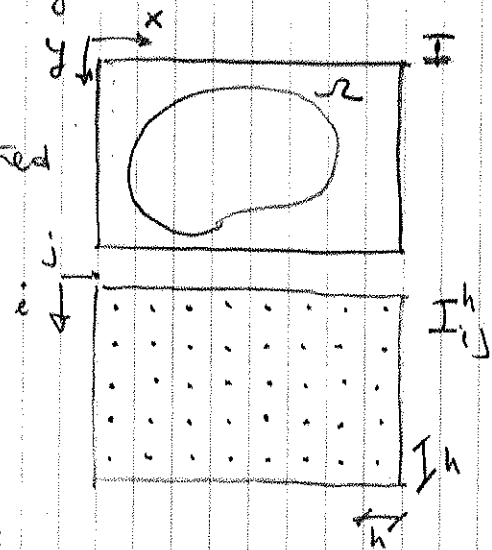


# CLASE 1: Introduction to signal processing.

An image is a function  $I(x,y): \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ ,  
 in practical applications this image is represented  
 by a sampled (Discrete) version of it:



$$I_{ij}^h \stackrel{\text{DEF}}{=} \iint_{-\frac{h}{2}-\frac{h}{2}}^{\frac{h}{2}-\frac{h}{2}} I(u-j, v-i) du dv \approx \text{conv}(H) I(ih, jh)$$

## USEFULL DEFINITIONS AND PROPERTIES ON IMAGES:

### (1) x/y - Partial derivatives:

Cont.  $I_x \stackrel{\text{def}}{=} \lim_{\delta \rightarrow 0} \frac{I(x+\delta, y) - I(x, y)}{\delta}$  (analogously for y)

Discrete approx:  $I_x(x, y) \approx \begin{cases} \frac{(I_{i+1,j}^h - I_{i,j}^h)}{h} & \text{(centered-scheme)} \\ \frac{(I_{i+1,j}^h - I_{i,j}^h)}{h} & \text{(forward-scheme)} \\ \frac{(I_{i,j}^h - I_{i,j-1}^h)}{h} & \text{(backward-scheme)} \end{cases}$

⊖ BE CAREFUL AT BOUNDARIES ⊖

### EXERCISE:

Demonstrate that the first approx has an error order  $O(h^3)$  and the other two-schemes are order  $O(h^2)$ .

Solution: (TAYLOR)  $I_{i+1,j}^h = I(x+h, y) = \overbrace{I(x, y)}^{= I_{ij}^h} + I_x(x, y)h + O(h^2)$   
 $\rightarrow I_{i+1,j}^h - I_{ij}^h = h I_x(x, y) + O(h^2)$  [the other are similar]

### (ii) Laplacian:

Cont:  $\Delta I \stackrel{\text{DEF}}{=} I_{xx} + I_{yy}$

Discret: 4-points stencil



$$\Delta^h I_{ij}^h = -4 I_{ij}^h + I_{(i+1)j}^h + I_{(i-1)j}^h + I_{i(j+1)}^h + I_{i(j-1)}^h$$

DEM:  $\Delta^h I_{ij}^h = \underbrace{(I_{(i+1)j}^h - I_{ij}^h)}_{I_{xx}^i} + \dots$

(iii) 2D-Convolution:

Cont: DEF:  $f * g(x, y) = \iint_{\Omega} f(u, v) g(x-u, y-v) du dv$

Discret:  $(f * g)_{i,j} = \sum_{i', j'} f_{i', j'} \cdot g_{(i-i')(j-j')}$   $\ominus$  BE CAREFUL AT BOUNDARIES

(iv) 2D-FOURIER TRANSFORM:  $I \in L^1(\Omega)$ , i.e.  $\int_{\Omega} |I| dx < \infty$

DEFINITION

Cont:  $\mathcal{F}[I](f_x, f_y) = \iint_{-\infty+\infty}^{+\infty+\infty} I(x, y) e^{-j2\pi(f_x x + f_y y)} dx dy = \dots$   
 inverse  $\rightarrow \mathcal{F}^{-1}[I] = \iint_{-\infty+\infty}^{+\infty+\infty} e^{+j2\pi(\dots)} dx dy$

PROP:

- Spatial shift:  $\mathcal{F}[I(x+\Delta x, y)] = \mathcal{F}[I(x, y)]_{(f_x, f_y)} \cdot e^{j2\pi f_x \Delta x}$

Der: EXERCISE!

