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Finite element simulation of thermal exchanges using isoparametric models





Barcelona 41:18:07 N



Paris 49.5° N



Círculo polar 66.5 N





Polo Norte 90° N



Trópico del Cáncer 23.5° N











San Salvador 13:42:00 N



Ecuador 0°



Zone équatoriale. Une architecture qui imite les arbres





9°36'N



Purus, Pérou 9°26'S



Île de Falik 7°15'N



Ambarita, Indonésie 2°40'N



South Sulawesi, Indonésie. 4°20'S



Kasubi, Ouganda0°20'N

Zone tropicale humide. Une architecture de parapluies et de saillants contre la pluie et le soleil



Diamantina, Brésil 18°12'S



Isla Waya, Fiji 17°17'S



Bonampak, Mexique 16°42'N



Valle de Viñales, Cuba 22°37'N



Sahebganj, Inde



He

Hoi An, Vietnam 17°20'N

Lijiang, Chine 26°51'N

Zone tropicale aride. Architecture de forteresses, tentes et carapaces contre le soleil





Shibam, Yemen 15°55'N







14°20'N



Djenné, Mali 13°54'N

Jaipur, Inde 27°N

Zona tempérée chaude. Architecture d'ombres et inertie thermique



33°31'N

Zone tempérée froide. Architecture où le soleil est bienvenu, mais où la priorité est de conserver la chaleur.



Reykiavik, Islande 64°08'N

Ushuaia, Argentine 54°47'S

Massachusetts, EUA 42°14'N

Visby, Suède 56°31'N

Zone froide. Architecture contre le froid, les maîtres de l'isolation





Norilsk, Russie 69°20'N







Campement d'été chez les Inuits Igloo chez les Inuits (Groenland, Alaska et Nord du Canada) Hotel de Glace, Kiruna, Suède 67°51'N























Isoparametric element

- 1. Early background: geometric mesh
- 2. CAD background
- 3. Mathematical formulation of the Coons patch
- 4. Formulation of the integrals in parametric coordinates
- 5. Computation of Cartesian gradients in intrinsic or parametric coordinates
- 6. Gauss quadrature
- 7. Numerical integration of the conduction matrix
- 8. Examples
- 9. Extension of Coons patch to 3D hexahedrons in elasticity
- 10. Conclusion



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A particularly well accepted application of Coons patches is the so-called "lofting" technique. It consists in generating a surface by linearly evolving a profile from an initial shape (polyline in red on the left) to another shape (arc of circle, in red on the right).

This has been a very widespread technique in defining aircraft wing profiles.

Principle of generating a patch (parameters *u* and *w*).

The patch is supported on two networks of curves.

When the curves are reduced to straight lines, we get the original **Coons patch**.



Coons patch: the four sides are straight lines. In this example, starting with a quadrilateral, which is a polygon (hence a planar object), we simply added a twist to transform it into a hyperbolic paraboloid.



The representation of a Coons patch is completed very easily by drawing the network of lines based on the two pairs of opposite sides.



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Coons patch



[Q] is a matrix with 4 rows and 3 columns containing the Cartesian coordinates of the 4 points or nodes defining the patch. The blending functions of the 4 vertices are some functions equal to 1 at one of the vertices and 0 at the others:

$$\begin{bmatrix} F \end{bmatrix} = \begin{bmatrix} f_1 & f_2 & f_3 & f_4 \end{bmatrix} = \begin{bmatrix} (1-s)(1-t) & s(1-t) & st & (1-s)t \end{bmatrix}$$

The points of the patch are defined by their two parametric coordinates s and t.

$$P^{T} = [F][Q]$$

The set of functions f_i represents a barycentric combination fulfilling the partition of unity condition.

$$f_1 + f_2 + f_3 + f_4 = 1$$
More explicitly, the transpose of the point vector is a line matrix which is a function of two parameters

$$P(s,t)^{T} = \begin{bmatrix} x(s,t) & y(s,t) & z(s,t) \end{bmatrix} = \begin{bmatrix} F \end{bmatrix} Q$$

