

# MONTE CARLO SIMULATION

The knowledge of a set of the sample functions of a random process allows to derive its power spectral density. On the other hand, the knowledge of a suitable model of the power spectral density of a random process allows to derive artificially its sample functions. This operation is known as simulation of a random process and falls into the broad family of the Monte Carlo methods.

Monte Carlo methods to simulate a random process may be classified into two main families: 1) the methods based on the superposition of harmonic waves with random phase angles (random phase method); 2) ARMA methods based on the filtering of uncorrelated white noises (Auto-Regressive and/or Mobile-Average methods). Both these methods may be applied to simulate stationary and non-stationary random processes, as well as normal and non-normal random processes. This section is aimed at providing a synthetic description of the application of the random phase method to random stationary normal processes with zero mean.

## Mono-variate processes

Let  $X(t)$  be a random stationary normal process with zero mean.  $S_{xx}(\omega)$  is its power spectral density. Using the random phase method, a generic sample function of  $X(t)$  is given by:

$$x(t) = 2 \sum_1^N \sqrt{S_{xx}(\omega_j) \Delta\omega_j} \sin(\omega_j t + \varphi_j) \quad (1)$$

where  $\Delta\omega_j$  ( $j=1,..N$ ) is the amplitude of the frequency steps into which the harmonic content of the process is sub-divided (with  $\omega \geq 0$ );  $\omega_j$  ( $j=1,..N$ ) is the central value of each step (Fig. 1a);  $\varphi_j$  is the  $j$ -th occurrence of the random phase  $\Phi$  uniformly distributed between 0 and  $2\pi$  (Fig. 1b):

$$p_{\Phi}(\varphi) = \begin{cases} 1/2\pi & \text{for } 0 < \varphi < 2\pi \\ 0 & \text{elsewhere} \end{cases} \quad (2)$$

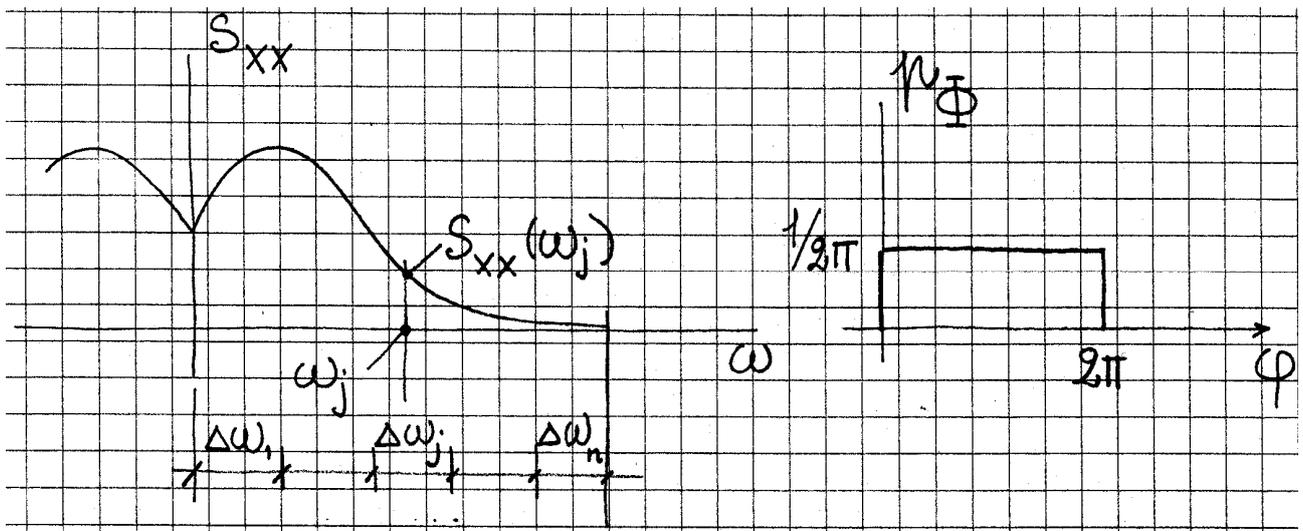


Fig. 1

To interpret Eq. (1), let us consider the  $j$ -th term of the sum:

$$x_j(t) = 2\sqrt{S_{XX}(\omega_j)\Delta\omega_j} \sin(\omega_j t + \phi_j) \quad (3)$$

and let us evaluate its variance (the variance of a harmonic function with unit amplitude is 1/2). Thus:

$$\sigma_{x_j}^2 = 4S_{XX}(\omega_j)\Delta\omega_j \frac{1}{2} = 2S_{XX}(\omega_j)\Delta\omega_j$$

