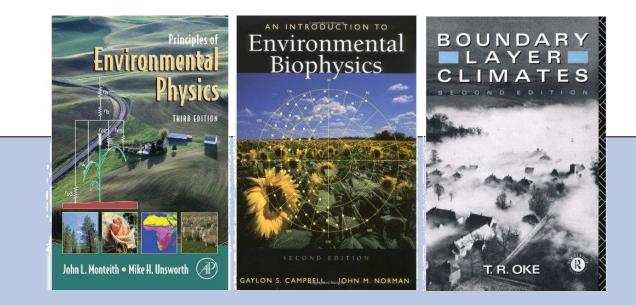
## **Benoit Beckers**

Architecture et Physique Urbaine - ISA BTP Université de Pau et des Pays de l'Adour Allée du Parc Montaury, 64600 Anglet (France) benoit.beckers@univ-pau.fr, www.heliodon.net

## **Finite element Simulation of convective heat transfers**

## **Urban Physics - references**

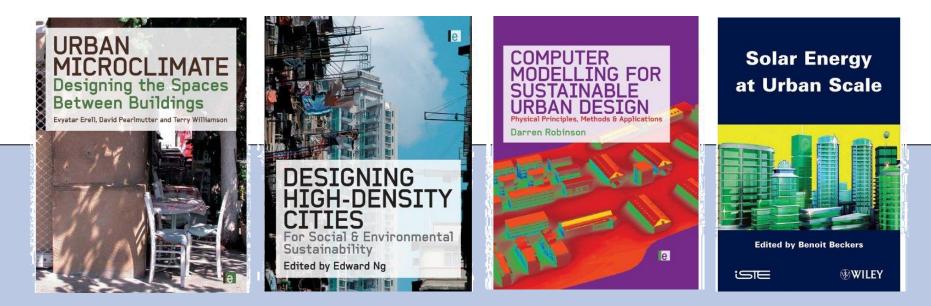
Environmental Physics developed in the 1970s (crop yield), 1980 (forest and acid rain), 1990 (hole in the ozone layer), 2000 (climate change). Among its methods: the local balance of energy flows (conductive, radiative, sensible and latent).



The application of the same methods to urban structures was proposed in the 1970s by T. R. Oke, around the issue of urban heat island. We can therefore speak of Urban Physics.

## **Urban Physics - references**

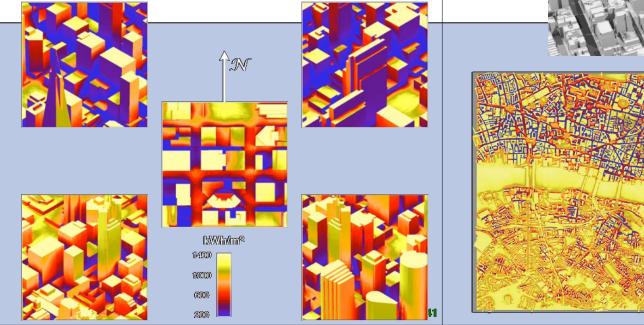
In recent years, considerable progress has been made in several ancillary areas: geographic information systems, standardization of the level of detail of 3D models, terrestrial and satellite measurements, computing power of computers...

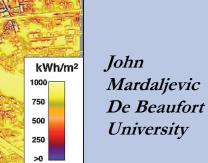


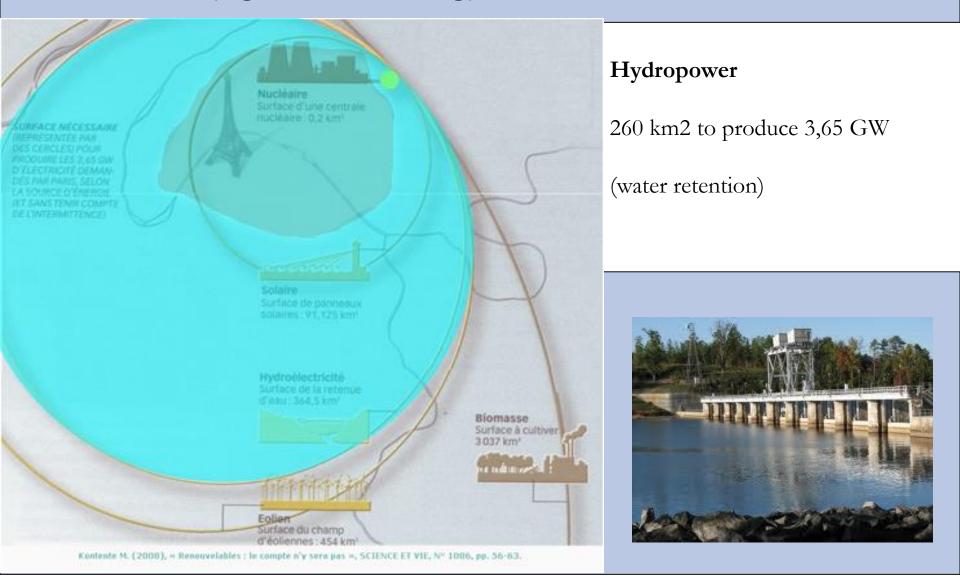
... Allowing for a first apprehension of urban physics by numerical simulation. Framework: "smart", "safe" and "sustainable" city. Emergence of urban thermal (urban climate, building-city-territory heat flux, energy efficiency, local production of renewable energy).

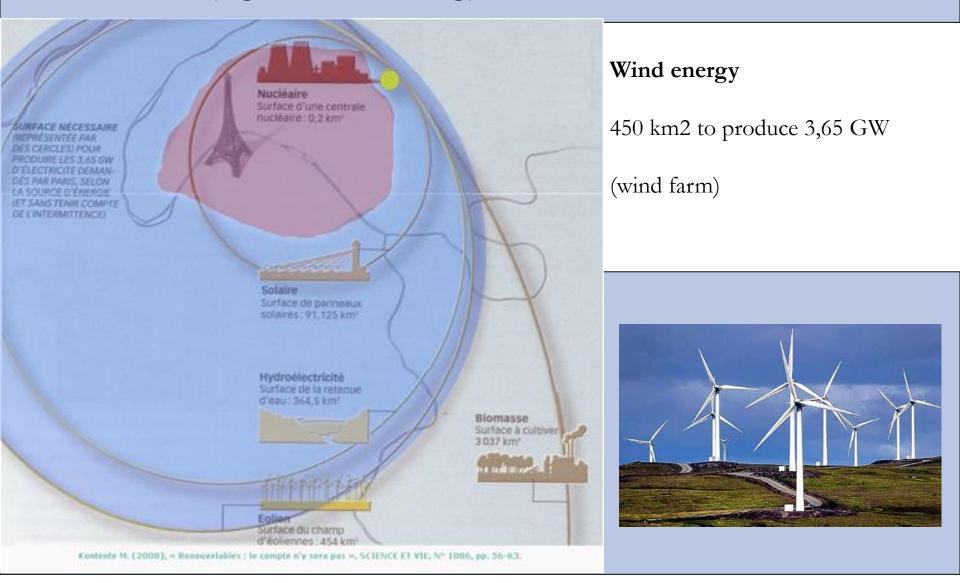
#### SOLAR ENERGY AT URBAN SCALE

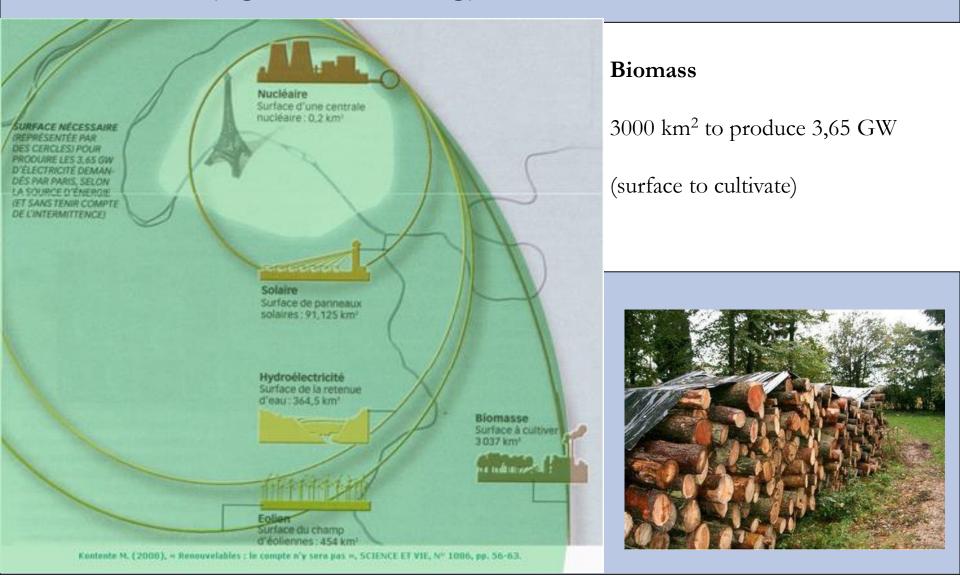
- SOLAR ENERGY AT URBAN SCALE
- 24 /25 may 2010, Compiègne
- www.utc.fr/seus

