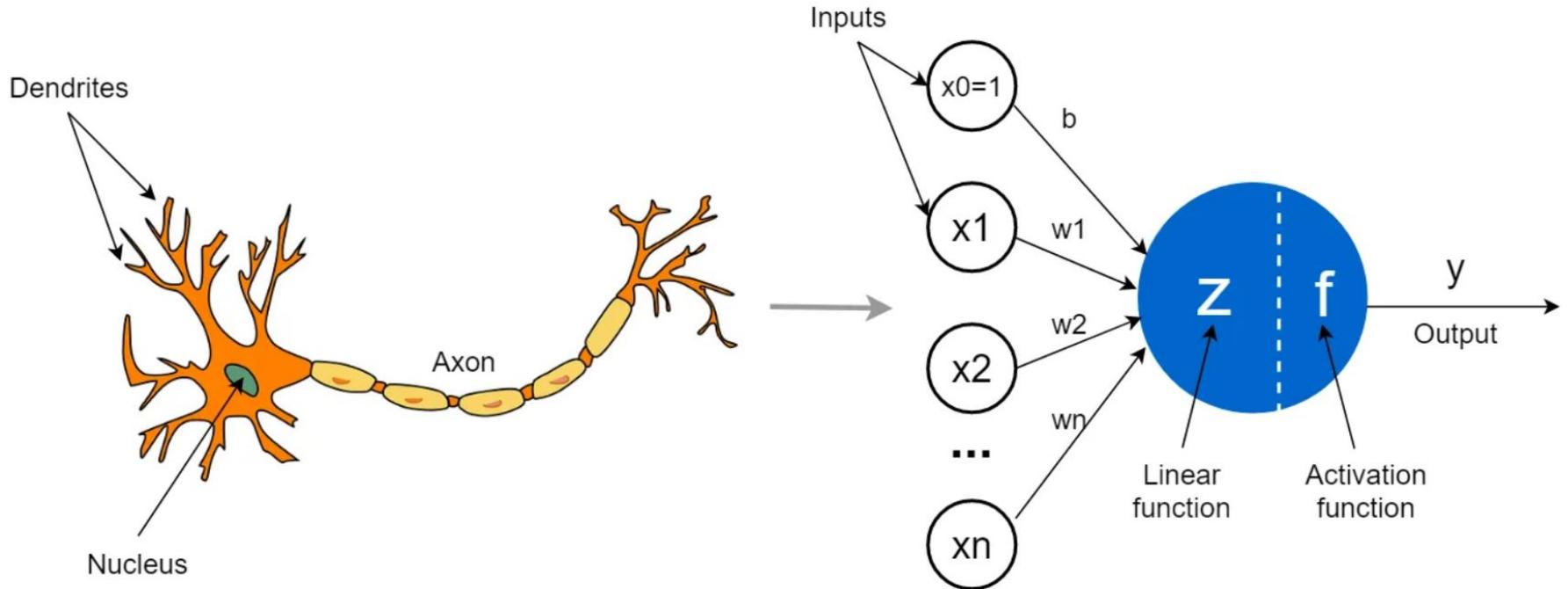
Together, they are referred to as the *learning model*.





Un posible set de hipótesis: el perceptrón

- Inspirado en modelo simplificado de neurona biológica



A simple hypothesis set - the 'perceptron'

For input $\mathbf{x} = (x_1, \dots, x_d)$ 'attributes of a customer'

Approve credit if $\sum_{i=1}^d w_i x_i > \text{threshold}$,

Deny credit if $\sum_{i=1}^d w_i x_i < \text{threshold}$.

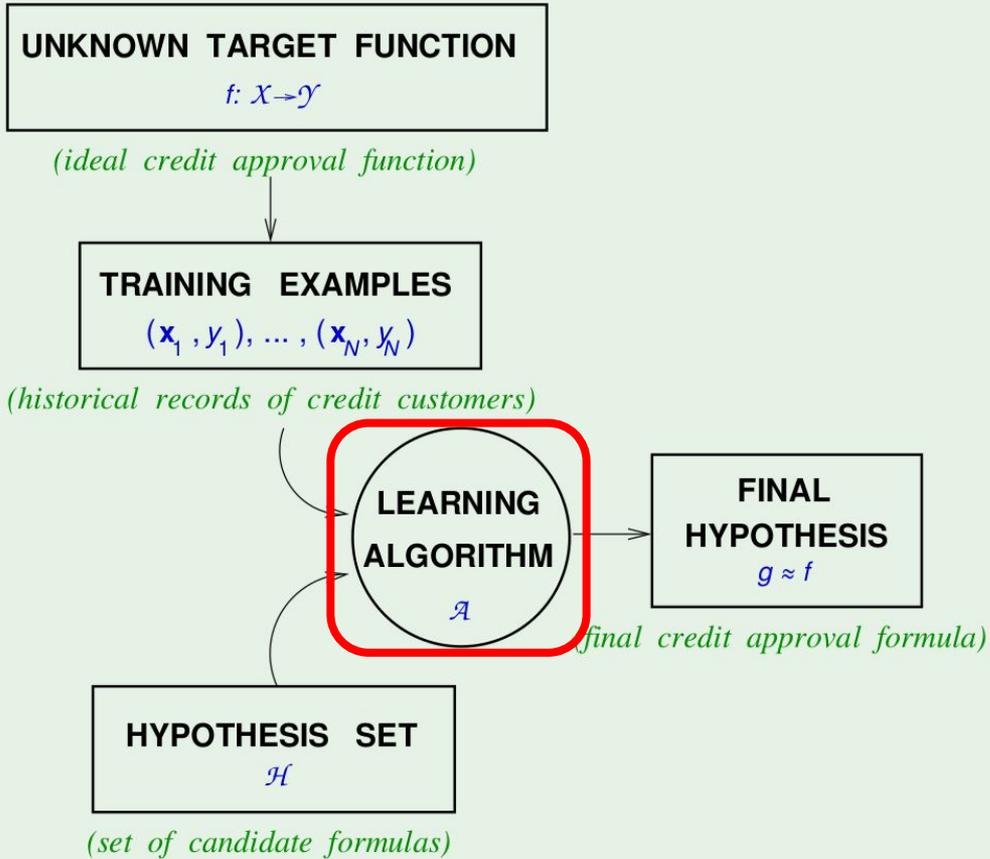
x_1	age
x_2	gender
x_3	annual salary
.	years in residence
-	years in job
x_d	current debt
	...