$\mathcal{F}[I(x+\Delta x, \cdot)] = \int I(x+\Delta x, y) e^{-j2\pi f_y y} dx dy = \int I(x, y) e^{-j2\pi f_y y} dx dy \cdot e^{j2\pi f_x \Delta x}$   
 $= \mathcal{F}[I(x, y)]_{(f_x, f_y)} \cdot e^{j2\pi f_x \Delta x}$

- DERIVATIVES:  $\mathcal{F}[I_x(x, y)] = (+j2\pi f_x) \mathcal{F}[I(x, y)]$  (the same y)

Der:

$\int I_x e^{-j2\pi f_y y} dx dy = - \int I e^{-j2\pi f_y y} dx dy + \int I e^{-j2\pi f_y y} dx dy$   
 (points to  $-j2\pi f_x$ )

- Linearity:  $\mathcal{F}[I_1 + \mu I_2] = \mathcal{F}[I_1] + \mu \mathcal{F}[I_2]$

- Convolution:  $\mathcal{F}[f * g] = \mathcal{F}[f] \cdot \mathcal{F}[g]$

Der:

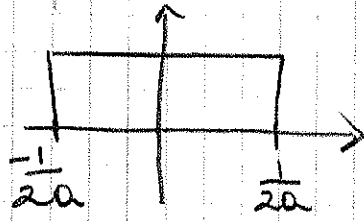
$\int \int (f(x-u) g(u)) e^{-j2\pi v x} dx = \int \int f(x-u) g(u) e^{-j2\pi v x} dx du$

CV:  $\left. \begin{matrix} v = v - u \\ u = u \end{matrix} \right\} \Rightarrow \int \int f(v) g(u) e^{-j2\pi v (v+u)} dv du = \mathcal{F}[f] \cdot \mathcal{F}[g]$

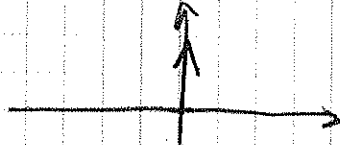
JACOBIAN  $\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \rightarrow \det(J) = 1$

Common FOURIER TRANSFORMS:

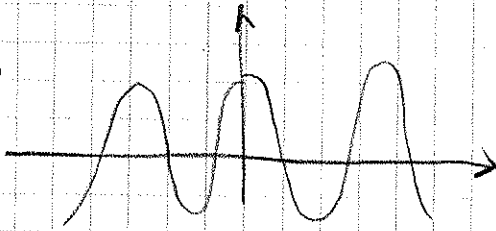
•  $\Pi(ax)$



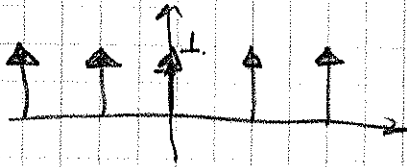
•  $\delta(x)$



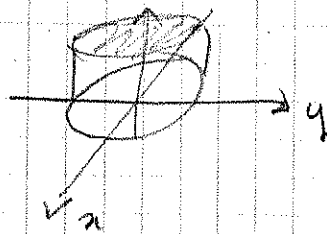
•  $\cos(2\pi vx)$



•  $\sum_{-\infty}^{+\infty} \delta(x-nT)$



•  $\text{circ}(\sqrt{x^2+y^2})$



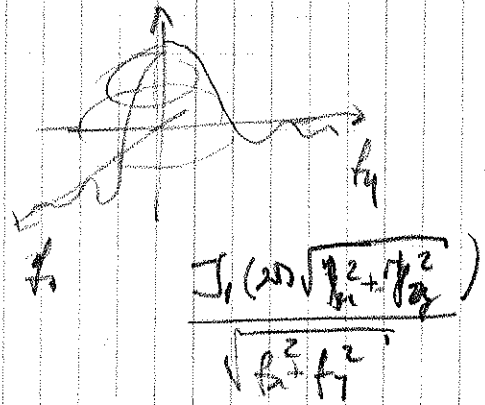
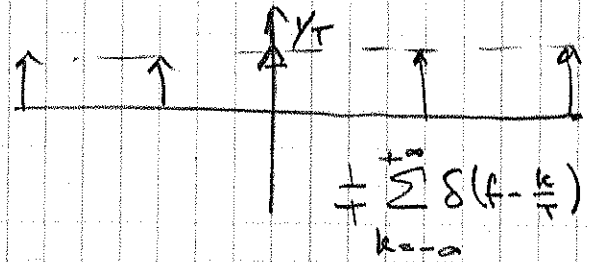
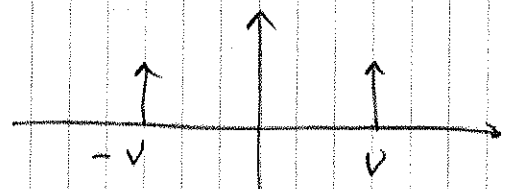
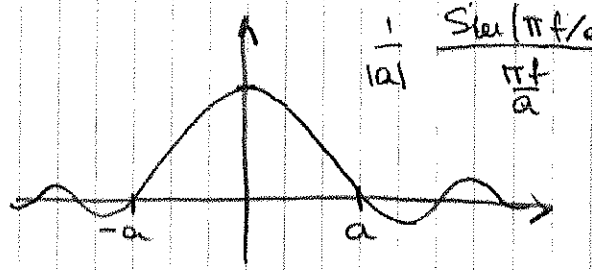
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• HANKEL TRANSFORM: MORE IN ITZUKA ENGINEERING OPTICS PAGE

