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- 1. $A_1 = \begin{pmatrix} 1 & 3 \\ 1 & -1 \end{pmatrix}$
- 2. $A_2 = \begin{pmatrix} 0 & -1 \\ 8 & -6 \end{pmatrix}$
- 3. $A_3 = \begin{pmatrix} 0 & 1 \\ -2 & -1 \end{pmatrix}$
- 4. $A_4 = \begin{pmatrix} 1 & 2 \\ -5 & -1 \end{pmatrix}$



A₂: $(1-\lambda)(-2-\lambda) - 3 = 0$

$$\lambda^2 - 1 - 3 = 0$$

$$\lambda^2 - 4 = 0 \rightarrow \lambda = \pm 2$$

A₂: $-\lambda(-6-\lambda) + 8 = 0$

$$\lambda^2 + 6\lambda + 8 = 0$$

$$\sqrt{36 - 32} = \sqrt{4} = 2 \quad \tau_0$$

A₃ $-\lambda(-2-\lambda) + 2 = 0$

$$\lambda^2 + \lambda + 2 = 0$$

$$\sqrt{1 - 8} \quad \text{non real } \tau_0$$

A₄: $(2-\lambda)(-2-\lambda) + 10 = 0$

$$\lambda^2 + 10 = 0$$

$$\lambda = \pm \sqrt{-10} \quad \text{complex } \tau_0$$

$$2. A_2 = \begin{pmatrix} 0 & -1 \\ 8 & -6 \end{pmatrix}$$

$$p(\lambda) = -\lambda(-6-\lambda) + 8$$

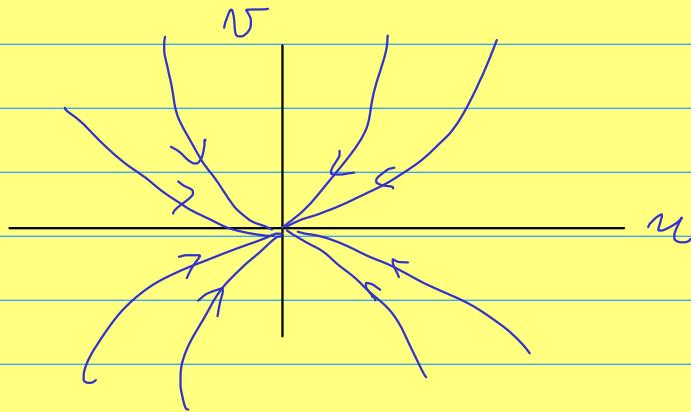
$$\lambda^2 + 6\lambda + 8$$

$$\lambda = \frac{-6 \pm \sqrt{36 - 32}}{2} = -3 \pm 1$$

$$D = \begin{pmatrix} -2 & 0 \\ 0 & -4 \end{pmatrix}$$

$$\dot{y} = D y$$

$$\lambda = 2$$



P:

$$2. A_2 = \begin{pmatrix} 0 & -1 \\ 8 & -6 \end{pmatrix}$$

$$\lambda = -4$$

$$\lambda = -2$$

v₁:

$$A_2 + 2I = \begin{pmatrix} 2 & -1 \\ 8 & -4 \end{pmatrix}$$

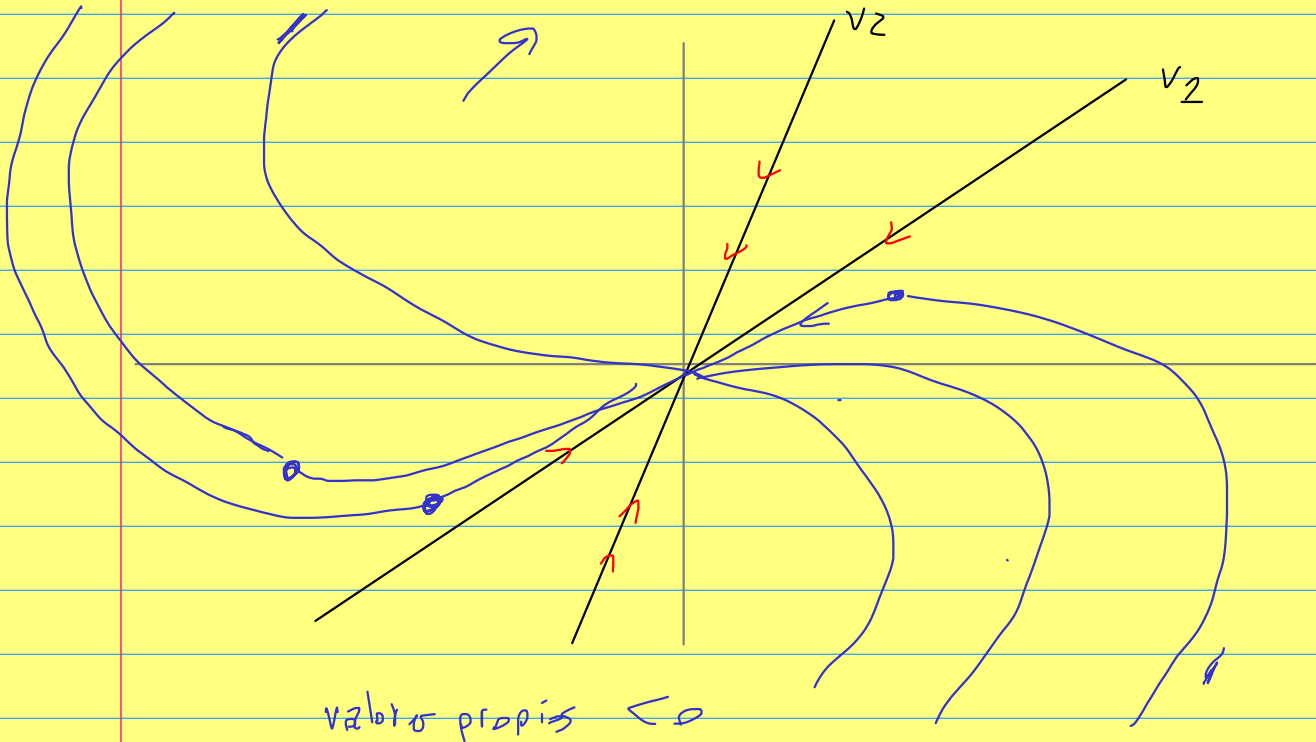
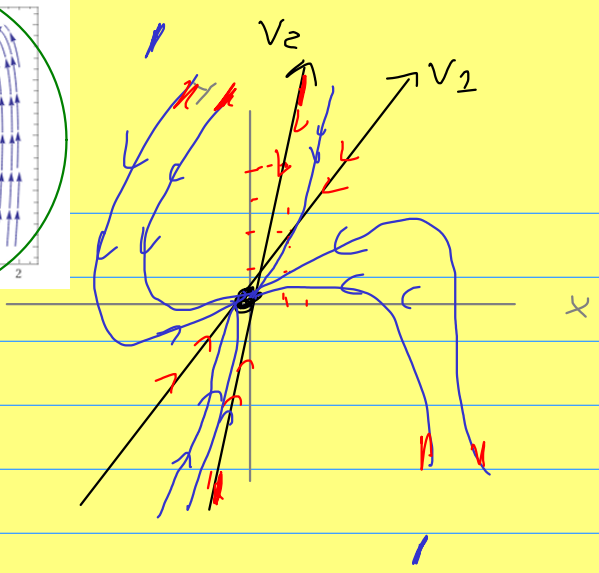
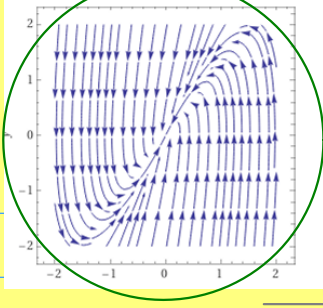
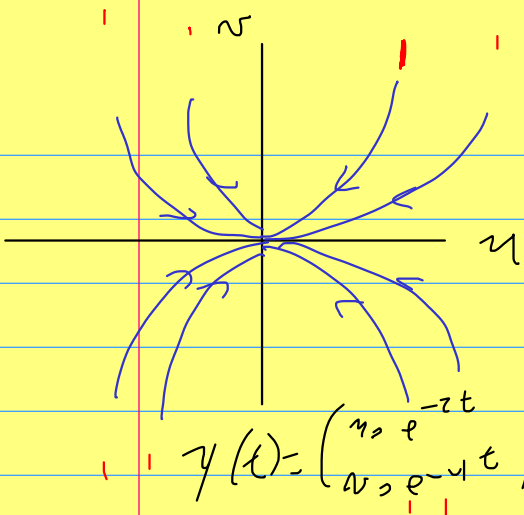
$$2x - y = 0 \rightarrow y = 2x \rightarrow v_1 = (2, 2)$$