This linear formula $h \in \mathcal{H}$ can be written as

$$h(\mathbf{x}) = \text{sign} \left(\left(\sum_{i=1}^d w_i x_i \right) - \text{threshold} \right)$$

Un posible set de hipótesis: el perceptrón

- Características del set de hipótesis ?
 - La función g va a ser:
 - Combinación lineal de las entradas + umbralización
- Cómo se espera que sean los datos de entrada ?
 - Linealmente separables



A simple learning algorithm - PLA

The perceptron implements

$$h(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x})$$

Given the training set:

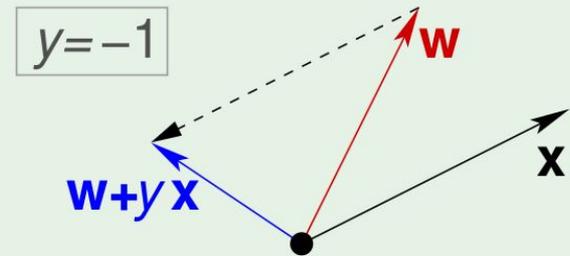
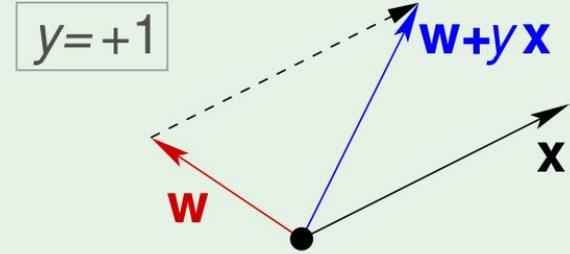
$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)$$

pick a **misclassified** point:

$$\text{sign}(\mathbf{w}^T \mathbf{x}_n) \neq y_n$$

and update the weight vector:

$$\mathbf{w} \leftarrow \mathbf{w} + y_n \mathbf{x}_n$$



Iterations of PLA

- One iteration of the PLA:

$$\mathbf{w} \leftarrow \mathbf{w} + y\mathbf{x}$$

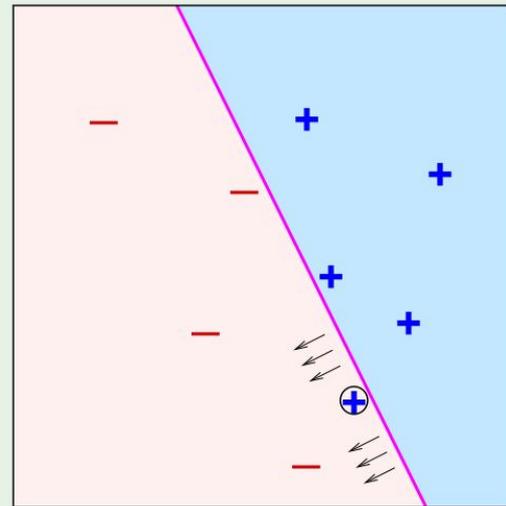
where (\mathbf{x}, y) is a misclassified training point.

- At iteration $t = 1, 2, 3, \dots$, pick a misclassified point from

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)$$

and run a PLA iteration on it.

- That's it!

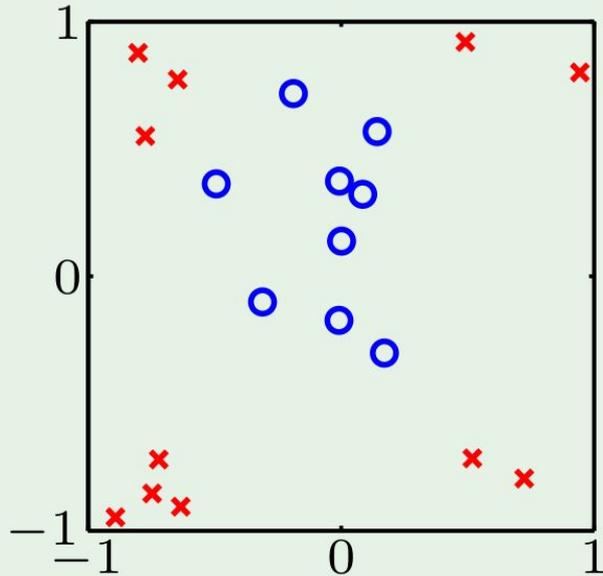


El algoritmo siempre para y llega a una solución ?

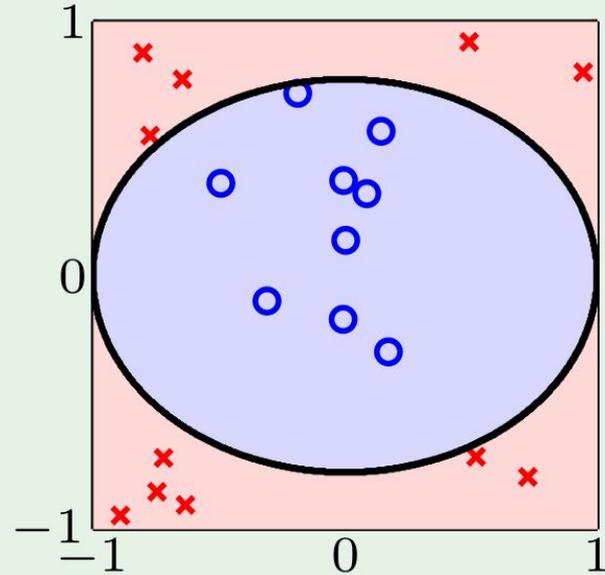
Qué pasa si los datos no son linealmente separables ?

Linear is limited

Data:



Hypothesis:



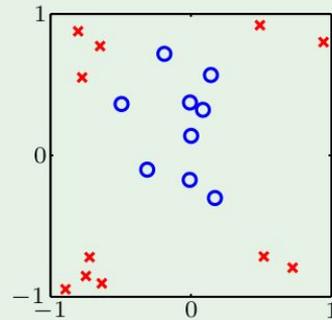
Another example

Credit line is affected by 'years in residence'

but **not** in a linear way!

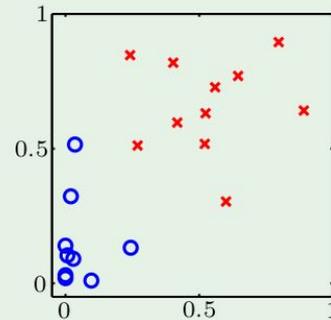
Nonlinear $[[x_i < 1]]$ and $[[x_i > 5]]$ are better.

Can we do that with linear models?



