# Deep generative neural networks Fundamentals & problem solving

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#### **Intended Learning Outcomes**

Attendees will, at the end of the course, be able to:

- describe the main principles of Artificial Neural Networks and Generative Adversarial Networks and their design
- identify problems that can be addressed by using Artificial Neural Networks
- use Python code to create and use Artificial Neural Networks to address classification and prediction problems
- identify problems that can be solved using Generative Machine Learning
- use Python code to create and use Generative Adversarial Networks to generate synthetic data



#### **Generative Adversarial Networks for fun**





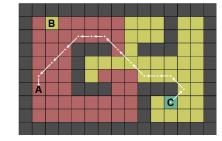


https://thispersondoesnotexist.com/

# Main Concepts

## **Artificial Intelligence**

- Artificial Intelligence: intelligence exhibited by machines and software
- Goal: automate "intellectual tasks" performed by humans
- Al models can be simple or complex
  - Simple: search, pathfinding, simple game playing, etc.
  - Complex: computer vision, control tasks, speech recognition, etc.





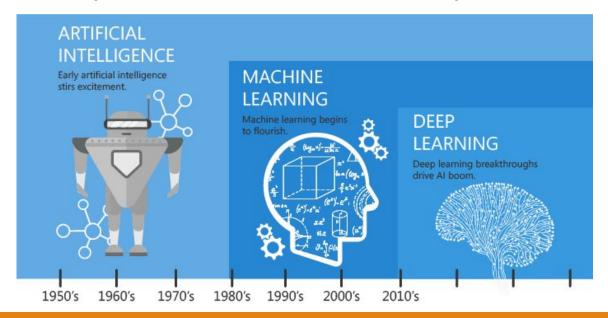


## Artificial intelligence

- The main idea is that AI imitates the human cognition process (perception, learning, pattern recognition, etc.)
- Key aspects: reasoning, problem solving, learning, knowledge representation
- Many types of algorithms: search, optimization, logic programming, or machine learning algorithms.

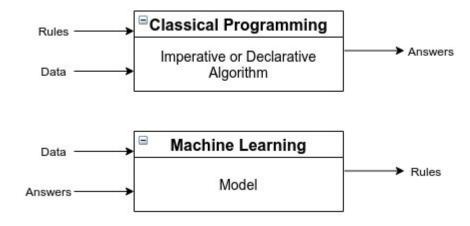
#### Machine Learning, Deep Learning, Al ....

- Artificial Intelligence is human-like "intelligence" exhibited by computers
- Machine Learning is the field of study that gives the computers the ability to learn without being explicitly programmed
- Deep Learning uses deep neural networks to implement machine learning



#### **Machine Learning**

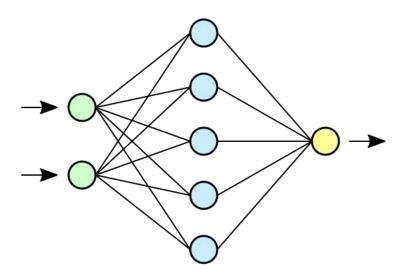
• Instead of being explicitly programmed (i.e. with a set of rules), machine learning algorithms try to infer the rules using a model.



Probabilistic (i.e., not deterministic) outputs. Characterized by an accuracy rate.

#### **Neural networks**

- A type of machine learning algorithms specialized on handling layered representations of data.
- Multi stage information extraction process: allows modeling complex (non-linear) functions.



## **Artificial Intelligence Applications**

- Facial recognition
- Game playing
- Speech recognition
- Language translation
- Self-driving cars
- Image translation: edges to photo
- Fake images
- Fake videos













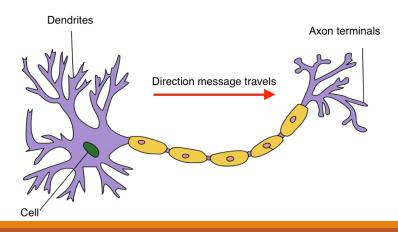
# Artificial Neural Networks

## Simple Biological Neuron

The neuron is the fundamental cell responsible for **processing and transmitting information** throughout the nervous system.