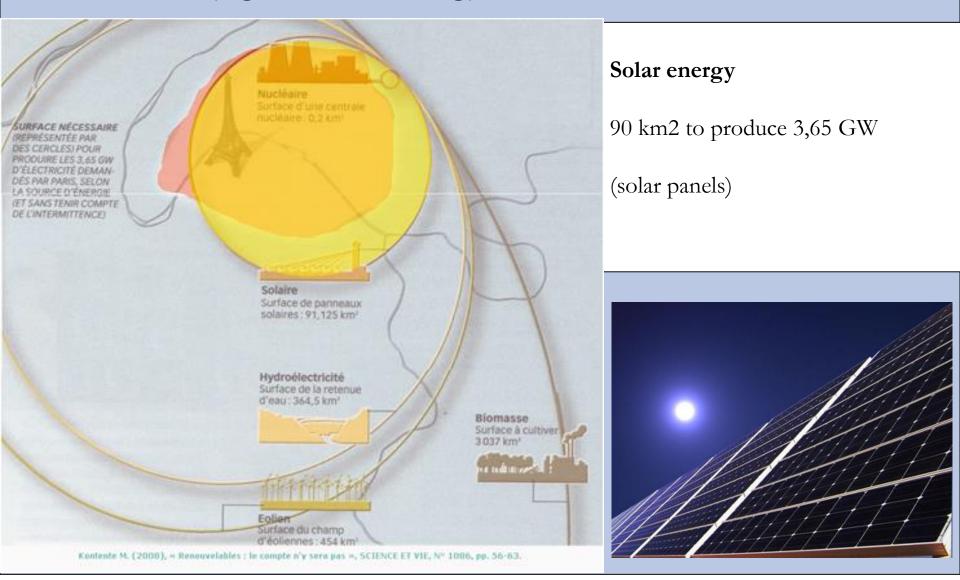








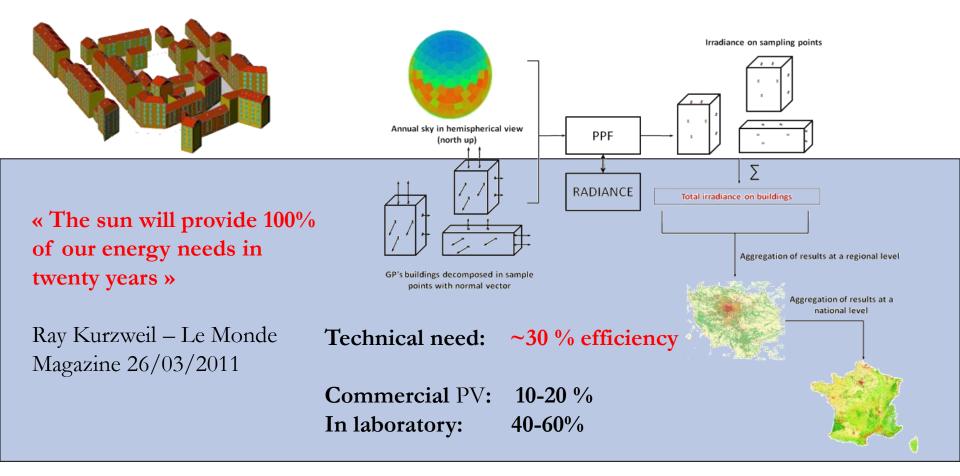




AVENUES

#### **General** issues

#### PhD (2012) : Elie Ghanassia (EDF, dir.: M. Maïzia & B. Beckers)



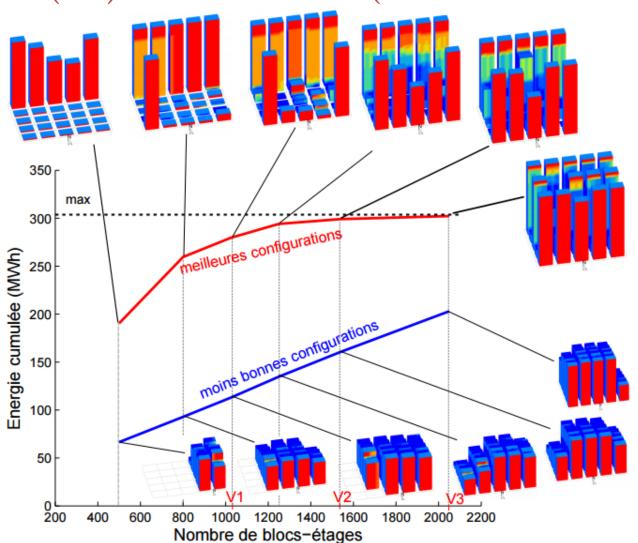


FIGURE 1.10: Evolution de la fonction-objectif avec la densité (21 décembre, 50°N, ciel clair, Liu & Jordan)

#### PhD (2014) : Thibaut Vermeulen (dir.: B. Beckers & P. Villon )

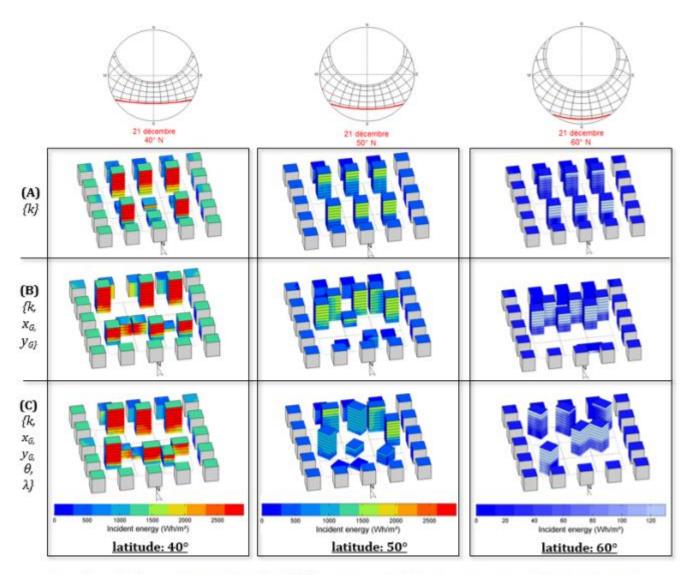


FIGURE 1.17: Formes optimales pour différents ensembles de paramètres et différentes latitudes (21 décembre, ciel clair, Liu & Jordan)

## **Convective heat transfers**

- 1. Partial differential equations
- 2. Variational methods
- 3. Finite element method (local level)
- 4. Finite element method (global level)
- 5. Examples
- 6. Prescribed heat flows
- 7. Matlab<sup>©</sup> procedures

We want to compute the temperature distribution in a domain  $\Omega$ , subjected to boundary conditions on the temperature and/or the heat flow and convection conditions, namely thermal exchanges with a fluid in which the domain. is fully or partially incorporated The following system of partial differential equations must be solved as well as the boundary conditions associated with it:

$$\vec{\tau} = \vec{\tau} \quad on \quad S_{1}$$
  
$$\vec{n} \cdot \vec{q} = \vec{q}_{n} \quad on \quad S_{2}$$
  
$$\vec{n} \cdot \vec{q} = \vec{q}_{n} \quad on \quad S_{2}$$
  
In these equations,  $\tau$  is the unknown temperature  
field expressed in  $K$ ,  $k$ , the thermal conductivity  
 $(Wm^{-1}K^{-1})$  and  $h$ , the convection coefficient  
 $(Wm^{-2}K^{-1})$ .  
The boundary of the domain is divided into 3  
parts:  $S_{1}$  where the temperature is imposed,  $S_{2}$   
where the normal heat flow is imposed and  $S_{3}$ ,

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where the convective flow is imposed. A bar indicates that the concerned quantity is imposed.

## **Convective heat transfers**

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In the presence of convective boundary conditions, the solution of the system of partial differential equations is equivalent to the search for the minimum of the past functional in which the convection term, which depends on the coefficient h, has been added:

$$< I(\tau) = \int_{\Omega} \frac{1}{2} k \ (grad\tau)^{T} \ grad\tau \ d\Omega + \frac{1}{2} \int_{S_{3}} h(\tau - \tau_{f})^{2} \ dS + \int_{S_{2}} \overline{q}_{n} \ \tau dS > minimum$$

To express the stationnarity condition, it is sufficient to write that under the boundary conditions: - c

$$\tau = \overline{\tau}, \ \delta \tau = 0 \ on \ S_1$$

the difference between the functional calculated with a small arbitrary variation  $\delta \tau$  of the temperature  $\tau$  and the present functional is equal to zero.

