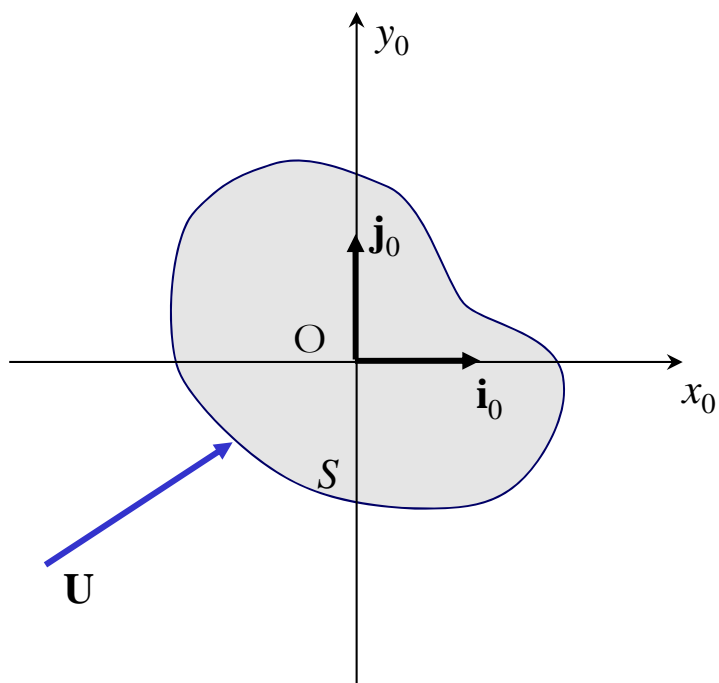
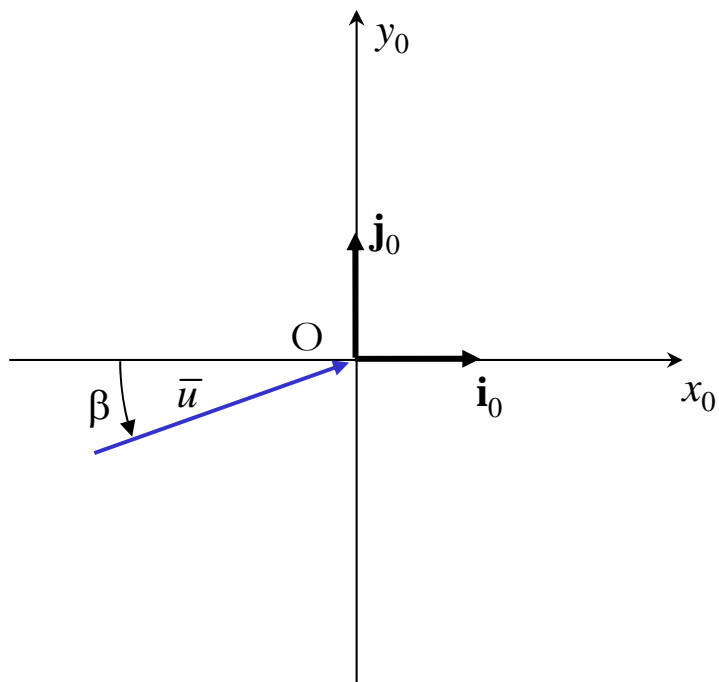


Slender cylinder in a turbulent wind field

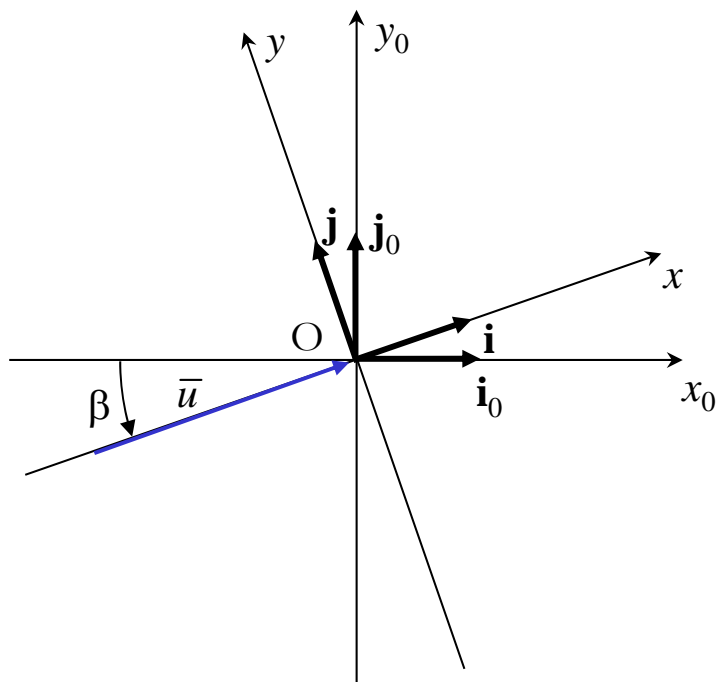


Turbulent wind field



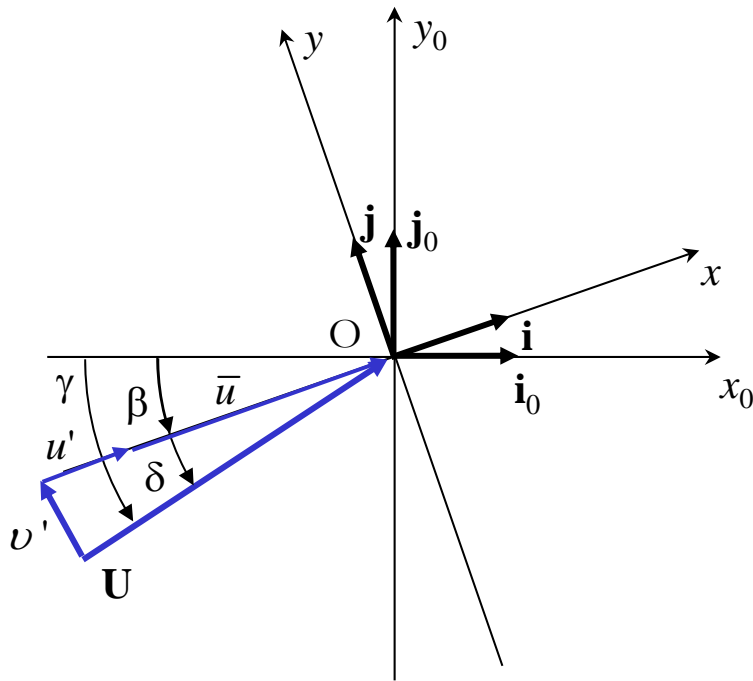
\bar{u} = mean wind velocity

Turbulent wind field



\bar{u} = mean wind velocity

Turbulent wind field



$$\mathbf{U}(t) = u(t)\mathbf{i} + v(t)\mathbf{j}$$

$$u(t) = \bar{u} + u'(t) \quad v(t) = v'(t)$$

$$\delta(t) = \arctg \left\{ \frac{v'(t)}{\bar{u} + u'(t)} \right\} \quad \gamma(t) = \beta + \delta(t)$$

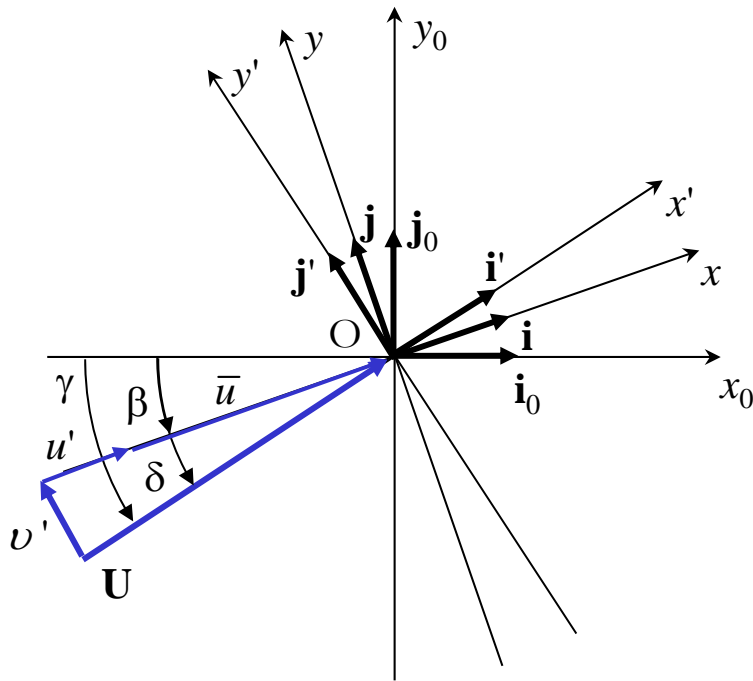
$$U(t) = \|\mathbf{U}(t)\| = \sqrt{[\bar{u} + u'(t)]^2 + [v'(t)]^2}$$

\bar{u} = mean wind velocity

u' = longitudinal turbulence component (parallel to \bar{u})

v' = transversal turbulence component (orthogonal to \bar{u})

Turbulent wind field



$$\mathbf{U}(t) = u(t)\mathbf{i} + v(t)\mathbf{j}$$

$$u(t) = \bar{u} + u'(t) \quad v(t) = v'(t)$$

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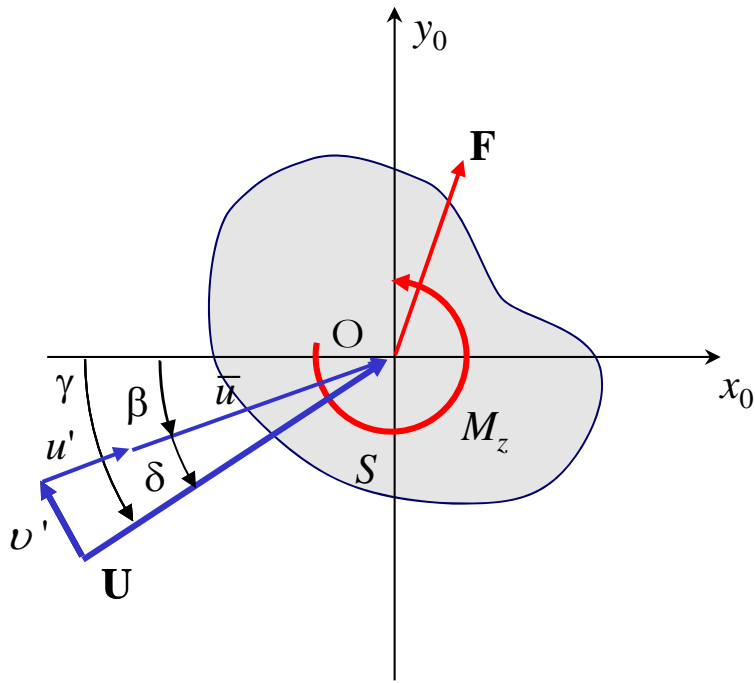
$$U(t) = \|\mathbf{U}(t)\| = \sqrt{[\bar{u} + u'(t)]^2 + [v'(t)]^2}$$

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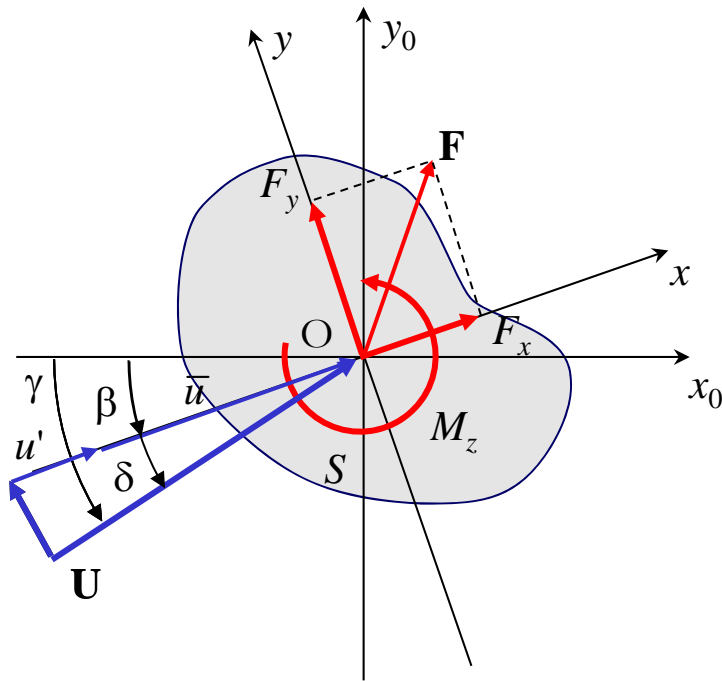
Wind induced actions on slender cylinders



$$\mathbf{F}(t) = \bar{\mathbf{F}} + \mathbf{F}'(t)$$

$$M_z(t) = \bar{M}_z + M'_z(t)$$

Wind induced actions on slender cylinders



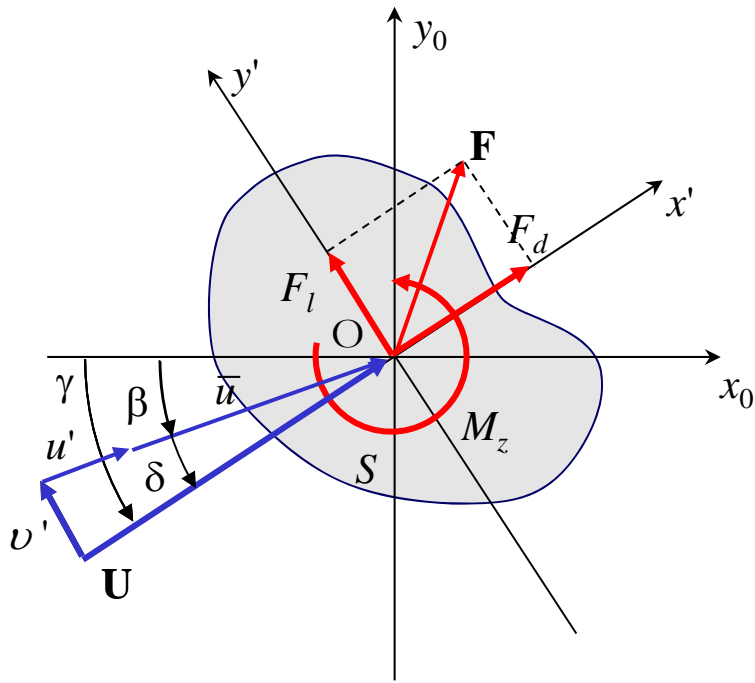
$$\mathbf{F}(t) = F_x(t)\mathbf{i} + F_y(t)\mathbf{j}$$

$$M_z(t) = \bar{M}_z + M'_z(t)$$

$$F_x(t) = \bar{F}_x + F'_x(t)$$

$$F_y(t) = \bar{F}_y + F'_y(t)$$

Wind induced actions on slender cylinders



$$\mathbf{F}(t) = F_x(t)\mathbf{i} + F_y(t)\mathbf{j} = F_d(t)\mathbf{i}' + F_l(t)\mathbf{j}'$$

$$M_z(t) = \bar{M}_z + M'_z(t)$$

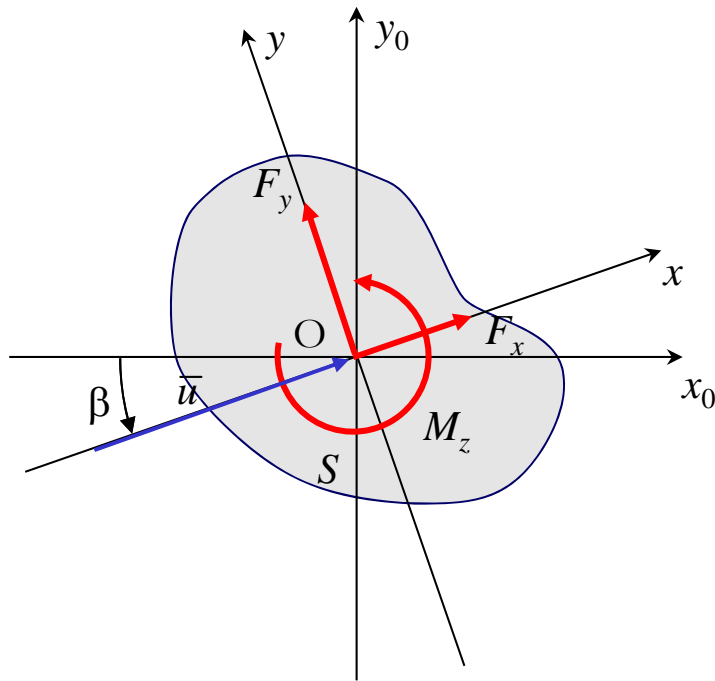
$$F_x(t) = \bar{F}_x + F'_x(t)$$

$$F_y(t) = \bar{F}_y + F'_y(t)$$

$$F_d(t) = \bar{F}_d + F'_d(t)$$

$$F_l(t) = \bar{F}_l + F'_l(t)$$

Wind induced actions on slender cylinders



Drag coefficient

$$c_d(\beta) = \frac{\bar{F}_x}{\frac{1}{2}\rho\bar{u}^2b}$$

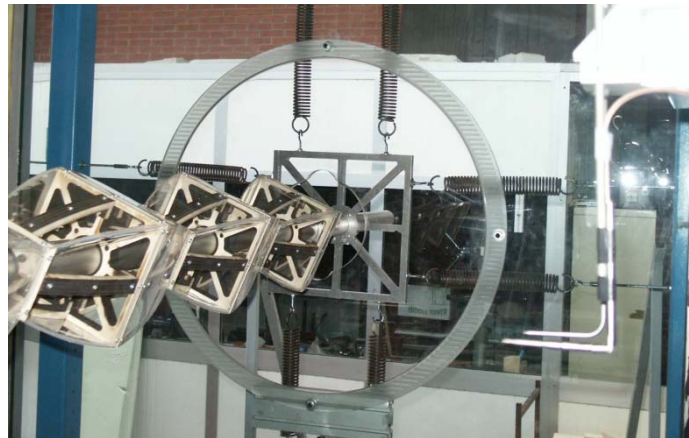
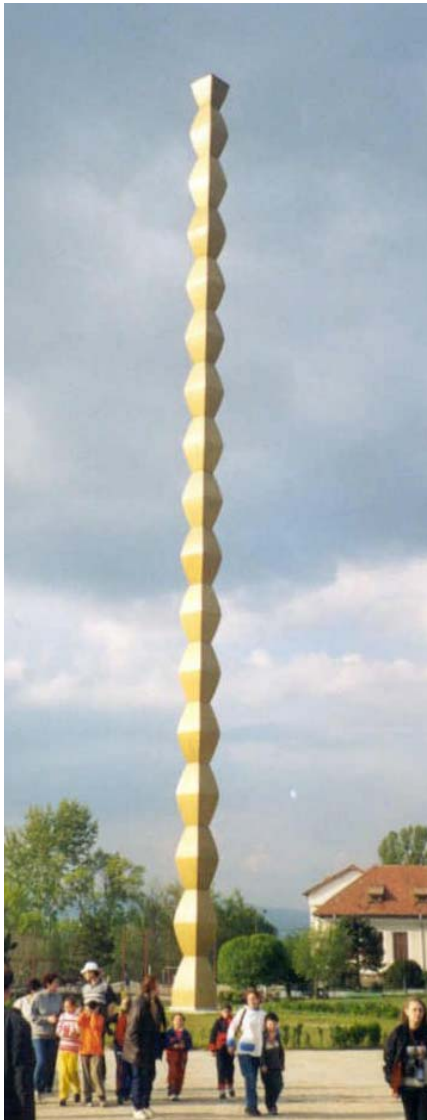
Lift coefficient

$$c_l(\beta) = \frac{\bar{F}_y}{\frac{1}{2}\rho\bar{u}^2b}$$

Torque coefficient

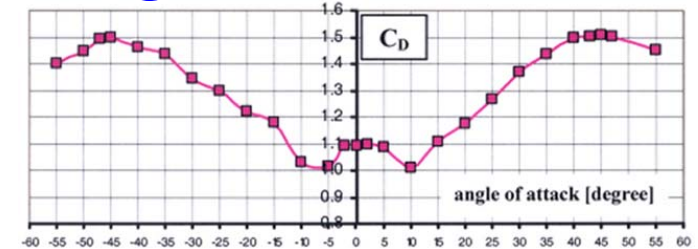
$$c_m(\beta) = \frac{\bar{M}_z}{\frac{1}{2}\rho\bar{u}^2b^2}$$

Brancusi Endless Column, Tîrgu Jiu, Rumania

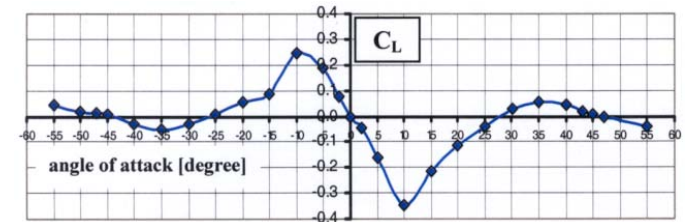


wind tunnel tests

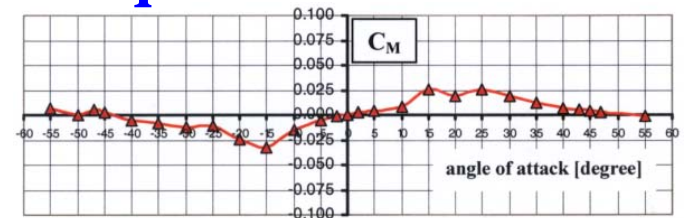
Drag coefficient



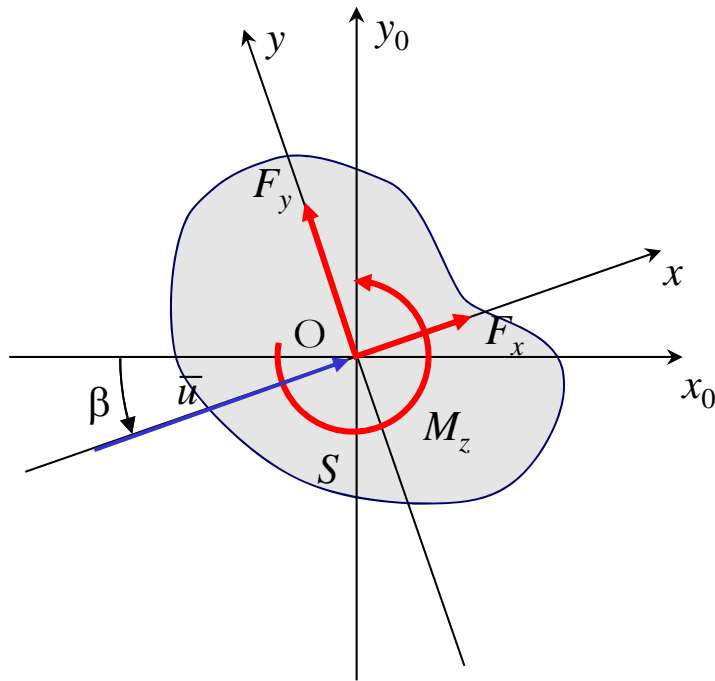
Lift coefficient



Torque coefficient



Wind induced actions on slender cylinders



Drag coefficient

$$c_d(\beta) = \frac{\bar{F}_x}{\frac{1}{2}\rho\bar{u}^2b}$$

Lift coefficient

$$c_l(\beta) = \frac{\bar{F}_y}{\frac{1}{2}\rho\bar{u}^2b}$$

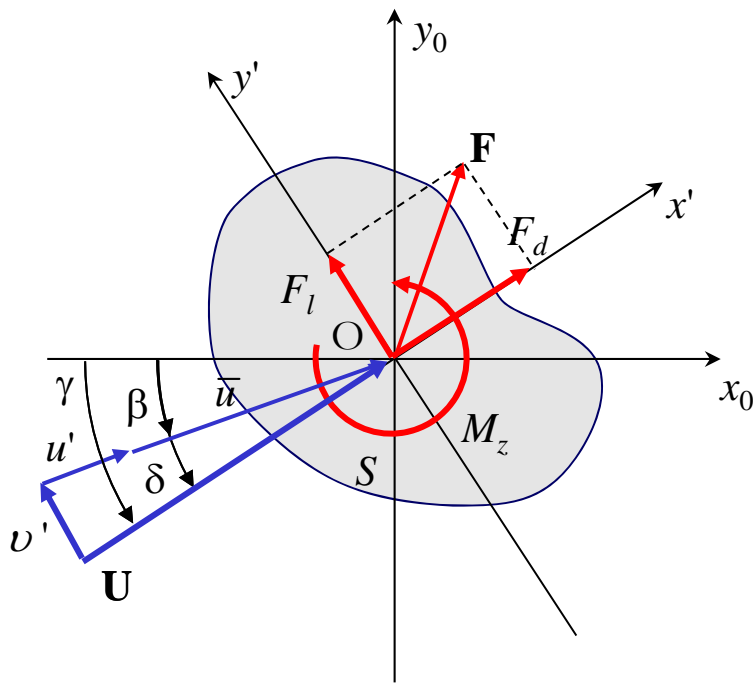
Torque coefficient

$$c_m(\beta) = \frac{\bar{M}_z}{\frac{1}{2}\rho\bar{u}^2b^2}$$

$$\bar{F}_x = \frac{1}{2}\rho\bar{u}^2bc_d(\beta) \quad \bar{F}_y = \frac{1}{2}\rho\bar{u}^2bc_l(\beta)$$