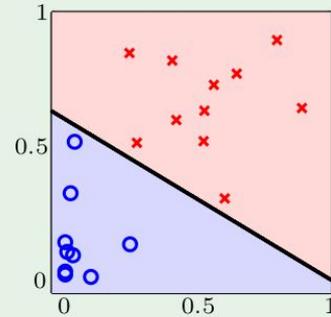
1. Original data
 $\mathbf{x}_n \in \mathcal{X}$

Φ



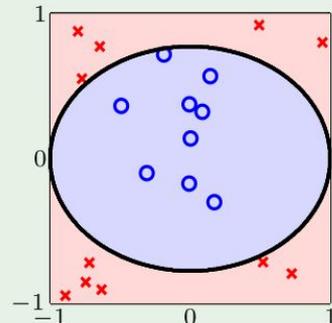
2. Transform the data
 $\mathbf{z}_n = \Phi(\mathbf{x}_n) \in \mathcal{Z}$

↓



3. Separate data in \mathcal{Z} -space
 $\tilde{g}(\mathbf{z}) = \text{sign}(\tilde{\mathbf{w}}^T \mathbf{z})$

Φ^{-1}



4. Classify in \mathcal{X} -space
 $g(\mathbf{x}) = \tilde{g}(\Phi(\mathbf{x})) = \text{sign}(\tilde{\mathbf{w}}^T \Phi(\mathbf{x}))$

What transforms to what

$$\mathbf{x} = (x_0, x_1, \dots, x_d) \xrightarrow{\Phi} \mathbf{z} = (z_0, z_1, \dots, z_{\tilde{d}})$$

$$\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N \xrightarrow{\Phi} \mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N$$

$$y_1, y_2, \dots, y_N \xrightarrow{\Phi} y_1, y_2, \dots, y_N$$

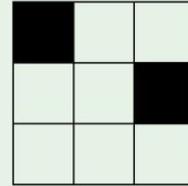
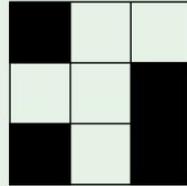
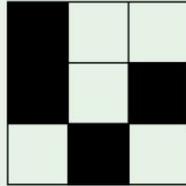
No weights in \mathcal{X}

$$\tilde{\mathbf{w}} = (w_0, w_1, \dots, w_{\tilde{d}})$$

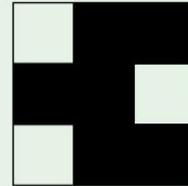
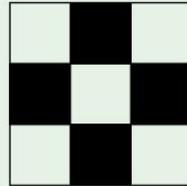
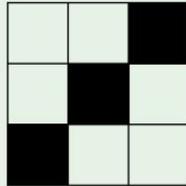
$$g(\mathbf{x}) = \text{sign}(\tilde{\mathbf{w}}^\top \Phi(\mathbf{x}))$$

Adivinanza

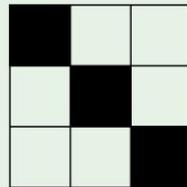
A Learning puzzle



$$f = -1$$



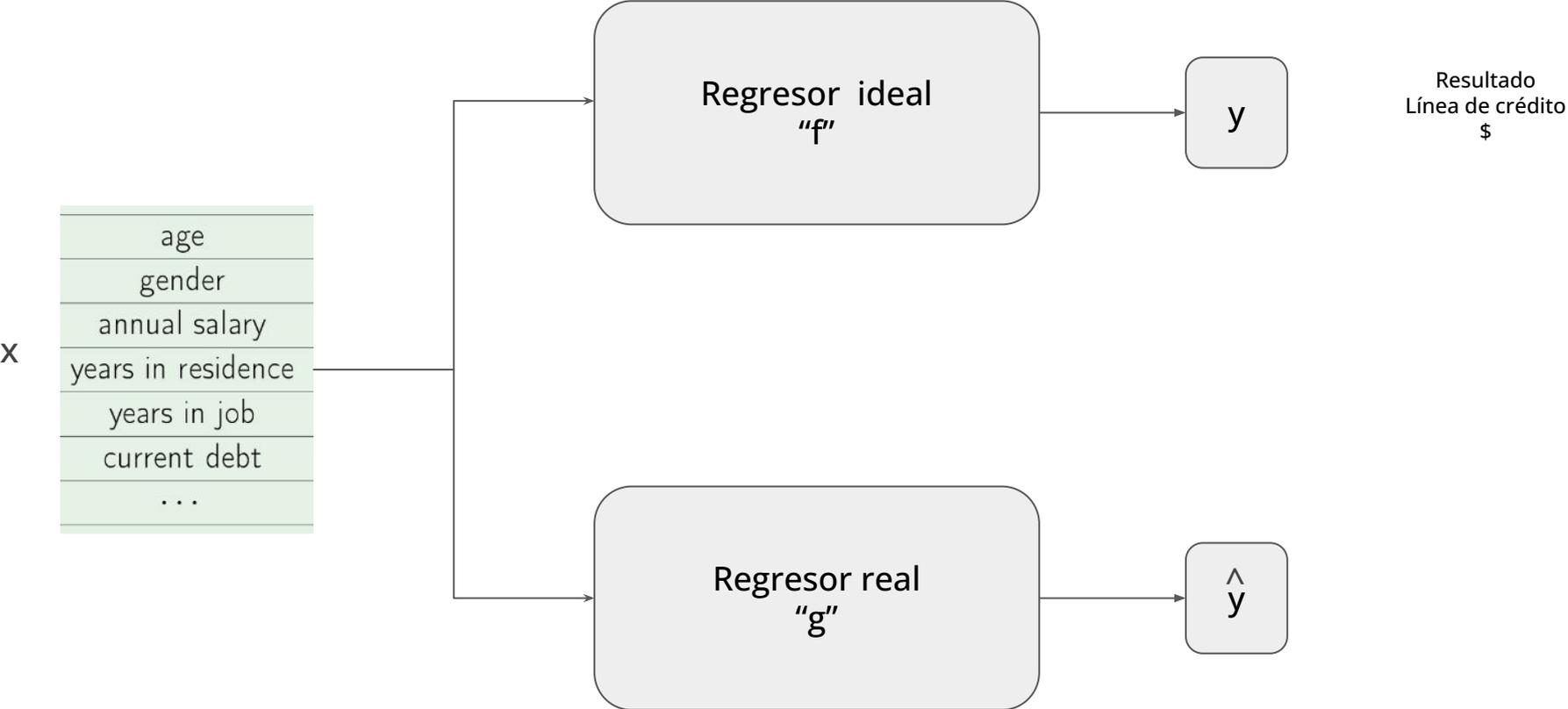
$$f = +1$$



$$f = ?$$

Volvemos al crédito...

Aprobación de nivel de crédito como un problema de regresión



Credit again

Classification: Credit approval (yes/no)

Regression: Credit line (dollar amount)

Input: $\mathbf{x} =$

age	23 years
annual salary	\$30,000
years in residence	1 year
years in job	1 year
current debt	\$15,000
...	...

Linear regression output:
$$h(\mathbf{x}) = \sum_{i=0}^d w_i x_i = \mathbf{w}^T \mathbf{x}$$

The data set

Credit officers decide on credit lines:

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)$$

$y_n \in \mathbb{R}$ is the credit line for customer \mathbf{x}_n .

Linear regression tries to replicate that.