Explicitly:  $I(\tau + \delta \tau) - I(\tau) = 0$ 

$$\int_{\Omega} \frac{1}{2} k \left( \operatorname{grad}(\tau + \delta \tau) \right)^{T} \cdot \operatorname{grad}(\tau + \delta \tau) d\Omega - \int_{\Omega} \frac{1}{2} k \left( \operatorname{grad}\tau \right)^{T} \cdot \operatorname{grad}\tau d\Omega$$
$$+ \frac{1}{2} \int_{S_{3}} h \left( \tau + \delta \tau - \tau_{f} \right)^{2} dS - \frac{1}{2} \int_{S_{3}} h \left( \tau - \tau_{f} \right)^{2} dS$$
$$+ \int_{S_{2}} \overline{q}_{n} (\tau + \delta \tau) dS - \int_{S_{2}} \overline{q}_{n} \tau dS = 0$$

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By developing this expression, we obtain:

$$\int_{\Omega} \left(\frac{1}{2}k \ grad(\tau)^{T} \cdot grad\tau + \frac{1}{2}k \ (grad(\delta\tau))^{T} \cdot grad(\delta\tau)\right) d\Omega + \int_{\Omega} \frac{1}{2}2 \ k \ (grad(\tau))^{T} \cdot grad(\delta\tau) \ d\Omega - \int_{\Omega} \frac{1}{2}k \ (grad\tau)^{T} \cdot grad\tau \ d\Omega + \frac{1}{2}\int_{S_{3}} h(\tau - \tau_{f})^{2} \ dS - \frac{1}{2}\int_{S_{3}} h(\tau - \tau_{f})^{2} \ dS + \frac{1}{2}\int_{S_{3}} \left(h(\delta\tau)^{2} + 2h(\tau - \tau_{f})\delta\tau\right) dS + \int_{S_{2}} \overline{q}_{n}(\tau + \delta\tau) dS - \int_{S_{2}} \overline{q}_{n}\tau dS = 0$$

The terms in blue are counterbalanced, the second term of the first line (in red) can be ignored because it is second order. So:

$$\int_{\Omega} k \ grad(\tau)^{T} \cdot grad(\delta\tau) \ d\Omega + \int_{S_{2}} \overline{q}_{n} \ \delta\tau \ dS + \int_{S_{3}} h(\tau - \tau_{f}) \delta\tau dS = 0$$

To exploit this result, it is necessary to put the term of variation  $\delta \tau$  in evidence. We thus carry out an integration by parts of the first term of the previous expression

$$-\int_{\Omega} \operatorname{div}\left(k \ grad(\tau)\right) \ \delta\tau \ d\Omega - \int_{S_1 + S_2 + S_3} q_n \ \delta\tau \ dS + \int_{S_2} \overline{q}_n \ \delta\tau \ dS + \int_{S_3} h\left(\tau - \tau_f\right) \delta\tau dS = 0$$

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Since the variation  $\delta \tau$  is zero on the boundary  $S_1$ , the expression is reduced to:

$$\left(-\int_{\Omega} \operatorname{div}\left(k \ \operatorname{grad}(\tau)\right) \ d\Omega + \int_{S_2} \left(\overline{q}_n - q_n\right) \ dS + \int_{S_3} \left(h\left(\tau - \tau_f\right) - q_n\right) dS\right) \ \delta\tau = 0$$

Because the variation is arbitrary, the factor must be zero, which makes it possible to write the equations that the thermal field must satisfy.

div 
$$(k \ grad(\tau)) = 0$$
 in  $\Omega$   
 $\vec{n} \cdot (k \ grad\tau) = \overline{q}_n$  on  $S_2$   
 $\vec{n} \cdot (k \ grad\tau) = h(\tau - \tau_f)$  on  $S_3$ 

In conclusion, we can replace the computation of the partial differential equations of the heat transfer problem by the expression of the stationnarity conditions of the functional:

$$< I(\tau) = \int_{\Omega} \frac{1}{2} k \ (grad\tau)^{T} \ grad\tau \ d\Omega + \frac{1}{2} \int_{S_{3}} h(\tau - \tau_{f})^{2} dS + \int_{S_{2}} \overline{q}_{n} \ \tau dS > minimum$$

## **Convective heat transfers**

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The Rayleigh Ritz procedure is the same as in the conduction problem, so we can directly examine how to compute the conductivity matrices of the convective elements

Functional at  
element level: 
$$I_{el} = \frac{1}{2} \int_{S_3} h(\tau - \tau_f)^2 dS$$

In this expression, *h* represents the convection coefficient. The fluid temperature  $\tau_f$  is assumed to be uniform. We consider an element side which is a line segment of length *L* and thickness *e* so that  $dS = e \, dx$  with *x* varying between 0 and *L*. We discretize the temperature as follows:

$$\tau = T_0 \left(1 - \frac{x}{L}\right) + T_1 \frac{x}{L}$$

In matrix formalism, with  $T_0$  et  $T_1$  the nodal temperatures and [T], the vector of nodal temperatures, we have:

$$T^{T} = \begin{bmatrix} T_{0} & T_{1} \end{bmatrix} \qquad \tau = \begin{bmatrix} 1 - \frac{x}{L} & \frac{x}{L} \end{bmatrix} \begin{bmatrix} T \end{bmatrix}$$

Replacing in the functional, we obtain:

$$I_{el} = \frac{1}{2} \int_{0}^{L} he\left(\left[1 - \frac{x}{L} \quad \frac{x}{L}\right] [T] - \tau_{f}\right)^{2} dx$$
$$= \frac{1}{2} he \int_{0}^{L} \left\{\left[T\right]^{T} \begin{bmatrix} 1 - \frac{x}{L} \\ \frac{x}{L} \end{bmatrix} \begin{bmatrix} 1 - \frac{x}{L} \quad \frac{x}{L} \end{bmatrix} [T] - 2\left[1 - \frac{x}{L} \quad \frac{x}{L}\right] [T] \tau_{f} + \tau_{f}^{2} \right\} dx$$

With a new definition of the nodal temperatures vector including the fluid temperature, we obtain with the notation  $\tau_f = T_f$  where we assimilate the fluid temperature to this of a virtual node:

$$T_{e} = \begin{bmatrix} T_{0} & T_{1} & T_{f} \end{bmatrix}^{T} \qquad \qquad \frac{1}{2}heT_{e}^{T} \left(\int_{0}^{L} \begin{bmatrix} 1-\frac{x}{L} \\ \frac{x}{L} \\ -1 \end{bmatrix} \begin{bmatrix} 1-\frac{x}{L} & \frac{x}{L} & -1 \end{bmatrix} dx \right) T_{e}$$

$$20$$

$$\frac{1}{2}heT_e^T \int_0^L \left[ \begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix}^2 & \begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix} \frac{x}{L} & -\begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix} \\ \begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix} \frac{x}{L} & \begin{pmatrix} \frac{x}{L} \end{pmatrix}^2 & -\frac{x}{L} \\ -\begin{pmatrix} 1 - \frac{x}{L} \end{pmatrix} & -\frac{x}{L} & 1 \\ \end{pmatrix} dx T_e$$

After integrating, we transform the functional into:

$$I_{el} = \frac{1}{12} h \ eL \ T_{e}^{T} \begin{bmatrix} 2 & 1 & -3 \\ 1 & 2 & -3 \\ -3 & -3 & 6 \end{bmatrix} T_{e}$$

From this expression, we deduce the conductivity matrix for convection. It is so called because it has dimensions  $WK^{-1}$ 

$$K_{h} = h \frac{eL}{6} \begin{bmatrix} 2 & 1 & -3 \\ 1 & 2 & -3 \\ -3 & -3 & 6 \end{bmatrix}$$

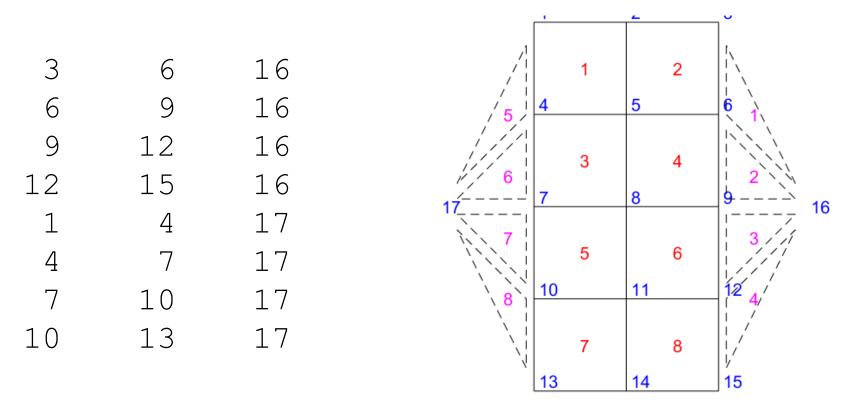
As well as the pure conduction matrix, this one also is singular. It means that with or without convection it is necessary to fix at least one node. 21

## **Convective heat transfers**

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#### Assembling the convection matrices into the global conduction matrix

This function performs the computation of the localization matrix of the convective elements on the sides of the domain (shown in blue). The process starts with the right side, then, the left side and finally the top side. The computation is performed only, it the number of the virtual node is given in the array *ntv* (third argument of the procedure)



To solve a problem including conduction and convection, we have to compute two conductivity matrices. We call the first one  $K_k$  and the second one  $K_h$ .