v₂:

$$A_2 + 4I = \begin{pmatrix} 4 & -1 \\ 8 & -2 \end{pmatrix} \rightarrow 4x - y = 0 \rightarrow y = 4x$$

$$v_2 = (2, 4)$$

$$P = \begin{pmatrix} 2 & 2 \\ 2 & 4 \end{pmatrix}$$



(i) repulsor (ii) atractor (iii) punto silla.

o valores propios de signo distinto.

valores
positivos

Ejercicio 3

Decidir si la siguiente afirmación es verdadera o falsa:

Si $\mathbf{u}(t) = \begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix}$ y $\mathbf{v}(t) = \begin{pmatrix} v_1(t) \\ v_2(t) \end{pmatrix}$ resuelven la ecuación

$$\mathbf{y}'(t) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \mathbf{y}(t)$$

con $\mathbf{u}(0) \perp \mathbf{v}(0)$ y $\mathbf{u}(1) \perp \mathbf{v}(1)$, entonces $\mathbf{u}(t) \perp \mathbf{v}(t)$ para todo t .

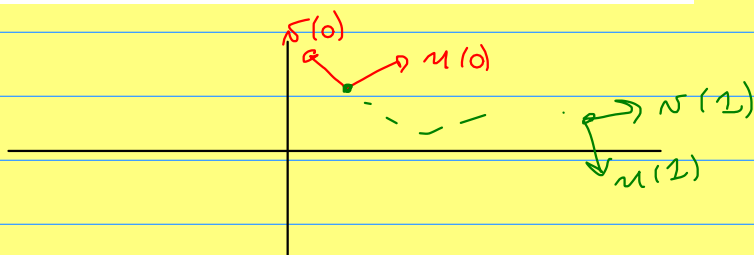
Respuesta:

- A) Verdadero
- B) Falso

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\mathbf{u}' = A\mathbf{u}$$

$$\mathbf{v}' = A\mathbf{v}$$



Resolver el siguiente sistema reescribiendolo en forma matricial y usando valores y vectores propios:

$$\begin{cases} \dot{x} = 2x - y + t \\ \dot{y} = 3x - 2y - 1 \\ x(0) = 0, y(0) = 0 \end{cases}$$

Sugerencia: buscar soluciones de la forma

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x_h \\ y_h \end{pmatrix} + \begin{pmatrix} x_p \\ y_p \end{pmatrix}$$

en donde $\begin{pmatrix} x_h \\ y_h \end{pmatrix}$ es solución de la ecuación homogénea y $\begin{pmatrix} x_p \\ y_p \end{pmatrix}$ es una solución particular de la forma $\begin{pmatrix} At+B \\ Ct+D \end{pmatrix}$.