To simplify the subsequent development, we limit ourselves to **two dimensions** by modeling patches and fields in the plane. We rewrite the nodes definition in 2D:

$$\begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \\ x_3 & y_3 \\ x_4 & y_4 \end{bmatrix} = \begin{bmatrix} X & Y \end{bmatrix}$$

$$\begin{bmatrix} x(s,t) & y(s,t) \end{bmatrix} = \begin{bmatrix} F \end{bmatrix} \begin{bmatrix} Q \end{bmatrix} = \begin{bmatrix} (1-s)(1-t) & s(1-t) & st & (1-s)t \end{bmatrix} \begin{bmatrix} Q \end{bmatrix}$$

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In the following developments we show how to realize the coordinates transformations from cartesian to parametric coordinates

We first establish the relations between Cartesian and parametric coordinates.



 $\begin{aligned} x(s,t) &= [F][X] &= [(1-s)(1-t) \quad s(1-t) \quad st \quad (1-s)t][X] \\ y(s,t) &= [F][Y] &= [(1-s)(1-t) \quad s(1-t) \quad st \quad (1-s)t][Y] \end{aligned}$

[J] is the Jacobian matrix. For the bilinear element it is equal to:

$$\begin{bmatrix} J \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} = \begin{bmatrix} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} X \end{bmatrix} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} Y \end{bmatrix} \begin{bmatrix} -(1-s) & -s & s & (1-s) \end{bmatrix} \begin{bmatrix} Y \end{bmatrix}$$

We formulate how to transform an integration in Cartesian space into the equivalent one in parametric space.

For this purpose we use the Jacobian J which is the determinant of the Jacobian matrix [J].

$$\boldsymbol{J}(s,t) = \det\left(\left[\boldsymbol{J}(s,t)\right]\right) = \frac{\partial x}{\partial s}\frac{\partial y}{\partial t} - \frac{\partial x}{\partial t}\frac{\partial y}{\partial s}$$

$$\iint_{\Omega_{Coons}} dxdy = \int_0^1 \int_0^1 J(s,t) dsdt$$

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Gradient of a scalar function, for instance the temperature $\tau(s, t)$.

$$\begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix}$$

The gradients are easily computed in parametric coordinates, but we need them in Cartesian ones (the real world).

$$\begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix}$$

The inverse of the Jacobian matrix [J] has to be known everywhere in the integration domain.

The temperature field is expressed in parametric coordinates as a function of the nodal temperatures:

$$\tau = \begin{bmatrix} (1-s)(1-t) & s(1-t) & st & (1-s)t \end{bmatrix} \begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} F \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$

It is easy to compute the gradient of τ in parametric coordinates:

$$\begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial F}{\partial s} \\ \frac{\partial F}{\partial t} \end{bmatrix} \begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} -(1-t) & (1-t) & t & -t \\ -(1-s) & -s & s & (1-s) \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$

However, the conductivity matrix uses the gradient of the temperature expressed in Cartesian coordinates, So, we have to express it in terms of parametric coordinates than to the invers of the Jacobian.

$$\begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial \tau}{\partial s} \\ \frac{\partial \tau}{\partial t} \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial F}{\partial s} \\ \frac{\partial F}{\partial t} \end{bmatrix} \begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} J \end{bmatrix}^{-1} \begin{bmatrix} -(1-t) & (1-t) & t & -t \\ -(1-s) & -s & s & (1-s) \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$

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In the isoparametric elements the blending functions of the geometry: x and y are the same as that of the temperature field τ :

$$\tau(s,t) = [F][T]$$
$$x(s,t) = [F][X]$$
$$y(s,t) = [F][Y]$$

[T] = nodal temperatures,
[X] = nodal x coordinates
[Y] = nodal y coordinates

If the patch is defined in the **3D** space to represent a surface geometry, the definitions seen above have to be slightly modified:

$$\begin{bmatrix} Q \end{bmatrix} = \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \begin{bmatrix} x_1 & y_1 & z_1 \\ x_2 & \cdots & \cdots \\ x_3 & \cdots & \cdots \\ x_4 & \cdots & z_4 \end{bmatrix}$$
$$P(s,t)^T = \begin{bmatrix} x(s,t) & y(s,t) & z(s,t) \end{bmatrix} = \begin{bmatrix} F \end{bmatrix} Q$$