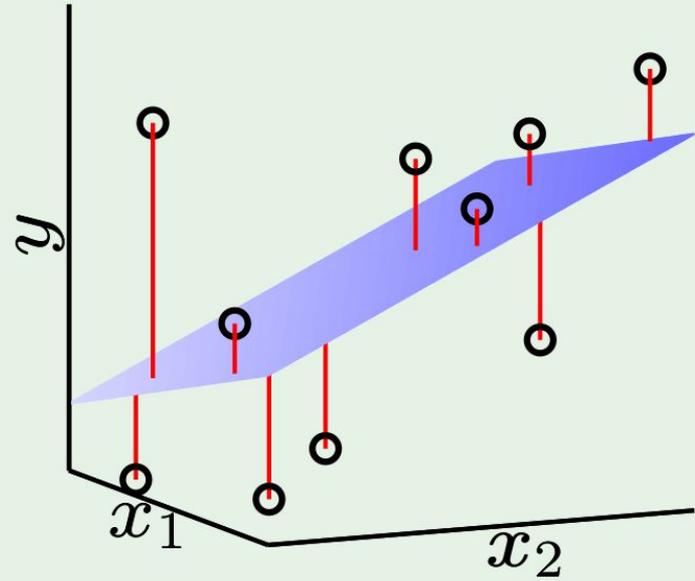
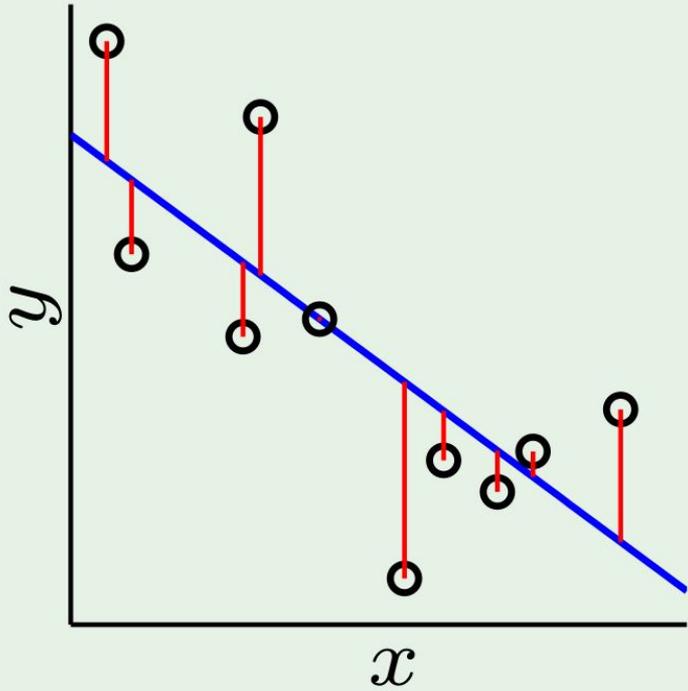
How to measure the error

How well does $h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$ approximate $f(\mathbf{x})$?

In linear regression, we use squared error $(h(\mathbf{x}) - f(\mathbf{x}))^2$

$$\text{in-sample error: } E_{\text{in}}(h) = \frac{1}{N} \sum_{n=1}^N (h(\mathbf{x}_n) - y_n)^2$$

Illustration of linear regression



The expression for E_{in}

$$\begin{aligned} E_{\text{in}}(\mathbf{w}) &= \frac{1}{N} \sum_{n=1}^N (\mathbf{w}^T \mathbf{x}_n - y_n)^2 \\ &= \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 \end{aligned}$$

where

$$\mathbf{X} = \begin{bmatrix} -\mathbf{x}_1^T- \\ -\mathbf{x}_2^T- \\ \vdots \\ -\mathbf{x}_N^T- \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$$

Minimizing E_{in}

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$

$$\nabla E_{in}(\mathbf{w}) = \frac{2}{N} \mathbf{X}^T (\mathbf{X}\mathbf{w} - \mathbf{y}) = \mathbf{0}$$

$$\mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

$$\mathbf{w} = \mathbf{X}^\dagger \mathbf{y} \quad \text{where} \quad \mathbf{X}^\dagger = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T$$

\mathbf{X}^\dagger is the 'pseudo-inverse' of \mathbf{X}

The linear regression algorithm

- 1: Construct the matrix \mathbf{X} and the vector \mathbf{y} from the data set $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$ as follows

$$\underbrace{\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^\top \\ \mathbf{x}_2^\top \\ \vdots \\ \mathbf{x}_N^\top \end{bmatrix}}_{\text{input data matrix}}, \quad \underbrace{\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}}_{\text{target vector}}.$$

- 2: Compute the pseudo-inverse $\mathbf{X}^\dagger = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$.
- 3: Return $\mathbf{w} = \mathbf{X}^\dagger \mathbf{y}$.

