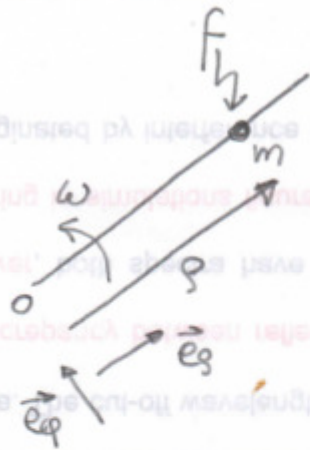


Ejercicio N° 1



$$\rho(0) = L \quad \dot{\rho}(0) = -v_0$$

parte a: $m\vec{a} = T\vec{e}_s + N\vec{e}_\phi$

$$\vec{a} = (\ddot{\rho} - \rho\dot{\phi}^2)\vec{e}_s + (\rho\ddot{\phi} + 2\dot{\rho}\dot{\phi})\vec{e}_\phi$$

$$\dot{\phi} = \omega \quad \ddot{\phi} = 0$$

$$m\ddot{\rho} - m\rho\omega^2 = T > 0 \text{ porque } \dot{\rho} < 0$$

$$N = 2m\dot{\rho}\omega < 0$$

$$|T| = f|N| \Rightarrow T = -2fm\dot{\rho}\omega$$

$$\Rightarrow m\ddot{\rho} + 2fm\dot{\rho}\omega - m\rho\omega^2 = 0 \Rightarrow \boxed{\ddot{\rho} + 2f\omega\dot{\rho} - \rho\omega^2 = 0}$$

parte b: $\rho = Ae^{\lambda t} \Rightarrow \lambda^2 + 2f\omega\lambda - \omega^2 = 0$

$$\Rightarrow \lambda_{\pm} = \frac{-2f\omega \pm \sqrt{4f^2\omega^2 + 4\omega^2}}{2} \Rightarrow \lambda_{\pm} = \omega(-f \pm \sqrt{f^2 + 1})$$

$\lambda_+ > 0, \lambda_- < 0$

$$\rho(t) = C_+ e^{\lambda_+ t} + C_- e^{\lambda_- t}$$

$$\rho(0) = L = C_+ + C_- \Rightarrow C_+ = L - C_-$$

$$\dot{\rho}(t) = C_+ \lambda_+ e^{\lambda_+ t} + C_- \lambda_- e^{\lambda_- t} \Rightarrow \dot{\rho}(0) = -v_0 = C_+ \lambda_+ + C_- \lambda_-$$

$$-v_0 = L\lambda_+ + C_- (\lambda_- - \lambda_+) \Rightarrow C_- = \frac{v_0 + L\lambda_+}{\lambda_+ - \lambda_-} \quad \lambda_+ - \lambda_- = 2\omega\sqrt{f^2 + 1}$$

$$C_+ = L - \frac{v_0 + L\lambda_+}{\lambda_+ - \lambda_-} = -\frac{v_0 + L\lambda_-}{\lambda_+ - \lambda_-}$$

$$\boxed{\rho(t) = -\frac{v_0 + L\lambda_-}{\lambda_+ - \lambda_-} e^{\lambda_+ t} + \frac{v_0 + L\lambda_+}{\lambda_+ - \lambda_-} e^{\lambda_- t}}$$

parte c: $\rho(t) = 0 \Rightarrow (v_0 + L\lambda_-) e^{\lambda_+ t} = (v_0 + L\lambda_+) e^{\lambda_- t}$

$$e^{(\lambda_+ - \lambda_-)t} = \frac{v_0 + L\lambda_+}{v_0 + L\lambda_-} \Rightarrow \boxed{t = \frac{1}{\lambda_+ - \lambda_-} \ln \frac{v_0 + L\lambda_+}{v_0 + L\lambda_-}}$$

parte d: Para que t exista $\frac{v_0 + L\lambda_+}{v_0 + L\lambda_-} > 0$

$$v_0, \lambda_+ > 0 \Rightarrow v_0 + L\lambda_+ > 0 \Rightarrow v_0 + L\lambda_- > 0 \Rightarrow \boxed{v_0 > L\omega(f + \sqrt{f^2 + 1})}$$

parte e:

Si $v_0 = -L\lambda_- \quad t \rightarrow \infty \quad C_+ = 0 \quad \dot{\rho}(t) = C_- \lambda_- e^{\lambda_- t} \rightarrow 0 \quad (\lambda_- < 0)$

$$C_- = L$$

$$P = T\vec{e}_\phi \cdot \vec{v} = T\vec{e}_\phi \cdot (\dot{\rho}\vec{e}_s + \rho\omega\vec{e}_\phi) = T\dot{\rho} = -2fm\dot{\rho}\omega$$

$$W_T = \int_0^t P(t) dt = -2fm\omega \int_0^{\infty} L^2 \lambda_-^2 e^{2\lambda_- t} dt =$$

$$= -fm\omega L^2 \lambda_- e^{2\lambda_- t} \Big|_0^{\infty} = \boxed{-fm\omega L^2 (f + \sqrt{f^2 + 1}) = W_T < 0}$$

Verificación: $T(t) - T(0) = W_N + W_T$

$$T = \frac{1}{2} m \dot{\vartheta}^2 + \frac{1}{2} m \vartheta^2 \omega^2 \quad T(t) = 0$$

$$T(0) = \frac{1}{2} m v_0^2 + \frac{1}{2} m L^2 \omega^2$$

$$W_N = \int_0^t dt P_N \quad P_N = N \vec{e}_\varphi \cdot \vec{v} = N \vartheta \omega = 2m\omega^2 \vartheta \dot{\vartheta}$$

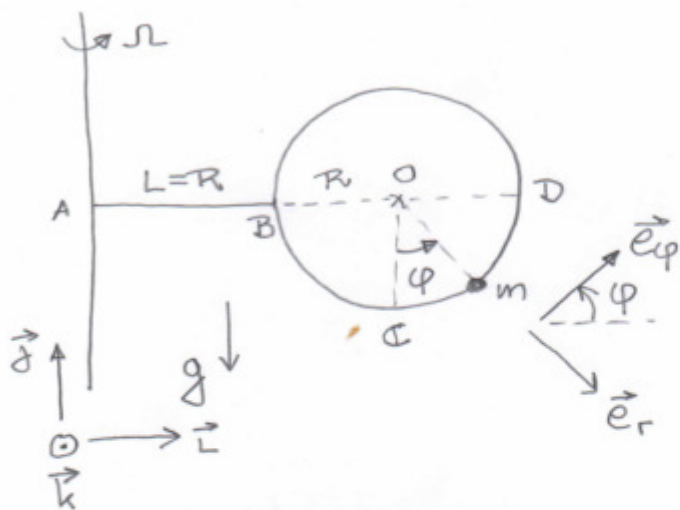
$$W_N = \int_0^t dt 2m\omega^2 \vartheta \dot{\vartheta} = m\omega^2 \vartheta^2 \Big|_L^0 = -m\omega^2 L^2$$

$$W_T - m\omega^2 L^2 = -\frac{1}{2} m v_0^2 - \frac{1}{2} m L^2 \omega^2$$

$$W_T = -\frac{1}{2} m v_0^2 + \frac{1}{2} m \omega^2 L^2 = -\frac{1}{2} m L^2 \omega^2 (f^2 + f^2 + 1 + 2f\sqrt{f^2 + 1})$$

$$\boxed{W_T = -m L^2 \omega^2 f (f + \sqrt{f^2 + 1})} < 0$$

Ejercicio N° 2:



parte a:

$$m\vec{a} = -mg\vec{j} + N\vec{e}_r + B\vec{k}$$

$$\vec{a} = \vec{a}' + \vec{a}_T + \vec{a}_C$$

$$\vec{a}' = R\ddot{\varphi}\vec{e}_\varphi - R\dot{\varphi}^2\vec{e}_r$$

$$\vec{a}_T = \vec{a}_A + \vec{\omega} \wedge (\vec{P}-\vec{A}) + \ddot{\omega} \wedge (\vec{P}-\vec{A}) + \vec{\omega} \wedge [\vec{\omega} \wedge (\vec{P}-\vec{A})]$$

$$\vec{P} = \vec{A} + 2R\vec{l} + R\vec{e}_r$$

$$\vec{\omega} = \Omega\vec{j}$$

$$\vec{\omega} \wedge (\vec{P}-\vec{A}) = 2R\Omega\vec{j} \wedge \vec{l} + R\Omega\vec{j} \wedge \vec{e}_r = -\Omega R\vec{k} - \Omega R \sin\varphi \vec{k}$$