Later, both matrices have to be added together.

The second one involves extra degrees of freedom corresponding to the virtual convective nodes.

$$K = K_k + K_h$$

The convective nodes may be free or fixed, but the full set of nodal temperatures has to contain at least one fixed node.

### The pure conduction matrix introduced in the Matlab<sup>©</sup> procedure $pp\_Conduction.m$ K\*6/(e\*co(1)) = [

4	-1	0	-1	-2	0	0	0	0	0	0	0	0	0	0
-1	8	-1	-2	-2	-2	0	0	0	0	0	0	0	0	0
0	-1	4	0	-2	-1	0	0	0	0	0	0	0	0	0
-1	-2	0	8	-2	0	-1	-2	0	0	0	0	0	0	0
-2	-2	-2	-2	16	-2	-2	-2	-2	0	0	0	0	0	0
0	-2	-1	0	-2	8	0	-2	-1	0	0	0	0	0	0
0	0	0	-1	-2	0	8	-2	0	-1	-2	0	0	0	0
0	0	0	-2	-2	-2	-2	16	-2	-2	-2	-2	0	0	0
0	0	0	0	-2	-1	0	-2	8	0	-2	-1	0	0	0
0	0	0	0	0	0	-1	-2	0	8	-2	0	-1	-2	0
0	0	0	0	0	0	-2	-2	-2	-2	16	-2	-2	-2	-2
0	0	0	0	0	0	0	-2	-1	0	-2	8	0	-2	-1
0	0	0	0	0	0	0	0	0	-1	-2	0	4	-1	0
0	0	0	0	0	0	0	0	0	-2	-2	-2	-1	8	-1
0	0	0	0	0	0	0	0	0	0	-2	-1	0	-1	4

 $K_k$  is a 15 x 15 matrix

]

The new conduction matrix computed in the Matlab<sup>©</sup> procedure <u>pp\_Convection.m</u>. This matrix includes two additional virtual nodes to take into account the convection on the two vertical sides.

#### K\*6/(e\*co(1)) = [

6	-1	0	0	-2	0	0	0	0	0	0	0	0	0	0	0	-3
-1	8	-1	-2	-2	-2	0	0	0	0	0	0	0	0	0	0	0
0	-1	6	0	-2	0	0	0	0	0	0	0	0	0	0	-3	0
0	-2	0	12	-2	0	0	-2	0	0	0	0	0	0	0	0	-6
-2	-2	-2	-2	16	-2	-2	-2	-2	0	0	0	0	0	0	0	0
0	-2	0	0	-2	12	0	-2	0	0	0	0	0	0	0	-6	0
0	0	0	0	-2	0	12	-2	0	0	-2	0	0	0	0	0	-6
0	0	0	-2	-2	-2	-2	16	-2	-2	-2	-2	0	0	0	0	0
0	0	0	0	-2	0	0	-2	12	0	-2	0	0	0	0	-6	0
0	0	0	0	0	0	0	-2	0	12	-2	0	0	-2	0	0	-6
0	0	0	0	0	0	-2	-2	-2	-2	16	-2	-2	-2	-2	0	0
0	0	0	0	0	0	0	-2	0	0	-2	12	0	-2	0	-6	0
0	0	0	0	0	0	0	0	0	0	-2	0	6	-1	0	0	-3
0	0	0	0	0	0	0	0	0	-2	-2	-2	-1	8	-1	0	0
0	0	0	0	0	0	0	0	0	0	-2	0	0	-1	6	-3	0
0	0	-3	0	0	-6	0	0	-6	0	0	-6	0	0	-3	24	0
-3	0	0	-6	0	0	-6	0	0	-6	0	0	-3	0	0	0	24

## K is a 17 x 17 matrix

Band matrices methods are less efficient but they are replaced by the frontal methods 26

The convection matrix computed in the Matlab<sup>©</sup> procedure  $pp\_Convection.m$ . This matrix includes two additional virtual nodes to take into account the convection on the two vertical sides. The conduction terms are removed from this global matrix.

K*6/	(e*c	co(1	)) =	= [												
2	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	-3
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	2	0	0	1	0	0	0	0	0	0	0	0	0	-3	0
1	0	0	4	0	0	1	0	0	0	0	0	0	0	0	0	-6
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	1	0	0	4	0	0	1	0	0	0	0	0	0	-6	0
0	0	0	1	0	0	4	0	0	1	0	0	0	0	0	0	-6
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	1	0	0	4	0	0	1	0	0	0	-6	0
0	0	0	0	0	0	1	0	0	4	0	0	1	0	0	0	-6
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	1	0	0	4	0	0	1	-6	0
0	0	0	0	0	0	0	0	0	1	0	0	2	0	0	0	-3
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	1	0	0	2	-3	0
0	0	-3	0	0	-6	0	0	-6	0	0	-6	0	0	-3	24	0
-3	0	0	-6	0	0	-6	0	0	-6	0	0	-3	0	0	0	24

 $K_h$  is a 17 x 17 matrix

## **Convective heat transfers**

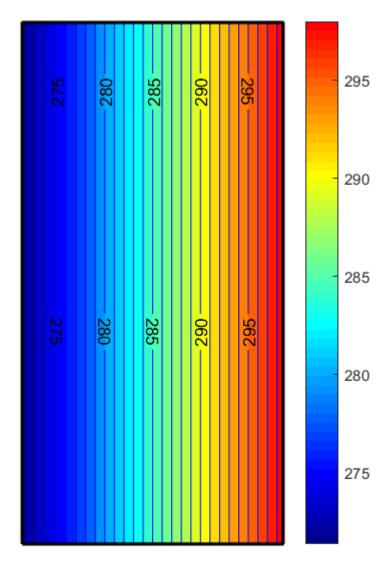
- 1. Partial differential equations
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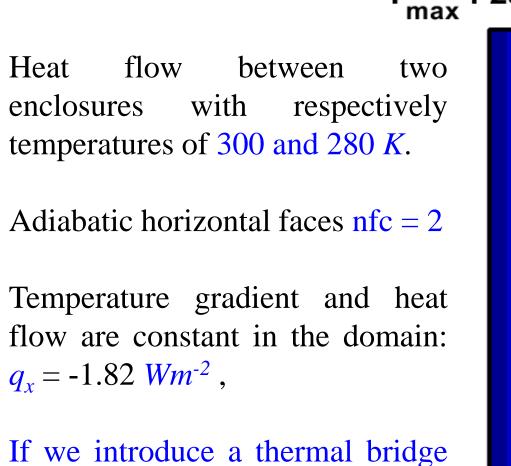
This example is related to a domain with only convective boundaries. To get a non trivial solution, we have to fix at least 2 nodes with different temperatures in order to generate a temperature gradient. Here we chose to fix the 2 virtual ones related to the vertical sides (300 & 270 K).