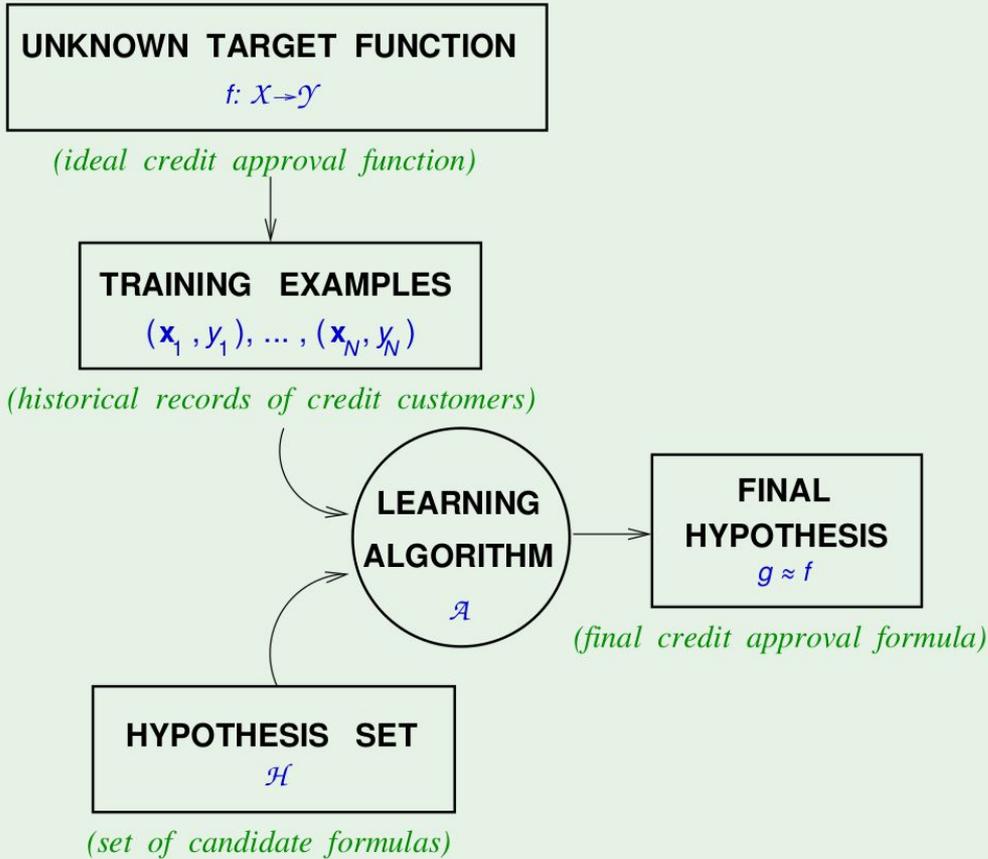
Aproximación y generalización



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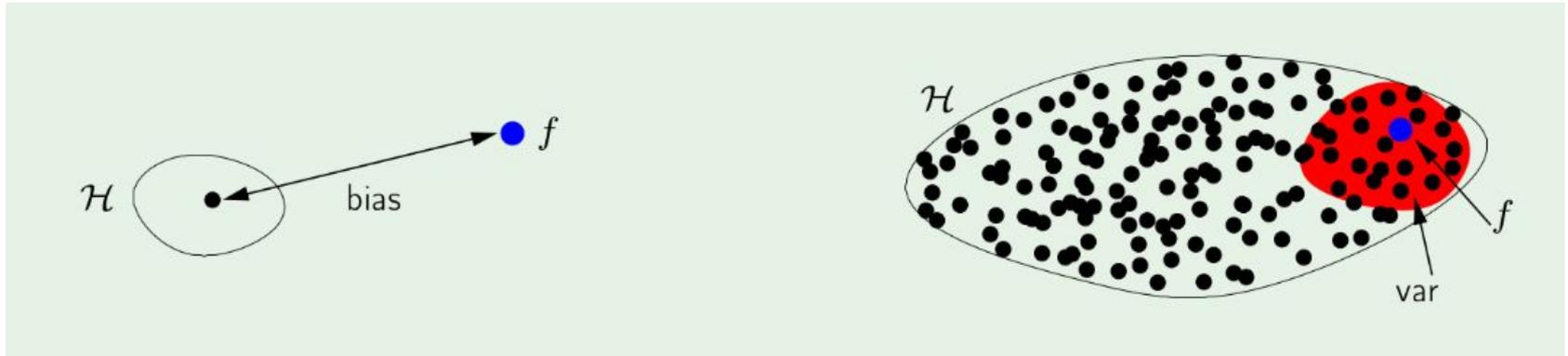


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El problema

- El set de hipótesis elegido influye en:
 - El error dentro de la muestra E_{in} (aproximación a las muestras disponibles)
 - El error fuera de la muestra E_{out} (error fuera de muestra)
- Queremos que nuestro modelo
 - aproxime bien a las muestras (x,y) disponibles
 - generalice bien para nuevos datos
- Va a existir un compromiso



Approximation-generalization tradeoff

Small E_{out} : good approximation of f out of sample.

More complex $\mathcal{H} \implies$ better chance of **approximating** f

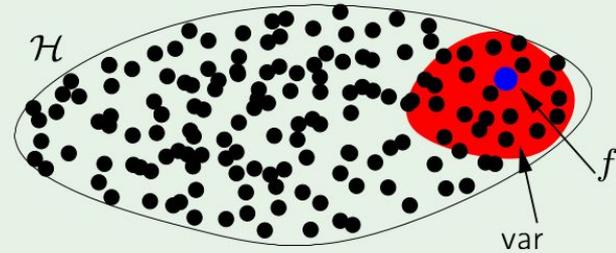
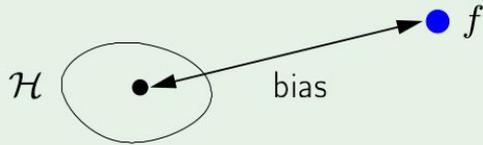
Less complex $\mathcal{H} \implies$ better chance of **generalizing** out of sample

Ideal $\mathcal{H} = \{f\}$ winning lottery ticket 😊

The tradeoff

$$\text{bias} = \mathbb{E}_{\mathbf{x}} \left[(\bar{g}(\mathbf{x}) - f(\mathbf{x}))^2 \right]$$

$$\text{var} = \mathbb{E}_{\mathbf{x}} \left[\mathbb{E}_{\mathcal{D}} \left[(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x}))^2 \right] \right]$$



$\mathcal{H} \uparrow$



Quantifying the tradeoff

Bias-variance analysis

1. How well \mathcal{H} can approximate f
2. How well we can zoom in on a good $h \in \mathcal{H}$

Applies to **real-valued targets** and uses **squared error**

Example: sine target

f

$$f : [-1, 1] \rightarrow \mathbb{R} \quad f(x) = \sin(\pi x)$$

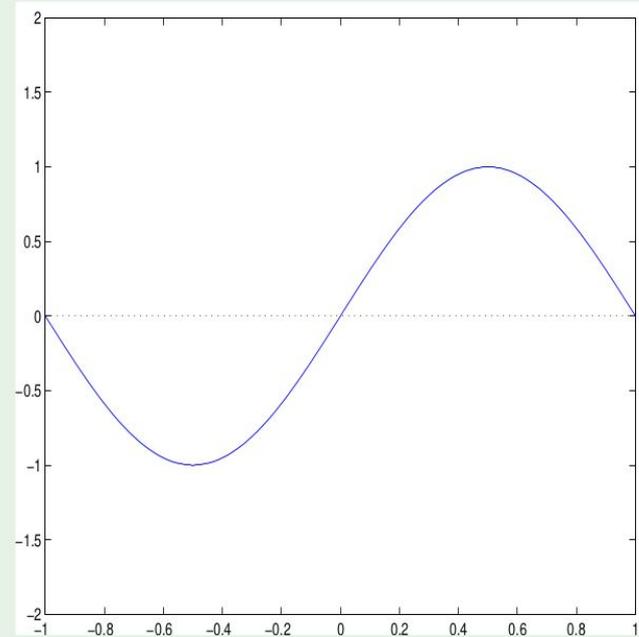
Only two training examples! $N = 2$

Two models used for learning:

$$\mathcal{H}_0: \quad h(x) = b$$

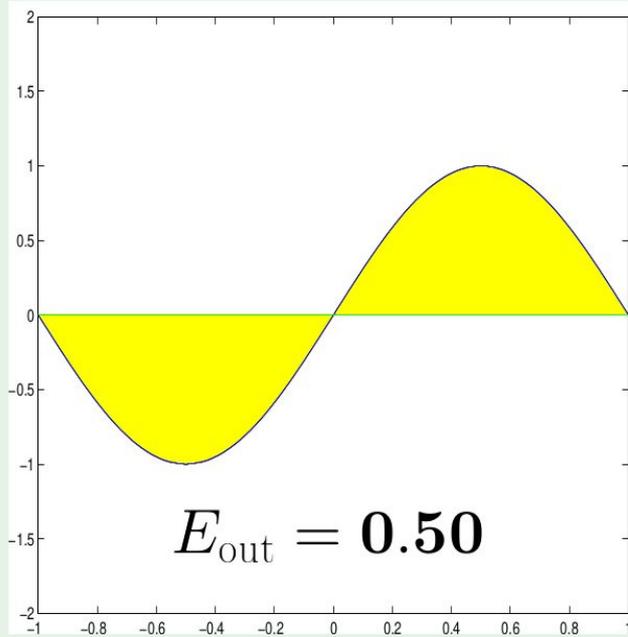
$$\mathcal{H}_1: \quad h(x) = ax + b$$

Which is better, \mathcal{H}_0 or \mathcal{H}_1 ?