$$\bar{M}_z = \frac{1}{2}\rho\bar{u}^2b^2c_m(\beta)$$

Wind induced actions on slender cylinders



Drag coefficient

$$c_d(\beta) = \frac{\bar{F}_x}{\frac{1}{2}\rho\bar{u}^2b}$$

Lift coefficient

$$c_l(\beta) = \frac{\bar{F}_y}{\frac{1}{2}\rho\bar{u}^2b}$$

Torque coefficient

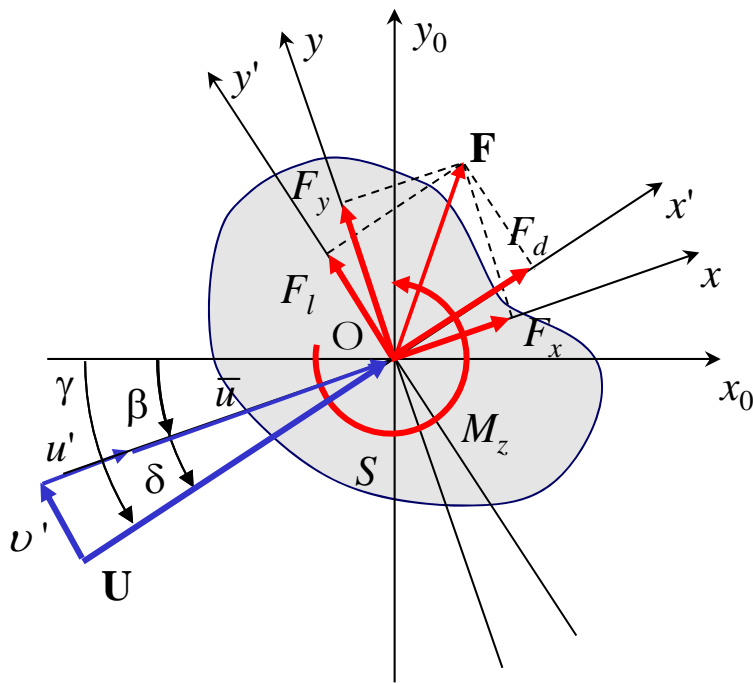
$$c_m(\beta) = \frac{\bar{M}_z}{\frac{1}{2}\rho\bar{u}^2b^2}$$

$$\bar{F}_x = \frac{1}{2}\rho\bar{u}^2bc_d(\beta) \quad \bar{F}_y = \frac{1}{2}\rho\bar{u}^2bc_l(\beta) \quad \bar{M}_z = \frac{1}{2}\rho\bar{u}^2b^2c_m(\beta)$$

Quasi-steady theory

$$F_d(t) = \frac{1}{2}\rho U^2(t)bc_d(\gamma(t)) \quad F_l(t) = \frac{1}{2}\rho U^2(t)bc_l(\gamma(t)) \quad M_z(t) = \frac{1}{2}\rho U^2(t)b^2c_m(\gamma(t))$$

Wind induced actions on slender cylinders



Drag coefficient

$$c_d(\beta) = \frac{\bar{F}_x}{\frac{1}{2}\rho\bar{u}^2b}$$

Lift coefficient

$$c_l(\beta) = \frac{\bar{F}_y}{\frac{1}{2}\rho\bar{u}^2b}$$

Torque coefficient

$$c_m(\beta) = \frac{\bar{M}_z}{\frac{1}{2}\rho\bar{u}^2b^2}$$

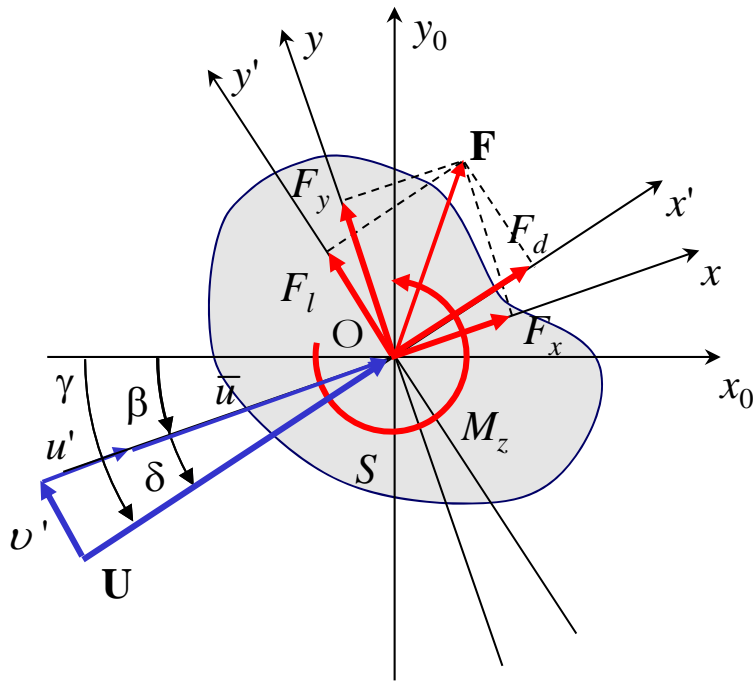
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Projection on x, y axes

$$F_x(t) = F_d(t)\cos\delta(t) - F_l(t)\sin\delta(t) \quad F_y(t) = F_d(t)\sin\delta(t) + F_l(t)\cos\delta(t)$$

Wind induced actions on slender cylinders



$$F_x(t) = \frac{1}{2} \rho U^2(t) b c_x(\gamma)$$

$$F_y(t) = \frac{1}{2} \rho U^2(t) b c_y(\gamma)$$

$$M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma)$$



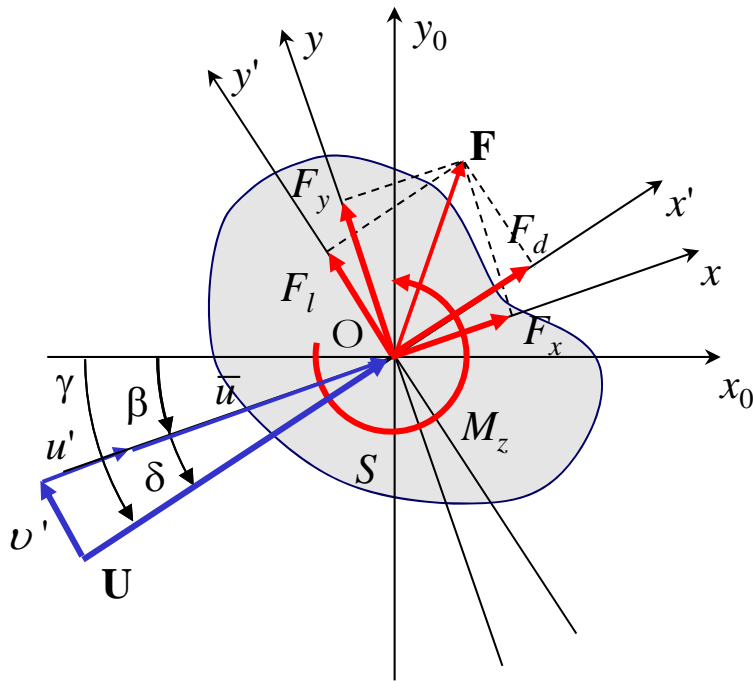
Quasi-steady theory

$$F_d(t) = \frac{1}{2} \rho U^2(t) b c_d(\gamma(t)) \quad F_l(t) = \frac{1}{2} \rho U^2(t) b c_l(\gamma(t)) \quad M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma(t))$$

Projection on x, y axes

$$F_x(t) = F_d(t) \cos \delta(t) - F_l(t) \sin \delta(t) \quad F_y(t) = F_d(t) \sin \delta(t) + F_l(t) \cos \delta(t)$$

Wind induced actions on slender cylinders



$$F_x(t) = \frac{1}{2} \rho U^2(t) b c_x(\gamma)$$

$$F_y(t) = \frac{1}{2} \rho U^2(t) b c_y(\gamma)$$

$$M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma)$$



$$c_x(\gamma) = c_d(\gamma) \cos \delta - c_l(\gamma) \sin \delta$$

$$c_y(\gamma) = c_d(\gamma) \sin \delta + c_l(\gamma) \cos \delta$$

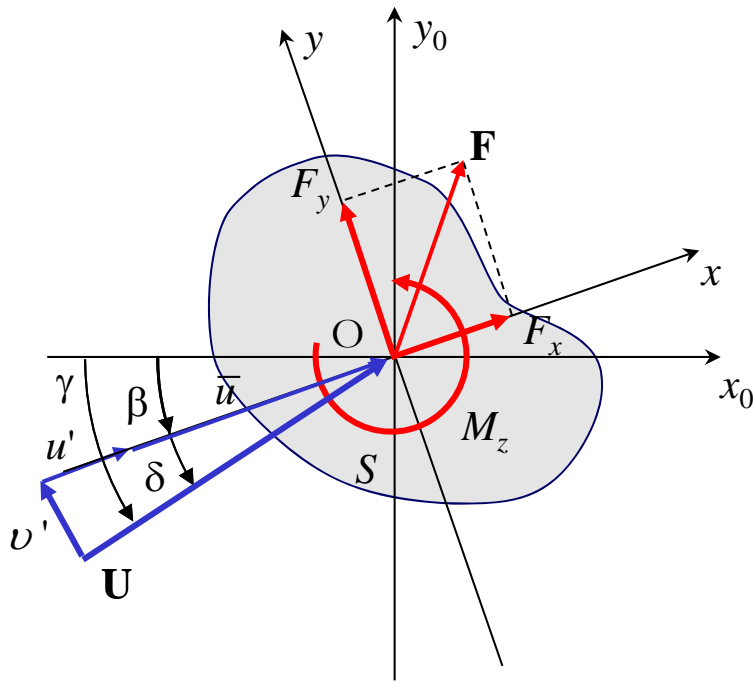
Quasi-steady theory

$$F_d(t) = \frac{1}{2} \rho U^2(t) b c_d(\gamma(t)) \quad F_l(t) = \frac{1}{2} \rho U^2(t) b c_l(\gamma(t)) \quad M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma(t))$$

Projection on x, y axes

$$F_x(t) = F_d(t) \cos \delta(t) - F_l(t) \sin \delta(t) \quad F_y(t) = F_d(t) \sin \delta(t) + F_l(t) \cos \delta(t)$$

Wind induced actions on slender cylinders



$$F_x(t) = \frac{1}{2} \rho U^2(t) b c_x(\gamma)$$

$$F_y(t) = \frac{1}{2} \rho U^2(t) b c_y(\gamma)$$

$$M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma)$$

$$c_x(\gamma) = c_d(\gamma) \cos \delta - c_l(\gamma) \sin \delta$$

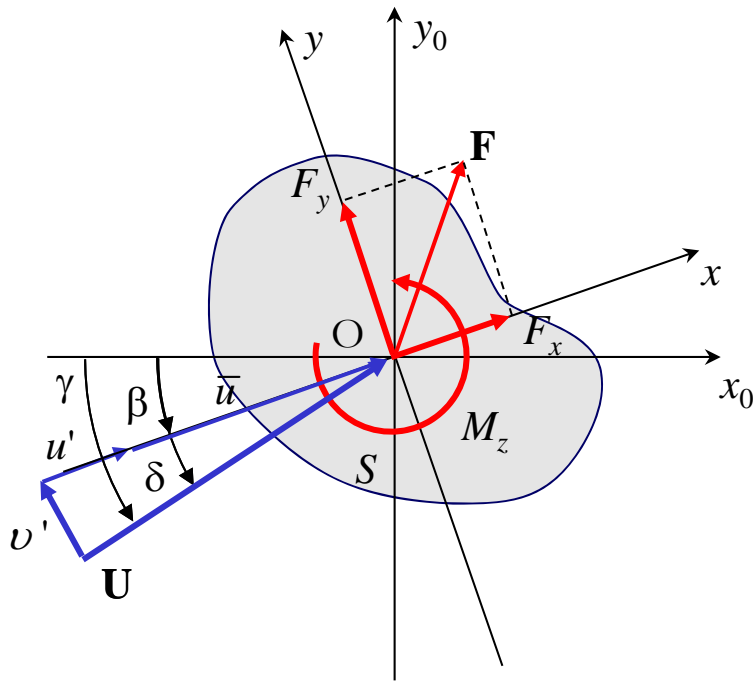
$$c_y(\gamma) = c_d(\gamma) \sin \delta + c_l(\gamma) \cos \delta$$

$$c_x(\gamma) = c_d + \delta(c'_d - c_l) + \frac{\delta^2}{2}(c''_d - c_d - 2c'_l) + \dots$$

$$c_y(\gamma) = c_l + \delta(c_d + c'_l) + \frac{\delta^2}{2}(2c'_d + c''_l - c_l) + \dots$$

$$c_m(\gamma) = c_m + \delta c'_m + \frac{\delta^2}{2} c''_m + \dots$$

Wind induced actions on slender cylinders



$$F_x(t) = \frac{1}{2} \rho U^2(t) b c_x(\gamma)$$

$$F_y(t) = \frac{1}{2} \rho U^2(t) b c_y(\gamma)$$

$$M_z(t) = \frac{1}{2} \rho U^2(t) b^2 c_m(\gamma)$$

$$c_x(\gamma) = c_d(\gamma) \cos \delta - c_l(\gamma) \sin \delta$$

$$c_y(\gamma) = c_d(\gamma) \sin \delta + c_l(\gamma) \cos \delta$$

$$c_x(\gamma) = c_d + \delta(c'_d - c_l) + \frac{\delta^2}{2}(c''_d - c_d - 2c'_l) + \dots$$

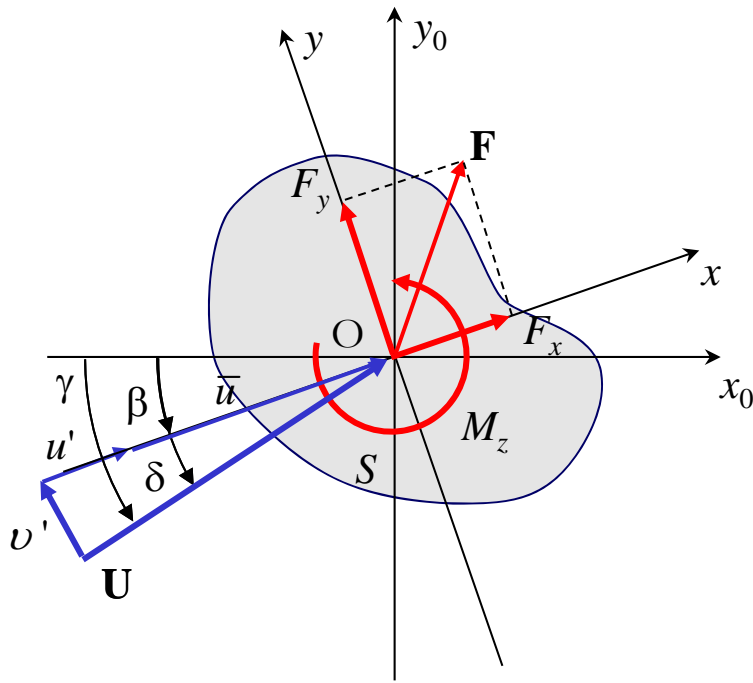
$$c_y(\gamma) = c_l + \delta(c_d + c'_l) + \frac{\delta^2}{2}(2c'_d + c''_l - c_l) + \dots$$

$$c_m(\gamma) = c_m + \delta c'_m + \frac{\delta^2}{2} c''_m + \dots$$

$$\delta = \arctg \left\{ \frac{v'(t)}{\bar{u} + u'(t)} \right\} = \frac{v'(t)}{\bar{u} + u'(t)} - \frac{[v'(t)]^3}{3[\bar{u} + u'(t)]^3} + \dots$$

$$U^2(t) = [\bar{u} + u'(t)]^2 + v'^2(t)$$

Wind induced actions on slender cylinders

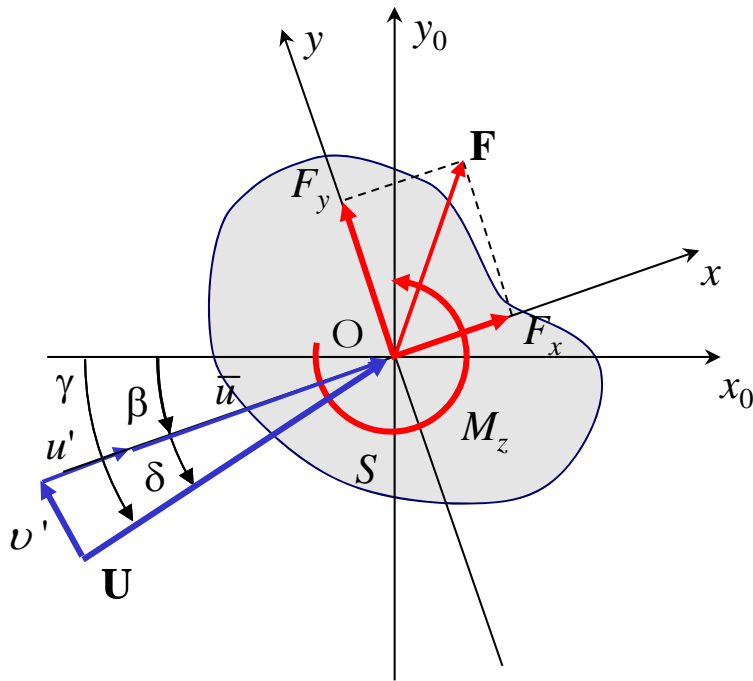


$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

$$\bar{M}_z = \frac{1}{2} \rho \bar{u}^2 b^2 c_m$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

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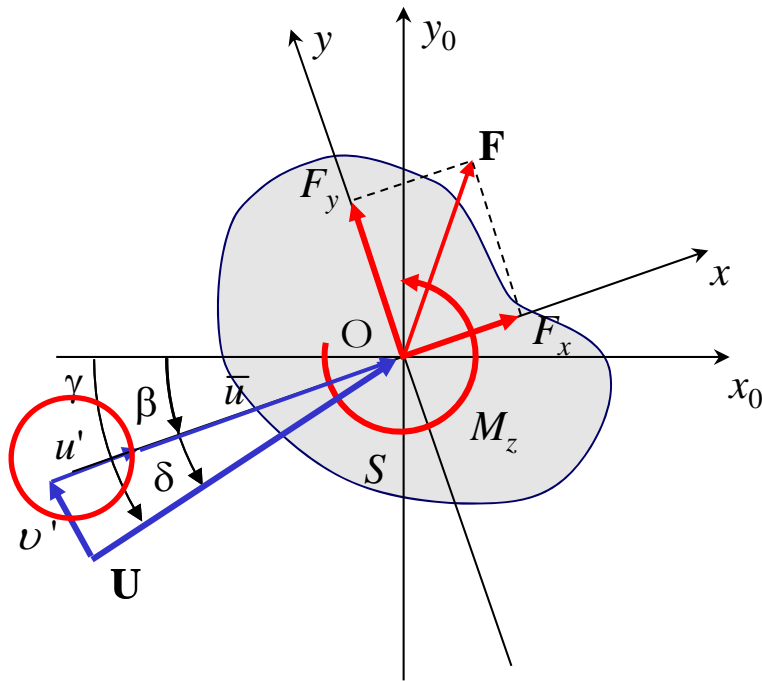
Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

$$F'_x(t) = \rho \bar{u} b c_d u'(t) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) v'(t)$$

$$F'_y(t) = \rho \bar{u} b c_l u'(t) + \frac{1}{2} \rho \bar{u} b (c_d + c'_l) v'(t)$$

$$M'_z(t) = \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

$$\bar{M}_z = \frac{1}{2} \rho \bar{u}^2 b^2 c_m$$

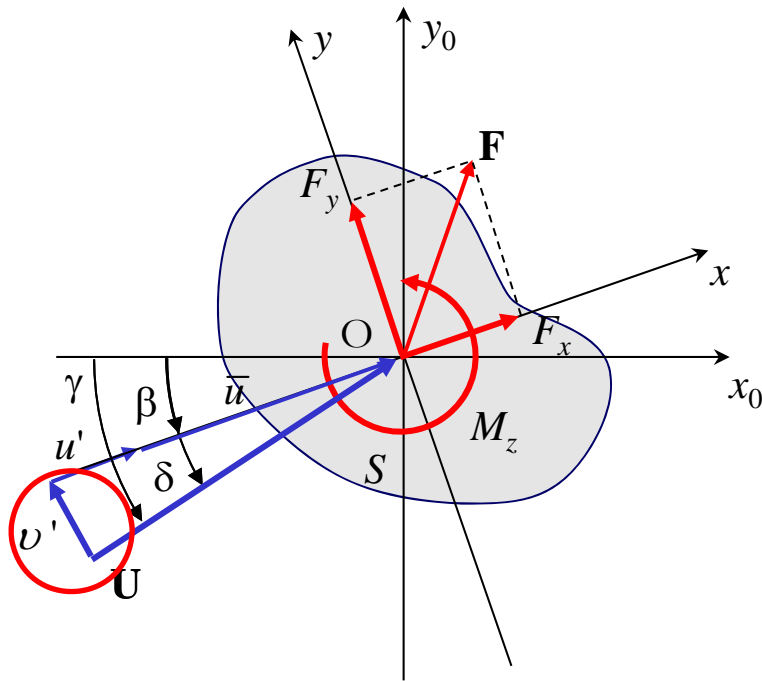
Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

$$F'_x(t) = \rho \bar{u} b c_d \mathbf{u}'(t) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) v'(t)$$

$$F'_y(t) = \rho \bar{u} b c_l \mathbf{u}'(t) + \frac{1}{2} \rho \bar{u} b (c_d + c'_l) v'(t)$$

$$M'_z(t) = \rho \bar{u} b^2 c_m \mathbf{u}'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

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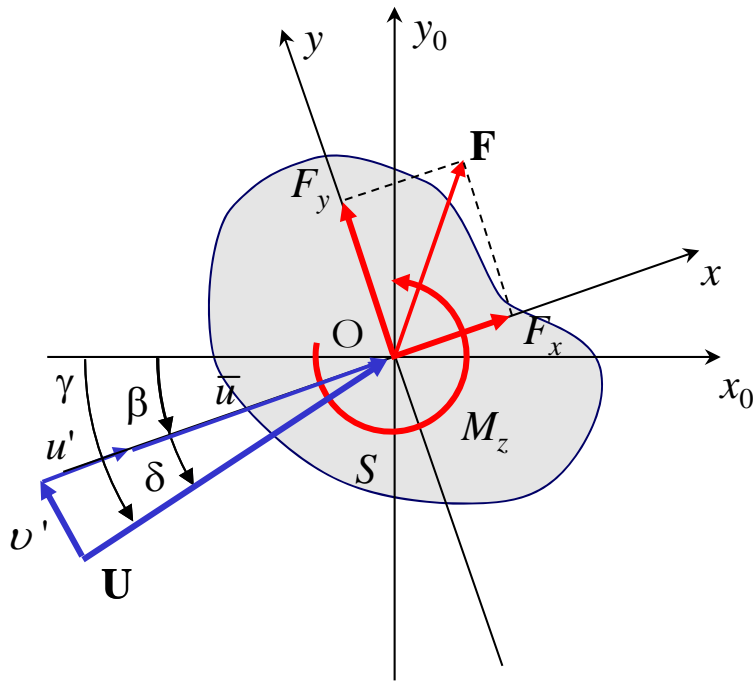
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$$M'_z(t) = \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