Jacobian matrix:

$$\begin{bmatrix} J \end{bmatrix} = \begin{bmatrix} \frac{\partial P}{\partial s} \times \frac{\partial P}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial y}{\partial s} \frac{\partial z}{\partial t} - \frac{\partial y}{\partial t} \frac{\partial z}{\partial s} & \frac{\partial z}{\partial s} \frac{\partial x}{\partial t} - \frac{\partial x}{\partial s} \frac{\partial z}{\partial t} & \frac{\partial x}{\partial s} \frac{\partial y}{\partial t} - \frac{\partial x}{\partial t} \frac{\partial y}{\partial s} \end{bmatrix}$$

Determinant of the Jacobian:

$$\det\left(\left[J\left(s,t\right)\right]\right) = \sqrt{\left(\frac{\partial y}{\partial s}\frac{\partial z}{\partial t} - \frac{\partial y}{\partial t}\frac{\partial z}{\partial s}\right)^2 + \left(\frac{\partial z}{\partial s}\frac{\partial x}{\partial t} - \frac{\partial x}{\partial s}\frac{\partial z}{\partial t}\right)^2 + \left(\frac{\partial x}{\partial s}\frac{\partial y}{\partial t} - \frac{\partial x}{\partial t}\frac{\partial y}{\partial s}\right)^2}$$

Same result as in slide 14:
$$\det\left(\left[J(s,t)\right]\right) = \frac{\partial x}{\partial s}\frac{\partial y}{\partial t} - \frac{\partial x}{\partial t}\frac{\partial y}{\partial s}$$

Integral on the patch of a function g depending of the two parameters s and t:

$$\iint_{\Omega_{Coons}} g^*(x, y) \, dxdy = \int_0^1 \int_0^1 g\left(s, t\right) J\left(s, t\right) \, dsdt$$

In particular situations it is possible to express g(s, t) in cartesian coordinates

 $g(s; t) \rightarrow g^*(x, y)$

The above integral must often be computed numerically, because its Jacobian cannot easily be calculated analytically.

Integration to perform for obtaining the conductivity matrix:

$$\iint_{\Omega_{Coons}} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix}^{T} \begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix} dxdy$$
$$\begin{bmatrix} \frac{\partial \tau}{\partial x} \\ \frac{\partial \tau}{\partial y} \end{bmatrix}^{-1} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} -(1-t) & (1-t) & t & -t \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$

Computation in parametric coordinates:

$$\int_{0}^{1} \int_{0}^{1} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix}^{-1} \begin{bmatrix} \left[-(1-t) & (1-t) & t & -t \right] \\ \left[-(1-s) & -s & s & (1-s) \end{bmatrix} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial t} & \frac{\partial y}{\partial t} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial s} \\ \frac{\partial x}{\partial s} \\ \frac{\partial x}{\partial s} \\ \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \right\}^{T} \left\{ \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial x}{\partial s} \\$$

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Numerical integration on the Coons patch

$$\iint_{Coons} f(x, y) dx dy = \sum f(x_i, y_i) w_i$$

This technique consists in evaluating the integral f(x, y) in a certain number of points. It is then sufficient to calculate the sum of its weighted values by *a priori* assigning a weight w_i to each of the evaluation points. For a parametric function, we must add the Jacobian transformation.

$$\iint_{Coons} g^*(x, y) dx dy = \int_0^1 \int_0^1 g(s, t) J(s, t) ds dt = \sum_i g(s_i, t_i) w_i J(s_i, t_i)$$