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} t \\ -1 \end{pmatrix}$$

Ecuación homogénea

$$\begin{pmatrix} At+B \\ Ct+D \end{pmatrix} = \begin{pmatrix} x_p(t) \\ y_p(t) \end{pmatrix}$$

$$A = \dot{x}_p = 2(At+B) - (Ct+D) + t$$

$$C = \dot{y}_p = 3(At+B) - 2(Ct+D) - 1$$

Matriz Fundamental

Si D es una matriz diagonal, $D = \text{diag}(\lambda_1, \dots, \lambda_n)$

$$\dot{x} = Dx \quad \leadsto \quad x(t) = x(0) e^{Dt}$$

Def: $e^{Dt} = \sum_{k=0}^{\infty} \frac{(Dt)^k}{k!}$, entendiendo $(Dt)^0 = Id$

$(Dt)^k = D^k t^k$
 $D = \text{diag}(\lambda_1, \dots, \lambda_n)$

$$D^k = \text{diag}(\lambda_1^k, \dots, \lambda_n^k)$$

Id

$$e^{Dt} = \text{diag}(1, \dots, 1) + \sum_{k=1}^{+\infty} \frac{\text{diag}(\lambda_1^k t^k, \dots, \lambda_n^k t^k)}{k!}$$

Entrada $(e^{Dt})_{ii}$ $= 1 + \sum_{k=1}^{+\infty} \frac{\lambda_i^k t^k}{k!} = e^{\lambda_i t}$ Taylor

$$e^{Dt} = \text{diag}(e^{\lambda_1 t}, \dots, e^{\lambda_n t})$$

$$= \begin{pmatrix} e^{\lambda_1 t} & 0 & \dots & 0 \\ 0 & e^{\lambda_2 t} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & e^{\lambda_n t} \end{pmatrix}$$

$$x(t) = x(0) e^{At} = \underline{(x_2(0) e^{\lambda_2 t}, \dots, x_n(0) e^{\lambda_n t})}$$

¿Qué pasa cuando cambiamos la base?

$$A \underset{P}{\leftarrow} = \underset{P}{\rightarrow} B P$$

$$\underline{AF}: (P^{-1} B P)^K = P^{-1} B^K P$$

Dem. K=1 ✓

K=n: Sabemos que $(P^{-1} B P)^n = P^{-1} B^n P$
 queremos ver que $(P^{-1} B P)^{n+2} = P^{-1} B^{n+2} P$

$$\begin{aligned} (P^{-1} B P)^{n+2} &= (P^{-1} B P)^n (P^{-1} B P) \\ &= P^{-1} B^n \underbrace{P P^{-1}}_{Id} B P = P^{-1} B^{n+1} P \end{aligned}$$

$$e^{P^{-1} B P t} = \sum_{K=0}^{+\infty} \frac{(P^{-1} B P)^K}{K!} = \sum_{K=0}^{+\infty} \frac{P^{-1} B^K P}{K!} = P^{-1} \underbrace{\left(\sum_{K=0}^{+\infty} \frac{B^K}{K!} \right)}_{e^B} P$$

$$A t = P^{-1} B P t \rightarrow e^{A t} = P^{-1} e^{B t} P$$

$$1) A = \begin{pmatrix} 4 & -6 \\ 2 & -4 \end{pmatrix} \quad e^A$$

$$\underline{B}: (4-\lambda)(-4-\lambda) + 12 = 0$$

$$\lambda^2 - 26 + 12 = 0 \rightarrow \lambda^2 - 4 = 0 \rightarrow B = \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix}$$

$$\lambda = \pm 2$$

$$e^B = \begin{pmatrix} e^2 & 0 \\ 0 & e^{-2} \end{pmatrix} \rightarrow B \text{ diagonal}$$

$$e^A = P^{-1} e^B P$$

P: v_1 : 1) $A = \begin{pmatrix} 4 & -6 \\ 2 & -4 \end{pmatrix}$ $\rightarrow A - 2I = \begin{pmatrix} 2 & -6 \\ 2 & -6 \end{pmatrix}$