A simple biological network has three major parts:

- **Dendrites:** They branch out into a tree around the cell body. They get incoming signals to cell body with their strength as weights.
- Cell: Collects input through dendrites and processes to produce output.
- Axon: Responsible for transmitting signals to other neurons.





## **Collective Intelligence**

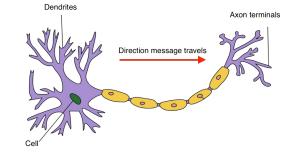
Shared or group intelligence that emerges from collaboration, collective efforts, and/or competition of many agents.

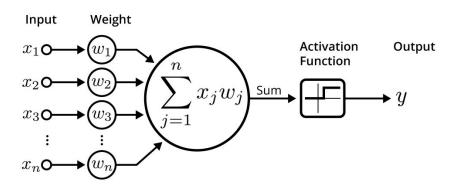
• A single neuron has limited processing capabilities: response speed is about several milliseconds.

However, the human brain is very powerful for problem solving: it uses
the aggregated power of millions of neurons.

#### **Artificial Neuron**

- An Artificial Neuron is a computational model of a biological neuron.
- The idea is that the artificial neuron receives input signals from other connected artificial neurons and via a non-linear transmission function emits a signal itself.
- Main operation:
  - Receives *n inputs*
  - Computes the weighted sum
  - Passes through an activation function
  - Sends the signal to succeeding neurons





## Artificial Neuron. Basic example

#### Two-inputs neuron operation:

1. Each input is multiplied by a weight

$$x_1 
ightarrow x_1 * w_1$$

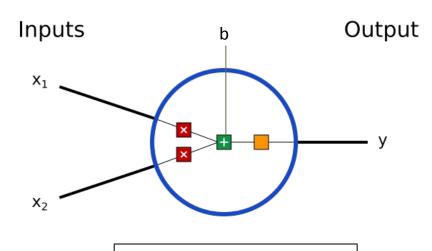
$$x_2 
ightarrow x_2 * w_2$$

2. All weighted sums are added with a **bias** b (*feedforward*)

$$(x_1 * w_1) + (x_2 * w_2) + b$$

The sum is passed through an activation function

$$y = f(x_1 * w_1 + x_2 * w_2 + b)$$



Code: <u>basic-neuron.py</u>

The output of the network depends on the **weights**, the **bias**, and the **activation function** 

#### Artificial Neuron. Basic example

#### Two-inputs neuron operation:

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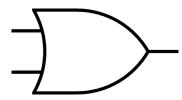
$$y = f(x_1 * w_1 + x_2 * w_2 + b)$$

```
class BasicNeuron:
    """ It encapsulates a basic neuron that is constructed
   and an activation function. """
   def init (self, weights, bias, activation):
        self.weights = weights
       self.bias = bias
        self.activation = activation
   def feedforward(self, inputs):
           It applies the feedforward of the function: it
       function. """
        total = np.dot(self.weights, inputs) + self.bias
        return self.activation(total)
```

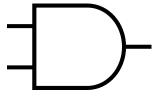
The output of the network depends on the **weights**, the **bias**, and the **activation function** 

#### Artificial Neuron. What can we do?

Try to implement a logic function with the two-input neuron.



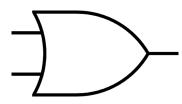
$\mathbf{x_1}$	X <sub>2</sub>	x <sub>1</sub> OR x <sub>2</sub>
0	0	0
0	1	1
1	0	1
1	1	1



X <sub>1</sub>	X <sub>2</sub>	x <sub>1</sub> AND x <sub>2</sub>
0	0	0
0	1	0
1	0	0
1	1	1

#### Artificial Neuron. What can we do?

Try to implement a logic function with the two-input neuron.