1D Gauss quadrature						
Number of points	<i>Positions</i> x_i <i>in the interval</i> [0 1]	Weight w _i				
1	0.5	1				
2	$0.5 \pm \sqrt{3} / 6$.5				
3	0.5 , $0.5 \pm \sqrt{3/20}$	4/9, 5/18, 5/18				
4	$0.5 \pm 1/70\sqrt{525 - 70\sqrt{30}}$ $0.5 \pm 1/70\sqrt{525 + 70\sqrt{30}}$	$\frac{1/4 + \sqrt{30}/72 ; 1/4 + \sqrt{30}/72}{1/4 - \sqrt{30}/72 ; 1/4 - \sqrt{30}/72}$				

Gauss quadrature on a 1m x 1m square

Evaluated function		Exact	Number of Gauss points						
		Solution	1	$4 = 2 \ge 2$	$9 = 3 \ge 3$	$16 = 4 \ge 4$			
1.	$\sin(\pi s)$	0.6366	1.0	0.6162	0.6371	0.6366			
2.	<i>s</i> ³	0.25	0.125	0.25	0.25	0.25			
3.	<i>s</i> ⁵	0.1667	0.0313	0.1528	0.1667	0.1667			
4.	<i>s</i> ⁷	0.1250	0.0078	0.0949	0.1238	0.1250			

The above results confirm that n integration points are necessary to obtain an exact solution for polynomials of degree (2n-1).

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Numerical quadrature of the conductivity matrix Matlab[©] function *Kelu.m* for the Gauss quadrature.

(the Matlab[©] instructions reproduce the formula that have just been presented.)

Matlab[©] function *Kelu.m* for isoparamatric evaluation of the conductivity matrix

```
function [K] = Kelu(xyz, lo)
 1
 2
   Q = [xyz(lo(1), 1:3); xyz(lo(2), 1:3); xyz(lo(3), 1:3); xyz(lo(4), 1:3)];
 3
   s = [.5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6 .5-sqrt(3)/6]; % 4 Gauss pts
   t = [.5-sqrt(3)/6 .5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6]; % 4 Gauss pts
 4
 5
   K = zeros(4, 4); area=0.;
 6
   for i=1:4
                                                % Loop on the 4 Gauss points
       fs = [-(1-t(i)) (1-t(i)) t(i) -t(i) ];
                                                             % Derivative s
 7
 8
       ft = [-(1-s(i)) - s(i) s(i) (1-s(i))]; % Derivative t
 9
                      % Gradient of the scalar bilinear function
       gra = [fs;ft];
       ds = fs * O;
10
11
       dt = ft * O;
12
       area = area + sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
13
            = [fs*Q(:,1) ft*Q(:,1); fs*Q(:,2) ft*Q(:,2)];
       J
       K=K+((J^(-1)*gra)'*J^(-1)*gra)*sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
14
15
                                     % disp(['Patch area : ',num2str(area)])
   end
16
   end
```

This Matlab function allows computing the conductivity matrix of an isoparametric quadrilateral with a bilinear temperature field. To obtain the conductivity matrix, this result has to be multiplied by the conductivity coefficient and the thickness. Matlab[©] function *Kelu.m* for isoparamatric evaluation of the conductivity matrix

1	<pre>function [K] = Kelu(xyz,lo)</pre>
2	Q = [xyz(lo(1), 1:3); xyz(lo(2), 1:3); xyz(lo(3), 1:3); xyz(lo(4), 1:3)];
3	s = [.5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6 .5-sqrt(3)/6]; % 4 Gauss pts
4	t = [.5-sqrt(3)/6 .5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6]; % 4 Gauss pts
5	<pre>K = zeros(4,4);area=0.;</pre>
6	for i=1:4 % Loop on the 4 Gauss points
7	fs = [-(1-t(i)) (1-t(i)) t(i) -t(i)]; % Derivative s
8	ft = $[-(1-s(i)) - s(i) s(i) (1-s(i))];$ % Derivative t
9	<pre>gra = [fs;ft]; % Gradient of the scalar bilinear function</pre>
10	ds = fs \star Q;
11	dt = ft * Q;
12	<pre>area = area + sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;</pre>
13	J = [fs*Q(:,1) ft*Q(:,1); fs*Q(:,2) ft*Q(:,2)];
14	K=K+((J^(-1)*gra)'*J^(-1)*gra)*sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
15	end % disp(['Patch area : ',num2str(area)])
16	end