#### pp\_Convection

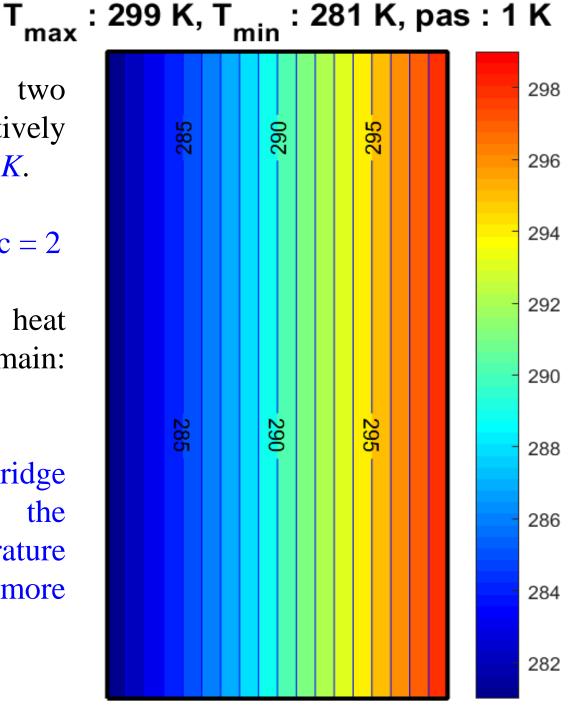
Thermal conductiv. :	1 Wm-1K-1
CoKr.m conv. coeff. :	20 Wm-2K-1
Domain dim. w, y, t :	1 2 0.1 m
Biot number h w / k :	20
Delta T in the solid:	27.2727 K
Heat flows balance :	5.4545 -5.4545 W
Virt. nodes temp. :	300 270 270 K
Checking heat flows :	-2.73 -2.73 -2.73 Wm-2
Checking temper. :	<b>271.4</b> 271.4 <b>298.6</b> 298.6 K
Temp. virt. nodes :	<b>300 270</b> K

Multiplying the global conductive matrix by the temperatures gives the second member of the system of equations. Here, we obtain everywhere 0. except for the virtual nodes. Their flow are equal to 5.4545 & -5.4545 W. As the exact solution is a linear field, these values do not depend on the mesh, but only on the relative values of the convective and conductive coefficients : Biot number  $\beta = h w / k$ .

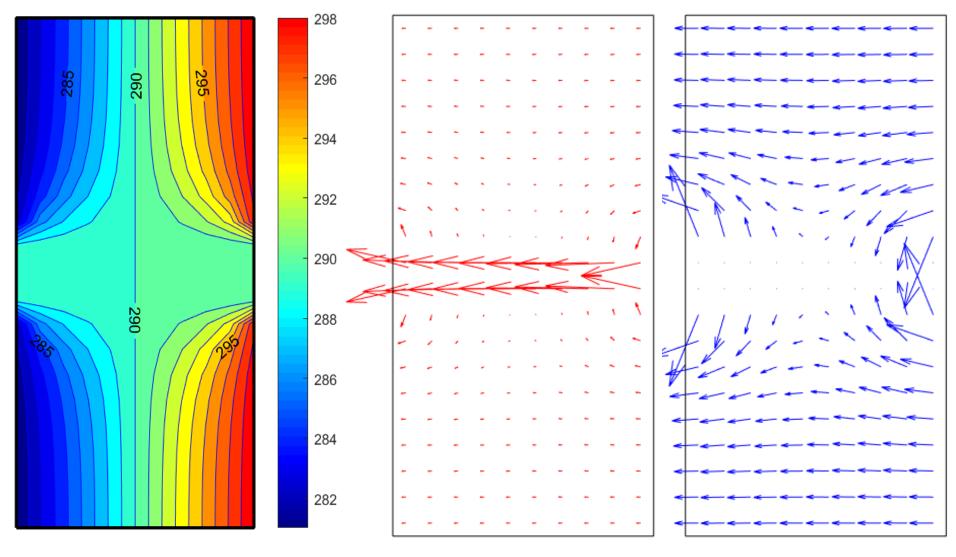




If we introduce a thermal bridge like in the following slide, the visualizations of temperature gradients & heat flows are more effective than isotherms.



Same problem, with horizontal thermal bridge (0.1 height around the horizontal median, with *k ratio* = 1000,  $h = 18 Wm^{-2}K^{-1}$ )

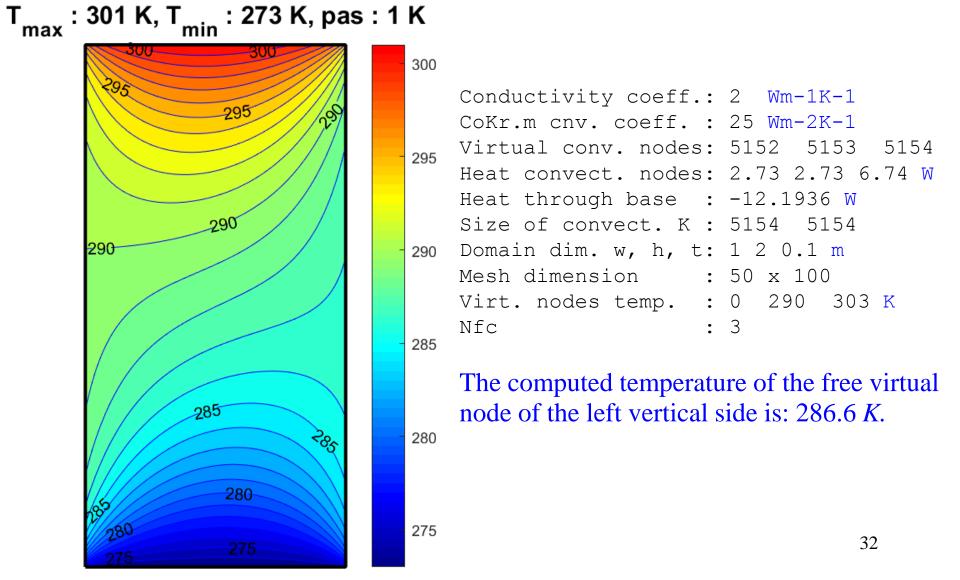


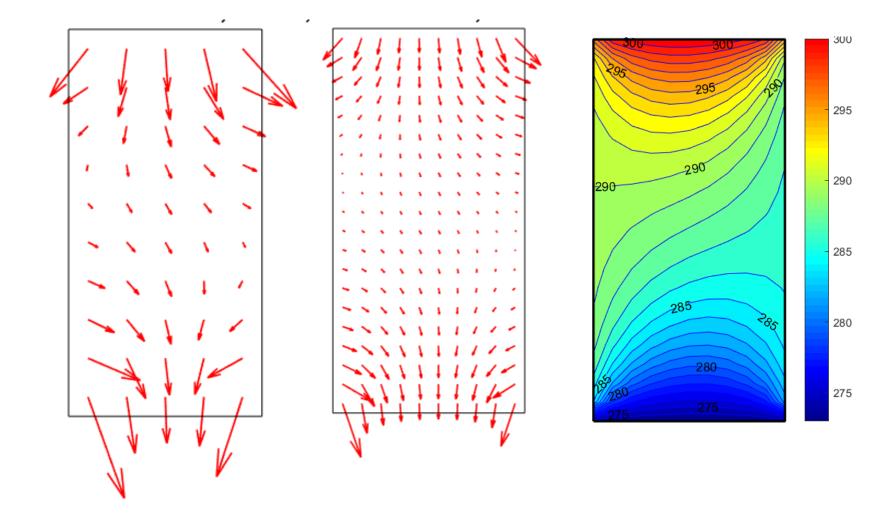
 $\vec{q} = -k \ grad \ \tau$ 

Heat flow, max:  $347 \text{ Wm}^{-2}$ , mean:  $49 \text{ Wm}^{-2}$ -grad  $\tau$ : max: 59. Km<sup>-1</sup>, mean: 17 Km<sup>-1</sup>

31

In the next example, we consider convection boundary conditions on 3 faces, the fourth face being fixed (273 K). The temperature of the virtual node related to the right vertical face is free.





Same problem, but: 5 x 10 & 10 x 20 meshes For both tests, the maximum heat flow =  $120 \text{ Wm}^{-2}$ , and the mean flow =  $33 \text{ Wm}^{-2}$ 

# Properties of a conductivity matrix including convective elements

The conductivity matrix is symmetric and semi-definite positive .

The sum of the terms of each column or of each line is zero.

For any thermal problem, at least 1 nodal temperature has to be specified in order to make the conductivity matrix definite positive.