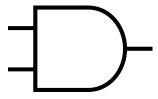


$\mathbf{x}_{1}$	X <sub>2</sub>	x <sub>1</sub> OR x <sub>2</sub>
0	0	0
0	1	1
1	0	1
1	1	1

```
weights = np.array([2, 2]) # w1 = 0, w2 = 1
bias = 0 # b = 0

offinction = BasicNeuron(weights, bias, step)
input = np.array([1, 0]) # x1 = 1, x2 = 0

output = or_function.feedforward(input)
print('OR({}) = {}'.format(input, output))
```



X <sub>1</sub>	X <sub>2</sub>	x <sub>1</sub> AND x <sub>2</sub>
0	0	0
0	1	0
1	0	0
1	1	1

```
weights = np.array([1, 1]) # w1 = 1, w2 = 1
bias = 0 # b = 0
and_function = BasicNeuron(weights, bias, step)
input = np.array([0, 1]) # x1 = 0, x2 = 1
output = and_function.feedforward(input)
print('AND({{}}) = {{}}'.format(input, output))
```

## Artificial Neuron. Basic example (2)

#### Two-inputs neuron operation:

1. Each input is multiplied by a weight

$$x_1 
ightarrow x_1 * w_1$$

$$x_2 
ightarrow x_2 * w_2$$

2. All weighted sums are added with a **bias** b (*feedforward*)

$$(x_1 * w_1) + (x_2 * w_2) + b$$

3. The sum is passed through an activation function

$$y = f(x_1 * w_1 + x_2 * w_2 + b)$$

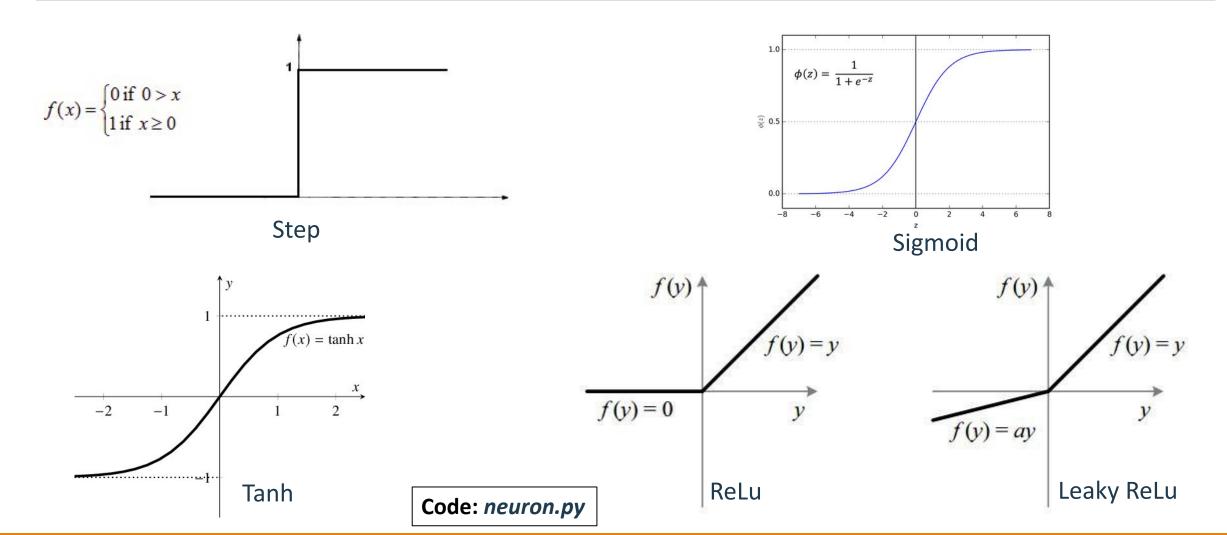
```
class BasicNeuron:
    """ It encapsulates a basic neuron that is constructed
   and an activation function. """
   def init (self, weights, bias, activation):
        self.weights = weights
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        self.activation = activation
   def feedforward(self, inputs):
           It applies the feedforward of the function: it
       function. """
        total = np.dot(self.weights, inputs) + self.bias
        return self.activation(total)
```

The output of the network depends on the **weights**, the **bias**, and the **activation function** 

#### **Activation Function**

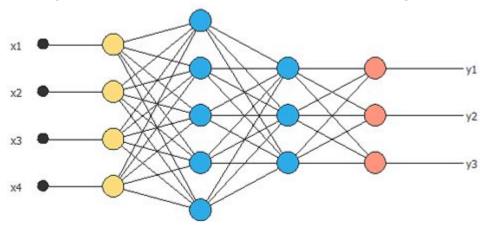
- Activation function decides whether a neuron should be activated or not by calculating the weighted sum and further adding bias to it. The motive is to introduce non-linearity into the output of a neuron.
- If we do not apply activation function then the output signal would be simply linear function (one-degree polynomial).
- Linear functions are limited in their complexity, have **less power**. Without activation function, our model cannot learn and model complicated data such as images, videos, audio, speech, etc.