Since the harmonics that constitute the sample function defined by Eq. (1) is uncorrelated with each other (having different circular frequencies), the variance of  $X(t)$  is the sum of the variances of its components. Thus (Fig. 2):

$$\sigma_x^2 = \sum_1^N \sigma_{x_j}^2 = 2\sum_1^N S_{XX}(\omega_j)\Delta\omega_j \approx \sigma_X^2$$

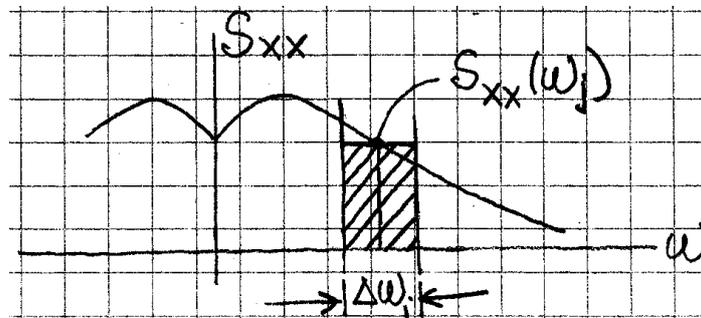


Fig. 2.

Moreover, the amplitude of each harmonic defines the power content and the distribution of the sample function and of the process. Fig. 3 shows the simulation of 3 sample functions of the wind velocity studied in the previous section. The functions are normalised in order to have  $\sigma_v = 1$ .

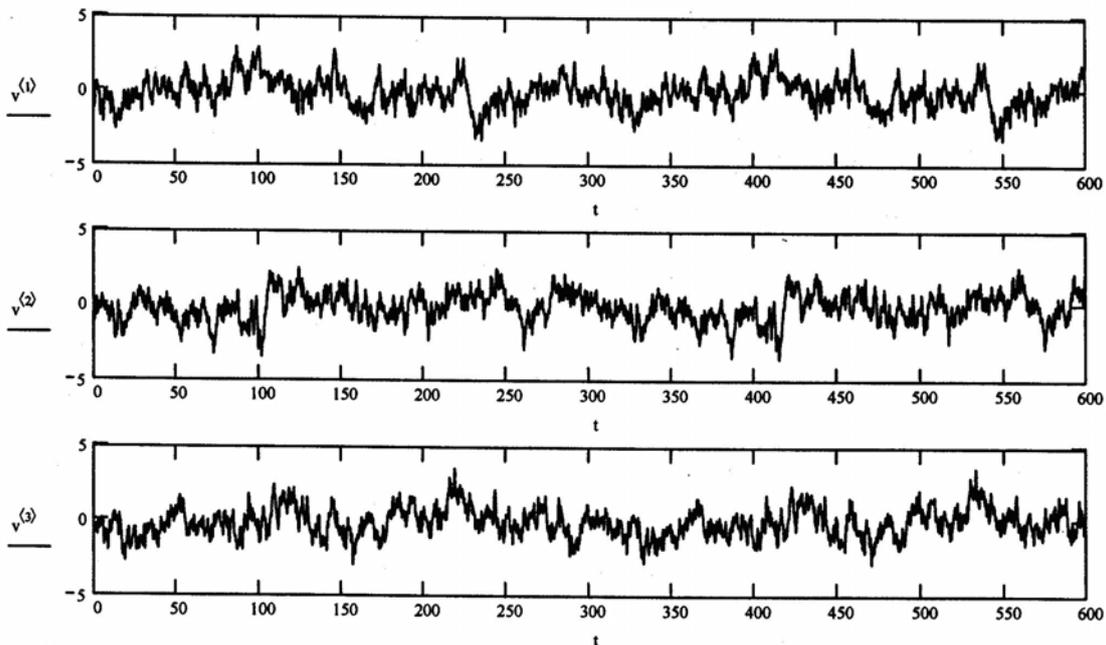


Fig. 3

## Multi-variate processes

Let  $\mathbf{X}(t)$  be a  $n$ -variate random stationary normal process with zero mean. Let  $\mathbf{S}_x(\omega)$  be its power spectral density matrix. The random phase method allows to simulate any number of sample vectors  $\mathbf{x}(t)$  of  $\mathbf{X}(t)$ . Fig. 4 shows the basic concepts of the simulation of a 3-variate process.