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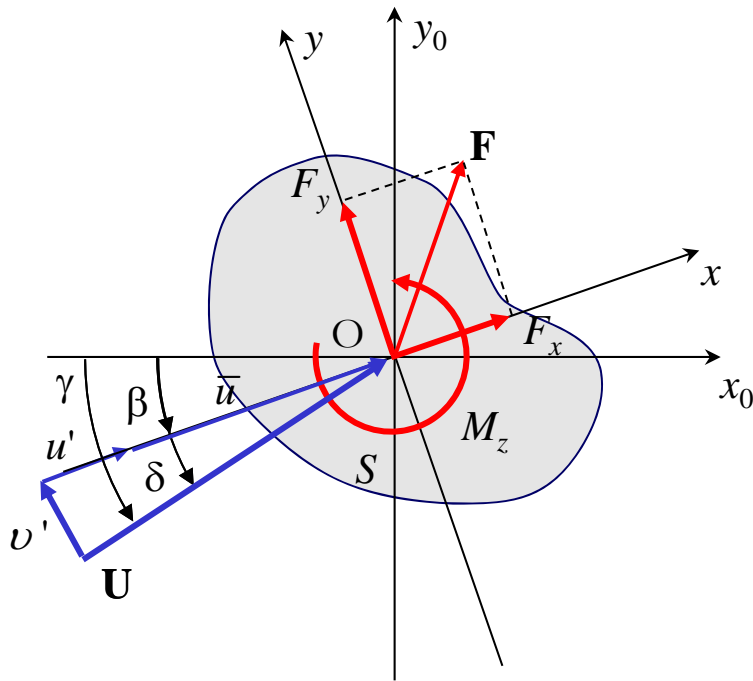
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Wind induced actions on slender cylinders



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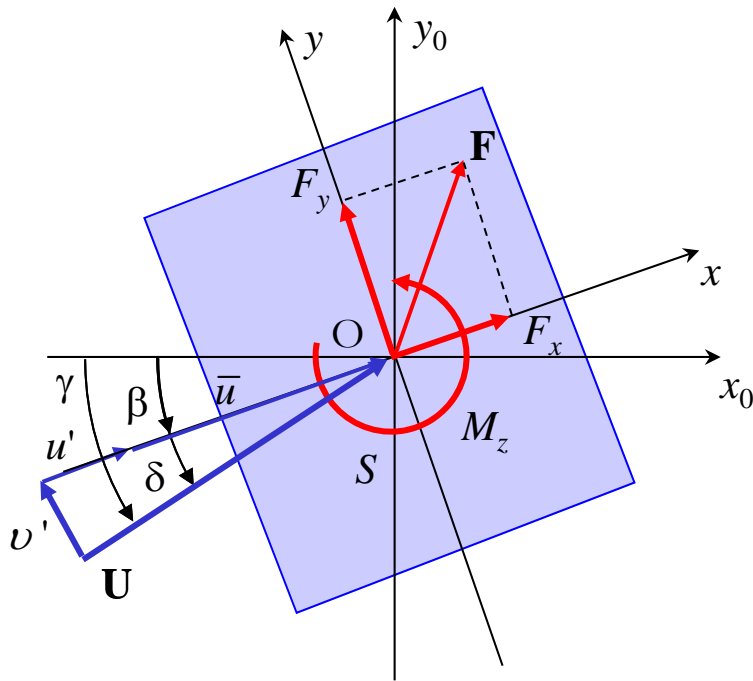
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Wind induced actions on slender cylinders



x = symmetry axis

$$c_l = c_m = c'_d = 0$$

$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

$$\bar{M}_z = \frac{1}{2} \rho \bar{u}^2 b^2 c_m$$

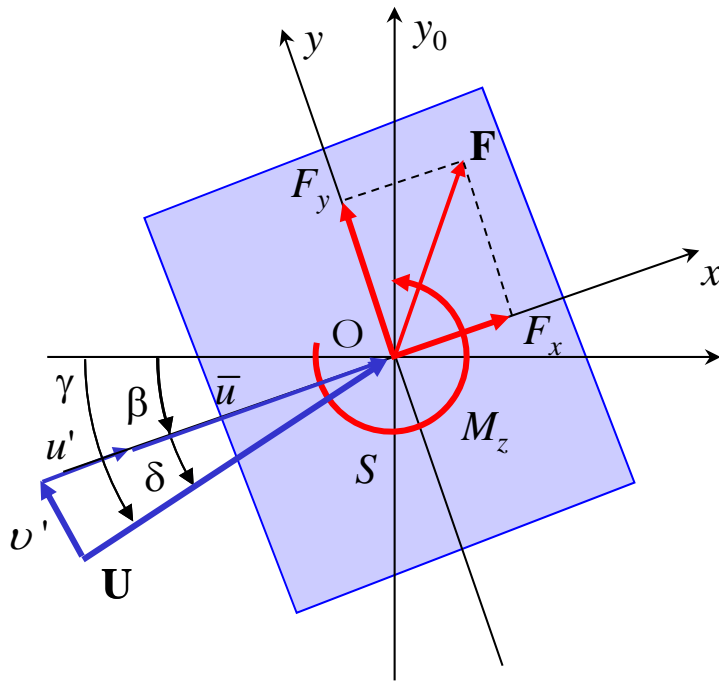
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Wind induced actions on slender cylinders



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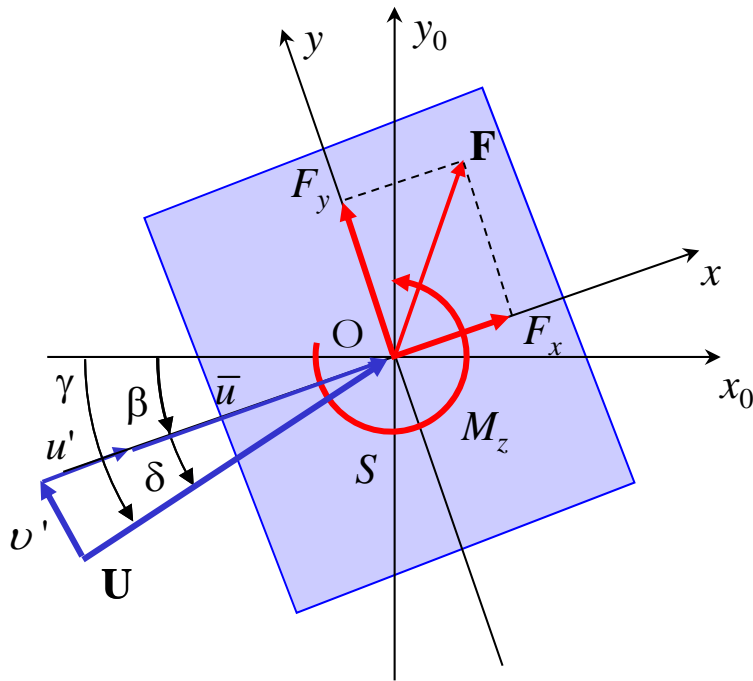
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Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = 0$$

$$\bar{M}_z = 0$$

Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

x = symmetry axis

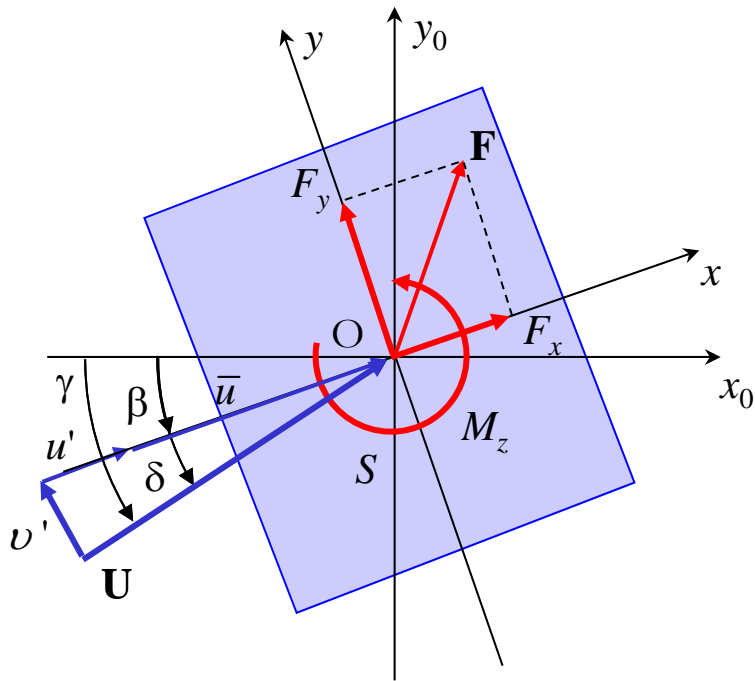
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Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = 0$$

$$\bar{M}_z = 0$$

Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

x = symmetry axis

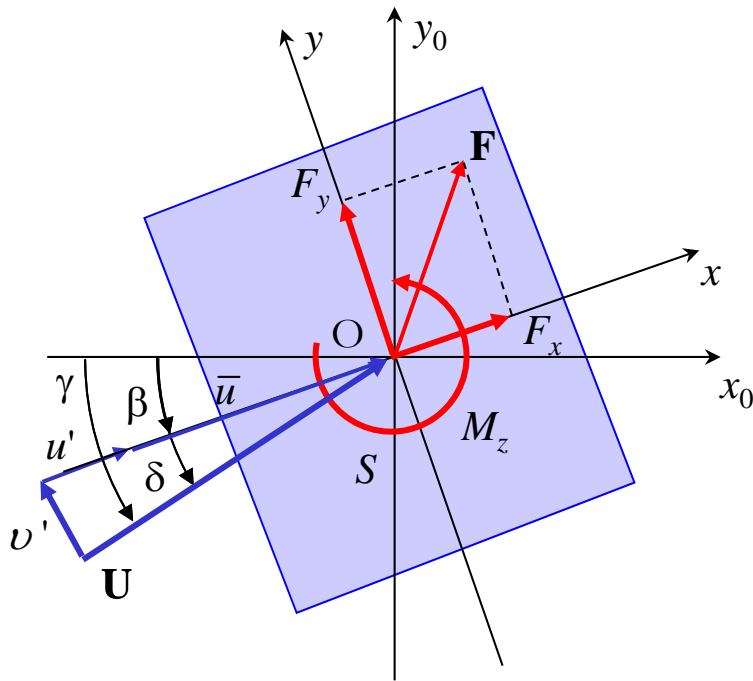
$$c_l = c_m = c'_d = 0$$

$$F'_x(t) = \rho \bar{u} b c_d u'(t)$$

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Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = 0$$

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Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

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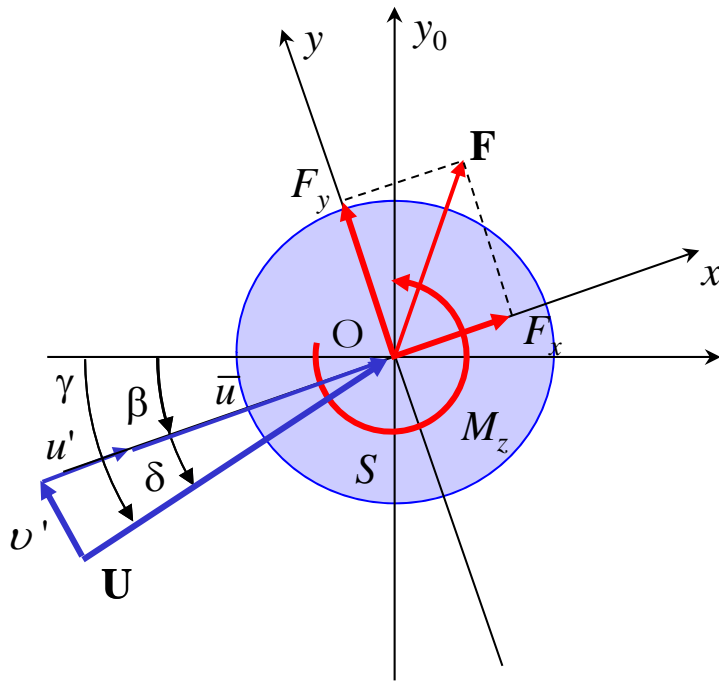
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Wind induced actions on slender cylinders



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Small turbulence, i.e. $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

polar symmetry

$$c_l = c_m = c'_d = 0$$

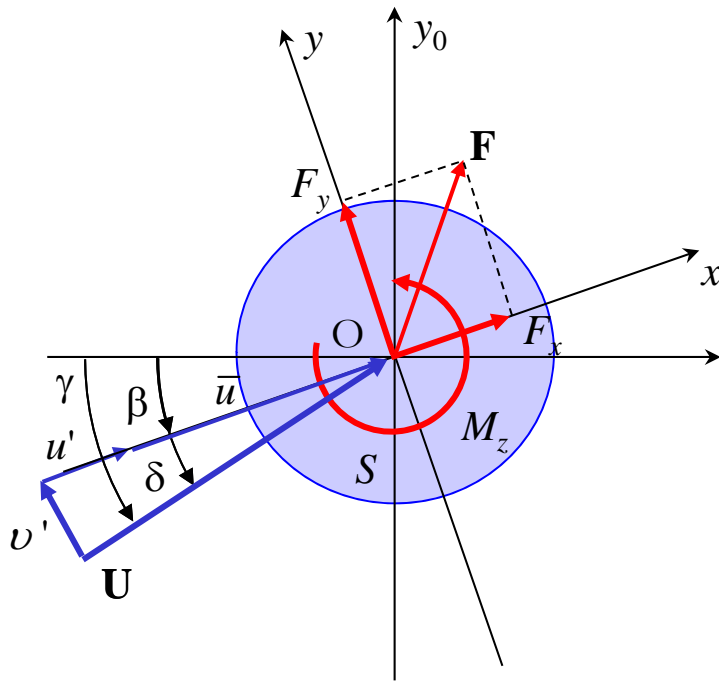
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Wind induced actions on slender cylinders



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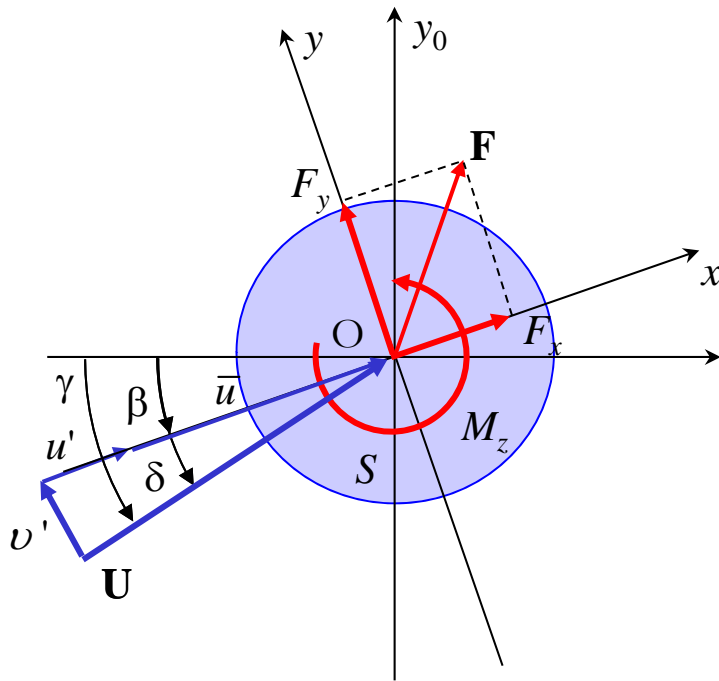
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$$F'_y(t) = \frac{1}{2} \rho \bar{u} b (c_d + \cancel{c'_d}) v'(t)$$

$$M'_z(t) = \frac{1}{2} \rho \bar{u} b^2 \cancel{c'_m} v'(t)$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

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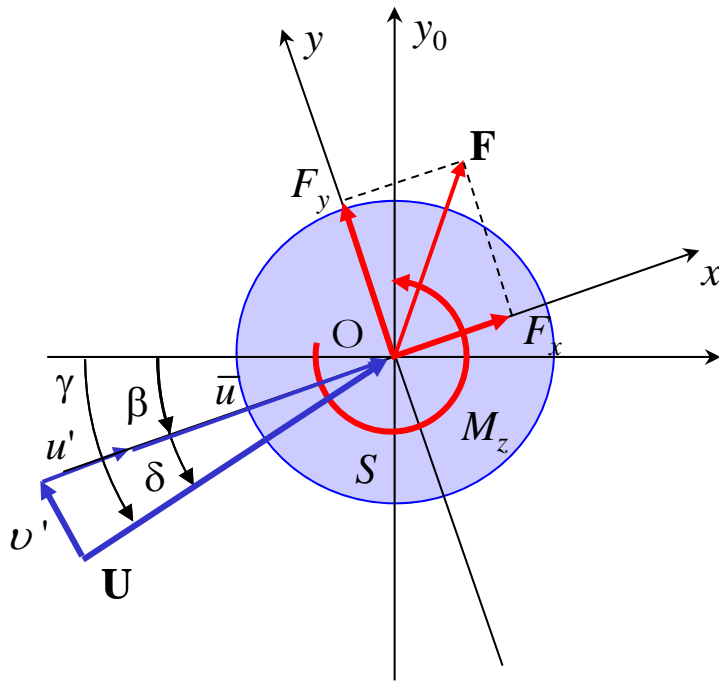
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Wind induced actions on slender cylinders



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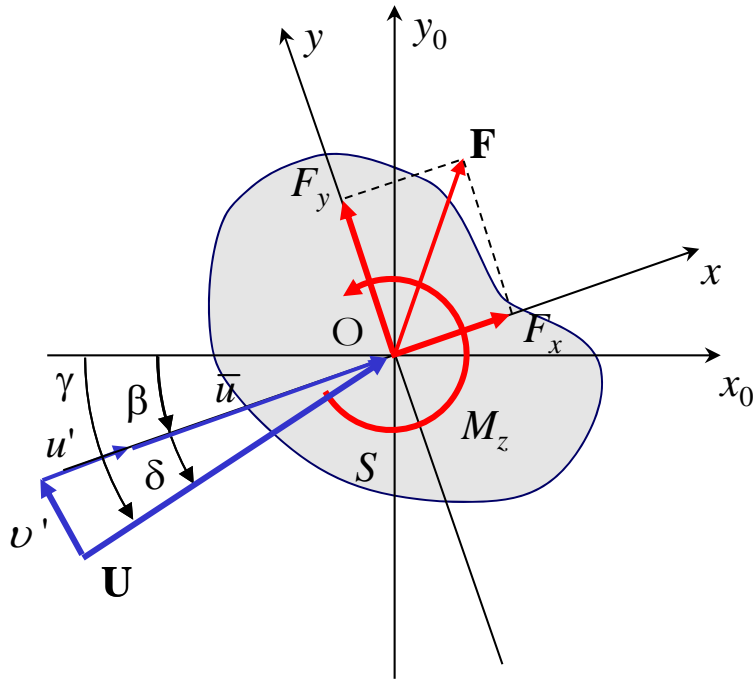
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Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

$$\bar{M}_z = \frac{1}{2} \rho \bar{u}^2 b^2 c_m$$

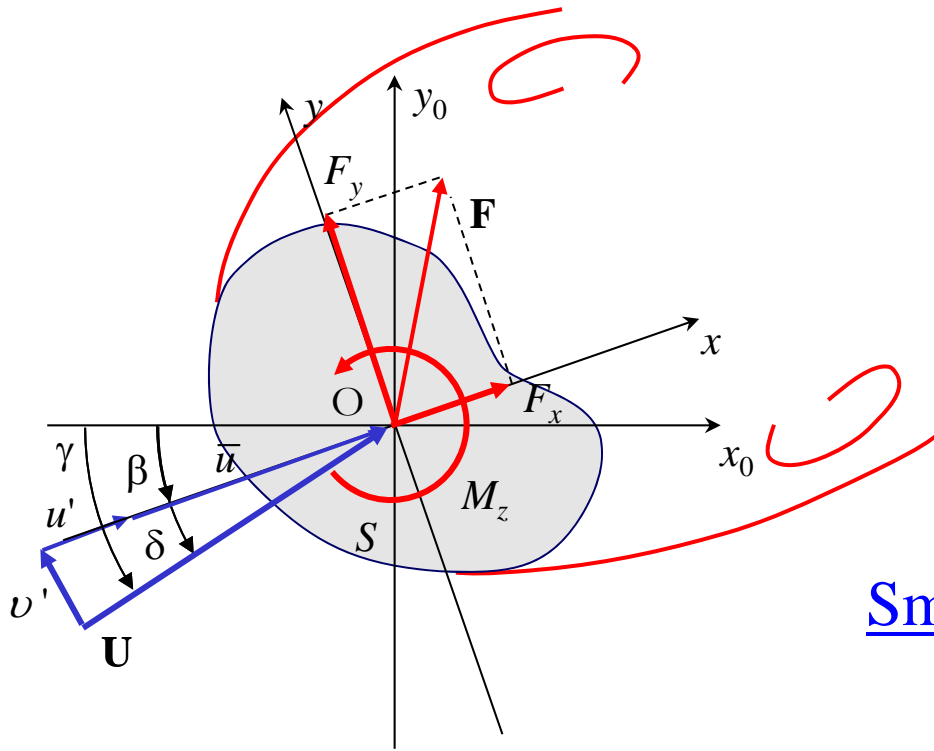
Small turbulence: $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

$$F'_x(t) = \rho \bar{u} b c_d u'(t) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) v'(t)$$

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$$M'_z(t) = \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$

Wind induced actions on slender cylinders



$$\bar{F}_x = \frac{1}{2} \rho \bar{u}^2 b c_d$$

$$\bar{F}_y = \frac{1}{2} \rho \bar{u}^2 b c_l$$

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Small turbulence: $u' / \bar{u} \ll 1, v' / \bar{u} \ll 1$

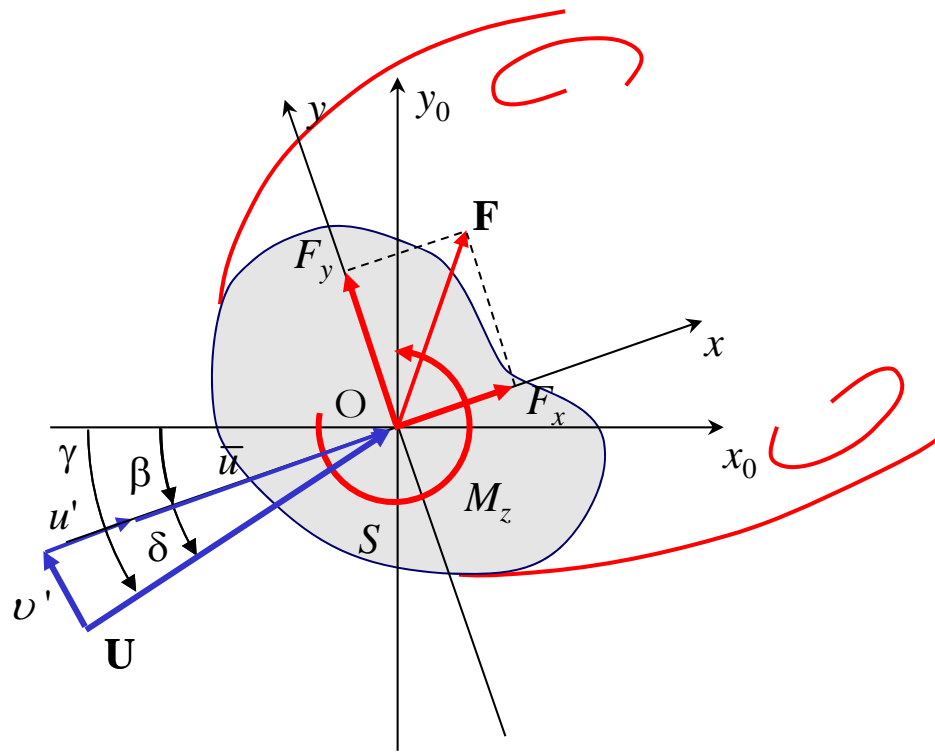
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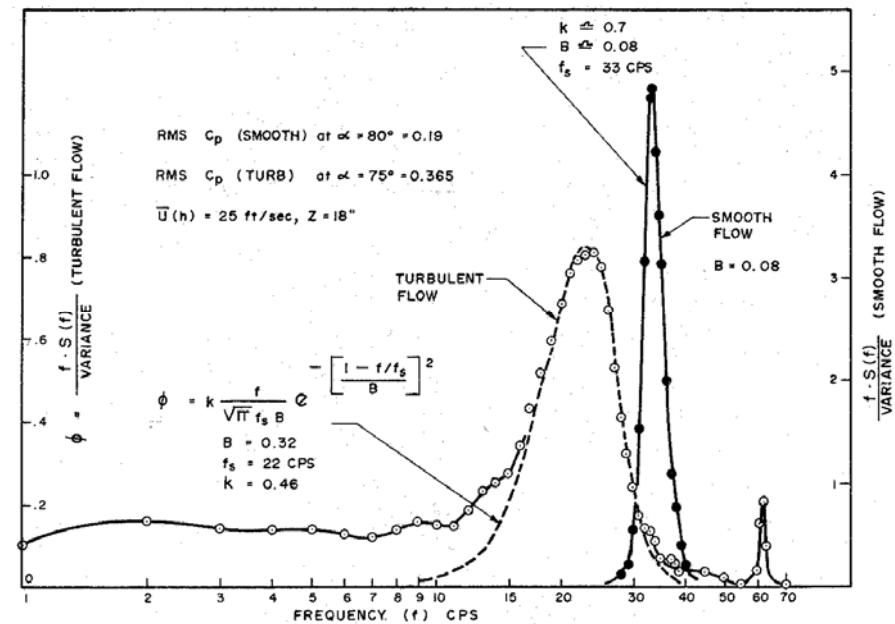
$$M'_z(t) = \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$