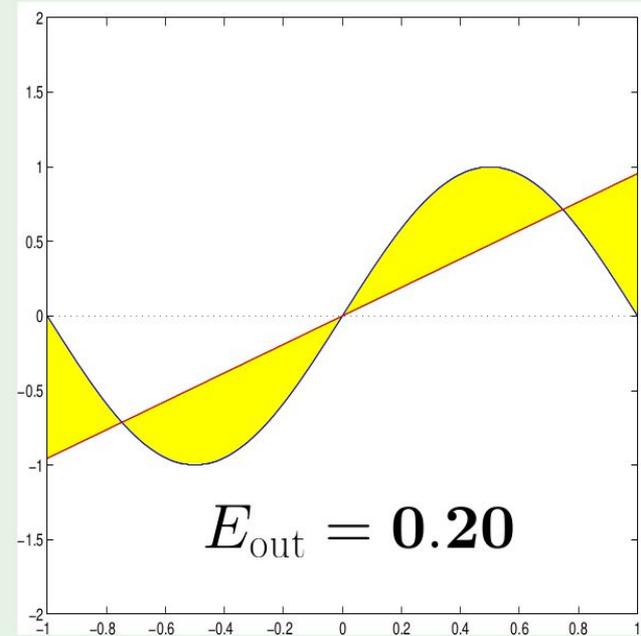


Approximation - \mathcal{H}_0 versus \mathcal{H}_1

\mathcal{H}_0

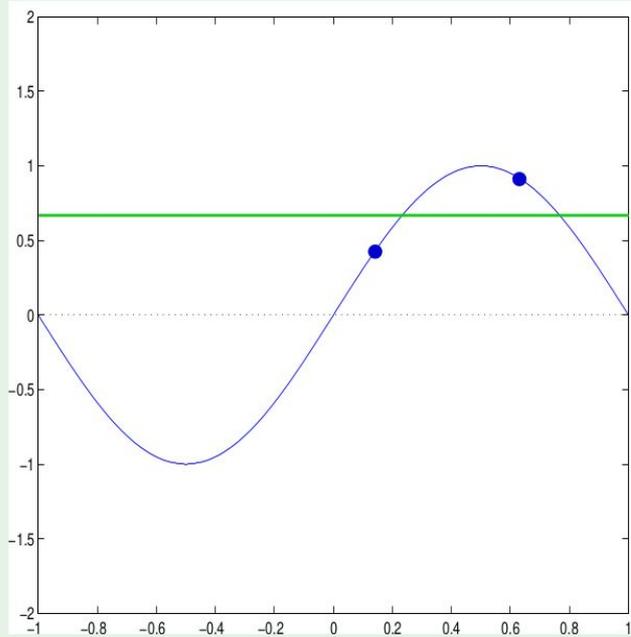


\mathcal{H}_1

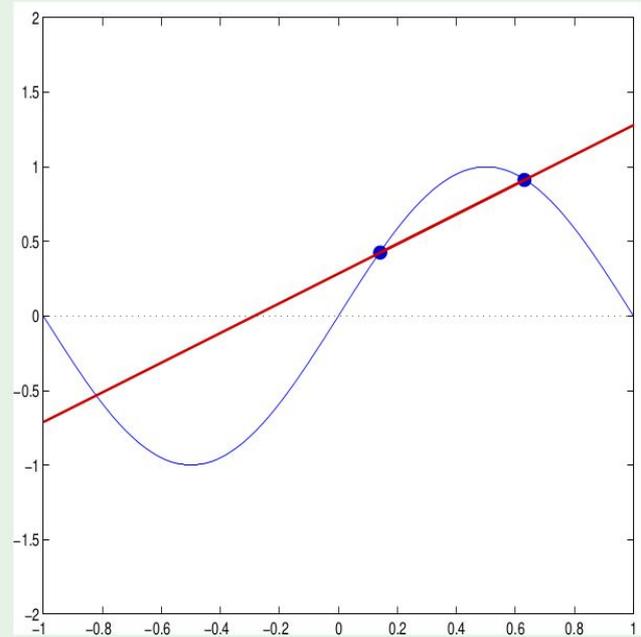


Learning - \mathcal{H}_0 versus \mathcal{H}_1

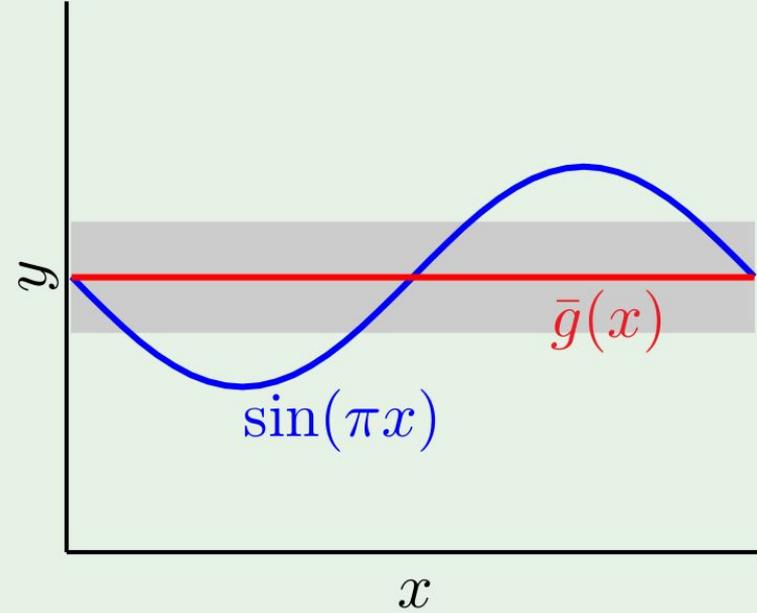
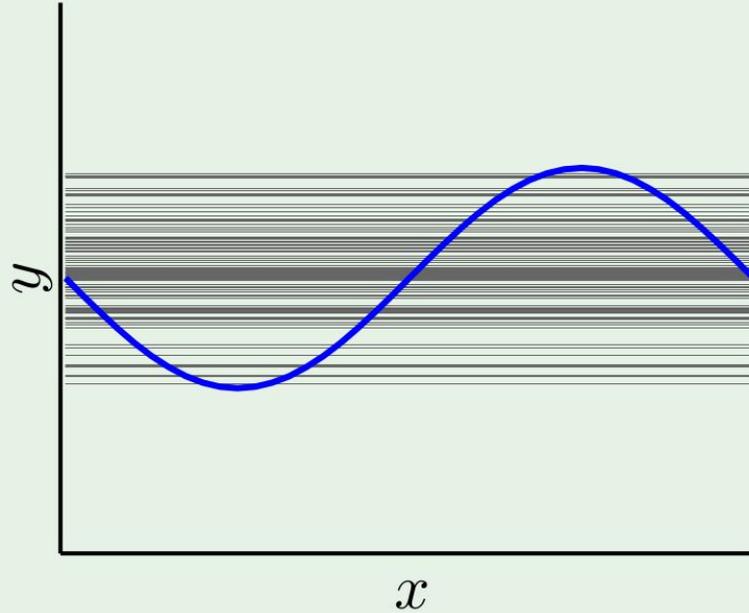
\mathcal{H}_0