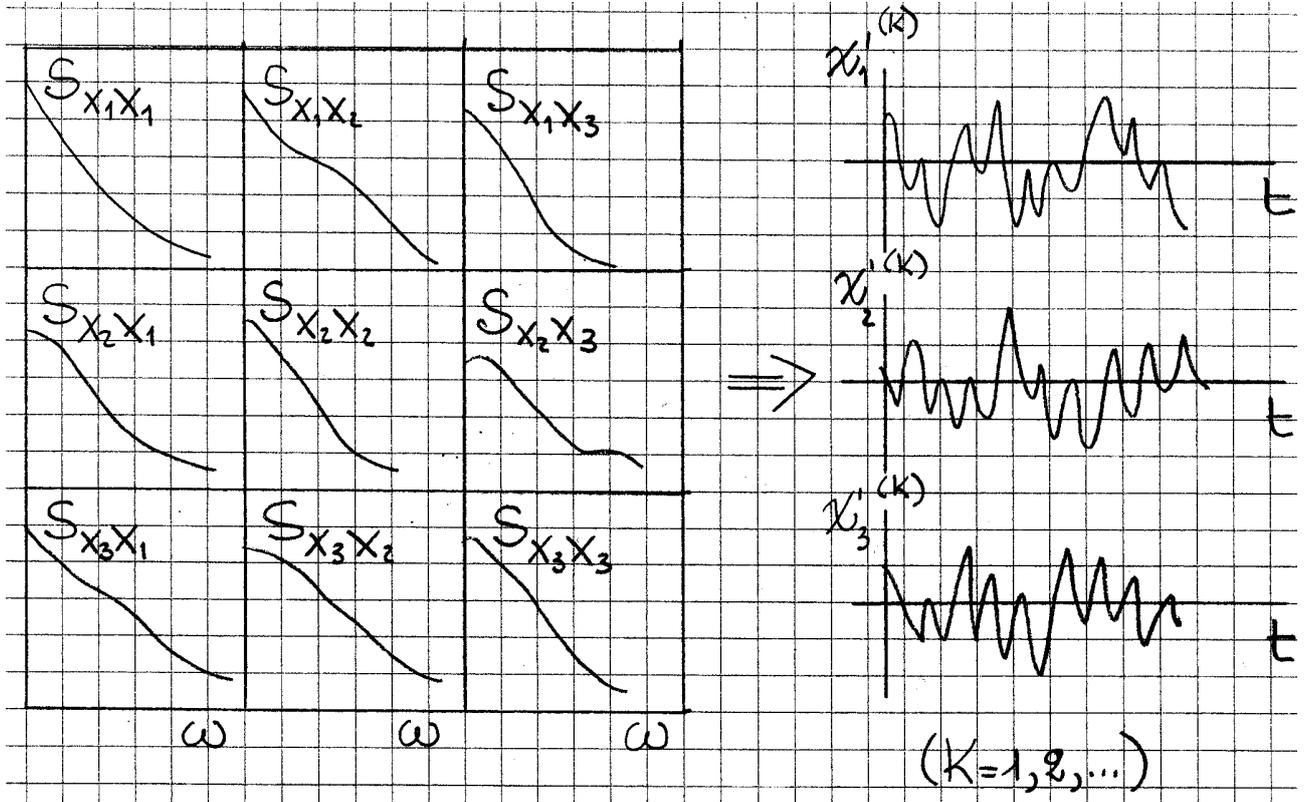


Fig. 4

It is possible to demonstrate that the  $i$ -th component of the sample vector  $\mathbf{x}(t)$  of  $\mathbf{X}(t)$  is given by:

$$x_i(t) = 2 \sum_1^N \sum_1^n D_{ik}(\omega_j) \sqrt{\Delta\omega_j} \sin(\omega_j t + \varphi_{jk}) \quad (i=1, 2, \dots, n) \quad (4)$$

where  $\Delta\omega_j (j=1, \dots, N)$  is the amplitude of the frequency steps into which the harmonic content of the process is sub-divided (with  $\omega \geq 0$ );  $\omega_j (j=1, \dots, N)$  is the central value of each frequency step (Fig. 1a);  $\varphi_{jk}$  is the  $j, k$ -th occurrence of the random phase  $\Phi$  uniformly distributed between 0 and  $2\pi$ .