$$\vec{e}_r = \sin\varphi\vec{l} - \cos\varphi\vec{j}$$

$$\vec{a}_T = -R\Omega^2(2 + \sin\varphi)\vec{j} \wedge \vec{k} = -R\Omega^2(2 + \sin\varphi)\vec{l}$$

$$\vec{a}_C = 2\vec{\omega} \wedge \vec{v}' = 2\Omega\vec{j} \wedge R\dot{\varphi}\vec{e}_\varphi = -2\Omega R\dot{\varphi}\cos\varphi\vec{k}$$

$$\vec{e}_\varphi = \cos\varphi\vec{l} + \sin\varphi\vec{j}$$

$$m\vec{a} \cdot \vec{e}_\varphi = -mg\vec{j} \cdot \vec{e}_\varphi = -mg\sin\varphi$$

$$\boxed{R\ddot{\varphi} - R\Omega^2(2 + \sin\varphi)\cos\varphi = -g\sin\varphi}$$

Verificación: Aplico teorema de la energía en el sistema relativo

1) $-mg\vec{j}$ conservativo: $U_g = mgy = -mgR\cos\varphi$

2) $N\vec{e}_r + B\vec{k} \perp \vec{v}' = R\dot{\varphi}\vec{e}_\varphi \Rightarrow$ potencia nula

3) $-m\vec{a}_C \perp \vec{v}' \Rightarrow$ también es de potencia nula

4) $-m\vec{a}_T = m\Omega^2 R(2 + \sin\varphi)\vec{l} = m\Omega^2 x\vec{l}$

$$U_T = -\frac{m\Omega^2 x^2}{2} \Rightarrow \vec{F}_T = -\frac{\partial U_T}{\partial x}\vec{l}$$

$$T' + U' = E \Rightarrow \frac{mR^2\dot{\varphi}^2}{2} - mgR\cos\varphi - \frac{m\Omega^2 R^2(2 + \sin\varphi)^2}{2} = E$$

$$mR^2\dot{\varphi}\ddot{\varphi} + mgR\sin\varphi\dot{\varphi} - m\Omega^2 R^2(2 + \sin\varphi)\cos\varphi\dot{\varphi} = 0 \quad \checkmark$$

parte b: $\frac{\partial U'}{\partial \varphi} = mgR\sin\varphi - m\Omega^2 R^2(2 + \sin\varphi)\cos\varphi$

Punto medio $\varphi = \frac{\pi}{4} \Rightarrow \sin\varphi = \cos\varphi = \frac{\sqrt{2}}{2}$

$$\frac{\partial U'}{\partial \varphi} \Big|_{\varphi=\frac{\pi}{4}} = mgR\frac{\sqrt{2}}{2} - m\Omega^2 R^2 \left(2 + \frac{\sqrt{2}}{2}\right) \frac{\sqrt{2}}{2} = 0$$

$$\boxed{g = \frac{4 + \sqrt{2}}{2} R\Omega^2}$$

$$\frac{\partial^2 U'}{\partial \varphi^2} = mgR \cos \varphi + m\Omega^2 R^2 (2 + \operatorname{sen} \varphi) \operatorname{sen} \varphi - m\Omega^2 R^2 \cos^2 \varphi$$

$$\left. \frac{\partial^2 U'}{\partial \varphi^2} \right|_{\varphi = \frac{\pi}{4}} = mgR \frac{\sqrt{2}}{2} + m\Omega^2 R^2 \left(\sqrt{2} + \frac{1}{2} \right) - \frac{m\Omega^2 R^2}{2} > 0$$

La posición es de equilibrio estable

parte c: $\varphi(0) = 0, \dot{\varphi}(0) = 0 \Rightarrow E = -mgR - m\Omega^2 R^2 2$

$$\frac{mR^2 \dot{\varphi}^2}{2} = mgR (\cos \varphi - 1) + \frac{m\Omega^2 R^2}{2} \operatorname{sen}^2 \varphi + 2m\Omega^2 R^2 \operatorname{sen} \varphi$$

$\dot{\varphi}(0) = 2\Omega^2 > 0 \Rightarrow$ la partícula efectivamente se mueve hacia D