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Back to the heat conduction problem involving prescribed heat fluxes according to the functional presented in the first lecture.

$$< I(\tau) = \int_{\Omega} \frac{1}{2} k (grad\tau)^{T} grad\tau d\Omega + \int_{S_{2}} \overline{q}_{n} \tau dS > minimum$$

Limiting the demonstration to 1 element edge, we can write that the second term of the above functional corresponds to the sum of products of heat flows (W) by temperatures (K) and we can write it as follows:

$$\int_{S_{2edge}} \overline{q}_n \tau \ dS_{el} = F_1 T_1 + F_2 T_2$$

If we express the edge temperature in term of blending functions:

$$\tau_{edge} = T_1 \left( 1 - \frac{x}{l} \right) + T_2 \frac{x}{l}$$

We can write the discretized functional:

$$\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left( T_1 \left( 1 - \frac{x}{l} \right) + T_2 \frac{x}{l} \right) dS_{el}$$

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In matrix form,

with: 
$$\begin{bmatrix} T \end{bmatrix} = \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$$
 we have:  $\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \frac{x}{l} \right] \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} dS_{el}$ 

We can now get the nodal temperatures out of the integral:

$$\int_{S_{2edge}} \overline{q}_n \tau dS_{el} = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \quad \frac{x}{l} \right] dS_{el} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$$

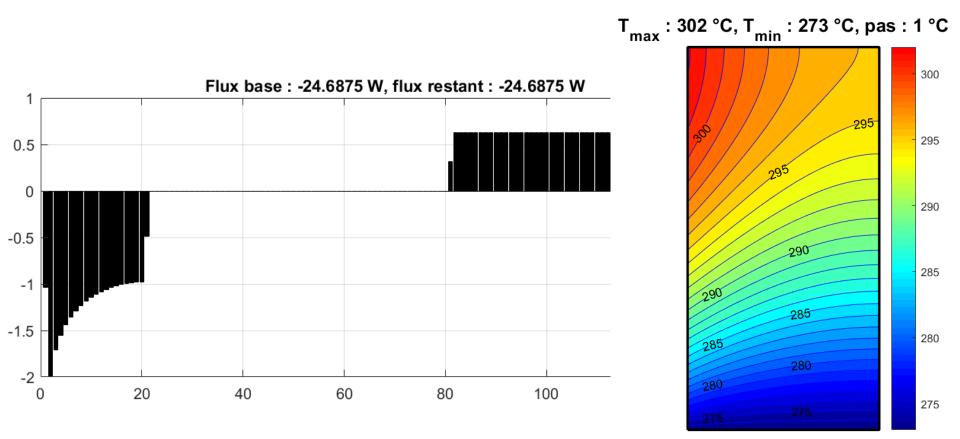
And, finally, we can write the prescribed second member in matrix form:

$$\begin{bmatrix} F_1 \\ F_2 \end{bmatrix}^T = \int_{S_{2edge}} \overline{q}_n \left[ \left( 1 - \frac{x}{l} \right) \quad \frac{x}{l} \right] dS_{el}$$
$$F_1 = \int_{S_{2edge}} \overline{q}_n \left( 1 - \frac{x}{l} \right) dS_{el} \quad ; \quad F_2 = \int_{S_{2edge}} \overline{q}_n \frac{x}{l} dS_{el}$$

We note that the term  $dS_{el}$  is equal to edx, where e is the thickness and dx the differential on the side of the element. We have above, the general method to build the 2<sup>d</sup> members of the heat transfer equations corresponding to imposed heat flows. If the prescribed heat flow is constant on the edge, for an edge of length l and a thickness e, we obtain:

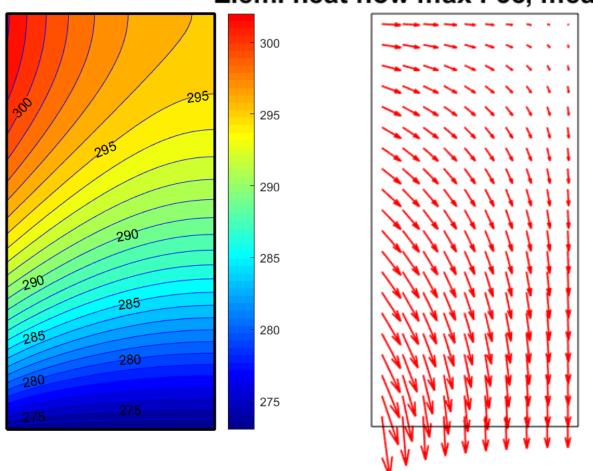
$$F_1 = \overline{q}_n \frac{el}{2} \quad ; \quad F_2 = \overline{q}_n \frac{el}{2} \tag{37}$$

We treat a very simple case with imposed temperatures on the lower face (base) and a constant flow on the left vertical wall. The mesh has  $20 \times 40$  elements. As the upper and right faces are adiabatic, the isotherms are orthogonal to them. The base temperature is fixed to 273 K. The total flow on the left side is equal to 25 Watt.



In computing the second member of the system of equations, there is ambiguity for the node of the lower left corner that receives a flux of 0.3125 *W*, but is fixed. This flow is therefore removed from the balance sheet in the <sub>38</sub> above graph.

#### pp\_conduction conde.m uniform k : 1 W/(mK) - gradT element max : 43.3, mean: 14.6 K/m Max elem. heat flow : 43.3, mean: 14.6 W/m2 Base temperature : 273 K Max temperature : 302 K Mesh size : 20 x 40 Fix. nod. 2 hor. fa.: 21 Diss tcaT\*(K\*tca)/2 : 254 WK Cpu : 0.378 sec. Elem. heat flow max : 38, mean: 15 W/m2



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# **Convective heat transfers**

- 1. Partial differential equations
- 2. Variational methods
- 3. Finite element method (local level)
- 4. Finite element method (global level)
- 5. Examples
- 6. Prescribed heat flows
- 7. Matlab<sup>©</sup> procedures

Matlab<sup>©</sup> procedure *pp\_convection.m* to solve a convection problem

```
= 25;k = 2;nfc = 3;ta = [290; 290; 303];pge = [1;2;.1;50];tb = 273;
 1
    hh
 2
    th
         = pge(3); %tt=tb+50;pf=[0;0;0];
 3
         = pqe(4);ny = nx*2;nel = nx*ny;no = (nx+1)*(ny+1);%nf = nx+1; % Mesh
    nx
         = f1 convection(nx, ny, k);
                                                        % k measured in W/(m K)
 4
    со
         = th/6*[4 - 1 - 2 - 1; -1 4 - 1 - 2; -2 - 1 4 - 1; -1 - 2 - 1 4];
 5
    Kel
                                                                   % elem. K
 6
    [K] = f2 convection(nx, ny, pge(2), pge(3), hh, nfc);
                                                         % With convection K
         = f2 conduction (nx, ny);
 7
    lK
    for n=1:nel;for i=1:4;for j=1:4
                                     % Assembling nel conduct. matrices Kel
 8
 9
              K(lK(n,i), lK(n,j)) = K(lK(n,i), lK(n,j)) + co(n) * Kel(i,j); end; end; end
10
    if nfc == 2
                                                             % 1. Adiabatic base
11
        gco = K(1:no, no+1:no+size(K, 1) -no) *ta(1:size(K, 1) -no, 1);
12
        tca = -K(1:no, 1:no) \setminus qco;
13
               f3 conduction(nx,ny,tca(1:no));axis off
                                                         % Drawing isotherms
             = (K*[tca;ta(1:size(K,1)-no)])';% Compute second member of system
14
        sm
15
            = th*hh*(ta(2)-min(tca));
        axa
16
            = th*co(1)*(min(tca)-max(tca))/pge(1);
        qxc
17
        qxd = th*hh*(max(tca)-ta(1));
18
             = (co(1) * ta(1) + (co(1) + hh*pqe(1)) * ta(2)) / (2*co(1) + hh*pqe(1));
        t1
19
        t.2
             = ta(2)+ta(1)-t1;
20
    end
21
                             % sequence 1: fixed base and 3 fixed virtual nodes
    if nfc == 3
    % gco = K(1:no-nx-1, no-nx:size(K,1))*[ones(nx+1,1)*tb;...
22
23
          ta(1:size(K,1)-no,1)];
24
      tca = -K(1:no-nx-1, 1:no-nx-1) \gco; 
25
             qrisb(nx,ny,[tca;ones(nx+1,1)*tb]);axis off % Drawing the isot.
26
          = (K*[tca;ones(nx+1,1)*tb; ta(1:size(K,1)-no,1)])';% 2d member svs.
    % sm
27
          ni = size(sm, 2)-nfc+1;
          disp(['Heat convect. nodes : ',num2str(sm(ni:size(sm,2))),' W'])
28
29
          disp(['Heat through base : ',num2str(sum(sm(no-nx:no))),' W'])
    8
30
        ta(1) = 0.;nfc = 3; % sequence 2: fixed base and 2 fixed virtual nodes
31
        K11
              = K(1:no-nx-1,1:no-nx-1); K12 = K(1:no-nx-1,no-nx:no);
32
                                     K14 = K(1:no-nx-1, no+2:no+3);
        K13
              = K(1:no-nx-1, no+1);
33
        K31
              = K(no+1, 1:no-nx-1);
                                          K32 = K(no+1, no-nx:no);
34
        К33
              = K(no+1, no+1);
                                           K34 = K(no+1, no+2:no+3);
35
        т2
              = ones(nx+1,1)*tb;
                                            T4 = [ta(2); ta(3)];
36
        tcb
              = [K11 K13;K31 K33]\(-[K12 K14;K32 K34]*[T2;T4]);
37
              = [tcb(1:no-nx-1); ones(nx+1,1)*tb; tcb(size(tcb,1)); T4];
        tca
38
        f3 conduction(nx,ny,tca(1:no));axis off
                                                        % Drawing the isotherms
39
    end
40
    disp(['Size of convect. K : ',num2str(size(K))])
41
    disp(['Domain dim. w, h, t : ',num2str(pge(1:3,1)'),' m'])
42
    disp(['Mesh dimension : ',num2str(nx),' x ',num2str(nx*2)])
43
    disp(['Virt. nodes temp.
                                : ',num2str(ta(1:size(ta,1))'), ' K'])
44
    if nfc == 2
45
      disp(['Checking heat flows : ',num2str([gxg qxc qxd]),' Wm-2'])
                                : ',num2str([t1 min(tca) t2 max(tca)]), ' K'])
46
      disp(['Checking temper.
47
    end
```