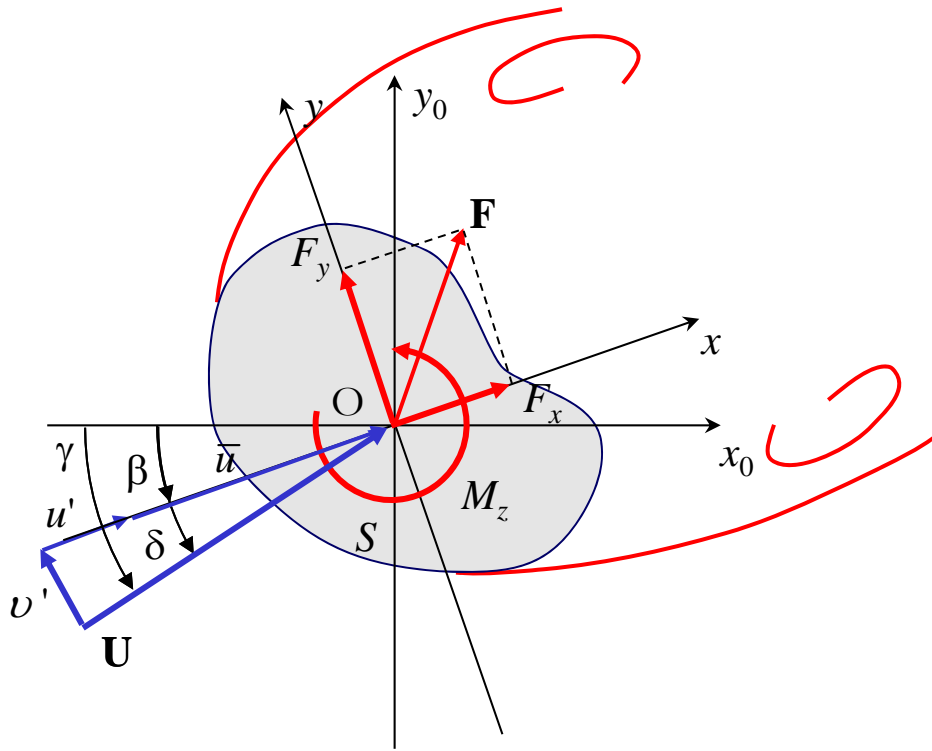
Wind induced actions on slender cylinders



Vickery & Clark (1972)



Wind induced actions on slender cylinders



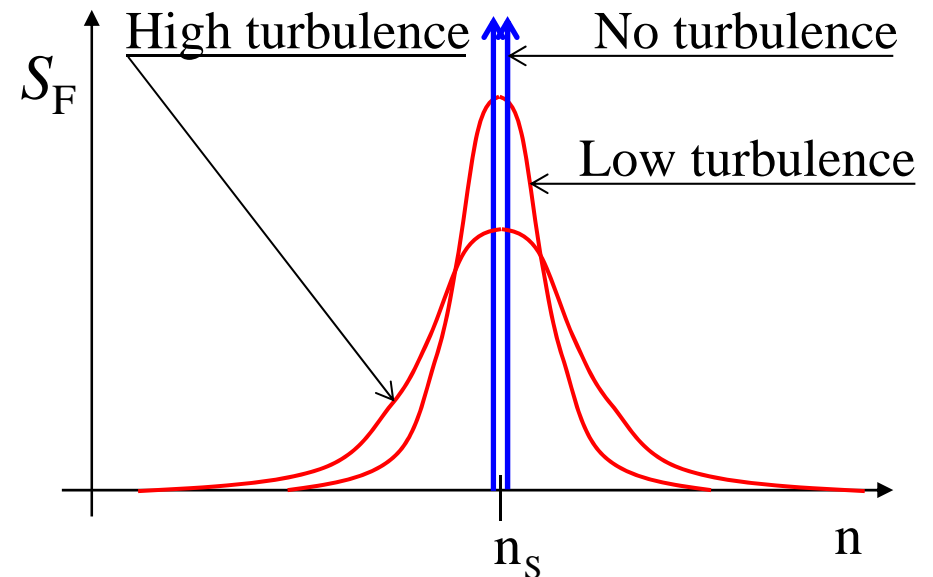
Vickery & Clark (1972)

$$\frac{nS(n)}{\tilde{C}_L^2} = \frac{n}{\sqrt{\pi}\beta n_s} \exp \left\{ - \left[\frac{1 - \frac{n}{n_s}}{\beta} \right]^2 \right\}$$

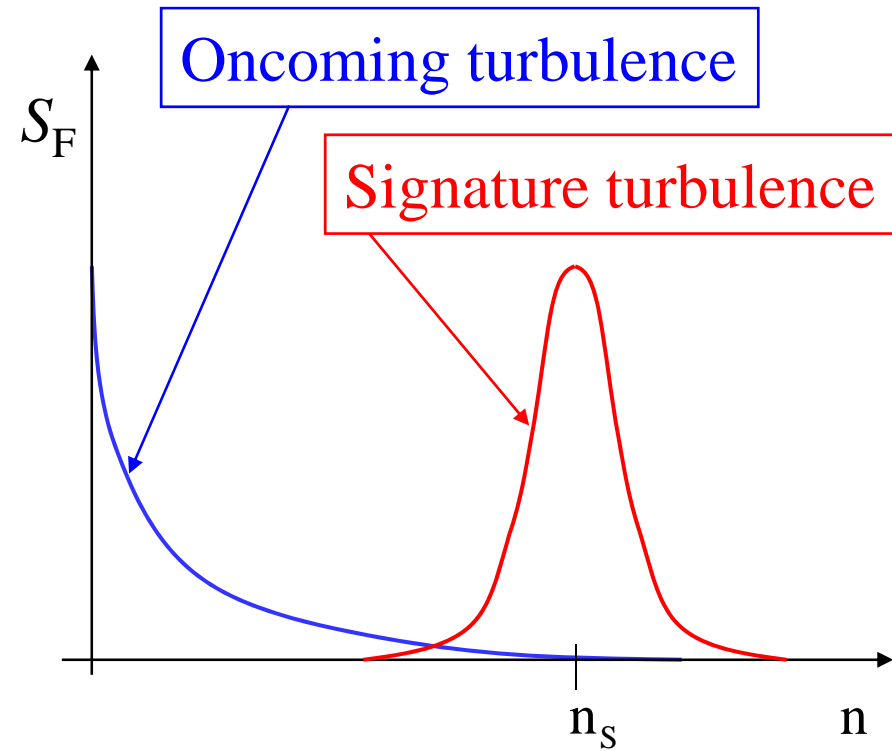
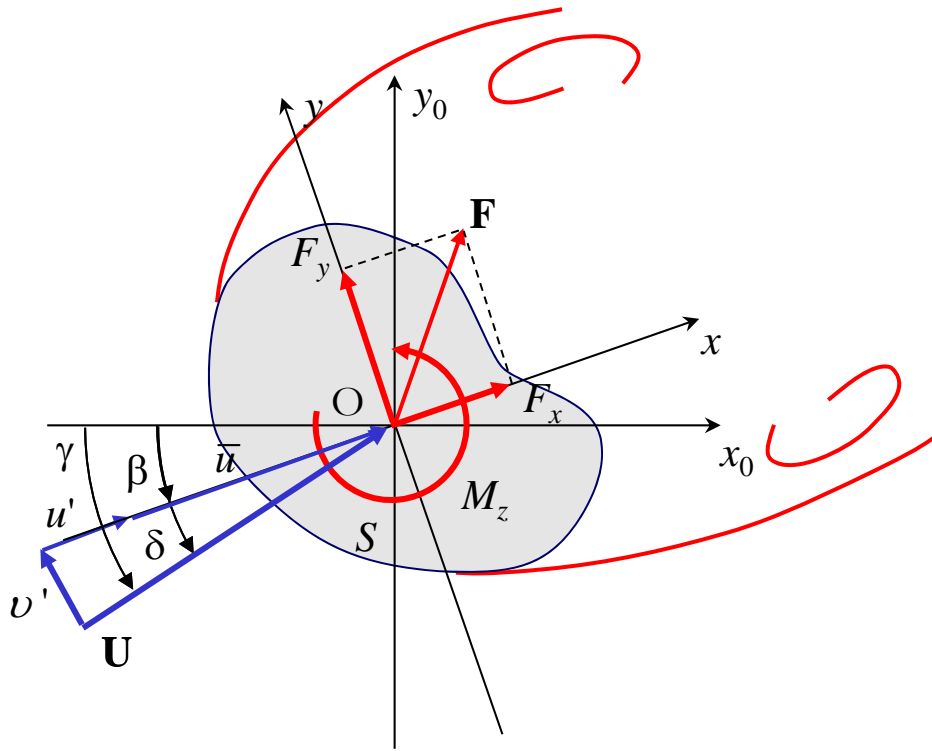
Shedding frequency

$$n_s = \frac{\bar{u}S}{b}$$

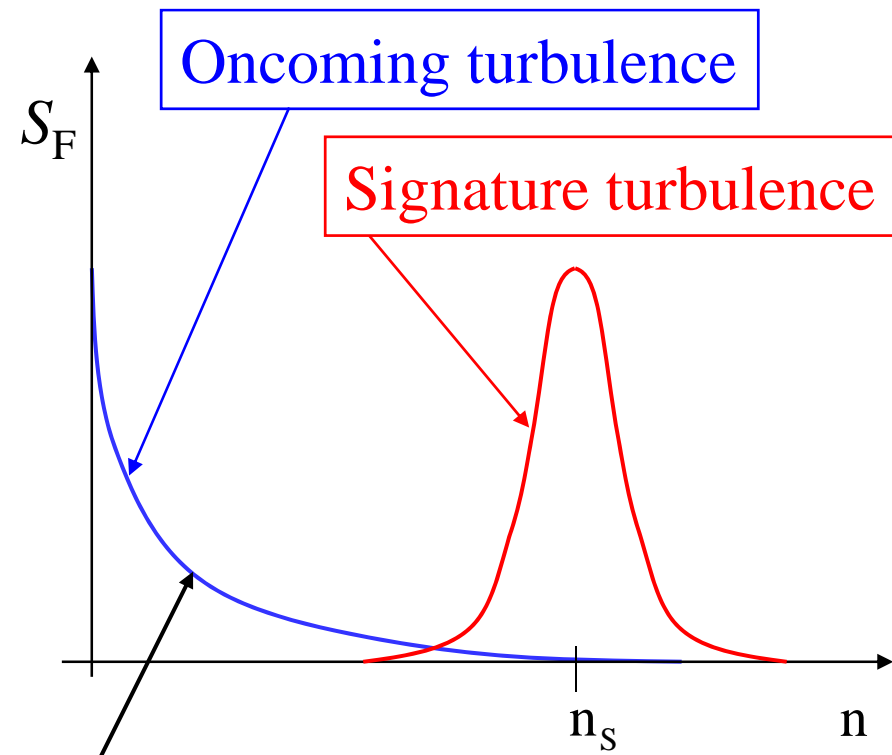
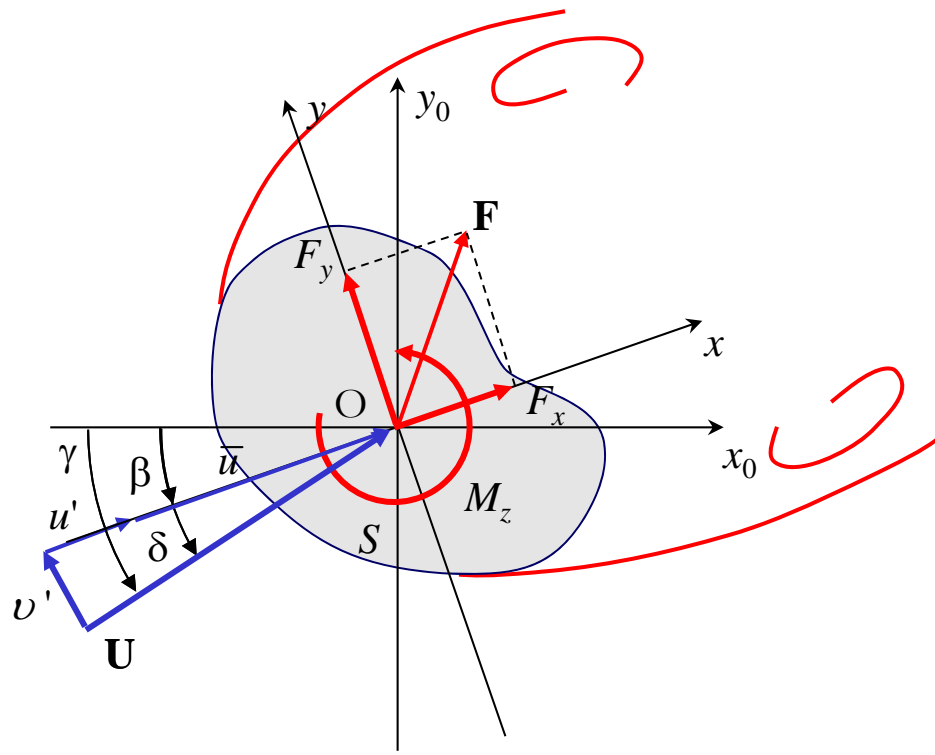
Strouhal number



Wind induced actions on slender cylinders

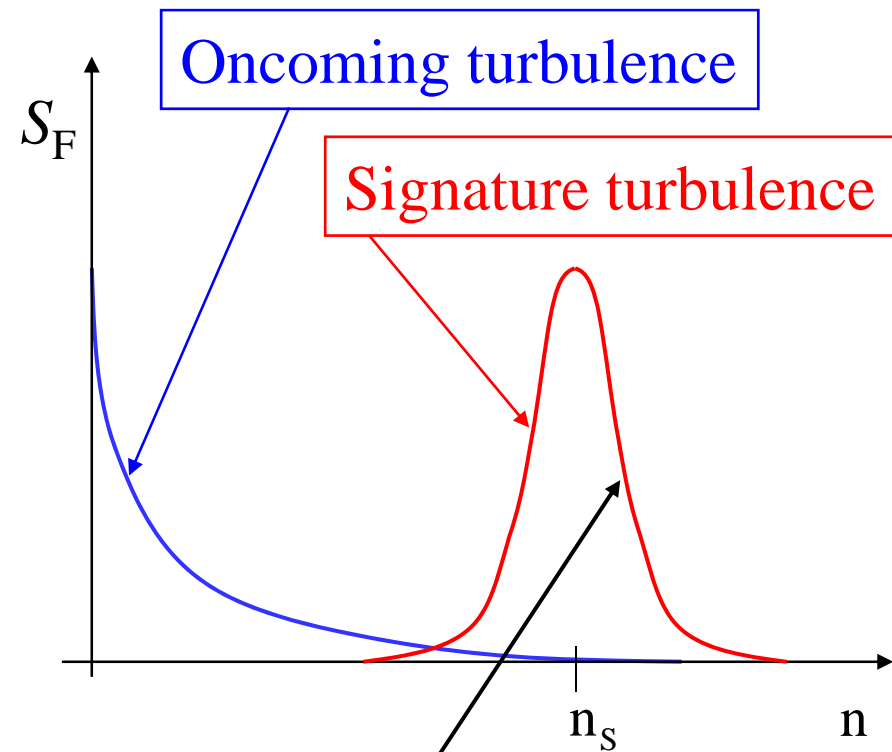
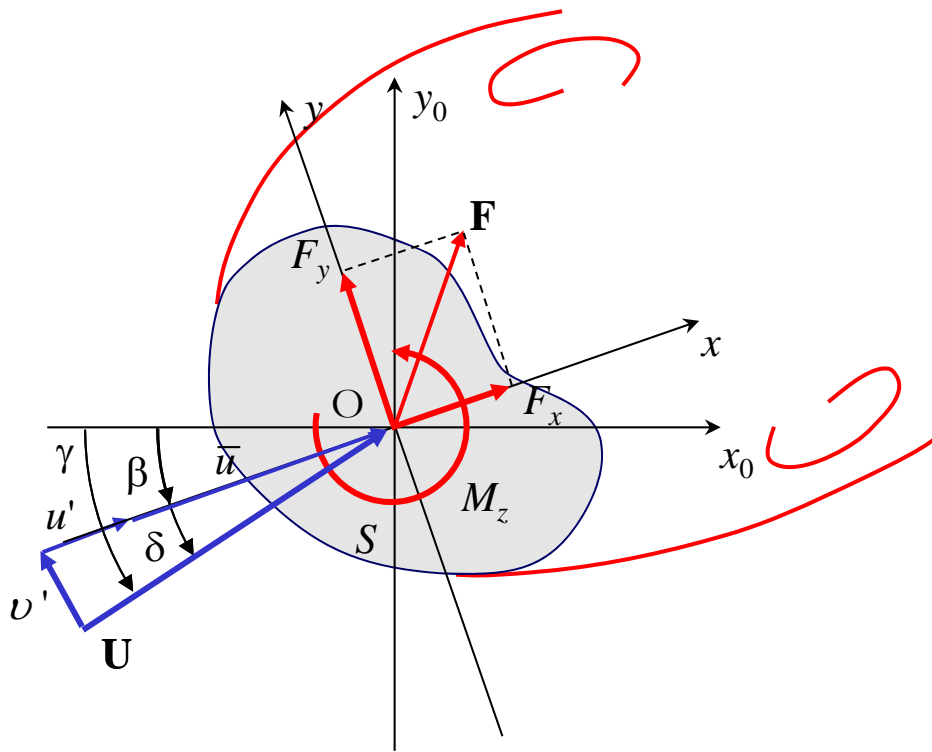


Wind induced actions on slender cylinders



$$\begin{aligned}
 F'_x(t) &= \rho \bar{u} b c_d u'(t) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) v'(t) & + \frac{1}{2} \rho \bar{u}^2 b \tilde{c}_{ds} s_x^*(t) \\
 F'_y(t) &= \rho \bar{u} b c_l u'(t) + \frac{1}{2} \rho \bar{u} b (c_d + c'_l) v'(t) & + \frac{1}{2} \rho \bar{u}^2 b \tilde{c}_{ls} s_y^*(t) \\
 M'_z(t) &= \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t) & + \frac{1}{2} \rho \bar{u}^2 b^2 \tilde{c}_{ms} s_z^*(t)
 \end{aligned}$$

Wind induced actions on slender cylinders



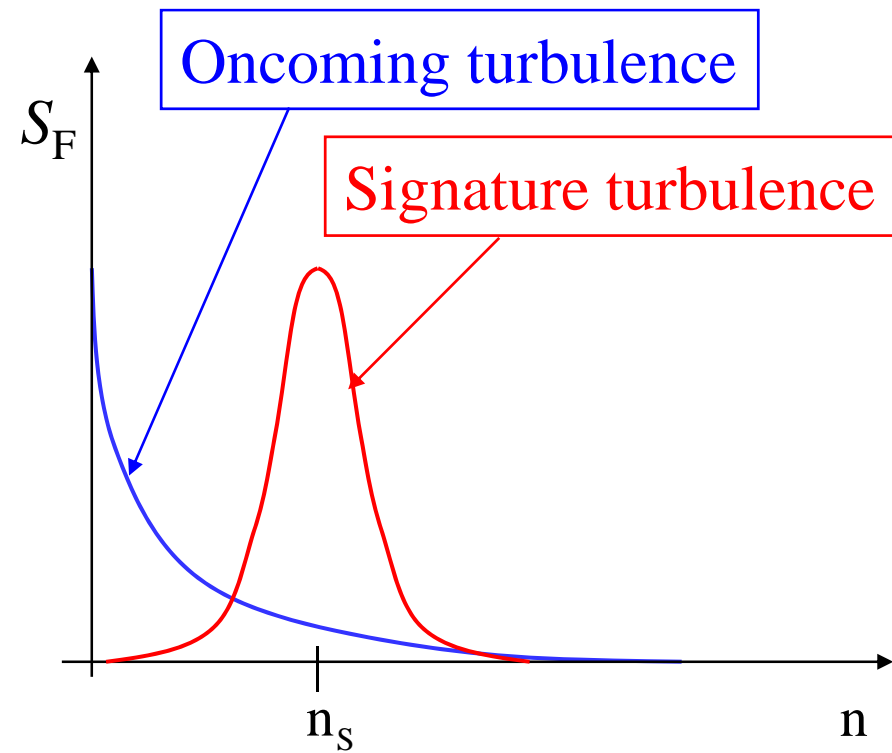
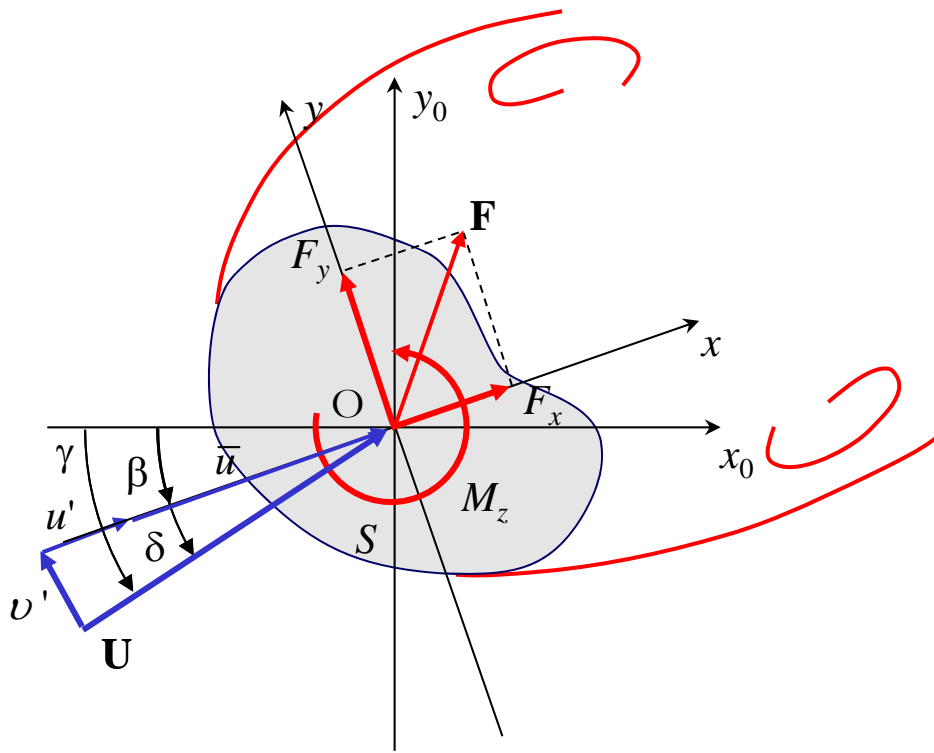
$$F'_x(t) = \rho \bar{u} b c_d u'(t) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) v'(t)$$

