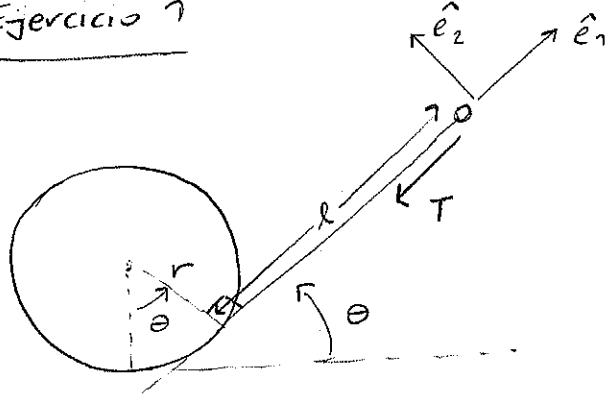


Ejercicio 7



a) $\vec{r} = -r\hat{e}_1 + l\hat{e}_2 ; \quad l = b - r\theta$

$$\vec{v} = \dot{\vec{r}} = -r\dot{\hat{e}}_2 + \dot{l}\hat{e}_1 + l\dot{\hat{e}}_2 = -r(-\dot{\theta}\hat{e}_1) - r\dot{\theta}\hat{e}_2 + l\dot{\theta}\hat{e}_2$$

$$\boxed{\vec{v} = (b - r\theta)\dot{\theta}\hat{e}_2}$$

b) $\vec{T} = -T\hat{e}_1 \Rightarrow \vec{T} \cdot \vec{v} = 0$: la energía de la partícula se conserva

$$\Rightarrow |\vec{v}| = \text{cte.} = u$$

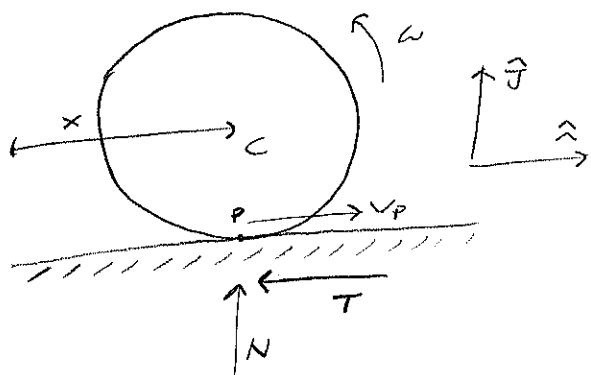
c) $(b - r\theta)\dot{\theta} = u$

$$\Leftrightarrow (b - r\theta)d\theta = u dt$$

$$\Rightarrow \int_0^{b/r} (b - r\theta)d\theta = \int_0^{t_f} u dt = ut_f : t_f = \frac{u}{b/r} \int_0^{b/r} (b - r\theta)d\theta$$

$$t_f = \frac{u}{b/r} \left(b\theta - \frac{1}{2}r\theta^2 \right) \Big|_0^{b/r} = \boxed{\frac{u}{b/r} \frac{b^2}{2r}}$$

Ejercicio 2)



a) 1era (vertical): $\hat{x} \ddot{x} = -T$
 $\hat{z} \cdot \vec{\omega} = N - mg$

$$T = f_D N : \frac{m \ddot{x} = -f_D mg}{\ddot{x} = -f_D g}$$

2da (horizontal desde C):

$$I_C \dot{\omega} = -R T = -R f_D mg ; I_C = \frac{1}{2} m R^2$$

$$\Rightarrow \boxed{\dot{\omega} = -2 f_D g / R}$$

b) Cuando deja de deslizar: $\vec{v}_P = \vec{0}$

$$\vec{v}_P = v_P \hat{z} = (\dot{x} + \omega R) \hat{z}$$

Integrando en el tiempo las ecuaciones de movimientos: $\dot{x} = v_0 - f_D g t$

$$\omega = \omega_0 - 2 f_D g / R \cdot t$$

$$\Rightarrow v_P(t) = v_0 + \omega_0 R - 3 f_D g t$$

$$v_P(t^*) = 0 : v_0 + \omega_0 R - 3 f_D g t^* = 0 : \boxed{t^* = \frac{v_0 + \omega_0 R}{3 f_D g}}$$

$$c) E(t=0) = \frac{1}{2} m v_0^2 + \frac{1}{2} \left(\frac{m R^2}{2} \right) \omega_0^2$$

$$E(t^*) = \frac{1}{2} m \dot{x}^2(t^*) + \frac{1}{2} \left(\frac{m R^2}{2} \right) \omega^2(t^*)$$

$$W_T = E(t^*) - E(0) =$$

$$\frac{1}{2} m \left[v_0 - \frac{2}{3} (v_0 + \omega_0 R) \right]^2 + \frac{3}{4} m \left[\omega_0 R - \frac{2}{3} (v_0 + \omega_0 R) \right]^2 - \frac{1}{2} m v_0^2 - \frac{3}{4} m (\omega_0 R)^2$$