Lines 1-3: Data input 4 : Definition of element Line conductivities (function *f1\_convection.m*) Line : Conductivity matrix of 5 a square element Line : global convection 6 matrix (function *f2\_convection.m*) Line : localization matrix 7 (function *f2\_conduction.m*) Lines 8-9: assembling the global conductivity matrix Line 11 : computation of the

second member of the system Line 12 : solution of the system

Line	13	: drawing the isotherms		
in the function <i>f3_conduction.m</i>				

#### Lines 1-3 : Data input

```
tb = 270;tt = tb+50; pge = [1;2;1;50];
nx = pge(4);ny = nx*2;nel = nx*ny;no = (nx+1)*(ny+1);nf = nx+1; % Mesh
```

The variables tb & tt give the temperatures on the top and the bottom of the domain. The vector pge contains the dimensions of the domain: width, height, thickness and the number nx of elements in the horizontal direction. ny is the number of elements in the vertical direction: twice nx. The following items concern the computation of nel: number of elements, no: number of nodes, nf: number of nodes on a horizontal line of the mesh.

Matlab<sup>©</sup> function *kf1\_conduction.m* to handle non-uniform k

```
function [co] = kfl conduction(nx, ny, k) % Treatment of non uniform conduct.
1
  nel = nx*ny; % Number of element computed from mesh definition
2
3
  fa = 1 ; % Ratio between the 2 conductivities, if 1, k is a cst
4
  co = ones(nel, 1) * k;
5
          co(nx*nx+1:nx*nx+nx) = k*fa; % Second k on horizontal band 1
  if nx>2;co(nx*(nx-1)+1:nx*nx) = k*fa;end % Second k on horizontal band 2
6
  disp(['Thermal conductiv. : ',num2str(k,'%0.3g'),' W/(m K)'])
7
8
  disp(['Main & bridge k. : ',num2str([co(1) co(nx*nx+1)]),' W/(m K)'])
9
  end
```

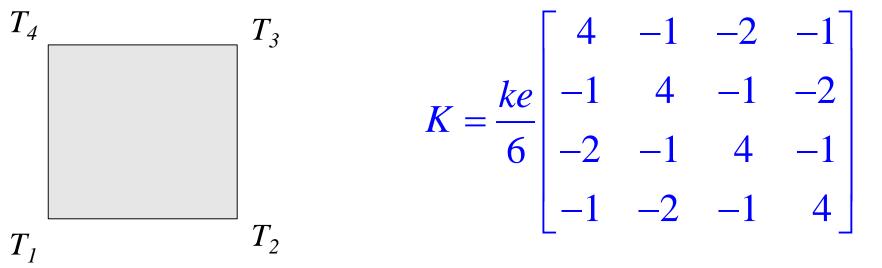
Line 4 : conductivity coefficients in the elements (function *kf1\_conduction.m*)

For a mesh of  $nx \ge ny$  elements (arguments of the function), one defines the vector *co* (output of the function) which contains the values of the coefficients of conductivity of all the elements..

In a non-homogeneous medium, the conductivities may vary from one element to another, it is necessary to add to the previous procedure the two lines defining the elements operating with the second conductivity and modify the assembly of the elements. The conductivity coefficient acts as coefficients in the assembly of the global matrix (line 9). The conductivities of the elements are stored in the vector *co* of dimension *nel*.

Line 5 : conductivity matrix of a square element

The variable pge(3) corresponds to the thickness of the element. The matrix coefficients are written in compact form.



### Line 6: Compute the conductivity matrix for convection (function *hf1.m*)

The element is a vertical or a horizontal one. Its length is *L*, its thickness is *e* and the convection coefficient is  $h (Wm^{-2}K^{-1})$ . The sequence of nodes start with the two real ones and finish with the virtual one.

$$K_{convection} = h \frac{eL}{6} \begin{bmatrix} 2 & 1 & -3 \\ 1 & 2 & -3 \\ -3 & -3 & 6 \end{bmatrix}$$

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```
Matlab<sup>©</sup> function hf1_convection.m to assemble the convection matrix
   function[K] = hfl convection(nx, ny, ep, he, hh, nfc)
  disp(['CoKr.m conv. coeff. : ',num2str(hh),' Wm-2K-1'])
  Kelc = [2 \ 1 \ -3; 1 \ 2 \ -3; -3 \ -3 \ 6] *hh*ep*he/ny/6;
                                                        % Elem. conv. matrix
   if nfc ==2
 5
   Ntca = (nx+1) * (ny+1) + nfc;
                                                        % Mesh nx x ny elements
   ntv2 = [ Ntca-1 Ntca]; % Numbering of the convective virtual nodes
 6
          = f4 convection(nx,ny,ntv2); % Local. convection matrices 2 sides
 7
   lc
   disp(['Virtual conv. nodes : ',num2str(ntv2)])
 8
 9
   end
10
   if nfc ==3
11
   Ntca = (nx+1) * (ny+1) + nfc;
                                                        % Mesh nx x ny elements
12 ntv3 = [Ntca-2 Ntca-1 Ntca]; % Numbering of the convective virtual nodes
          = f3 convection(nx,ny,ntv3); % Local. of the convection mat. 3 sides
13 lc
14
  disp(['Virtual conv. nodes : ',num2str(ntv3)])
15
   end
16 if nfc ==4
17
   Ntca = (nx+1) * (ny+1) + nfc;
                                                        % Mesh nx x ny elements
18
   ntv4 = [Ntca-3 Ntca-2 Ntca-1 Ntca]; % Number. convective virtual nodes
19
  lc
          = f5 convection(nx,ny,ntv4); % Local. of convection matrices 4 sides
   disp(['Virtual conv. nodes : ',num2str(ntv4)])
20
21
   end
22
  K
          = zeros(Ntca, Ntca); % Dimension of K including fixed DOF & add. nodes
23
   for n = 1:size(lc,1);for i=1:3;for j=1:3 % Assembling conv. matrices Kelc
24
              K(lc(n,i),lc(n,j)) = K(lc(n,i),lc(n,j)) + Kelc(i,j); end; end; end
25
    end
```

This function computes the convection matrices of a mesh  $nx \ge ny$  (arguments 1 and 2 of the function) for a domain of dimensions given by arguments 3 and 4 and a convection coefficient given by argument 5.

### Line 7 : compute the localization matrix (function kfl.m)

The element node sequence is always the same and must be satisfied during assembling

 $T_1$   $T_2$ For each element, the four nodes must be located in the domain mesh. For the first element, line 1 of the localization matrix, we have then the global nodes: 4, 5, 2 and 1, etc..

 $T_{4}$ 

Element 1 : 4	5	2	1
Element 2 : 5	6	3	2
Element 3 : 7	8	5	4
Element 4 : 8	9	6	5
Element <b>5</b> : <b>10</b>	11	8	7
Element <b>6</b> : <b>11</b>	12	9	8
Element <b>7</b> : <b>13</b>	14	11	10
Element <b>8</b> : 14	15	12	11

Here, to improve the efficiency of the procedure, we use direct localization instead of the matrix formalism seen before in the theoretical presentation.

 $T_3$ 

### Lines 8-9 : global conductivity matrix assembling

The external loop is performed on the elements and the 2 internal ones on the lines and columns of the element conductivity matrices. Each term (i, j) of element *n* is located at (lK(n, i), lK(n, j)) in the global *K* matrix according to the *lK* matrix computed in *kf1.m* (see previous slide).

Moreover, the coefficients of the element matrices *Kel* are multiplied by their conductivity coefficient co(n) (see *line 4*).