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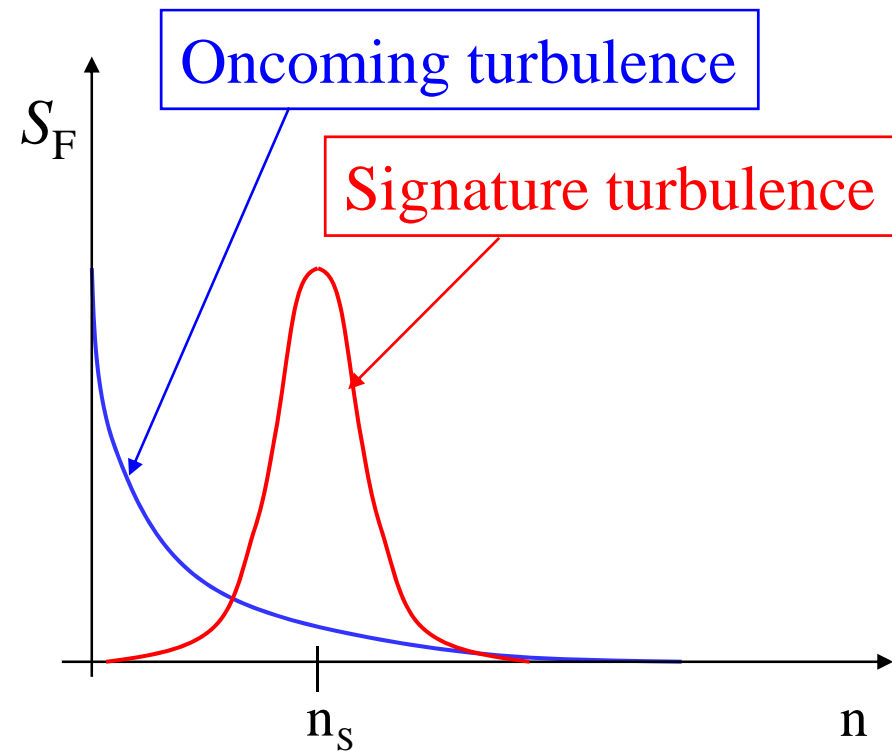
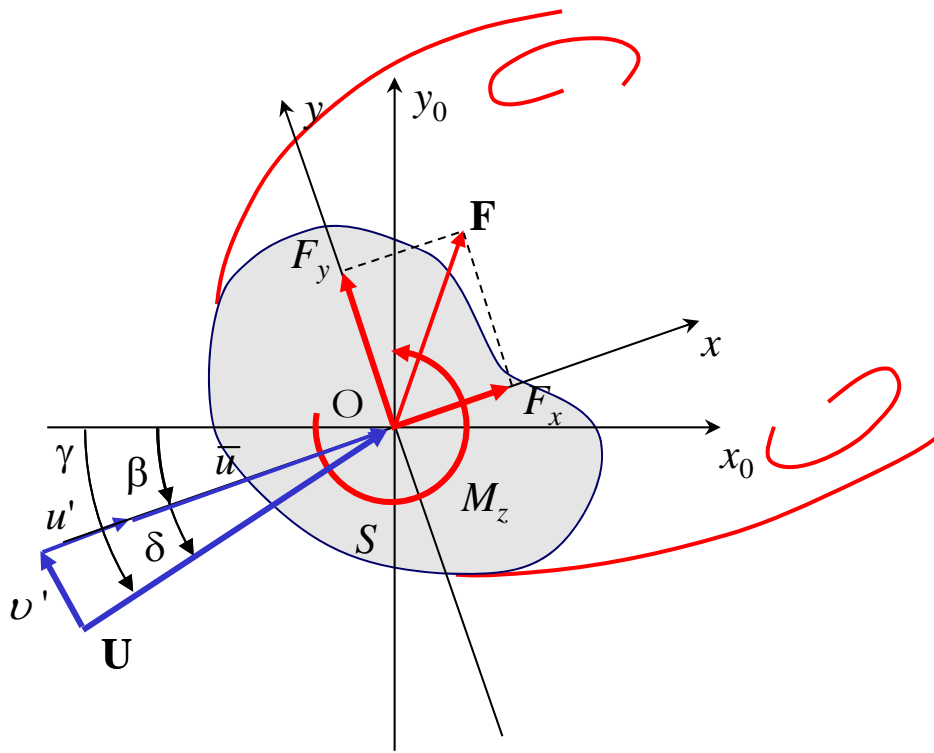
$$M'_z(t) = \rho \bar{u} b^2 c_m u'(t) + \frac{1}{2} \rho \bar{u} b^2 c'_m v'(t)$$

$$\begin{aligned} & + \frac{1}{2} \rho \bar{u}^2 b \tilde{c}_{ds} s_x^*(t) \\ & + \frac{1}{2} \rho \bar{u}^2 b \tilde{c}_{ls} s_y^*(t) \\ & + \frac{1}{2} \rho \bar{u}^2 b^2 \tilde{c}_{ms} s_z^*(t) \end{aligned}$$

Wind induced actions on slender cylinders



Wind induced actions on slender cylinders

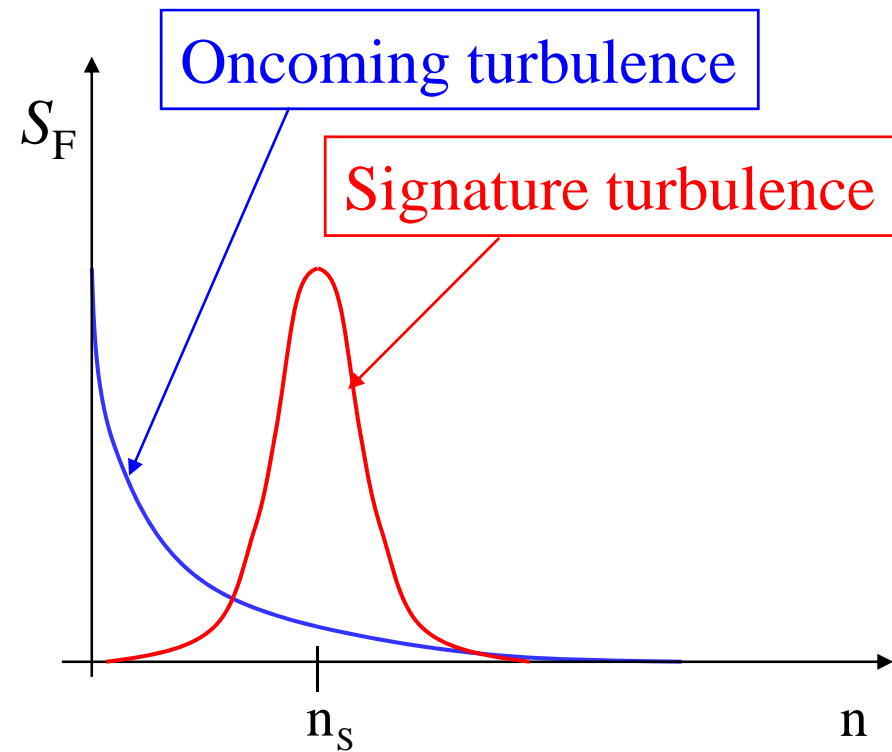
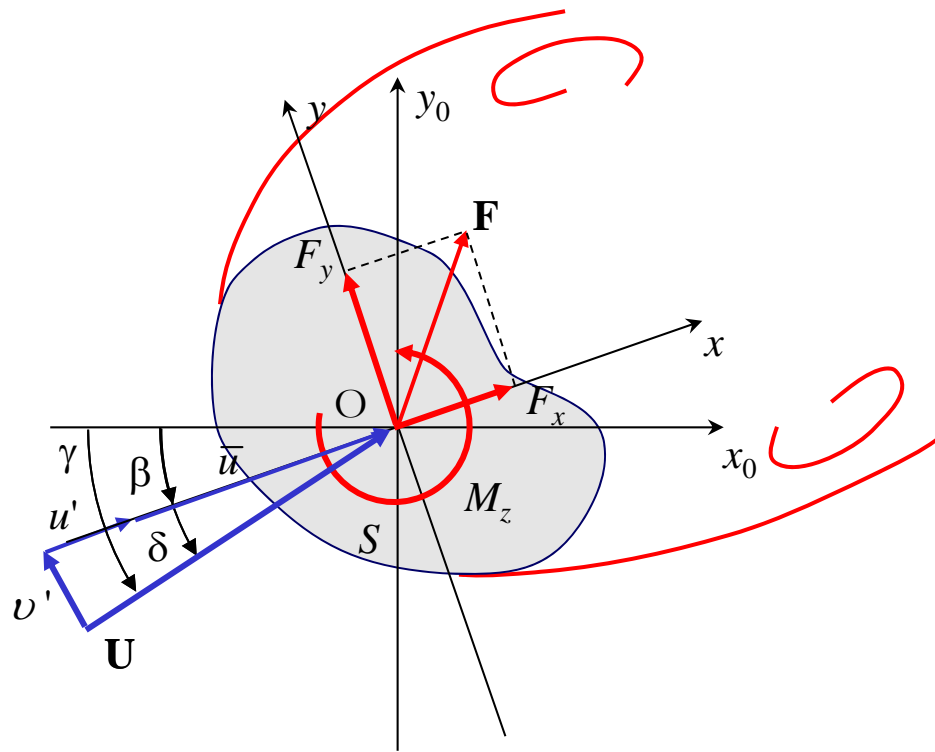


$$\tilde{F}'_x(n) = \rho \bar{u} b c_d \tilde{u}'(n) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) \tilde{v}'(n)$$

$$\tilde{F}'_y(n) = \rho \bar{u} b c_l \tilde{u}'(n) + \frac{1}{2} \rho \bar{u} b (c_d + c'_l) \tilde{v}'(n)$$

$$\tilde{M}'_z(n) = \rho \bar{u} b^2 c_m \tilde{u}'(n) + \frac{1}{2} \rho \bar{u} b^2 c'_m \tilde{v}'(n)$$

Wind induced actions on slender cylinders



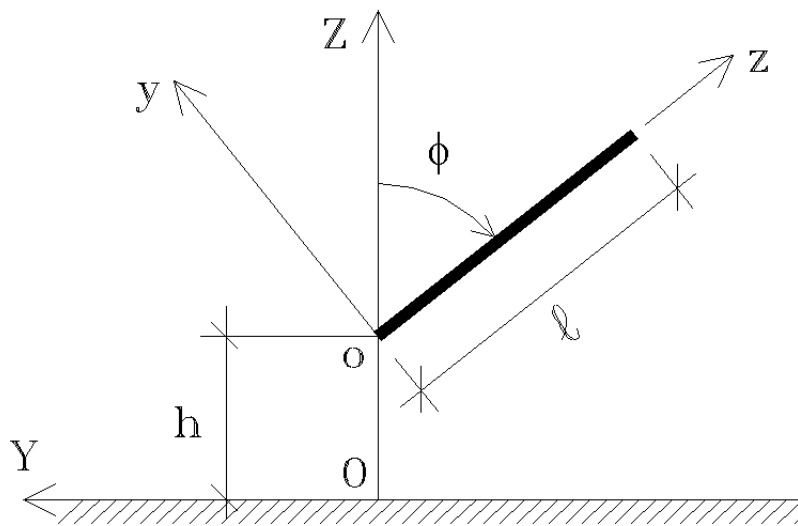
$$\tilde{F}'_x(n) = \rho \bar{u} b c_d \tilde{u}'(n) \chi_{xu}(n) + \frac{1}{2} \rho \bar{u} b (c'_d - c_l) \tilde{v}'(n) \chi_{xv}(n)$$

$$\tilde{F}'_y(n) = \rho \bar{u} b c_l \tilde{u}'(n) \chi_{yu}(n) + \frac{1}{2} \rho \bar{u} b (c_d + c'_l) \tilde{v}'(n) \chi_{yv}(n)$$

$$\tilde{M}'_z(n) = \rho \bar{u} b^2 c_m \tilde{u}'(n) \chi_{zu}(n) + \frac{1}{2} \rho \bar{u} b^2 c'_m \tilde{v}'(n) \chi_{zv}(n)$$

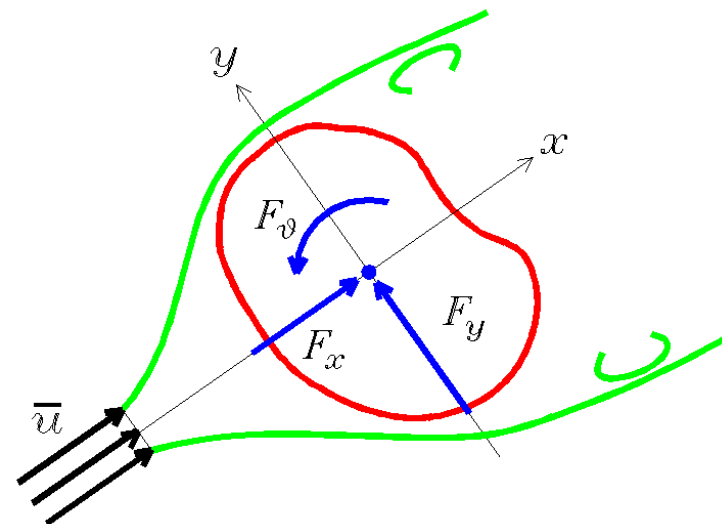
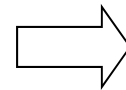
3-D WIND-EXCITED RESPONSE **OF SLENDER STRUCTURES AND STRUCTURAL ELEMENTS**

Solari (1993), Piccardo & Solari (1996 - 2000)



EXCITING MECHANISMS

u = longitudinal turbulence
 v = lateral turbulence
 w = vertical turbulence
 s = vortex shedding



3-D RESPONSE

x = alongwind response
 y = crosswind response
 ϑ = torsional response

GUST RESPONSE FACTOR

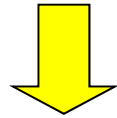
Alongwind response

$$\begin{aligned}\bar{X}_{\max} &= G_x \bar{X} \\ F_{x,es} &= G_x \bar{F}_x \\ G_x &= 1 + g_x \frac{\sigma_x}{\bar{X}}\end{aligned}$$

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

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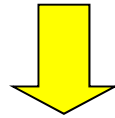
3-D response ($\alpha=x,y,\vartheta$)

$$\begin{aligned}\bar{\alpha}_{\max} &= G_{\alpha} \bar{\alpha} \\ F_{\alpha,es} &= G_{\alpha} \lambda_{\alpha} \bar{F}_{\alpha} \\ G_{\alpha} &= 1 + g_{\alpha} \frac{\sigma_{\alpha}}{\bar{\alpha}}\end{aligned}$$

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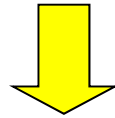
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$$\lambda_x = \lambda_y = 1; \lambda_\vartheta = b$$

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

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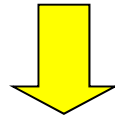
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$\bar{\alpha}$ may be equal to zero

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

Alongwind response

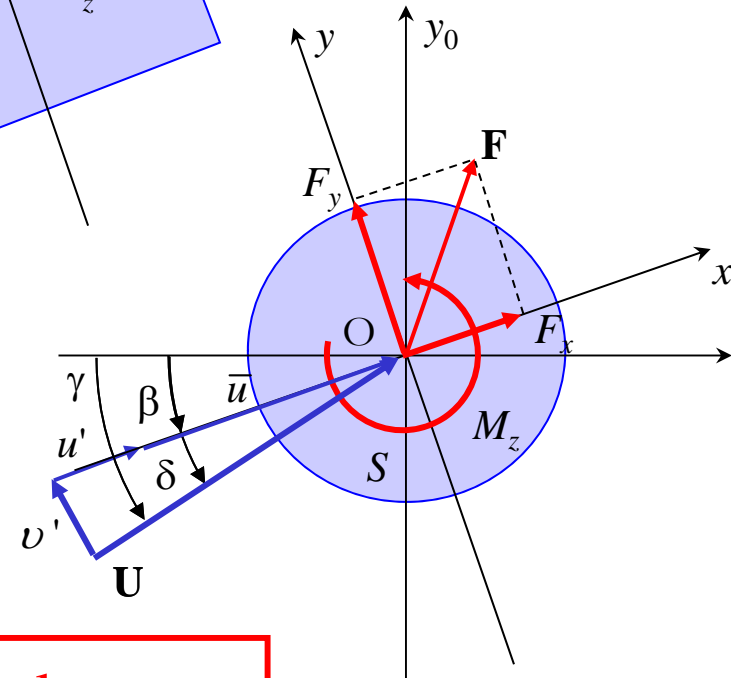
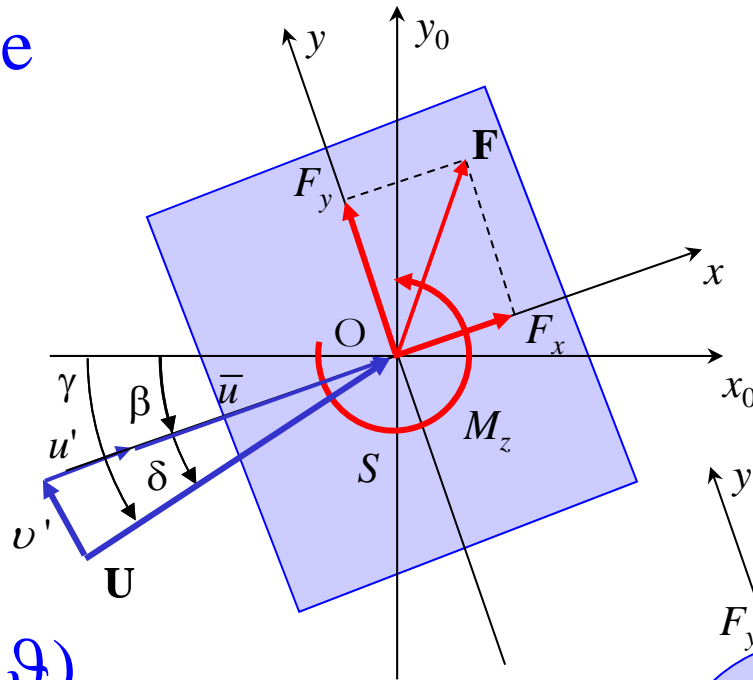
$$\begin{aligned}\bar{X}_{\max} &= G_x \bar{X} \\ F_{x,es} &= G_x \bar{F}_x \\ G_x &= 1 + g_x \frac{\sigma_x}{\bar{X}}\end{aligned}$$



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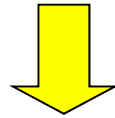


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3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

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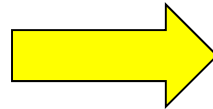
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3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

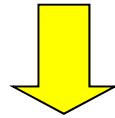
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3-D response ($\alpha=x,y,\vartheta$)

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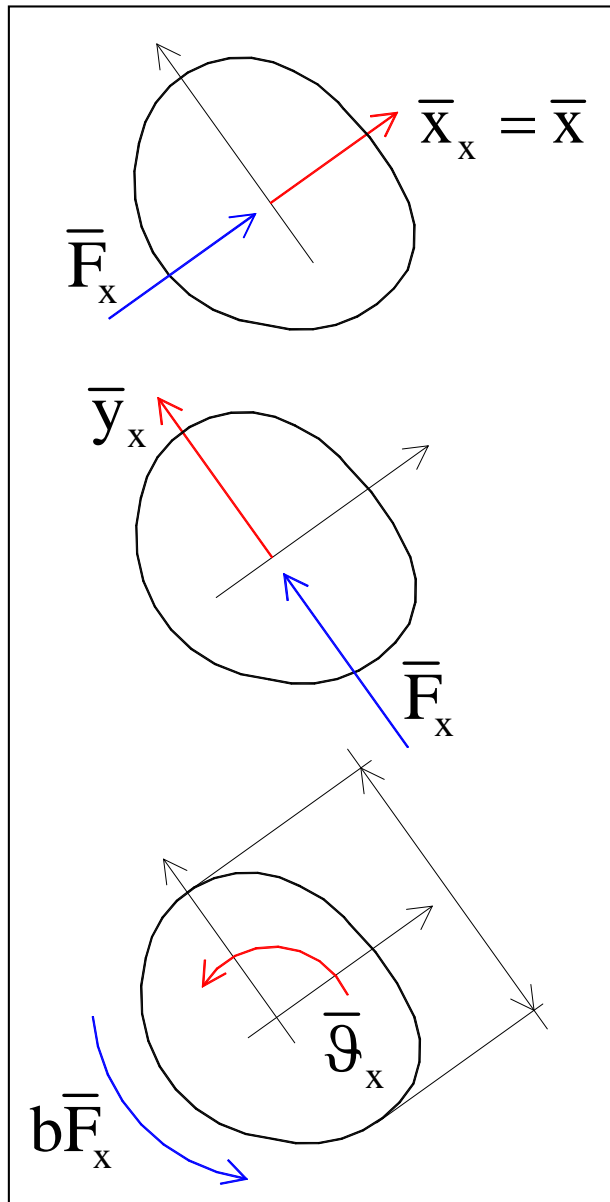
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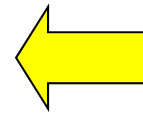
$\bar{\alpha}_x$ = generalised displacement
produced applying $\lambda_{\alpha} \bar{F}_x$
in α direction

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)



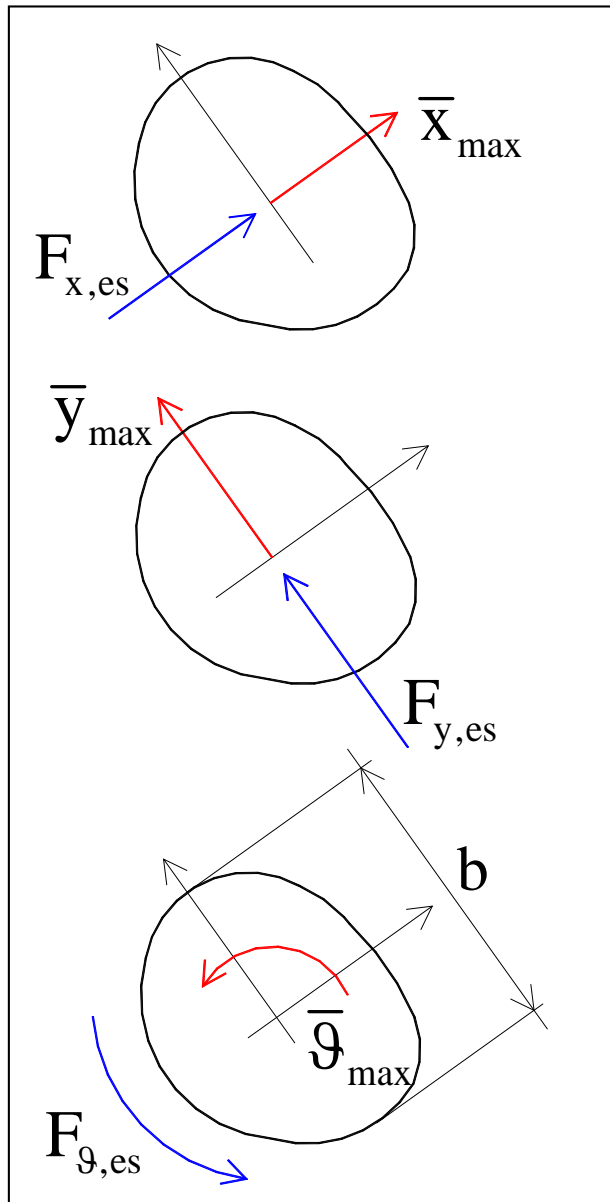
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3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)



3-D response ($\alpha=x,y,\vartheta$)