Line 2 : Definition of the 4 vertices of the patch: the coordinates are stored in the xyz matrix of nodal coordinates and the vector *lo* is a pointer of positions in the xyz matrix. For instance, it is possible to define both in Matlab[©] notations:

xyz = [0 0 0;1 0 0;1 1 0;0 1 0];lo=[1 2 3 4];

Lines 3 & 4 : Define the sequence of positions of Gauss points in a unit square according to the table of 1D Gauss quadrature (slide 24)

Line 5

: Initialization of the conductivity matrix.

Lines 7 to 15 : Loop on the 2 x 2 = 4 Gauss points. The weights $w_i = 1/4$

Matlab[©] function *Kelu.m* for isoparamatric evaluation of the conductivity matrix

```
function [K] = Kelu(xyz, lo)
 1
 2
      = [xyz(lo(1), 1:3); xyz(lo(2), 1:3); xyz(lo(3), 1:3); xyz(lo(4), 1:3)];
   Q
 3
   s = [.5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6 .5-sqrt(3)/6]; % 4 Gauss pts
   t = [.5-sqrt(3)/6 .5-sqrt(3)/6 .5+sqrt(3)/6 .5+sqrt(3)/6]; % 4 Gauss pts
 4
 5
   K = zeros(4, 4); area=0.;
 6
   for i=1:4
                                               % Loop on the 4 Gauss points
                                                % Derivative s
 7
       fs = [-(1-t(i)) (1-t(i)) t(i) -t(i)];
 8
       ft = [-(1-s(i)) - s(i) s(i) (1-s(i))]; % Derivative t
 9
       gra = [fs; ft];
                      % Gradient of the scalar bilinear function
10
       ds = fs * Q;
11
       dt = ft * O;
12
       area = area + sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
13
       J
            = [fs*Q(:,1) ft*Q(:,1);fs*Q(:,2) ft*Q(:,2)];
       K=K+((J^(-1)*gra)'*J^(-1)*gra)*sqrt(dot(cross(ds,dt),cross(ds,dt)))/4;
14
15
                                     % disp(['Patch area : ',num2str(area)])
   end
16
   end
```

: Computation of the derivatives of the blending functions
: Define the gradient in parametric coordinates
: Compute the volume differentials in parametric coordinates
: Determinant of the Jacobian which will enable to compute
es 14 or 19)
: Jacobian matrix (slides 14 or 19)
: Compute the conductivity matrix (slide 21) 55

The following tests corroborate the previous analytical results.

-7. -5. 2.

Unit square xyz = [0 0 0;1 0 0;1 1 0;0 1 0];lo=[1 2 3 4];[K]=Kelu(xyz,lo)*6 Patch area : 1, K =4 -1 -2 -1 4 -1 -2 -1 -2 -1 4 -1 -1 -2 -1 4 Other size xyz = [0 0 0;4 0 0;4 4 0;0 4 0];lo=[1 2 3 4];[K]=Kelu(xyz,lo)*6 Patch area : 16, K = -1 -2 -1 4 4 -1 -2 -1 -2 -1 4 -1 -1 -2 -1. 4 Other xyz = [1 0 0;0 1 0;-1 0 0;0 -1 0];lo=[1 2 3 4];[K]=Kelu(xyz,lo)*6 Patch area : 2, K =orientation 4 -1 -2 -1 -1 4 -1 -2 -2 -1 4 -1 -1 -2 -1 4 xyz = [0 0 0;2 0 0;2 1 0;0 1 0];lo=[1 2 3 4];[K]=Kelu(xyz,lo)*6 Rectangle Patch area : 2, K =10. 2. -5. -7. 2. 10. -7. -5. -5. -7. 10. 2.

10.