Eq. (4) may be re-written in the following matrix form:

$$\mathbf{x}(t) = 2 \sum_1^N \mathbf{D}(\omega_j) \sqrt{\Delta\omega_j} \sin(\omega_j \mathbf{1}t + \boldsymbol{\varphi}_j) \quad (5)$$

where  $\mathbf{1} = \{1 \ 1 \dots 1\}^T$  is a vector of  $n$  unit components,  $\boldsymbol{\varphi}_j = \{\varphi_{j1} \ \varphi_{j2} \ \dots \ \varphi_{jn}\}^T$ ,  $\mathbf{D}$  is a matrix provided by the relationship:

$$\mathbf{D}(\omega)\mathbf{D}^T(\omega) = \mathbf{S}_x(\omega) \quad (6)$$

Eq. (6) is referred to as matrix decomposition. There are infinite possible matrices  $\mathbf{D}(\omega)$  that satisfy Eq. (6) and several methods to determine such matrices. The most well-known methods are referred to as the Cholesky and spectral decompositions.

Fig. 5 shows the simulation of 3 correlated time-histories of the wind velocity.

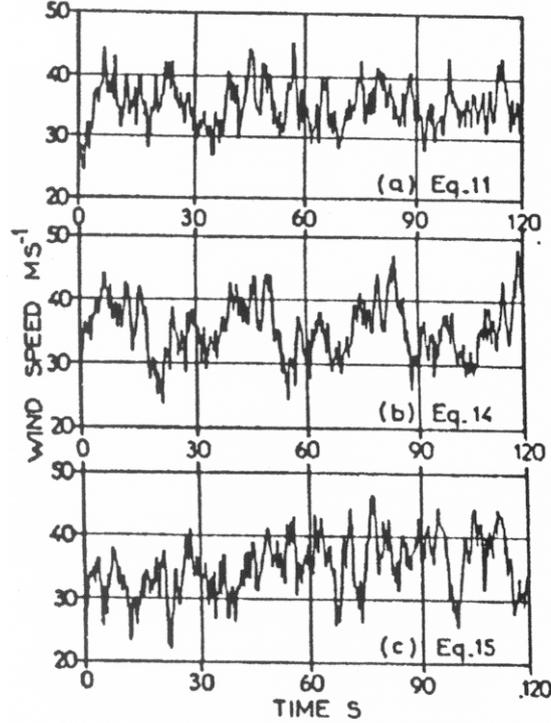


Fig. 5

### Cholesky decomposition

A square matrix  $\mathbf{A}$  of order  $n$  that is real, symmetric, semi-positive definite can be decomposed as:

$$\mathbf{A} = \mathbf{L}\mathbf{L}^T \quad (7)$$

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}; \mathbf{L} = \begin{bmatrix} l_{11} & 0 & \cdots & 0 \\ l_{21} & l_{22} & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ l_{n1} & l_{n2} & \cdots & l_{nn} \end{bmatrix} \quad (8)$$

where  $\mathbf{L}$  is a lower triangular matrix whose terms are given by the recursive formulae:

$$l_{ii} = \left[ a_{ii} - \sum_{j=1}^{i-1} l_{ij}^2 \right]^{1/2} \quad (i=1,2,..n) \quad (9)$$

$$l_{ki} = \frac{1}{l_{ii}} \left[ a_{ik} - \sum_{j=1}^{i-1} l_{ij} l_{kj} \right] \quad (k=i+1, i+2, ..n; i=1,2,..n) \quad (10)$$

### Example

$$\mathbf{A} = \begin{bmatrix} 4 & -1 \\ -1 & 2 \end{bmatrix}$$

From Eq. (9):  $i = 1 \Rightarrow \ell_{11} = \sqrt{a_{11}} = \sqrt{4} = 2$

From Eq. (10):  $k = 2, i = 1 \Rightarrow \ell_{21} = \frac{1}{\ell_{11}}[a_{12}] = \frac{1}{2}(-1) = -\frac{1}{2}$

From Eq. (9): (a)  $i = 2 \Rightarrow \ell_{22} = [a_{22} - (\ell_{21}^2)]^{1/2} = \sqrt{1 - \frac{1}{4}} = \frac{\sqrt{3}}{2}$

Therefore:

$$\mathbf{L} = \begin{bmatrix} 2 & 0 \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \Rightarrow$$

$$\mathbf{L}\mathbf{L}^T = \begin{bmatrix} 2 & 0 \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} 2 & -\frac{1}{2} \\ 0 & \frac{\sqrt{3}}{2} \end{bmatrix} = \begin{bmatrix} 4 & -1 \\ -1 & 2 \end{bmatrix} = \mathbf{A}$$