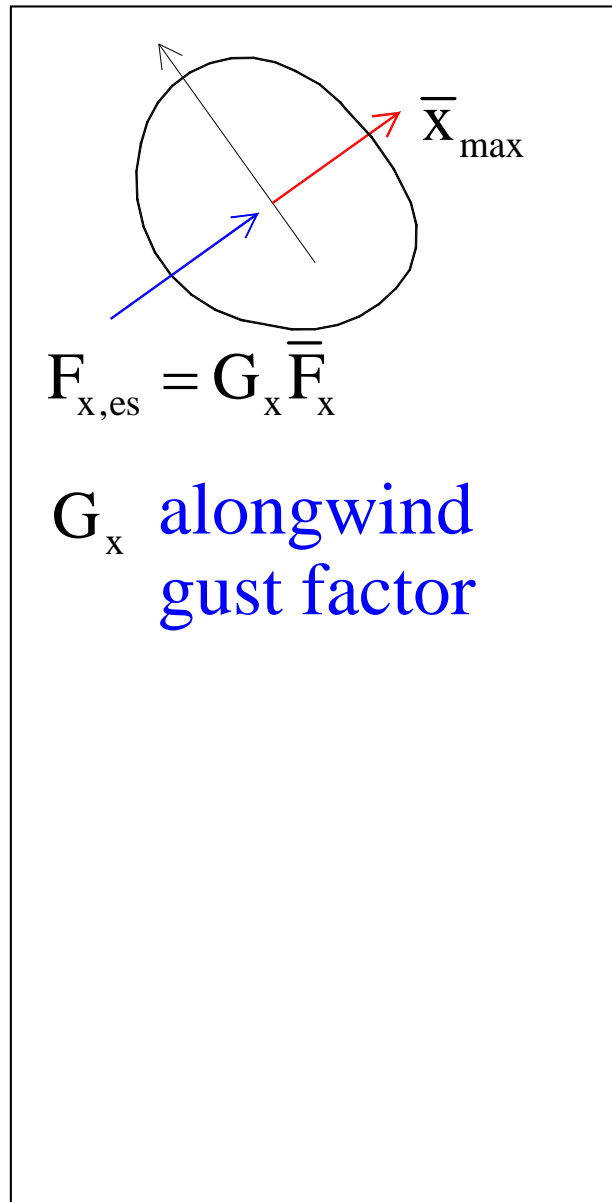
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$\bar{\alpha}_x$ = generalised displacement
produced applying $\lambda_{\alpha} \bar{\mathbf{F}}_x$
in α direction

3-D equivalent static forces

$$\begin{aligned}F_{x,es} &= G_x \bar{\mathbf{F}}_x \\ F_{y,es} &= G_y \bar{\mathbf{F}}_x \\ F_{\vartheta,es} &= G_{\vartheta} b \bar{\mathbf{F}}_x\end{aligned}$$

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)



3-D response ($\alpha=x,y,\vartheta$)

$$\bar{\alpha}_{\max} = G_{\alpha} \bar{\alpha}_x$$

$$F_{\alpha,es} = G_{\alpha} \lambda_{\alpha} \bar{F}_x$$

$$G_{\alpha} = \frac{\bar{\alpha}}{\bar{\alpha}_x} + g_{\alpha} \frac{\sigma_{\alpha}}{\bar{\alpha}_x}$$

$\bar{\alpha}_x$ = generalised displacement
produced applying $\lambda_{\alpha} \bar{F}_x$
in α direction

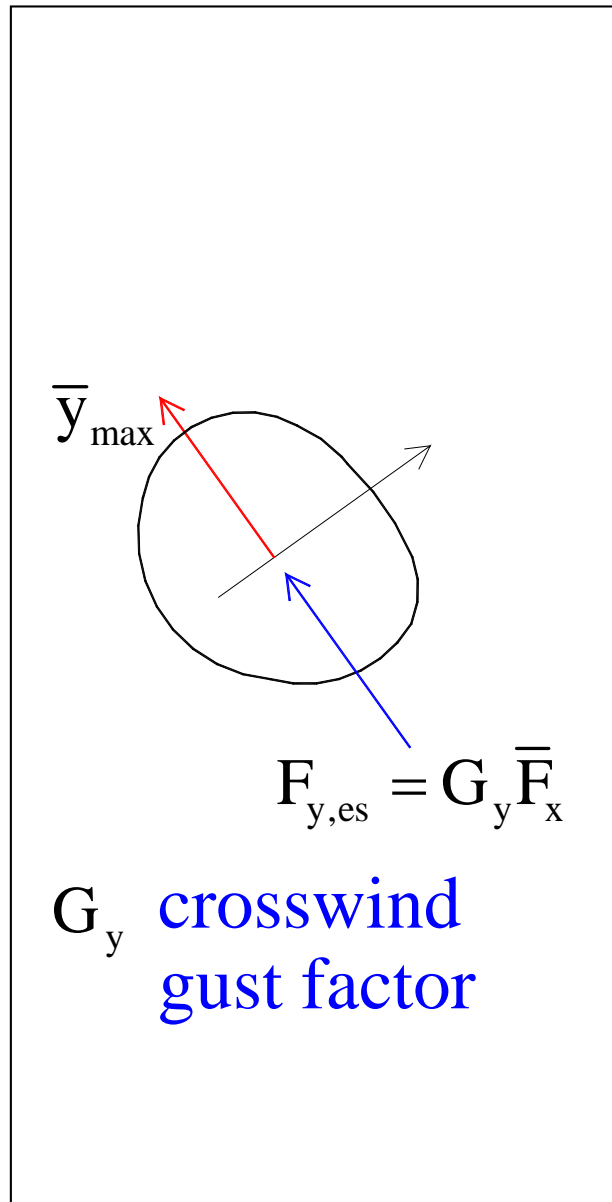
3-D equivalent static forces

$$F_{x,es} = G_x \bar{F}_x$$

$$F_{y,es} = G_y \bar{F}_x$$

$$F_{\vartheta,es} = G_{\vartheta} b \bar{F}_x$$

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)



3-D response ($\alpha=x,y,\vartheta$)

$$\begin{aligned}\bar{\alpha}_{\max} &= G_{\alpha} \bar{\alpha}_x \\ F_{\alpha,es} &= G_{\alpha} \lambda_{\alpha} \bar{F}_x \\ G_{\alpha} &= \frac{\bar{\alpha}}{\bar{\alpha}_x} + g_{\alpha} \frac{\sigma_{\alpha}}{\bar{\alpha}_x}\end{aligned}$$

$\bar{\alpha}_x$ = generalised displacement
produced applying $\lambda_{\alpha} \bar{F}_x$
in α direction

3-D equivalent static forces

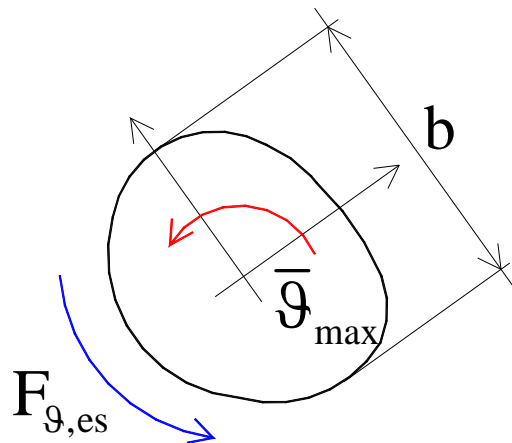
$$\begin{aligned}F_{x,es} &= G_x \bar{F}_x \\ F_{y,es} &= G_y \bar{F}_x \\ F_{\vartheta,es} &= G_{\vartheta} b \bar{F}_x\end{aligned}$$

3-D GUST RESPONSE FACTOR (Piccardo & Solari 1998)

$$F_{\vartheta,es} = G_{\vartheta} b \bar{F}_x$$

G_{ϑ} torsional
gust factor

$G_{\vartheta} b$ = equivalent
eccentricity of \bar{F}_x



3-D response ($\alpha=x,y,\vartheta$)

$$\bar{\alpha}_{\max} = G_{\alpha} \bar{\alpha}_x$$

$$F_{\alpha,es} = G_{\alpha} \lambda_{\alpha} \bar{F}_x$$

$$G_{\alpha} = \frac{\bar{\alpha}}{\bar{\alpha}_x} + g_{\alpha} \frac{\sigma_{\alpha}}{\bar{\alpha}_x}$$

$\bar{\alpha}_x$ = generalised displacement
produced applying $\lambda_{\alpha} \bar{F}_x$
in α direction

3-D equivalent static forces

$$F_{x,es} = G_x \bar{F}_x$$

$$F_{y,es} = G_y \bar{F}_x$$

$$F_{\vartheta,es} = G_{\vartheta} b \bar{F}_x$$

GUST RESPONSE FACTOR

$$\bar{X}_{\max} = G_x \bar{X}$$

$$G_x = 1 + 2g_x I_u \sqrt{B_x^2 + R_x^2}$$

3-D GUST RESPONSE FACTOR

$$\bar{\alpha}_{\max} = G_\alpha \bar{\alpha}_x$$

$$G_\alpha = \mu_\alpha + 2g_\alpha I_u \sqrt{B_\alpha^2 + R_\alpha^2}$$

3-D GUST RESPONSE FACTOR

$$\boxed{\bar{\alpha}_{\max} = G_{\alpha} \bar{\alpha}_x} \quad \boxed{G_{\alpha} = \mu_{\alpha} + 2g_{\alpha} I_u \sqrt{B_{\alpha}^2 + R_{\alpha}^2}}$$

Closed Form Solution (Piccardo & Solari, 1998, 2000)

$$\mu_{\alpha} = \frac{c_{\alpha u} \bar{K}_{\alpha\alpha}}{c_{xu} \bar{K}_{\alpha x}}; \quad B_{\alpha}^2 = \sum_{\varepsilon} \chi_{\alpha\varepsilon}^2 B_{\alpha\varepsilon}^2; \quad R_{\alpha}^2 = \sum_{\varepsilon} \chi_{\alpha\varepsilon}^2 R_{\alpha\varepsilon}^2; \quad \chi_{\alpha\varepsilon} = \frac{J_{\varepsilon}(\bar{z}) c_{\alpha\varepsilon} K'_{\alpha\varepsilon}}{2I_u c_{xu} \bar{K}_{\alpha x}} \quad (\varepsilon=u, v, w, s)$$

$$B_{\alpha\varepsilon}^2 = \frac{1}{1 + 0.56 \tilde{\tau}_{\alpha\varepsilon}^{0.74} + 0.30 \tilde{\ell}_{\alpha\varepsilon}^{0.63}}; \quad R_{\alpha\varepsilon}^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{d_u \tilde{n}_{\alpha\varepsilon}}{(1 + 1.5 d_u \tilde{n}_{\alpha\varepsilon})^{5/3}} C\{\tilde{n}_{\alpha\varepsilon} \tilde{\ell}_{\alpha\varepsilon}\} \quad (\varepsilon=u, v, w)$$

$$B_{\alpha s}^2 = C\{\tilde{\ell}_{\alpha s}\} F\{\tilde{n}_{\alpha s}\}; \quad R_{\alpha s}^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{\tilde{n}_{\alpha s}}{\sqrt{\pi\beta(z_{\alpha s})}} \exp\left\{-\left[\frac{1 - \tilde{n}_{\alpha s}}{\beta(z_{\alpha s})}\right]^2\right\} C\{\tilde{\ell}_{\alpha s}\}$$

$$\tilde{\tau}_{\alpha\varepsilon} = \frac{\tau d_u \bar{u}(z_{\alpha\varepsilon})}{d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}; \quad \tilde{\ell}_{\alpha\varepsilon} = \frac{k_{\alpha\varepsilon} d_u C_{r\varepsilon} \ell}{d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}; \quad \tilde{n}_{\alpha\varepsilon} = \frac{n_{\alpha 1} d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}{d_u \bar{u}(z_{\alpha\varepsilon})}; \quad \tilde{\ell}_{\alpha s} = \frac{k_{\alpha s} \ell}{Lb}; \quad \tilde{n}_{\alpha s} = \frac{n_{\alpha 1} b}{Y_{\alpha} S \bar{u}(z_{\alpha s})}$$

3-D GUST RESPONSE FACTOR

$$\bar{\alpha}_{\max} = G_{\alpha} \bar{\alpha}_x$$

$$G_{\alpha} = \mu_{\alpha} + 2g_{\alpha} I_u \sqrt{B_{\alpha}^2 + R_{\alpha}^2}$$

Closed Form Solution (Piccardo & Solari, 1998, 2000)

$$\mu_{\alpha} = \frac{c_{\alpha u} \bar{K}_{\alpha\alpha}}{c_{xu} \bar{K}_{\alpha x}}; \quad B_{\alpha}^2 = \sum_{\varepsilon} \chi_{\alpha\varepsilon}^2 B_{\alpha\varepsilon}^2; \quad R_{\alpha}^2 = \sum_{\varepsilon} \chi_{\alpha\varepsilon}^2 R_{\alpha\varepsilon}^2; \quad \chi_{\alpha\varepsilon} = \frac{J_{\varepsilon}(\bar{z}) c_{\alpha\varepsilon} K'_{\alpha\varepsilon}}{2I_u c_{xu} \bar{K}_{\alpha x}} \quad (\varepsilon=u, v, w, s)$$

$$B_{\alpha\varepsilon}^2 = \frac{1}{1 + 0.56 \tilde{\tau}_{\alpha\varepsilon}^{0.74} + 0.30 \tilde{\ell}_{\alpha\varepsilon}^{0.63}}; \quad R_{\alpha\varepsilon}^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{d_u \tilde{n}_{\alpha\varepsilon}}{(1 + 1.5 d_u \tilde{n}_{\alpha\varepsilon})^{5/3}} C\{\tilde{n}_{\alpha\varepsilon} \tilde{\ell}_{\alpha\varepsilon}\} \quad (\varepsilon=u, v, w)$$

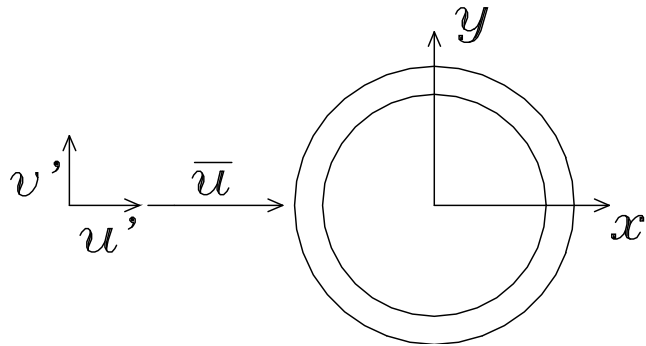
$$B_{\alpha s}^2 = C\{\tilde{\ell}_{\alpha s}\} F\{\tilde{n}_{\alpha s}\}; \quad R_{\alpha s}^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{\tilde{n}_{\alpha s}}{\sqrt{\pi\beta(z_{\alpha s})}} \exp\left\{-\left[\frac{1 - \tilde{n}_{\alpha s}}{\beta(z_{\alpha s})}\right]^2\right\} C\{\tilde{\ell}_{\alpha s}\}$$

$$\tilde{\tau}_{\alpha\varepsilon} = \frac{\tau d_u \bar{u}(z_{\alpha\varepsilon})}{d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}; \quad \tilde{\ell}_{\alpha\varepsilon} = \frac{k_{\alpha\varepsilon} d_u C_{r\varepsilon} \ell}{d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}; \quad \tilde{n}_{\alpha\varepsilon} = \frac{n_{\alpha 1} d_{\varepsilon} L_{\varepsilon}(z_{\alpha\varepsilon})}{d_u \bar{u}(z_{\alpha\varepsilon})}; \quad \tilde{\ell}_{\alpha s} = \frac{k_{\alpha s} \ell}{Lb}; \quad \tilde{n}_{\alpha s} = \frac{n_{\alpha 1} b}{Y_{\alpha} S \bar{u}(z_{\alpha s})}$$

PREDICTION OF 3-D RESPONSE

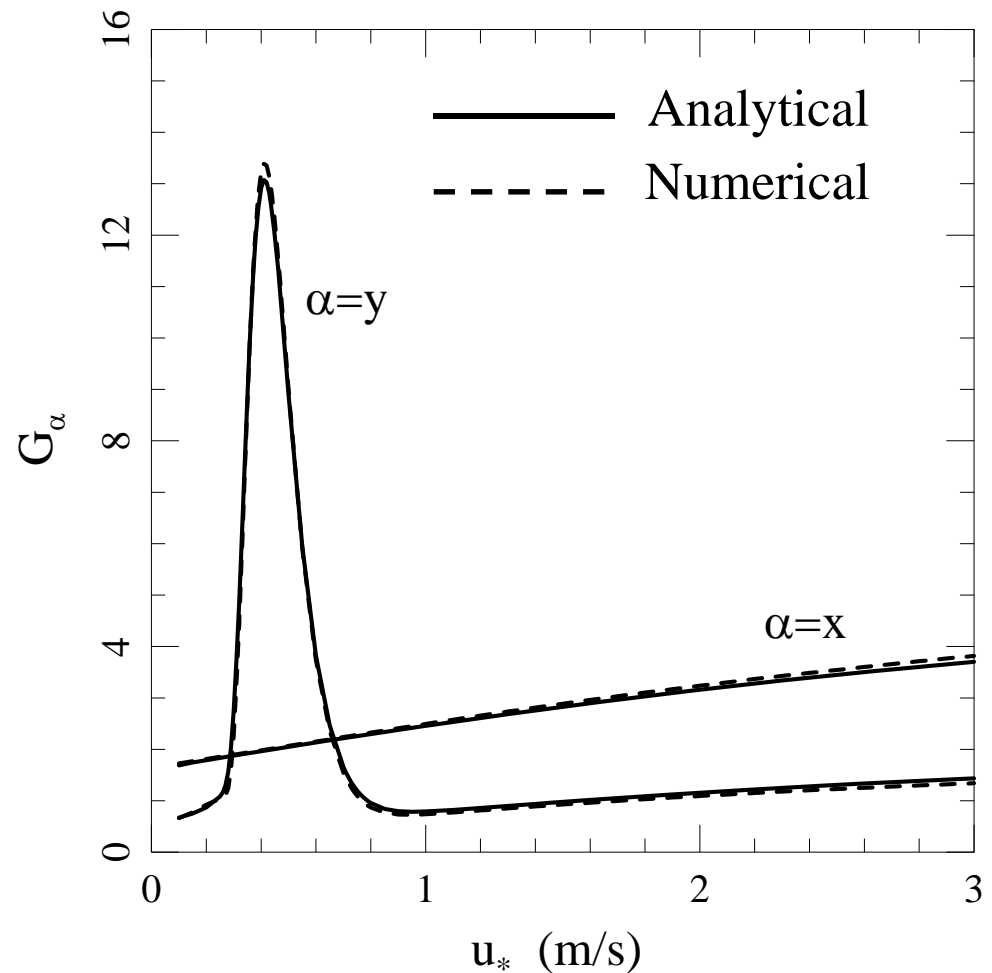
Piccardo & Solari (1998, 2000)

Concrete Chimney (aspect ratio 1:32)



Full-scale measurements

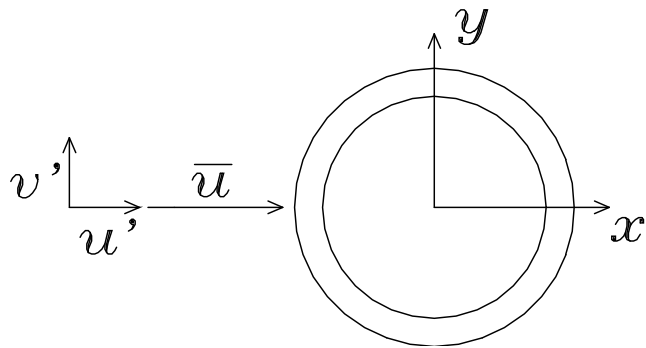
Müller-Nieser (1976) -
Alongwind and Crosswind
standard deviations



PREDICTION OF 3-D RESPONSE

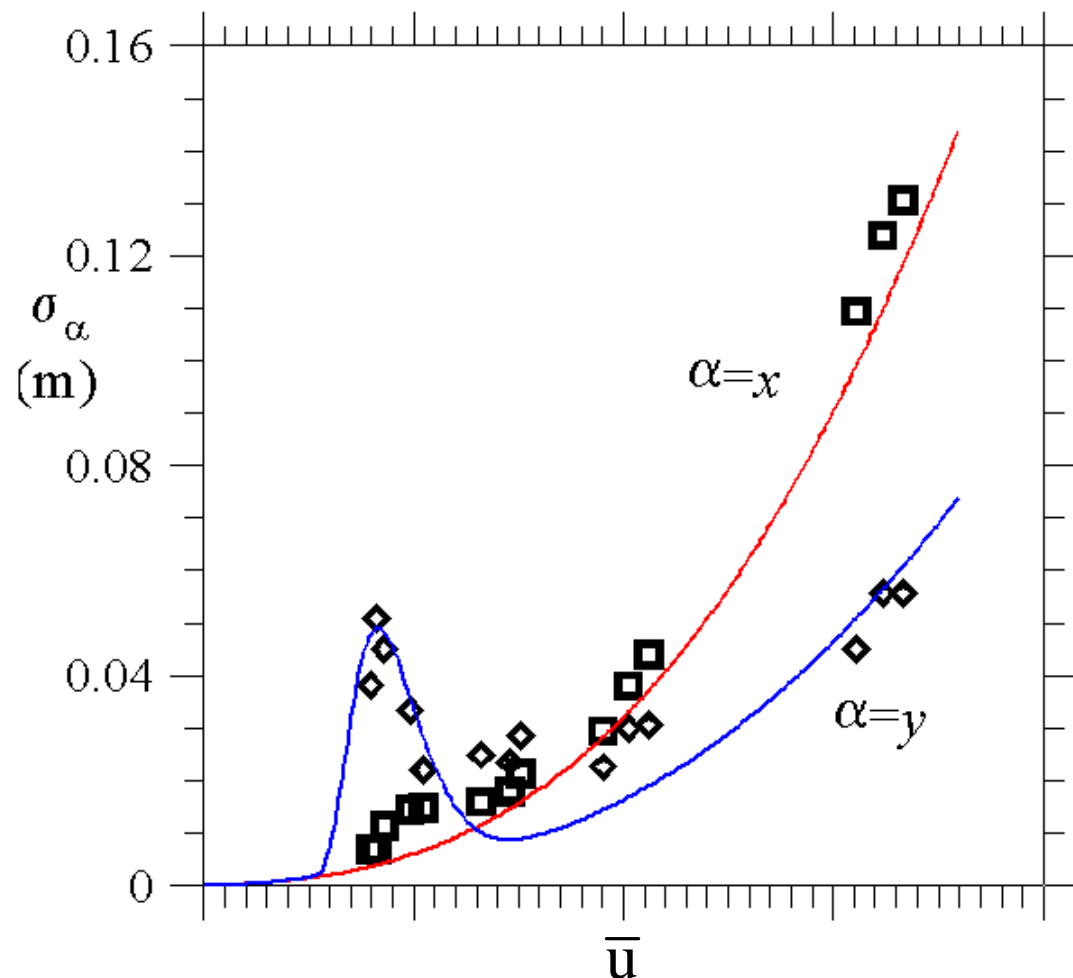
Piccardo & Solari (1998, 2000)

Concrete Chimney (aspect ratio 1:32)



Full-scale measurements

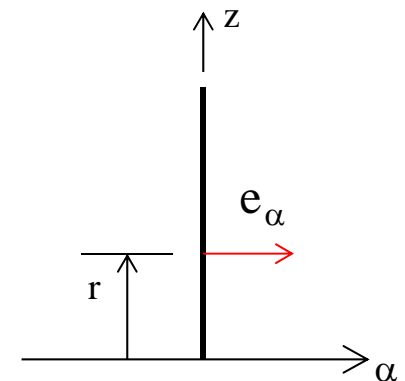
Müller-Nieser (1976) -
Alongwind and Crosswind
standard deviations



3-D WIND LOAD EFFECTS

Piccardo & Solari (2002)

$$e_{\alpha}(r; t) = \bar{e}_{\alpha}(r) + e'_{Q\alpha}(r; t) + e'_{D\alpha}(r; t); \quad \alpha = x, y, \theta$$