56

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conde.m conductivity: 1 W/(mK)									
Coord	dinates	P1,	P2	:	0	0	1	0	m
Coord	dinates	Ρ3 ,	P4	:	1	2	0	2	m
Base	tempera	ature		:	27	0 K			
Тор	tempera	ature		:	32	0 K			
Mesh	size			:	30	Х	60		
Fix.	nod. 2	hor.	fa.	:	30				
Diss	tcaT*(F	(*tca)	/2	:	50	0 W	K		



In the following example, temperatures are imposed on one segment of the upper face and on another of the lower base.

In this case 320 K on the upper face and 270 K on the base. The mesh is 30 x 60. The number of *DOF* is equal to 1891.

As expected, the isotherms are orthogonal to the walls, except in the two zones where the temperatures are imposed. In this example, the temperatures were imposed on 15 nodes of the upper and lower faces. The fluxes on both horizontal faces are ± 20 . W; they are highly concentrated on the corners.





-5 0

10

20

30

40

Decreasing significantly (coefficient 4) the number of elements in the y direction yields to aspect ratios of four for the elements but does not influence so much the solution.

> m m

conde	e.m cond	uctiv	rity	:	1	W/(mK)	
Coord	linates	P1,	P2	:	0	0	1	0
Coord	linates	Ρ3 ,	P4	:	1	2	0	2
Base	tempera	ture		:	27	0 <mark>K</mark>		
Тор	tempera	ture		:	32	0 K		
Mesh	size			:	30	Х	15	
Fix.	nod. 2 1	hor.	fa.	:	30			
Diss	tcaT*(K	*tca)	/2	:	50	6 W	K	



Bottom flow: -20.2 W, top flow: 20.2 W -3

50

60

70

80

90

100

With the same procedure, we can easily handle other shapes and change their orientation. As expected, the orientation does not influence the result.

conde.m conductivity: 1 W/(mK) Coordinates P1, P2 : 0 0 2 0 m Coordinates P3, P4 : 2 2 0 2 m Base temperature : 270 K Top temperature : 320 K Mesh size : 30 x 30 Fix. nod. 2 hor. fa.: 30 Diss tcaT*(K*tca)/2 : 817 WK



conde.m conductivity: 1 W/ (mK)Coordinates P1, P2 : 0 -1 1 0 mCoordinates P3, P4 : 0 1 -1 0 mBase temperature : 270 K Top temperature : 320 K Mesh size : 30×30 Fix. nod. 2 hor. fa.: 30Diss tcaT*(K*tca)/2 : 817 WK









Here we consider the drawing of the heat flows shown by one arrow in each element. The arrows are oriented in the opposite direction of the gradient and their length is proportional to the intensity of the gradient (Matlab[©] function: *Hflos.m*). $_{62}$



Now, the mesh is very fine, the dissipation energy seems to converge to the value of 490 WK, the total flows on the top and bottom sides tends to 19.6 W and the mean temperature gradient is equal to 9.9 Km^{-1} .



The objective of this example is to show that the results are not sensitive to the orientation of the domain. The areas of both domains being the same, we obtain exactly the same results



Visualization of a scalar field with isocurves showing the levels

Visualization of a vector field with one arrow in each element

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Finite element model from Aérospatiale -Eurocopter Marignane

The model is mainly composed of hexahedrons.

With these models the mesh perfectly respects the symmetries of the geometric model, which is very difficult to obtain with triangles or tetrahedrons.

Helicopter model from Eurocopter manufacturer.

The quadrilaterals of the outer surface are not planar.

The model is mainly composed of hexahedrons







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For the Coons patches and the similar elements, the basic feature is the integration (or quadrature). It is using the Jacobian of the transformation allowing to pass from parametric coordinates to Cartesian coordinates or *vice versa*.

The price to pay for using high degree elements and therefore curved edges is twofold

1. it is necessary to go through a numerical integration of the quantities to be evaluated on the domain of the element.

2. It is necessary to use a parametric formulation for the control of the geometry.
Higher degree elements: bi-cubic Béziers patch including the drawing of the interior lines network s = constant and t = constant. This patch is based on 16 nodes.

