

coord $T(2)$ in 1st base V

$$\text{circled } U(T)_E = \begin{pmatrix} 1 & -2 & 5 \\ 0 & 3 & 3 \\ 1 & 0 & 1 \end{pmatrix}$$

$$E = \left\{ 1, x+1, (x+1)^2 \right\}$$

$$\begin{aligned} T(1) &= 1 \cdot (1, 1, 0) + 0 \cdot (1, 2, 1) + 1 \cdot (3, 2, 1) \\ &= (1, 3, 1) = 1(1, 0, 0) + 3(0, 1, 0) + 1(0, 0, 1) \end{aligned}$$

$$x^2 + x - 1 \in \mathbb{R}_2[x] \xrightarrow{T} \mathbb{R}_3 \longrightarrow \mathbb{R}_3$$

$$E \underset{\cup}{\underset{\cap}{\sim}} (T)_E \cup, \underset{\cap}{\sim} (Id) \cup \Psi$$

$$\begin{aligned} x^2 + x - 1 &= 3 \cdot 1 + 6(x-1) + c(x+1)^2 \\ &= cx^2 + x[6 + 2c] + 3 - 6 + c \end{aligned}$$

$$\begin{cases} c = 1 \\ 6 + 2c = 1 \rightarrow 16 \geq -2 \\ 3 - 6 + c = -1 \rightarrow 2 \cancel{-6} + 1 = -1 \\ 3 = -3 \end{cases}$$

$$T(x^2 + x - 1) = T(3 \cdot 1 + \frac{-1}{3}(x-1) + 1(x+1)^2)$$

$$= \frac{-1}{3} T(1) + \frac{-1}{3} T(x-1) + 1 T(x+1)^2$$

Calculation

Conclusion: $T(x^2 + x - 1) \dots$

$$U(T)_E = \begin{pmatrix} 1 & -2 & 5 \\ 0 & 3 & 3 \\ 1 & 0 & 1 \end{pmatrix} \xrightarrow{\text{Coord}_V(T((x+z)^c))} \text{Coord}_V(T(x-z))$$

$$\begin{aligned} T(x-z) &= -2(1,1,0) + 3(1,2,1) + 0(1,1,1) = (1,0,9) \\ T((x+z)^c) &= 5(1,1,0) + 3(2,1,1) + 1(3,1,2) = (12,13,10) \\ T(z) &= (4,3,1) \end{aligned}$$

Escribir x^2+x-z como combinación lineal de las bases E.

$$x^2+x-z = -3 \cdot z - (x-z) + (x+z)^2$$

$$(-3, -1, 1) = \text{Coord}_E(x^2+x-z)$$

$$\begin{aligned} T(x^2+x-z) &= T(-3 \cdot z - (x-z) + (x+z)^2) \\ &= -3T(z) - T(x-z) + T((x+z)^2) \\ &= -3(4,3,1) - (1,0,9) + (12,13,10) \\ &= (2, 4, -2) = 2 \underbrace{(1,0,0)}_{\text{Base canónica}} + 4 \underbrace{(1,1,0)}_{\text{Base canónica}} - 2(0,0,1) \end{aligned}$$

Cambio de base de $\mathbb{U} \rightarrow \mathbb{Q}$

$$\mathbb{U} = \{(1,1,0), (1,2,1), (3,2,1)\}$$

$$\mathbb{Q} = \{(1,0,1), (0,1,0), (0,0,1)\}$$

$$(\text{Id})_{\mathbb{U}} = \begin{pmatrix} \textcircled{1} & \textcircled{0} & \textcircled{0} \\ \textcircled{1} & \textcircled{0} & \textcircled{0} \\ -1/2 & \textcircled{0} & \textcircled{1} \end{pmatrix}$$

$$\hookrightarrow \text{Coord}_{\mathbb{Q}}(\text{Id}(1,1,0)) = \text{Coord}_{\mathbb{Q}}(1,1,0)$$

$$(1,1,0) = 3(1,0,1) + 6(0,1,0) + (-1/2)(0,0,1)$$

$$\begin{cases} 3=1 \\ 6=1 \\ -1/2=c \end{cases} \rightarrow c = -1/2$$

Paso de vectores
de matrices

$$(\text{T})_{\mathbb{U}} \sim (\text{T})_{\mathbb{Q}} = (\text{Id})_{\mathbb{U}} \cdot (\text{T})_{\mathbb{E}}$$

9. Sean las funciones $S, T, U : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ dadas por

- $S(x, y, z) = (z, y, x + 8)$.
- $T(x, y, z) = (x, y, z - 8)$.
- $U(x, y, z) = (x + y, x - y, 0)$.

$$\begin{aligned} (S + T)(x_1, y_1, z_1) &= S(x_1, y_1, z_1) + T(x_1, y_1, z_1) \\ &= (\underbrace{z_1 + y_1, z_1 - y_1}_{x_1}, x_1 + z_1) \end{aligned}$$

$$S(x_1, y_1, z_1) = (z_1, y_1, x_1 + 8)$$

$$T(x_1, y_1, z_1) = (x_1, y_1, z_1 - 8)$$

$$S \circ T = S(x^2, e^t, z^2) = (0, 2x^2, e^t) \quad \text{No linear}$$

$$S_0 S \circ T = S(0, 2x^2, e^{-t}) = (0, 0, 2x^2)$$

$$S_0 S_0 S_0 T = S(0, 0, 2x^2) = (0, 0, 0) \rightarrow S^3 \circ T \text{ es la transformación} \\ (\text{lineal})$$

$S \circ T$ es no lineal, ya que $S^3 \circ T$ sea

lineal:

$$\text{i)} S^3 \circ T = (0, 0, 0)$$

$$\text{ii)} S^2 \circ T = (x^2, 0, 0) \Rightarrow S^3 \circ T \text{ sea lineal} \\ \Leftrightarrow S \text{ en algún lugar aplicar} \sqrt{} \\ \text{no es lineal}$$



$$\begin{aligned} T(0,0,1) &= (0,0,0) \\ T(0,1,0) &= (0,0,0) \\ T(1,0,0) &= (1,0,0) \end{aligned} \quad \left. \begin{array}{l} N(T) \text{ es el plan } \\ \text{yz} \\ \rightarrow \text{Im}(T) \text{ es el eje } x \end{array} \right\}$$