La condición $\frac{\partial U'}{\partial \varphi} = 0 \sim g \operatorname{tg} \varphi = \Omega R (2 + \operatorname{sen} \varphi)$

$\frac{\partial U'}{\partial \varphi} = 0$ en un único punto en $0 \leq \varphi \leq \frac{\pi}{2}$

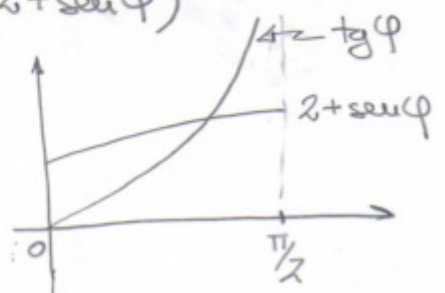
\Rightarrow solo habrá un extremo relativo de U' en $0 \leq \varphi \leq \frac{\pi}{2}$, que por la parte b es un mínimo. \Rightarrow alcanza $E \geq U$ en $\frac{\pi}{2}$

para que la partícula llegue.

$$\sim \dot{\varphi}^2(\pi/2) \geq 0$$

$$\dot{\varphi}^2(\pi/2) = \frac{2}{R} \left(-g + \Omega^2 R \frac{5}{2} \right) = \frac{2}{R} \left(-\frac{g}{2} - \frac{\sqrt{2}}{2} + \frac{5}{2} \right) R \Omega^2 = (1 - \sqrt{2}) \Omega^2 < 0$$

La partícula no alcanza el punto D.



parte d: $P = (N\vec{e}_r + B\vec{k}) \cdot \vec{v}$

$$\vec{v} = \vec{v}' + \vec{v}_T = R\dot{\varphi}\vec{e}_\varphi + \vec{v}_A + \vec{\omega} \wedge (P-A) = R\dot{\varphi}\vec{e}_\varphi - R\Omega(2 + \operatorname{sen} \varphi)\vec{k}$$

$$\left. \begin{aligned} P &= -B R \Omega (2 + \operatorname{sen} \varphi) \\ B &= m\vec{a} \cdot \vec{k} = -2m\Omega R \dot{\varphi} \cos \varphi \end{aligned} \right\} P = 2m\Omega^2 R^2 (2 + \operatorname{sen} \varphi) \cos \varphi \dot{\varphi}$$

$$W_{\vec{R}} = \int_0^{\pi/4} P(t) dt = m\Omega^2 R^2 (2 + \operatorname{sen} \varphi)^2 \Big|_0^{\pi/4} = m\Omega^2 R^2 \left[\left(2 + \frac{\sqrt{2}}{2} \right)^2 - 4 \right]$$

$$W_{\vec{R}} = m\Omega^2 R^2 \left(2\sqrt{2} + \frac{1}{2} \right) = \frac{m\Omega^2 R^2 (4\sqrt{2} + 1)}{2} = W_{\vec{R}}$$

Verificación: Aplico el teorema de la energía

$$T(\pi/4) + U_g(\pi/4) - T(0) - U_g(0) = W_{\vec{R}}$$

$$T = \frac{mR^2\dot{\varphi}^2}{2} + \frac{mR^2\Omega^2}{2} (2 + \sec\varphi)^2$$

$$T(\pi/4) = mg \left(\frac{\sqrt{2}}{2} - 1 \right) + \frac{m\Omega^2 R^2}{2} \frac{1}{2} + m\Omega^2 R^2 \sqrt{2} + \frac{mR^2\Omega^2}{2} \left(2 + \frac{\sqrt{2}}{2} \right)^2$$

$$U_g(\pi/4) = -mgR \frac{\sqrt{2}}{2}$$

$$T(0) = 2mR^2\Omega^2$$

$$U_g(0) = -mgR$$

$$W_{\vec{R}} = \frac{m\Omega^2 R^2}{4} \left(1 + 4\sqrt{2} + 2 \left(4 + 2\sqrt{2} + \frac{1}{2} \right) - 8 \right) = \frac{m\Omega^2 R^2}{4} (2 + 8\sqrt{2})$$

$$W_{\vec{R}} = \frac{m\Omega^2 R^2}{2} (1 + 4\sqrt{2}) \quad \checkmark$$