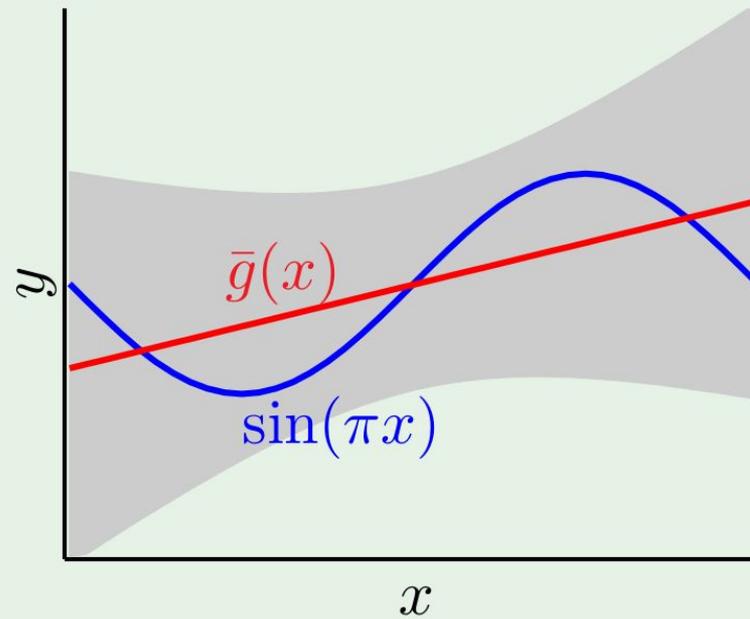
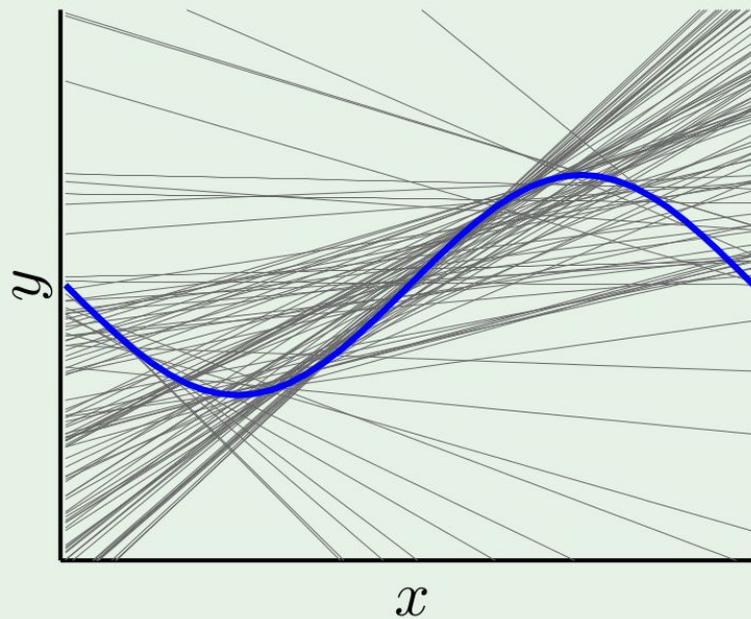
\mathcal{H}_1