3-D WIND LOAD EFFECTS

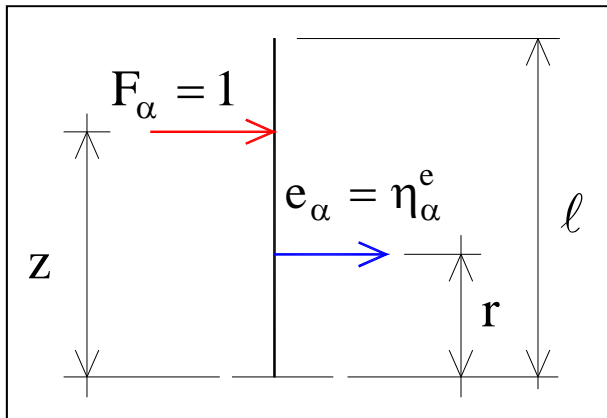
Piccardo & Solari (2002)

$$e_{\alpha}(r; t) = \bar{e}_{\alpha}(r) + e'_{Q\alpha}(r; t) + e'_{D\alpha}(r; t); \quad \alpha = x, y, \theta$$

$$\bar{e}_{\alpha}(r) = \int_0^{\ell} \bar{F}_{\alpha}(z) \eta_{\alpha}^e(r; z) dz$$

$$e'_{Q\alpha}(r; t) = \int_0^{\ell} F'_{\alpha}(z; t) \eta_{\alpha}^e(r; z) dz$$

$\eta_{\alpha}^e(r; z)$ = influence function of $e_{\alpha}(z)$



3-D WIND LOAD EFFECTS

Piccardo & Solari (2002)

$$e_{\alpha}(r; t) = \bar{e}_{\alpha}(r) + e'_{Q\alpha}(r; t) + e'_{D\alpha}(r; t); \quad \alpha = x, y, \theta$$

$$\bar{e}_{\alpha}(r) = \int_0^{\ell} \bar{F}_{\alpha}(z) \eta_{\alpha}^e(r; z) dz$$

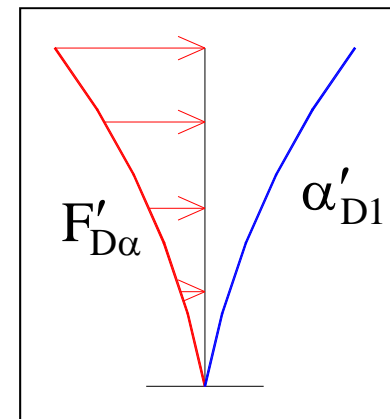
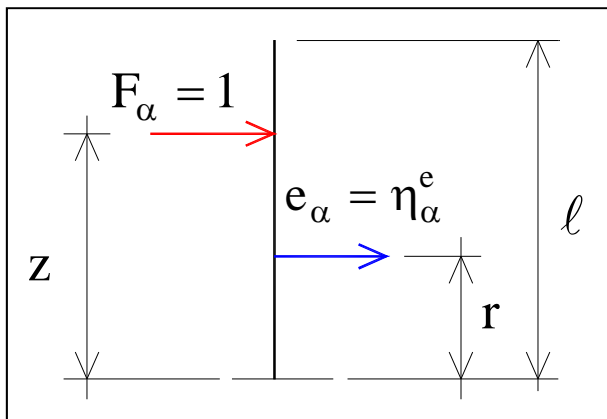
$$e'_{D\alpha}(r; t) = \int_0^{\ell} F'_{D\alpha}(z; t) \eta_{\alpha}^e(r; z) dz$$

$$e'_{Q\alpha}(r; t) = \int_0^{\ell} F'_{\alpha}(z; t) \eta_{\alpha}^e(r; z) dz$$

$$F'_{D\alpha}(z; t) = \mu_{\alpha}(z) (2\pi n_{\alpha 1})^2 \alpha'_{D1}(z; t)$$

$$\eta_{\alpha}^e(r; z) = \text{influence function of } e_{\alpha}(z)$$

$$\alpha'_{D1}(z; t) = \psi_{\alpha 1}(z) p'_{D\alpha 1}(t)$$



MEAN LOAD EFFECT

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sigma_{\alpha}^e(\mathbf{r})$$

$$\boxed{\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}^x(\mathbf{r}) G_{\alpha}^e(\mathbf{r})}$$

$\bar{e}_{\alpha}^x(\mathbf{r})$ is the static effect due to the generalised force $\lambda_{\alpha} \bar{F}_x$

$$\lambda_x = \lambda_y = 1; \lambda_{\theta} = b$$

EQUIVALENT STATIC FORCE

$$\boxed{F_{\alpha \text{eq}}^e(\mathbf{z}; \mathbf{r}) = \lambda_{\alpha} G_{\alpha}^e(\mathbf{r}) \bar{F}_x(\mathbf{z})}$$

MEAN LOAD EFFECT

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sigma_{\alpha}^e(\mathbf{r})$$

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}^x(\mathbf{r}) G_{\alpha}^e(\mathbf{r})$$

$\bar{e}_{\alpha}^x(\mathbf{r})$ is the static effect due to the generalised force $\lambda_{\alpha} \bar{F}_x$

$$\lambda_x = \lambda_y = 1; \lambda_{\theta} = b$$

3-D GUST EFFECT FACTOR

$$G_{\alpha}^e(\mathbf{r}) = \mu_{\alpha}^e(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sqrt{Q_{\alpha}^e(\mathbf{r}) + D_{\alpha}^e(\mathbf{r})}$$

EQUIVALENT STATIC FORCE

$$F_{\alpha \text{eq}}^e(\mathbf{z}; \mathbf{r}) = \lambda_{\alpha} G_{\alpha}^e(\mathbf{r}) \bar{F}_X(\mathbf{z})$$

MEAN LOAD EFFECT

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sigma_{\alpha}^e(\mathbf{r})$$

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}^x(\mathbf{r}) G_{\alpha}^e(\mathbf{r})$$

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$$\lambda_x = \lambda_y = 1; \lambda_{\theta} = b$$

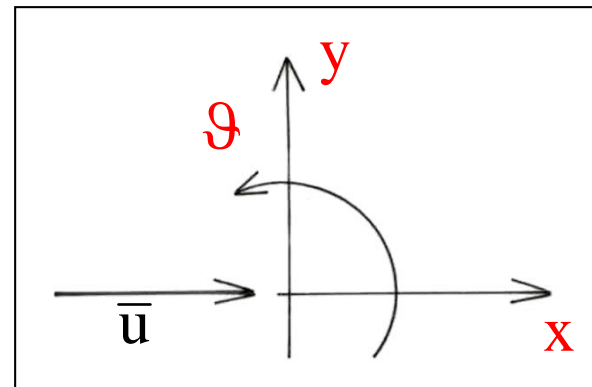
EQUIVALENT STATIC FORCE

$$F_{\alpha \text{eq}}^e(\mathbf{z}; \mathbf{r}) = \lambda_{\alpha} G_{\alpha}^e(\mathbf{r}) \bar{F}_x(\mathbf{z})$$

3-D GUST EFFECT FACTOR

$$G_{\alpha}^e(\mathbf{r}) = \mu_{\alpha}^e(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sqrt{Q_{\alpha}^e(\mathbf{r}) + D_{\alpha}^e(\mathbf{r})}$$

$$G_{\alpha}^e(\mathbf{r})$$



MEAN LOAD EFFECT

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sigma_{\alpha}^e(\mathbf{r})$$

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$\bar{e}_{\alpha}^x(\mathbf{r})$ is the static effect due to the generalised force $\lambda_{\alpha} \bar{F}_x$

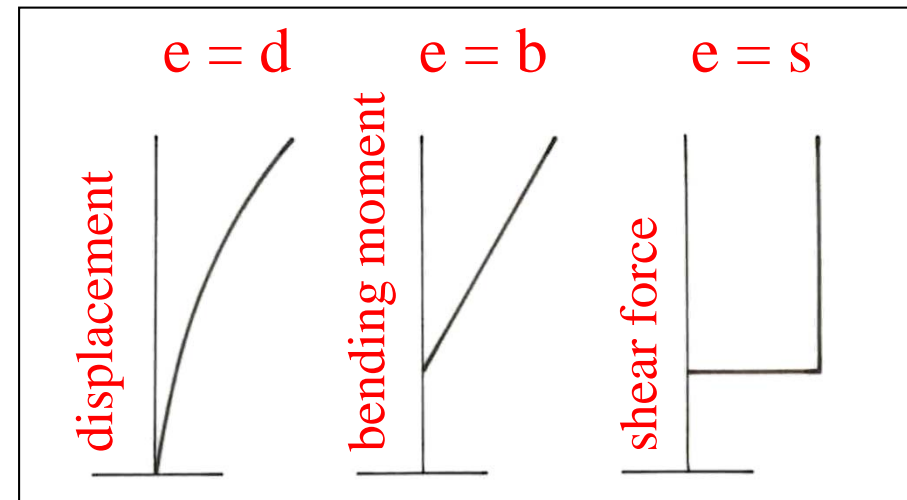
$$\lambda_x = \lambda_y = 1; \lambda_{\theta} = b$$

EQUIVALENT STATIC FORCE

$$F_{\alpha \text{eq}}^e(z; \mathbf{r}) = \lambda_{\alpha} G_{\alpha}^e(\mathbf{r}) \bar{F}_X(z)$$

3-D GUST EFFECT FACTOR

$$G_{\alpha}^e(\mathbf{r}) = \mu_{\alpha}^e(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sqrt{Q_{\alpha}^e(\mathbf{r}) + D_{\alpha}^e(\mathbf{r})}$$



$$G_{\alpha}^e(\mathbf{r})$$

MEAN LOAD EFFECT

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sigma_{\alpha}^e(\mathbf{r})$$

$$\bar{e}_{\alpha, \max}(\mathbf{r}) = \bar{e}_{\alpha}^x(\mathbf{r}) G_{\alpha}^e(\mathbf{r})$$

$\bar{e}_{\alpha}^x(\mathbf{r})$ is the static effect due to the generalised force $\lambda_{\alpha} \bar{F}_x$

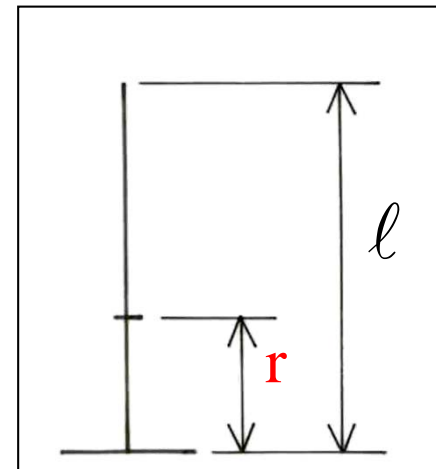
$$\lambda_x = \lambda_y = 1; \lambda_{\theta} = b$$

EQUIVALENT STATIC FORCE

$$F_{\alpha \text{eq}}^e(\mathbf{z}; \mathbf{r}) = \lambda_{\alpha} G_{\alpha}^e(\mathbf{r}) \bar{F}_X(\mathbf{z})$$

3-D GUST EFFECT FACTOR

$$G_{\alpha}^e(\mathbf{r}) = \mu_{\alpha}^e(\mathbf{r}) + g_{\alpha}^e(\mathbf{r}) \sqrt{Q_{\alpha}^e(\mathbf{r}) + D_{\alpha}^e(\mathbf{r})}$$



$$G_{\alpha}^e(\mathbf{r})$$

EQUIVALENT STATIC FORCES

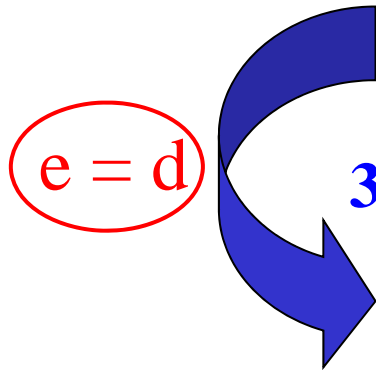
3-D GEF technique (Piccardo & Solari, 2002)

$$F_{\alpha,es}^e(r,z) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_x(z)$$

EQUIVALENT STATIC FORCES

3-D GEF technique (Piccardo & Solari, 2002)

$$F_{\alpha,es}^e(r,z) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_x(z)$$



3-D GRF technique (Piccardo & Solari, 2000)

$$F_{\alpha,es}(z) = \lambda_{\alpha} G_{\alpha} \bar{F}_x(z)$$

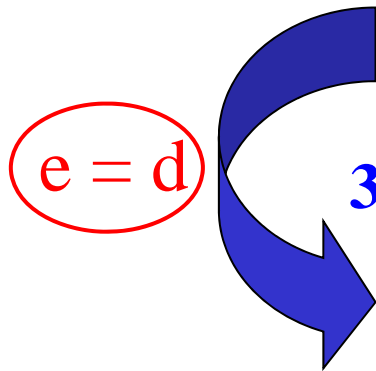
particular case

$$F_{\alpha,es} = F_{\alpha,es}^d ; G_{\alpha} = G_{\alpha}^d$$

EQUIVALENT STATIC FORCES

3-D GEF technique (Piccardo & Solari, 2002)

$$F_{\alpha,es}^e(r,z) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_x(z)$$

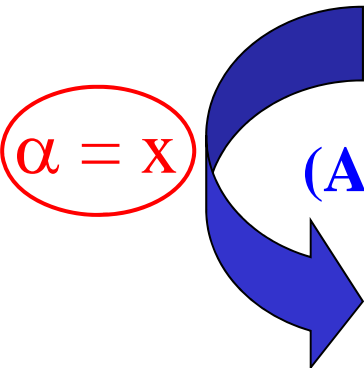


3-D GRF technique (Piccardo & Solari, 2000)

$$F_{\alpha,es}(z) = \lambda_{\alpha} G_{\alpha} \bar{F}_x(z)$$

particular case

$$F_{\alpha,es} = F_{\alpha,es}^d ; G_{\alpha} = G_{\alpha}^d$$



(Alongwind) GRF technique (Davenport, 1967)

$$F_{x,eq}(z) = G_x \bar{F}_x(z)$$

$$\lambda_x = 1$$

EQUIVALENT STATIC FORCES

3-D GEF technique (Piccardo & Solari, 2002)

$$F_{\alpha,es}^e(r,z) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_x(z)$$

3-D GRF technique (Piccardo & Solari, 2000)

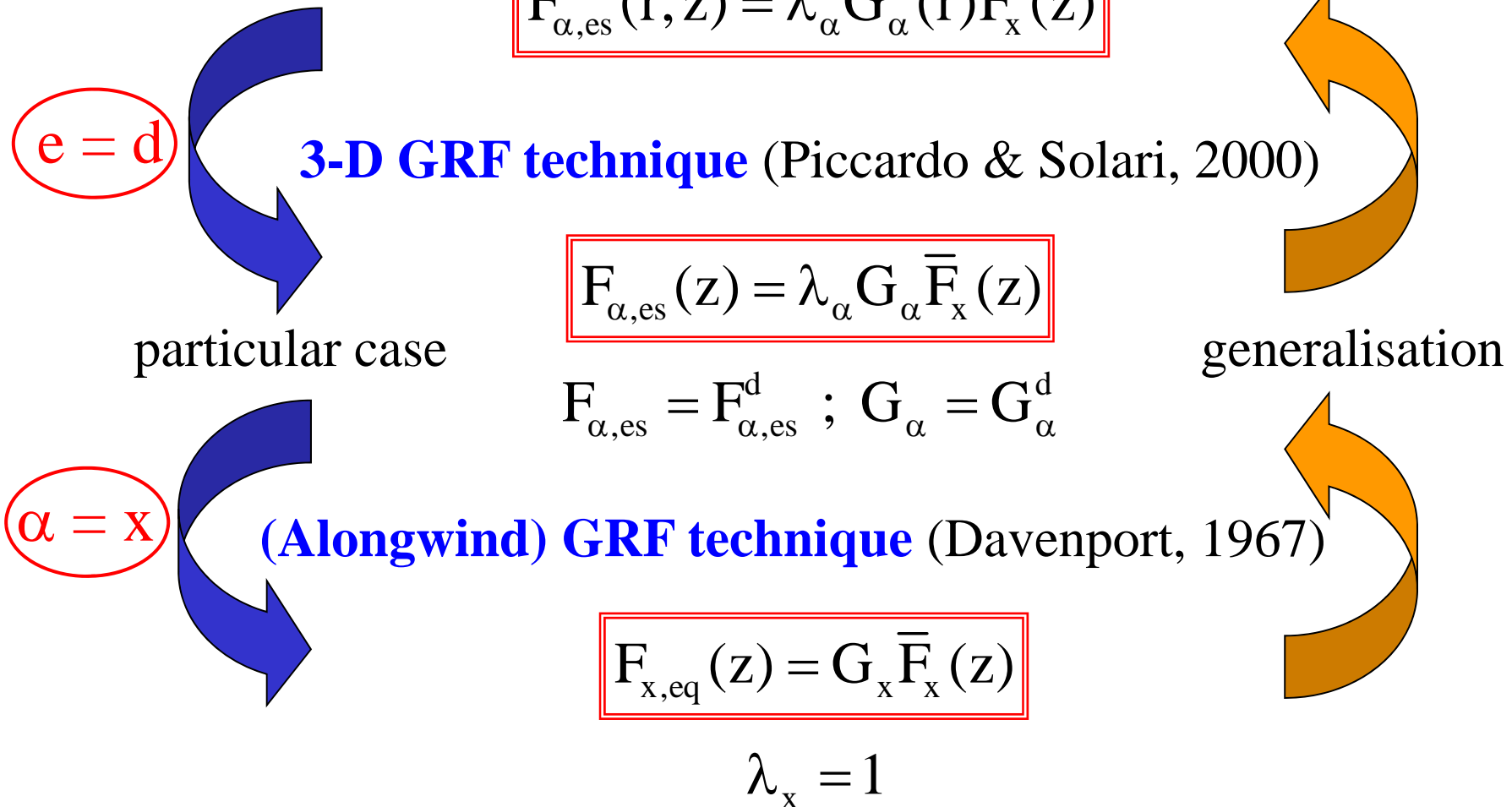
$$F_{\alpha,es}(z) = \lambda_{\alpha} G_{\alpha} \bar{F}_x(z)$$

$$F_{\alpha,es} = F_{\alpha,es}^d ; G_{\alpha} = G_{\alpha}^d$$

(Alongwind) GRF technique (Davenport, 1967)

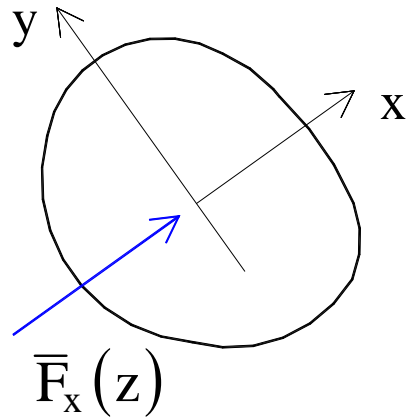
$$F_{x,eq}(z) = G_x \bar{F}_x(z)$$

$$\lambda_x = 1$$



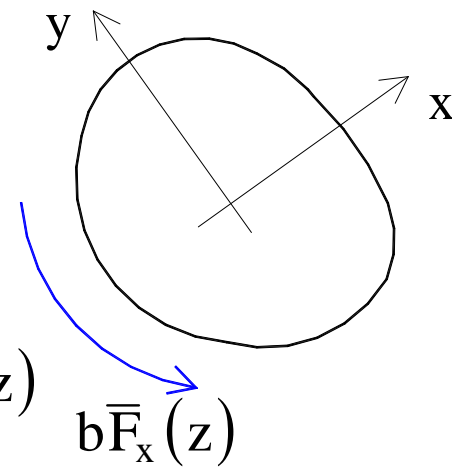
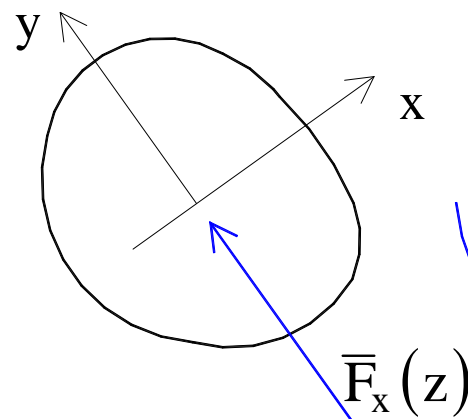
3-D EQUIVALENT STATIC FORCES

$$F_{\alpha \text{eq}}(z; r) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_X(z)$$



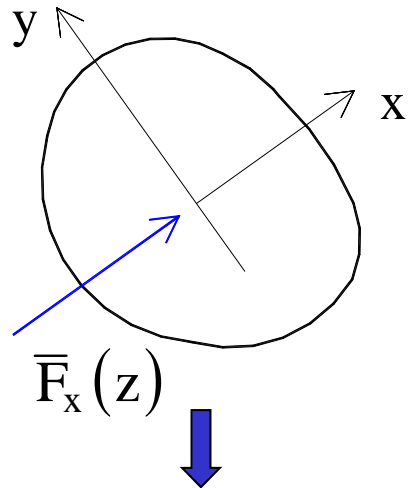
3-D MAXIMUM EFFECTS

$$\bar{e}_{\alpha, \max}(r) = \bar{e}_{\alpha}^X(r) G_{\alpha}^e(r)$$

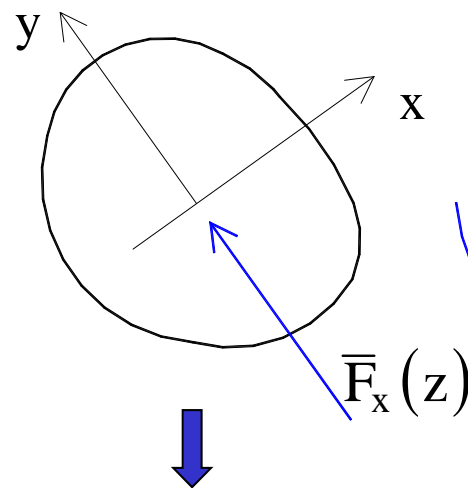


3-D EQUIVALENT STATIC FORCES

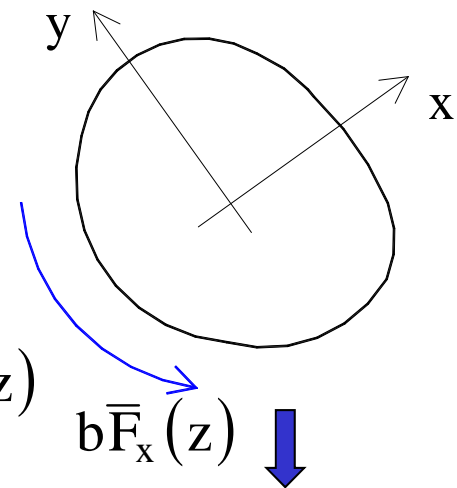
$$F_{\alpha \text{eq}}(z; r) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_X(z)$$



$$\bar{e}_X^X(r)$$



$$\bar{e}_Y^X(r)$$



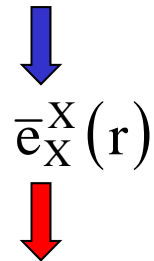
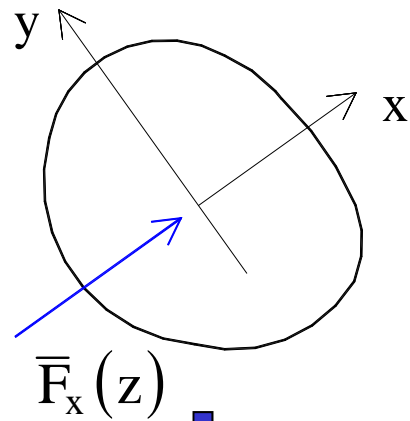
$$\bar{e}_{\theta}^X(r)$$

3-D MAXIMUM EFFECTS

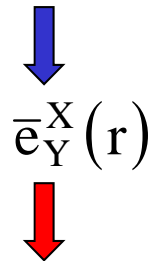
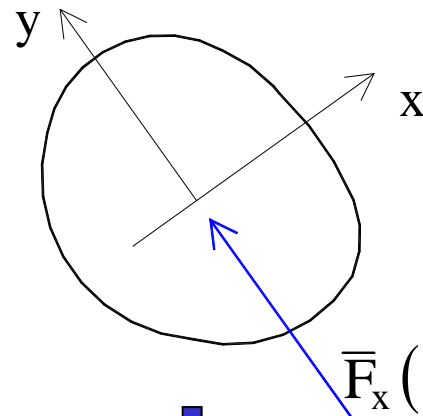
$$\bar{e}_{\alpha, \text{max}}(r) = \bar{e}_{\alpha}^X(r) G_{\alpha}^e(r)$$