```
gco=K(1:no-nx-1, no-nx:size(K,1))*[ones(nx+1,1)*tb;ta(1:size(K,1)-no,1)];
tca = -K(1:no-nx-1,1:no-nx-1)\gco;
```

In the proposed example, we fix the temperature of the base and of the virtual nodes. The solution of a problem including only imposed temperatures is performed as follows. Assuming that  $[\overline{T}_2]$  is given, we have only to compute  $[T_1]$  and the second member  $[?] = [F_2]$ . The computation of the incoming or outcoming heat flows through the fixations is simply obtained by multiplying the global conductivity matrix by the vector of temperatures.

$$\begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \begin{bmatrix} T_1 \\ \overline{T}_2 \end{bmatrix} = \begin{bmatrix} 0 \\ ? \end{bmatrix}$$
$$\begin{bmatrix} T_1 \end{bmatrix} = -\begin{bmatrix} K_{11} \end{bmatrix}^{-1} \begin{bmatrix} K_{12} \end{bmatrix} \begin{bmatrix} \overline{T}_2 \end{bmatrix}$$
$$\begin{bmatrix} F_2 \end{bmatrix} = \begin{bmatrix} K_{21} \end{bmatrix} \begin{bmatrix} T_1 \end{bmatrix} + \begin{bmatrix} K_{22} \end{bmatrix} \begin{bmatrix} \overline{T}_2 \end{bmatrix}$$

## Ligne 12 : drawing of the isotherms in the function *kf3\_conduction.m*

Matlab <sup>©</sup> function <i>kf3_conduction.m</i> to draw isotherm lines					
1	<pre>function [ ] = kf3 conduction(nx,ny,tca)</pre>				
2	figure('Position', [1 1 600 512]);				
3	my = ny+1; no=(nx+1) * (ny+1);				
4	<pre>B = ones(my,nx+1)*tca(1);x = zeros(my,nx+1);y = zeros(my,nx+1);</pre>				
5	<pre>for j = 1 : nx+1; for i = 1 : ny; x(i,j) = j-1; y(i,j) = my-i; end; end;</pre>				
6	ii = 0;				
7	<pre>for i = 1:ny; for j = 1:nx+1; ii = ii+1; B(i,j) = tca(ii); end; end</pre>				
8	x(my,:) = x(ny,:);y(:,1) = y(:,2);B(my,:) = tca(ii+1:no);				
9	<pre>gap = 1; % gap = max(round((tmax-tmin)/20),.5); % gap = 0.25;</pre>				
10	colormap(kf4_conduction); % Color map definition				
11	<pre>[CS,H] = contourf(x,y,B,(0.:gap:max(tca)),'b');hold on;axis equal</pre>				
12	clabel(CS,H,[275 280 285 290 295 300 305 310 315 320]);colorbar				
13	<pre>plot ([0 nx nx 0 0],[0 0 ny ny 0],'k','LineWidth',2);hold on;axis equal</pre>				
14	<pre>title (['T_m_a_x : ',num2str(round(max(tca))),' K, T_m_i_n : ',</pre>				
15	<pre>num2str(round(min(tca))),' K, step : ',num2str(gap),' K'],'fontsize',15);</pre>				
16	axis off;end % End isotherms drawing				

This function performs the visualization of the isotherms of a mesh  $nx \ge ny$  (arguments 1 and 2 of the function) based on the nodal temperatures stored in the vector *tca* (argument 3).

In line 9 of the function, the value of the intervals between successive isotherms can be adjusted. Let observe in line 10 the introduction of a particularly effective color bar (function  $kf4\_conduction.m$ ) <sup>48</sup>

Matlab<sup>©</sup> function *hf2\_convection.m* to build localizations of convective elements function [lc]=hf2 convection(nx,ny,ntv)% Loc. vectors for conv. on 3 sides 1 2 = (nx+1)\*(ny+1); lc = zeros(2\*ny+nx,3); ii = 0; no 3 if ntv(1) > 0% Right side 4 = 1:ny for i 5 lc(i,1) = (nx+1)\*i; lc(i,2) = lc(i,1)+nx+1; lc(i,3) = no+1;6 ii = ii + ny;end; 7 end 8 if ntv(2) > 0% Left side = 1:nx+1:(nx+1)\*ny; ii = ii + 1; 9 for i lc(ii,1) = i; lc(ii,2) = lc(ii,1) + nx+1; lc(ii,3) = no+2;10 11 end 12 end 13 if ntv(3) > 0% Top side 14 for i = 1:nx; ii = ii + 1;15 lc(ii,1) = i; lc(ii,2) = lc(ii,1)+1; lc(ii,3) = no+3;16 end % disp(['Number of conv. el. : ',num2str(ii)]) 17 end; 18 end

Matlab<sup>©</sup> function *hf3\_convection.m* to build localizations of convective elements

```
function [lc]=hf3 convection(nx,ny,ntv)% Loc. vectors for conv. on 3 sides
 1
 2
                     = (nx+1)*(ny+1); lc = zeros(2*ny,3); ii = 0;
    no
 3
   if ntv(1) > 0
                                                                   % Right side
 4
        for i
                = 1:nv
 5
            lc(i,1) = (nx+1)*i; lc(i,2) = lc(i,1)+nx+1; lc(i,3) = no+1;
 6
                                            ii = ii + ny;
        end;
 7
   end
 8
   if ntv(2) > 0
                                                                    % Left side
 9
        for i = 1:nx+1:(nx+1)*ny; ii = ii + 1;
            lc(ii,1) = i; lc(ii,2) = lc(ii,1) + nx + 1; lc(ii,3) = no+2;
10
11
        end
12
    end
13
   disp(['Number of conv. el. : ',num2str(ii)])
14
   end
```

```
Matlab<sup>®</sup> function hf4 convection.m to compute localization of convection matrices
    function [lc]=hf4 convection(nx,ny,ntv) % Loc. vectors conv. on 4 sides
                    - (nx+1)*(ny+1);lc = zeros(2*(ny+nx),3);ii = 0;
 2
    no
                                                                 % Right side
 3
    if ntv(1) > 0
       for i
 4
                    = 1:nv
 5
           lc(i,1) = (nx+1)*i; lc(i,2) = lc(i,1)+nx+1; lc(i,3) = no+1;
 6
        end;
                                           ii = ii + ny;
 7
    end
   if ntv(2) > 0
 8
                                                                  % Left side
 9
       for i = 1:nx+1:(nx+1)*ny; ii = ii + 1;
10
           lc(ii,1) = i; lc(ii,2) = lc(ii,1) + nx + 1; lc(ii,3) = no+2;
11
        end
12
   end
13
    if ntv(3) > 0
                                                                   % Top side
14
       for i
                    = 1:nx;
                                          ii = ii + 1;
           lc(ii,1) = i;lc(ii,2) = lc(ii,1)+1;lc(ii,3) = no+3;
15
16
       end
17
    end;
18 \text{ if } ntv(4) > 0
                                                                % Bottom side
19
                              ii = ii + 1;
       for i
                = 1:nx;
           lc(ii,1) = no-nx-1+i; lc(ii,2) = lc(ii,1)+1; lc(ii,3) = no+4;
20
21
       end
22 end;
23
   disp(['N. of convective el.: ',num2str(ii)])
24 end
```

Matlab<sup>©</sup> function *hf5\_convection.m* to compact matrices xyz, lK, lc.

```
function [sxyz,slK,slc]=hf5 convection(xyz,lK,lc)
 1
                                                                 % see cono.m
 2
          = zeros(size(xyz, 1), 1);
   pn
   for i = 1:size(lK,1); for j = 1:4; if lK(i,j) > 0; pn(lK(i,j))=1; end; end; end
   for i = 1:size(lc,1); for j = 1:3; if lc(i,j) > 0; pn(lc(i,j))=1; end; end; end
 4
   ii
 5
          = 0;
   for i = 1 : size(pn,1);if pn(i) == 1;ii=ii+1;pn(i)=ii;end;end
 6
   sxyz = zeros(max(pn), 3);
 7
   for i = 1:size(pn,1);if pn(i) > 0;sxyz(pn(i),:)=xyz(i,:);end;end
 8
   slK = zeros(size(lK));
 9
   for i = 1:size(lK,1);for j=1:4;slK(i,j)=pn(lK(i,j));end;end
10
11
   ii = 0;
12
   for i = 1:size(lc,1);if lc(i,1) > 0;ii=ii+1;end;end
13
   slc = zeros(ii,3); ii=0;
14
   for i = 1:size(lc,1)
15
       if lc(i,1) > 0; ii = ii+1; for j = 1:3; slc(ii, j) = pn(lc(i, j)); end; end;
16
    end
17
   end
```