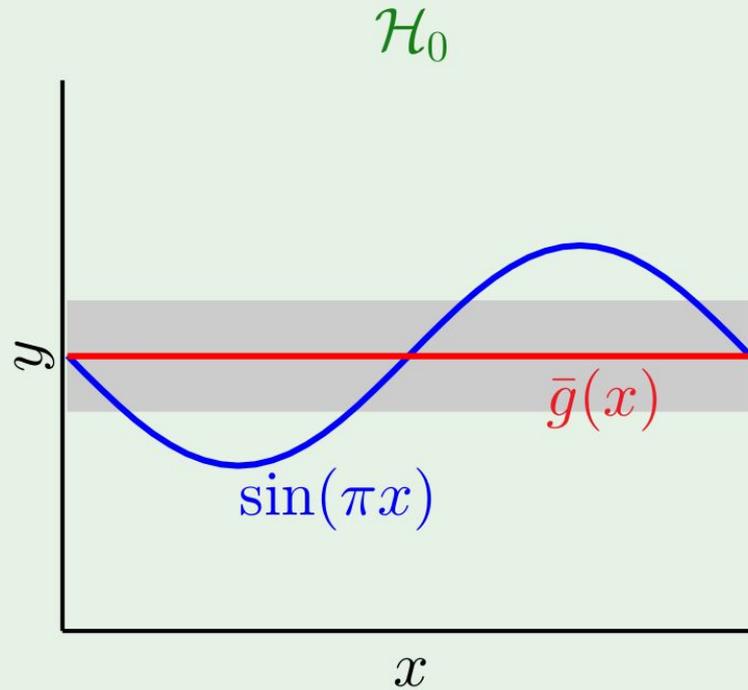
Bias and variance - \mathcal{H}_0



Bias and variance - \mathcal{H}_1

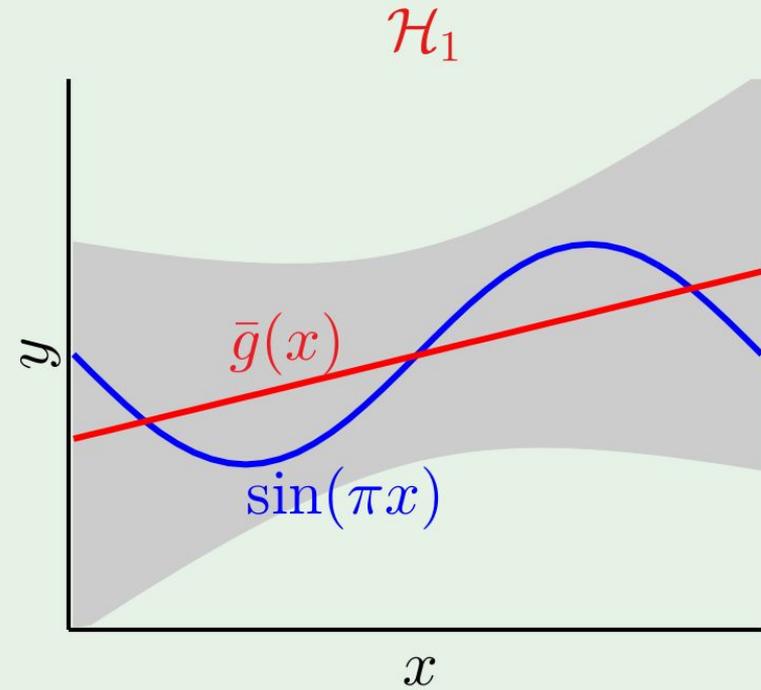


and the winner is ...



bias = **0.50**

var = **0.25**



bias = **0.21**

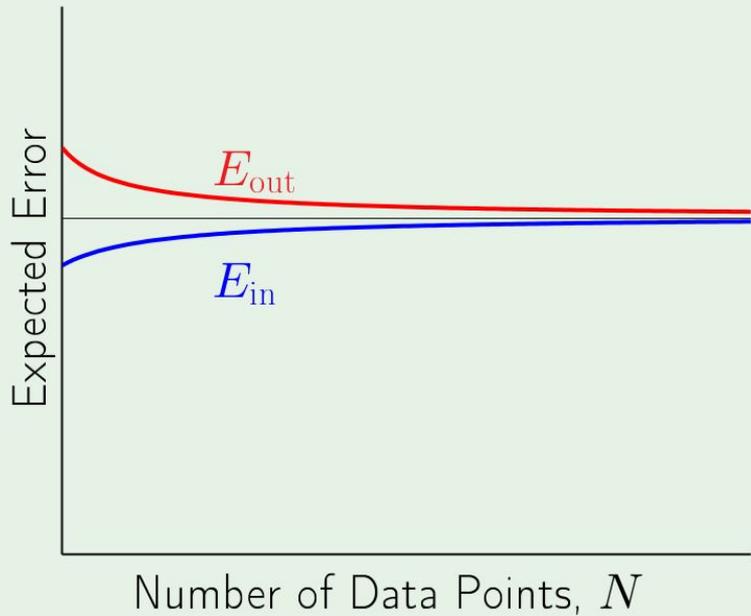
var = **1.69**

Lesson learned

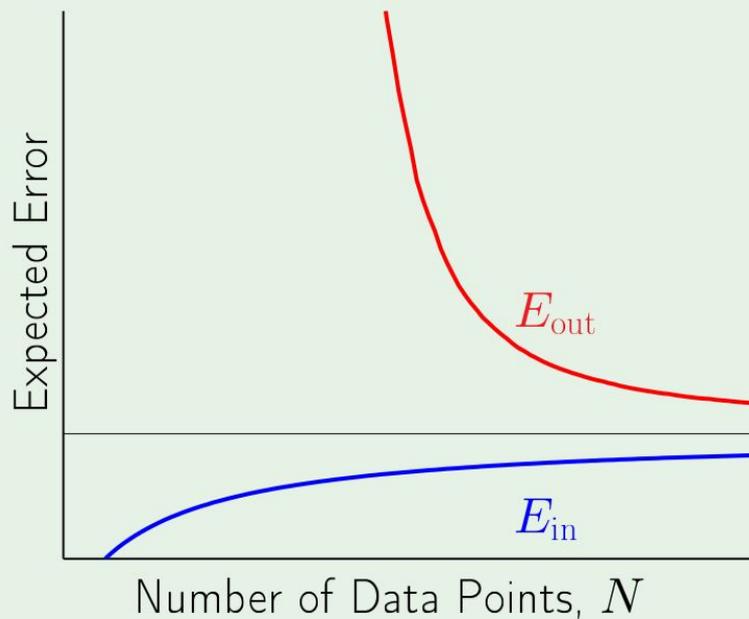
Match the 'model complexity'

to the **data resources**, not to the **target complexity**

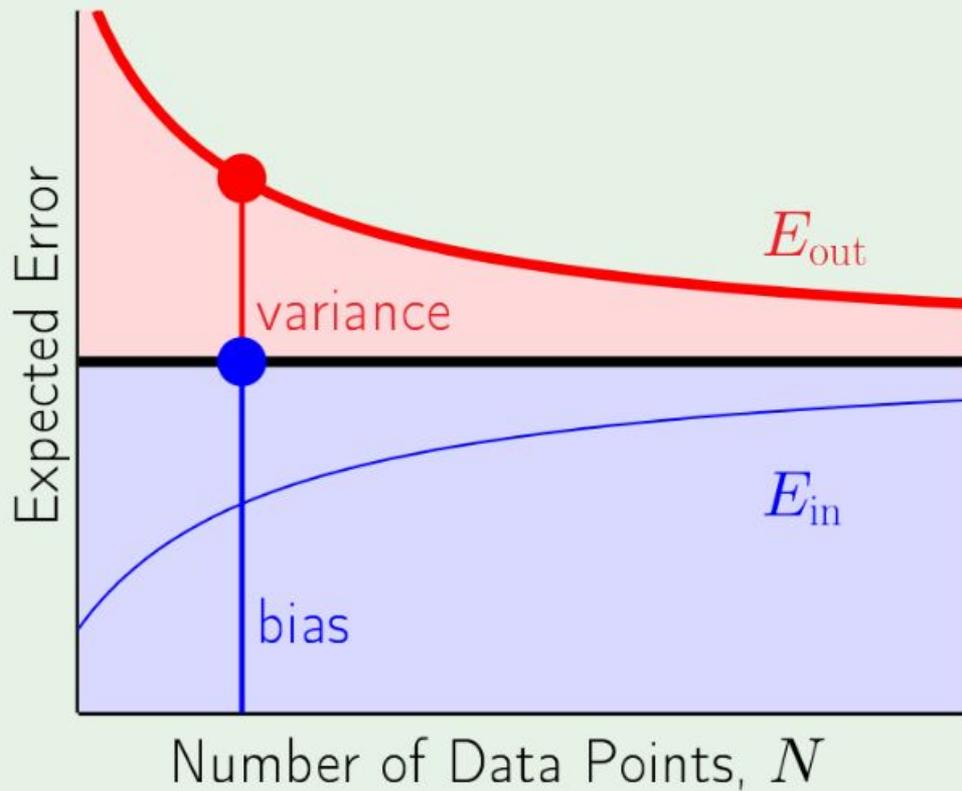
The curves



Simple Model



Complex Model



bias-variance