3-D EQUIVALENT STATIC FORCES

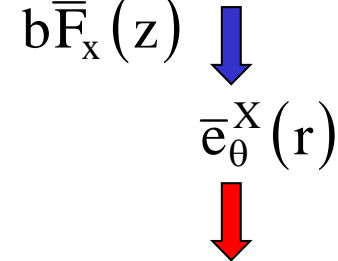
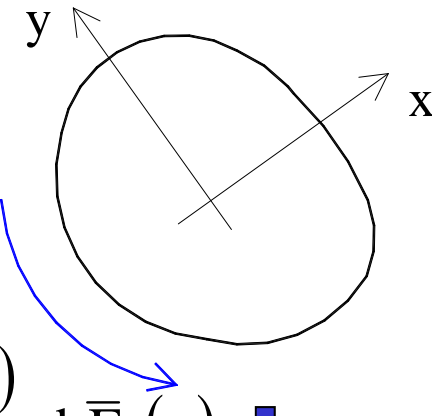
$$F_{\alpha \text{eq}}(z; r) = \lambda_{\alpha} G_{\alpha}^e(r) \bar{F}_X(z)$$



$$\bar{e}_{X, \max}(r) = \bar{e}_X^X G_X^e$$



$$\bar{e}_{Y, \max}(r) = \bar{e}_Y^X G_Y^e$$



$$\bar{e}_{\theta, \max}(r) = \bar{e}_{\theta}^X G_{\theta}^e$$

3-D MAXIMUM EFFECTS

$$\bar{e}_{\alpha, \max}(r) = \bar{e}_{\alpha}^X(r) G_{\alpha}^e(r)$$

3-D GUST EFFECT FACTOR

$$\boxed{\bar{e}_{\alpha, \max}(\mathbf{r}) = G_{\alpha}^e(\mathbf{r}) e_{\alpha}^x(\mathbf{r})} \quad \boxed{G_{\alpha}^e(\mathbf{r}) = \mu_{\alpha}^e(\mathbf{r}) + 2g_{\alpha}^e(\mathbf{r}) I_u \sqrt{[B_{\alpha}^e(\mathbf{r})]^2 + [R_{\alpha}^e(\mathbf{r})]^2}}$$

Closed Form Solution (Piccardo & Solari, 2002)

$$\mu_{\alpha}^e(r) = \frac{c_{\alpha u} \bar{K}_{\alpha\alpha}^e(r)}{c_{xu} \bar{K}_{\alpha x}^e(r)}; \quad [B_{\alpha}^e(r)]^2 = \sum_{\varepsilon} [\chi_{\alpha\varepsilon}^e(r)]^2 [B_{\alpha\varepsilon}^e(r)]^2; \quad [R_{\alpha}^e(r)]^2 = \sum_{\varepsilon} [\phi_{\alpha\varepsilon}^e(r)]^2 [R_{\alpha\varepsilon}^d(r)]^2 \quad (\varepsilon = u, v, w, s)$$

$$\chi_{\alpha\varepsilon}^e(r) = \frac{J_{\varepsilon}(\ell) c_{\alpha\varepsilon} K'_{\alpha\varepsilon}(r)}{2I_u c_{xu} \bar{K}_{\alpha x}^e(r)}; \quad \phi_{\alpha\varepsilon}^e(r) = \frac{J_{\varepsilon}(\ell) c_{\alpha\varepsilon} K'_{\alpha\varepsilon}(r) m_{\alpha 1}^e(r)}{2I_u c_{xu} \bar{K}_{\alpha x}^e(r) m_{\alpha 1}^d(r)}$$

$$[B_{\alpha\varepsilon}^e(r)]^2 = \frac{1}{1 + 0.56 [\tilde{\tau}_{\alpha\varepsilon}^e(r)]^{0.74} + 0.30 [\tilde{\ell}_{\alpha\varepsilon}^e(r)]^{0.63}}$$

$$[R_{\alpha\varepsilon}^d(r)]^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{d_u \tilde{n}_{\alpha\varepsilon}^d(r)}{[1 + 1.5 d_u \tilde{n}_{\alpha\varepsilon}^d(r)]^{5/3}} C\{\tilde{n}_{\alpha\varepsilon}^d(r) \tilde{\ell}_{\alpha\varepsilon}^d(r)\}$$

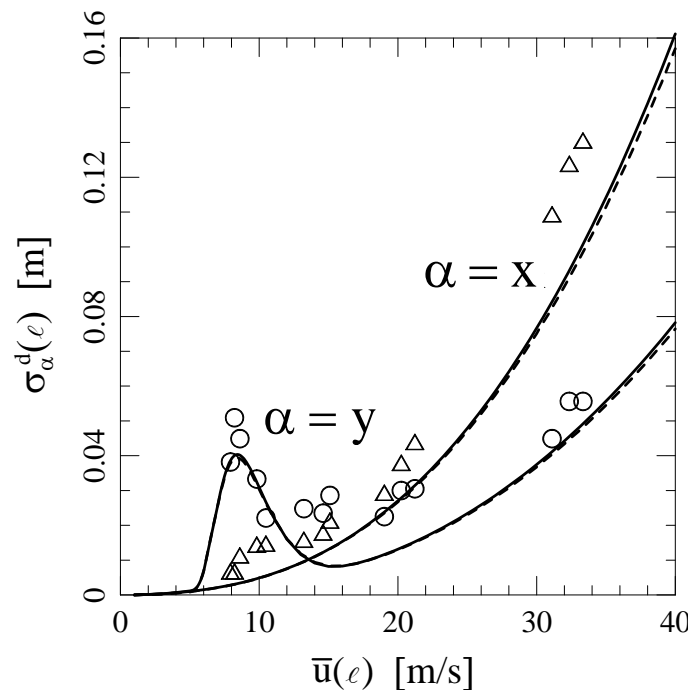
$$\tilde{\tau}_{\alpha\varepsilon}^e(r) = \frac{\tau d_u \bar{u} [z_{\alpha\varepsilon}^e(r)]}{d_{\varepsilon} L_{\varepsilon} [z_{\alpha\varepsilon}^e(r)]}; \quad \tilde{\ell}_{\alpha\varepsilon}^e(r) = \frac{k_{\alpha\varepsilon}^e(r) d_u C_{z\varepsilon} \ell}{d_{\varepsilon} L_{\varepsilon} [z_{\alpha\varepsilon}^e(r)]}; \quad \tilde{n}_{\alpha\varepsilon}^d(r) = \frac{n_{\alpha 1} d_{\varepsilon} L_{\varepsilon} [z_{\alpha\varepsilon}^d(r)]}{d_u \bar{u} [z_{\alpha\varepsilon}^d(r)]}$$

$$[B_{\alpha s}^e(r)]^2 = C\{\tilde{\ell}_{\alpha s}^e(r)\} F\{\tilde{n}_{\alpha s}^e(r)\}; \quad [R_{\alpha s}^d(r)]^2 = \frac{\pi}{4\xi_{\alpha 1}} \frac{\tilde{n}_{\alpha s}^d(r)}{\sqrt{\pi} \beta [z_{\alpha s}^d(r)]} \exp\left\{-\left[\frac{1 - \tilde{n}_{\alpha s}^d(r)}{\beta [z_{\alpha s}^d(r)]}\right]^2\right\} C\{\tilde{\ell}_{\alpha s}^d(r)\}$$

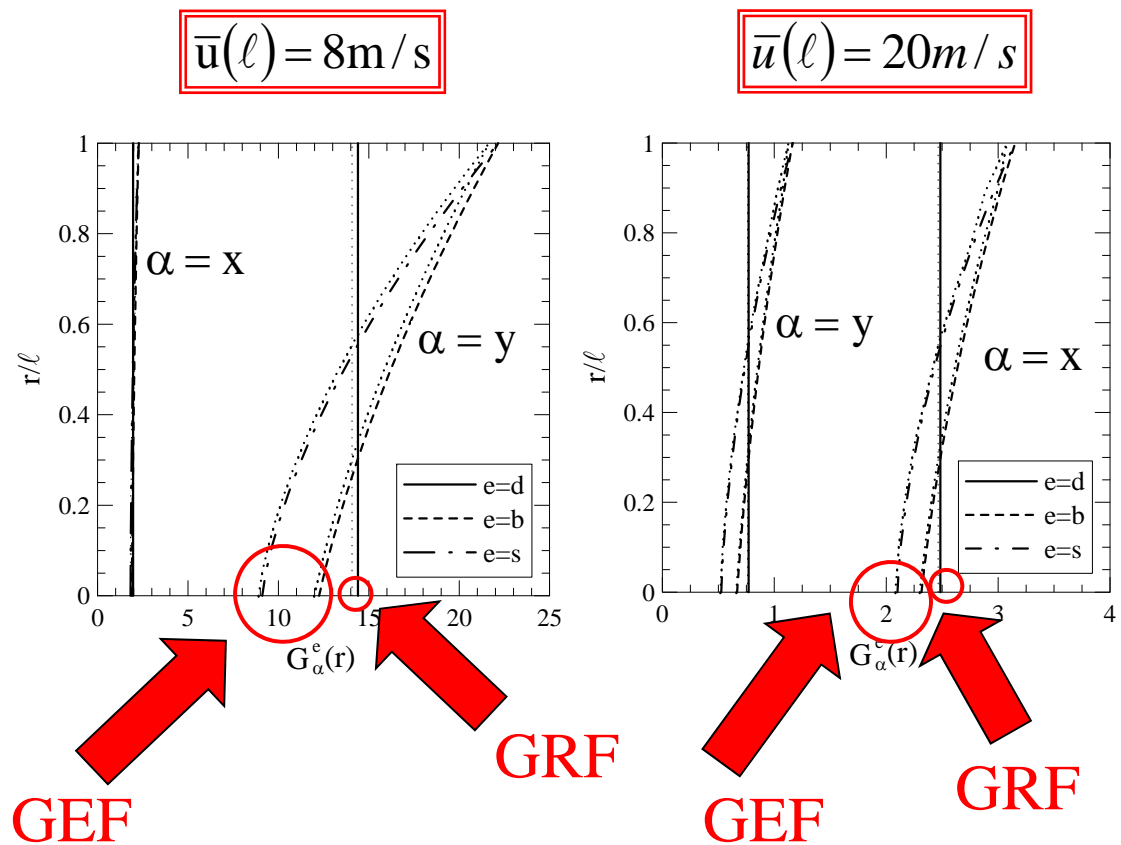
$$\tilde{\ell}_{\alpha s}^e(r) = \frac{k_{\alpha s}^e(r) \ell}{L b}; \quad \tilde{n}_{\alpha s}^e(r) = \frac{n_{\alpha 1} b}{Y_{\alpha} S \bar{u} [z_{\alpha s}^e(r)]}$$

Concrete Chimney: Mueller & Nieser (1976) Piccardo & Solari (2002)

3-D RESPONSE



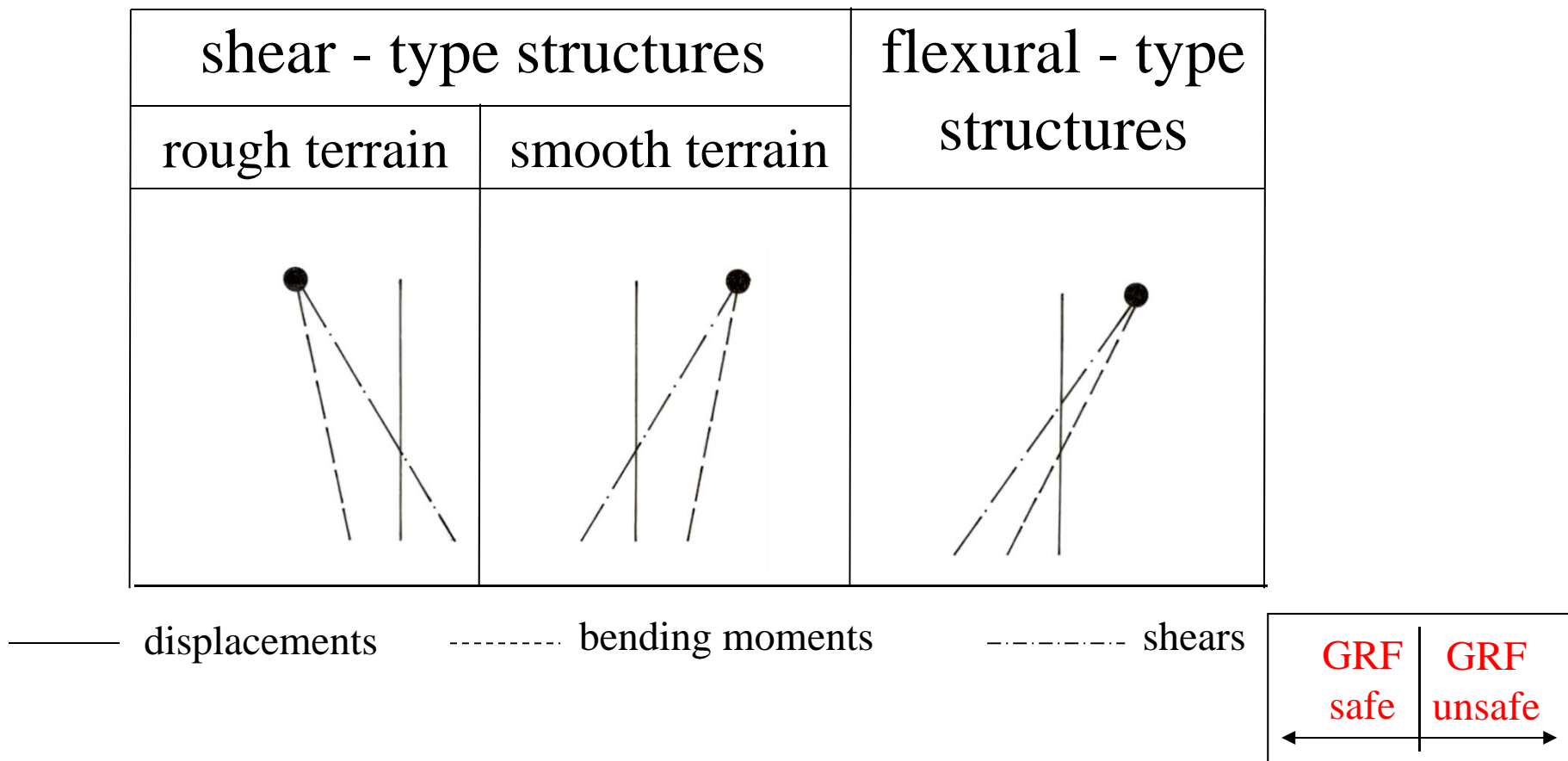
3-D GUST EFFECT FACTORS



ASSESSMENT OF GENERAL TENDENCIES

Solari & Repetto (2002)


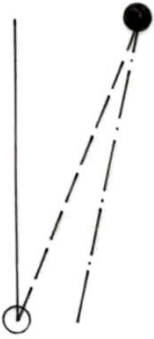
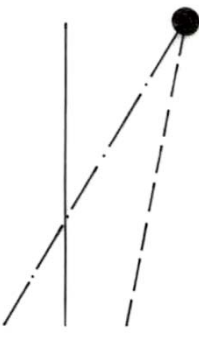
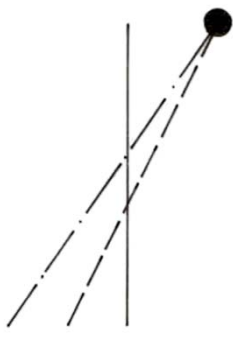
3-D Gust Effect Factor - Resonant Response



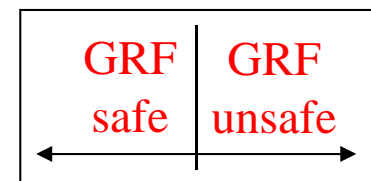
ASSESSMENT OF GENERAL TENDENCIES

Solari & Repetto (2002)

3-D Gust Effect Factor - Quasi-static Response

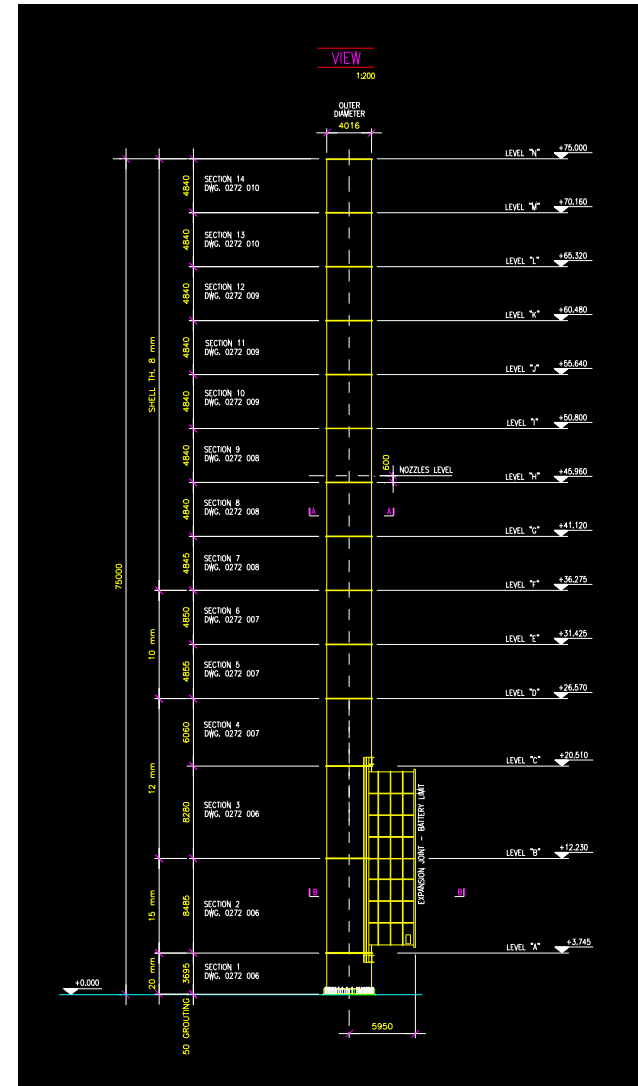
dominant buffeting		dominant wake	
low-rise str.	high-rise str.	shear-type str.	flexural-type str.
			

——— displacements bending moments - - - - - shears

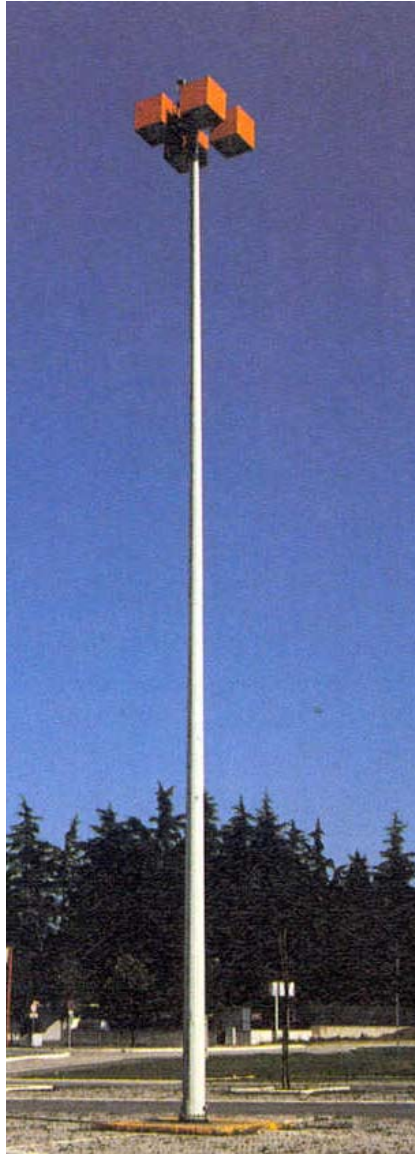


Centrale termoelettrica Enelpower

Ballylumford, Irlanda



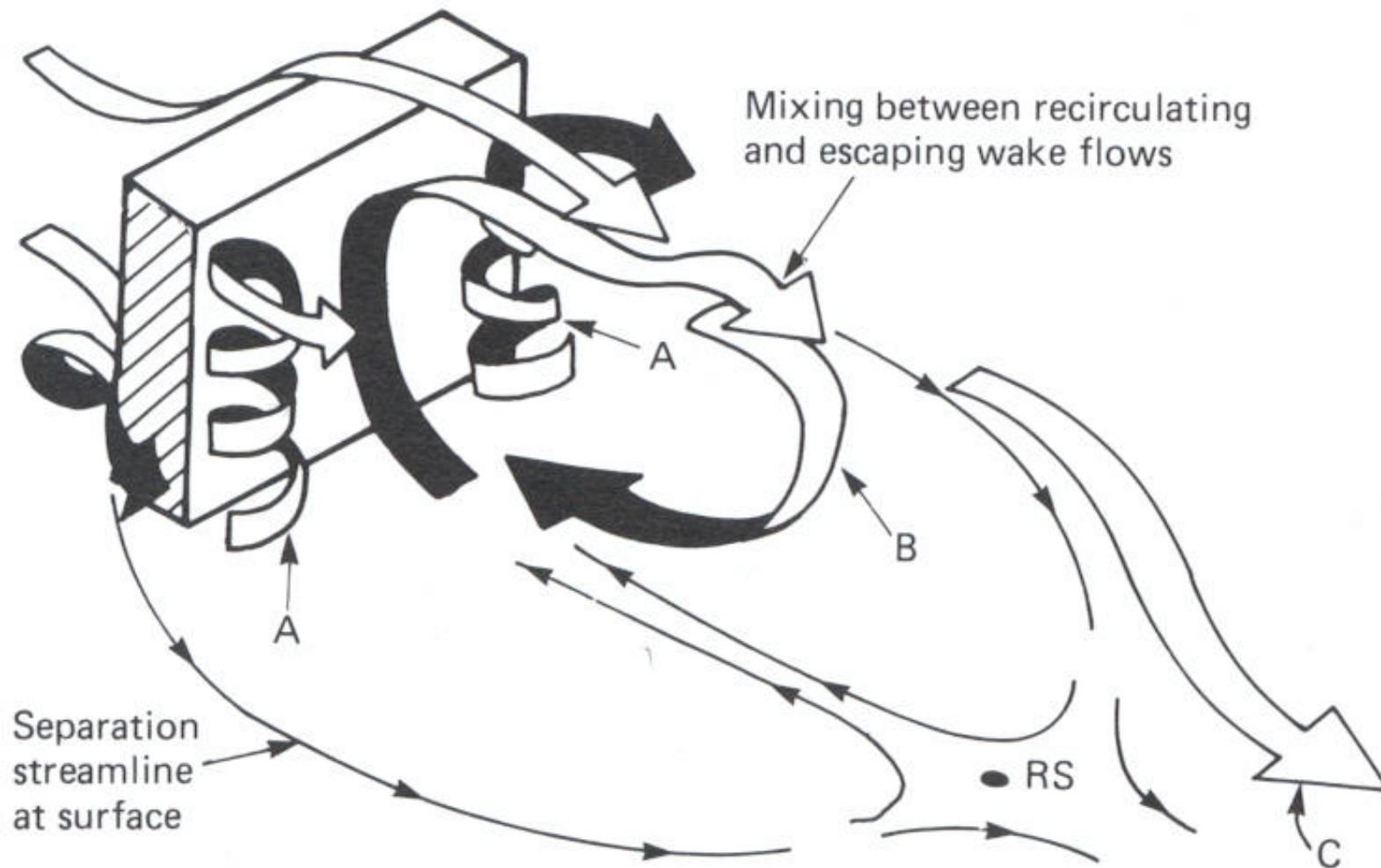
Poles and monotubular towers



Dockers, Calata Sanità, Genoa



3-D WIND-EXCITED RESPONSE OF THREE-DIMENSIONAL BLUFF-BODIES



Historical Area, Fiera di Milano