$$\lambda = 2$$

$$2x - 6y = 0 \rightarrow x = 3y$$

$$v_1 = (3, 1)$$

v_2 : $\lambda = -2$: $A + 2I = \begin{pmatrix} 6 & -6 \\ 4 & -4 \end{pmatrix}$

$$6x - 6y = 0 \rightarrow x = y \rightarrow v_2 = (1, 1)$$

$$P = \begin{pmatrix} 3 & 1 \\ 1 & 1 \end{pmatrix}$$

$$P^{-1} = \frac{1}{\det(P)} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$$e^A = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} e^2 & 0 \\ 0 & e^{-2} \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 1 \end{pmatrix}$$

¿Cómo se e^J cuando J es de Jordan?

$$J = \begin{pmatrix} \lambda & 0 & 0 & 0 & \dots & 0 \\ 1 & \lambda & 0 & 0 & \dots & 0 \\ 0 & 1 & \lambda & 0 & \dots & 0 \\ \vdots & & \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & 1 & \lambda & 0 \end{pmatrix}$$

Ej: $J = \begin{pmatrix} \lambda & 0 & 0 \\ 1 & \lambda & 0 \\ 0 & 1 & \lambda \end{pmatrix}$

$$e^{Jt}$$

$$e^J = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ \frac{t^2}{2!} & t & 1 \end{pmatrix}$$

$$e^{Jt} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ t & 1 & 0 & 0 \\ \frac{t^2}{2!} & t & 1 & 0 \\ \frac{t^3}{3!} & \frac{t^2}{2!} & t & 1 \end{pmatrix}$$

$$A = P^{-1} J P \quad \rightsquigarrow \quad e^{At} = P^{-1} e^{Jt} P$$

10. (a) Probar que si $A = \begin{pmatrix} \alpha & \beta \\ -\beta & \alpha \end{pmatrix}$ entonces $e^{At} = e^{\alpha t} \begin{pmatrix} \cos(\beta t) & \sin(\beta t) \\ -\sin(\beta t) & \cos(\beta t) \end{pmatrix}$.

Nota: Para probar esta parte vamos a admitir el siguiente resultado:

Si A y B son dos matrices tales que $A \cdot B = B \cdot A$ entonces $e^{(A+B)t} = e^{At} e^{Bt}$.

$$A = \underbrace{\begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}}_B + \underbrace{\begin{pmatrix} 0 & \beta \\ -\beta & 0 \end{pmatrix}}_C$$

$$\begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix} \begin{pmatrix} 0 & \beta \\ -\beta & 0 \end{pmatrix} = \begin{pmatrix} 0 & \alpha\beta \\ -\alpha\beta & 0 \end{pmatrix} \stackrel{v \neq v}{=} \begin{pmatrix} 0 & \beta \\ -\beta & 0 \end{pmatrix} \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}$$

$$e^{At} = e^{Bt} e^{Ct}$$

$Bt = \text{diag}_2(\alpha t, \alpha t) \rightarrow e^{Bt} = \text{diag}_2(e^{\alpha t}, e^{\alpha t}) = e^{\alpha t} I_2$

$$e^{At} = e^{\alpha t} I_2 e^{Ct} = e^{\alpha t} e^{Ct}$$

AF: $\therefore C = \begin{pmatrix} 0 & \beta \\ -\beta & 0 \end{pmatrix} \Rightarrow e^{Ct} = \begin{pmatrix} \cos(\beta t) & \sin(\beta t) \\ -\sin(\beta t) & \cos(\beta t) \end{pmatrix}$

Sugerencia: i) Verificar que las potencias de C se "repite" después de 4 potencias:

ii) Recordar las Taylor's de $\cos(\beta t)$ y $\sin(\beta t)$

2x2

$$A = P^{-1} B P \rightarrow B : \begin{cases} \text{Diagonal} \\ \text{Jordan} \\ \begin{pmatrix} \alpha & \beta \\ -\beta & \alpha \end{pmatrix} \end{cases}$$

3x3