### Spectral decomposition

Let us consider again Eq. (7) and let us evaluate the eigenvalues and the eigenvectors of  $\mathbf{A}$ :

$$(\mathbf{A} - \lambda\mathbf{I})\boldsymbol{\psi} = \mathbf{0} \tag{11}$$

$\boldsymbol{\Psi} = [\boldsymbol{\psi}_1 \ \boldsymbol{\psi}_2 \ \dots \ \boldsymbol{\psi}_n]$  is the matrix of the orthonormal eigenvectors;  $\boldsymbol{\Lambda} = \mathbf{diag}\{\lambda_1, \lambda_2, \dots, \lambda_n\}$  is the matrix of the eigenvalues:

$$\boldsymbol{\Psi}^T\boldsymbol{\Psi} = \mathbf{I} \ ; \ \boldsymbol{\Psi}^T\mathbf{A}\boldsymbol{\Psi} = \boldsymbol{\Lambda} \tag{12}$$

Using Eq. (12):

$$\underbrace{\boldsymbol{\Psi}\boldsymbol{\Psi}^T}_{\mathbf{I}} \mathbf{A} \underbrace{\boldsymbol{\Psi}\boldsymbol{\Psi}^T}_{\mathbf{I}} = \boldsymbol{\Psi}\boldsymbol{\Lambda}\boldsymbol{\Psi}^T \Rightarrow$$
$$\mathbf{A} \underbrace{\boldsymbol{\Psi}\sqrt{\boldsymbol{\Lambda}}}_{\mathbf{L}} \underbrace{\sqrt{\boldsymbol{\Lambda}}\boldsymbol{\Psi}^T}_{\mathbf{L}^T} = \mathbf{L}\mathbf{L}^T \Rightarrow$$

$$\mathbf{L} = \boldsymbol{\Psi}\sqrt{\boldsymbol{\Lambda}} \tag{13}$$

Example

$$\mathbf{A} = \begin{bmatrix} 4 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 4-\lambda & -1 \\ -1 & 1-\lambda \end{bmatrix} \begin{Bmatrix} \psi_1 \\ \psi_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

The characteristic equation results:

$$(4-\lambda)(1-\lambda)-1=0 \Rightarrow \lambda^2-5\lambda+3=0 \Rightarrow \lambda = \frac{5 \mp \sqrt{13}}{2}$$

$$\begin{cases} \left(4 - \frac{5 \mp \sqrt{13}}{2}\right) \psi_1 - \psi_2 = 0 \\ -\psi_1 + \left(1 - \frac{5 \mp \sqrt{13}}{2}\right) \psi_2 = 0 \end{cases}$$

$$\bar{\Psi} = \begin{bmatrix} \frac{\sqrt{13}-3}{2} & \frac{-\sqrt{13}-3}{2} \\ 1 & 1 \end{bmatrix} \quad (\text{matrix of the orthogonal eigenvectors})$$

$$\bar{\Psi}^T \bar{\Psi} = \begin{bmatrix} \frac{\sqrt{13}-3}{2} & 1 \\ \frac{-\sqrt{13}-3}{2} & 1 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{13}-3}{2} & \frac{-\sqrt{13}-3}{2} \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1.09 & 0 \\ 0 & 11.91 \end{bmatrix} \Rightarrow$$

$$\psi_1 = \bar{\Psi}_1^T / \sqrt{1.09}; \psi_2 = \bar{\Psi}_2^T / \sqrt{11.91} \Rightarrow$$

$$\Psi = \begin{bmatrix} 0.29 & -0.96 \\ 0.96 & 0.29 \end{bmatrix} \quad (\text{matrix of the orthonormal eigenvectors})$$

$$\mathbf{L} = \Psi \sqrt{\Lambda} = \begin{bmatrix} 0.29 & -0.96 \\ 0.96 & 0.29 \end{bmatrix} \begin{bmatrix} \sqrt{\frac{5-\sqrt{13}}{2}} & 0 \\ 0 & \sqrt{\frac{5+\sqrt{13}}{2}} \end{bmatrix} = \begin{bmatrix} 0.24 & -1.99 \\ 0.80 & 0.60 \end{bmatrix}$$

$$\mathbf{L}\mathbf{L}^T = \begin{bmatrix} 0.24 & -1.99 \\ 0.80 & 0.60 \end{bmatrix} \begin{bmatrix} 0.24 & 0.80 \\ -1.99 & 0.60 \end{bmatrix} = \begin{bmatrix} 4 & -1 \\ -1 & 1 \end{bmatrix} = \mathbf{A}$$