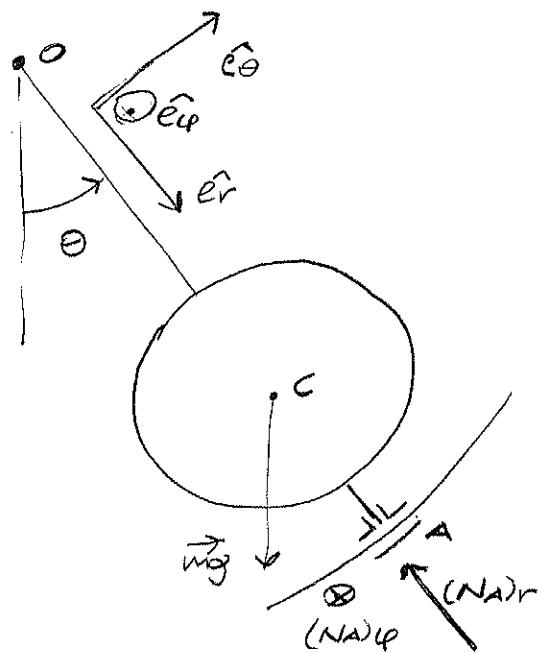
$$\boxed{W_T = -\frac{7}{6} m (v_0 + \omega_0 R)^2}$$

d) Despúis de dejar de deslizar, $T=0$ y el disco rozaere con \vec{v}_C constante; si hay inversión de la velocidad es previa a t^* , por lo que $\dot{x}(t^*) < 0$: $\boxed{v_0 < \frac{\omega_0 R}{2}}$

La inversión se da en un tiempo t_{inv} :

$$\dot{x}(t_{inv}) = 0 : v_0 - f_D g t_{inv} = 0 : \boxed{t_{inv} = \frac{v_0}{f_D g}}$$

Ejercicio 3)



$$a) \vec{\omega} = \dot{\theta} \hat{e}_\theta + \dot{\varphi} \hat{e}_\varphi$$

$$\vec{L}_o = I_o \vec{\omega}$$

$$I_o \{ \hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi \} = \begin{pmatrix} I_C & 0 & 0 \\ 0 & I_C + mR^2 & 0 \\ 0 & 0 & I_C + mR^2 \end{pmatrix}$$

$$I_C = \frac{2}{5} m R^2$$

$$\Rightarrow \vec{L}_o = \left(\frac{2}{5} m R^2 + mR^2 \right) \dot{\theta} \hat{e}_\theta + \frac{2}{5} m R^2 \dot{\varphi} \hat{e}_\varphi$$

$$b) \vec{L}_o = \vec{M}_o^{(ext)} ; \text{ como la reacción en A no tiene componente en } \hat{e}_\theta : \\ M_o^{(NA)} \cdot \hat{e}_r \Rightarrow M_o^{(NA)} \cdot \hat{e}_\varphi = 0$$

$$\Rightarrow \begin{cases} \vec{L}_o \cdot \hat{e}_r = 0 \\ \vec{L}_o \cdot \hat{e}_\varphi = -mgl \sin \theta \end{cases}$$

$$\vec{L}_o = \left(\frac{2}{5} m R^2 + mR^2 \right) \ddot{\theta} \hat{e}_\theta + \frac{2}{5} m R^2 \dot{\varphi} \hat{e}_\varphi + \frac{2}{5} m R^2 \dot{\varphi} \hat{e}_\theta$$

$$\Rightarrow \begin{cases} \ddot{\varphi} = 0 \\ \left(\frac{2}{5} m R^2 + mR^2 \right) \ddot{\theta} = -mgl \sin \theta \end{cases}$$

c) preintegrando la segunda ecuación de movimiento:

$$\left(\frac{2}{5} m R^2 + mR^2 \right) \frac{1}{2} (\dot{\theta}^2 - \dot{\theta}_0^2) = mgl(\cos \theta - 1) :$$

$$\dot{\theta}^2 = \dot{\theta}_0^2 + \frac{2mgl}{\left(\frac{2}{5} m R^2 + mR^2 \right)} (\cos \theta - 1)$$

Para que A de una vuelta completa: $\dot{\theta}^2 > 0 \quad \forall \theta \in [0, 2\pi]$

$$\Rightarrow \dot{\theta}_0^2 > \frac{4gl}{\frac{2}{5} R^2 + l^2}$$