$\mathcal{F}[g](k_x, k_y) = \iint g(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy$  in cylindrical coords.

$$\left. \begin{aligned} dx dy &\rightarrow r dr d\theta \\ k_x &= p \cos \phi \\ k_y &= p \sin \phi \end{aligned} \right\} \Rightarrow \mathcal{F}[g](p, \phi) = \int_{r=0}^{+\infty} \int_{\theta=0}^{+2\pi} g(r, \theta) e^{-j2\pi(r \cos \theta p \cos \phi + r \sin \theta p \sin \phi)} r dr d\theta$$

$$= \int_{r=0}^{+\infty} \int_{\theta=0}^{+2\pi} g(r, \theta) e^{-j2\pi r p \cos(\theta - \phi)} r dr d\theta$$



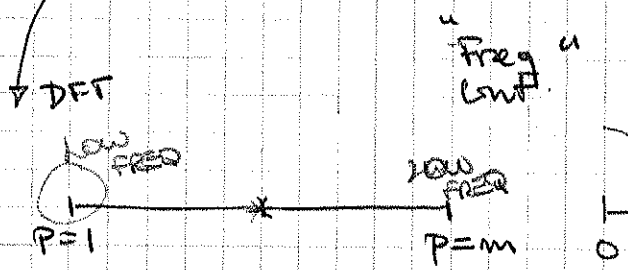
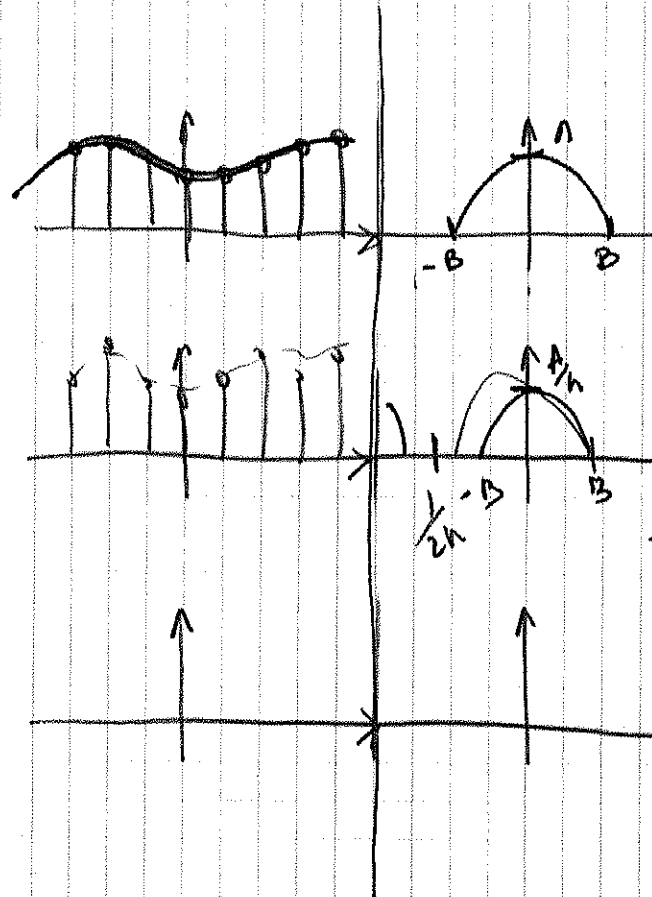
(N) Fourier in a Discrete Domain:

$$I^h = I(x) \cdot \sum_{k=-\infty}^{+\infty} \delta(x - kh)$$

$$\mathcal{F}[I^h] = \mathcal{F}[I] * \mathcal{F}[\sum_{k=-\infty}^{+\infty} \delta(t - k\frac{1}{h})]$$

DFT  $\rightarrow$  sinc de Fourier  $C_n = \frac{1}{T} \int_0^T e^{-j2\pi n x} dx$

$$\frac{1}{N} \sum_{n=0}^{N-1} I_{un} e^{j2\pi n \left( \frac{u-1}{N} + \frac{(N-1-k)}{N} \right)}$$



MAPPING

SEE: FFT2, FFTSHIFT (MATLAB)