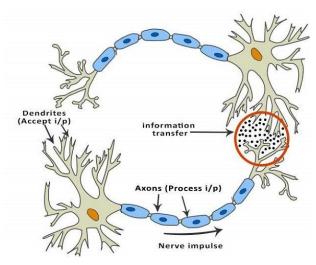
#### **Activation Function. Types**



#### **Artificial Neural Networks**

- A neural network is a bunch of neurons connected together.
- Neural networks are typically organized in layers.
- Layers are made up of a number of interconnected neurons.
- •Inputs are presented to the network via the **input layer**, which communicates to **one or more hidden layers** through **weighted connections**.
- The hidden layers then link to an output layer.

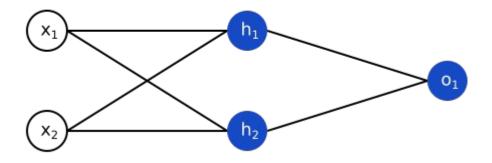




#### **Artificial Neural Networks. Code**

• Example 1: Two inputs, two neurons in a hidden layer, and one output

Input Layer Hidden Layer Output Layer



Code: <u>basic-two-layer-neural-network.py</u>

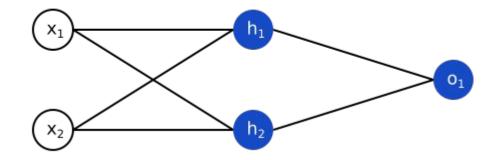
• Example 2: X inputs, H neurons in the hidden layer, and one output

Code: <u>two-layer-neural-network.py</u>

#### **Artificial Neural Networks. Code**

• Example 1: Two inputs, two neurons in a hidden lay

Input Layer Hidden Layer Output Layer



Code: <u>basic-two-layer-neural-network</u>

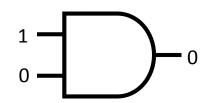
• Example 2: X inputs, H neurons in the hidden layer,

Code: <u>two-layer-neural-network.py</u>

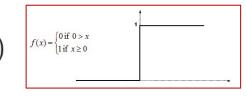
```
class BasicNeuralNetwork:
    A neural network with:
   - two inputs: x1, and x2
   - a hidden layer with two neurons: h1 and h2
   - an output layer with a neuron: o1
   The three neurons use the same weights and bias
   def init (self, weights, bias, activation):
        self.h1 = Neuron(weights, bias, activation)
        self.h2 = Neuron(weights, bias, activation)
        self.o1 = Neuron(weights, bias, activation)
    def feedforward(self, x):
        """First we compute the output of the first layer"""
        output h1 = self.h1.feedforward(x)
        output h2 = self.h2.feedforward(x)
        """The outputs of the hidden layer h1 and h2 are the input of the
        output o1 = self.o1.feedforward(np.array([output h1, output h2]))
        return output o1
```

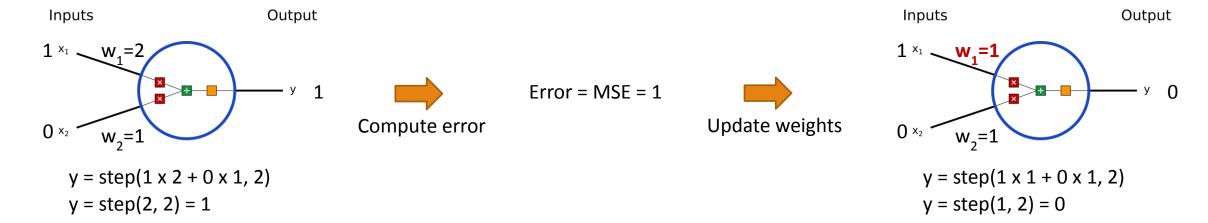
#### How do ANNs Learn?

- The output of the ANN depends on the weights
- Learning consist on updating the weights to get a desired output, i.e., minimize the error



$$y = f(x_1 * w_1 + x_2 * w_2 + b)$$



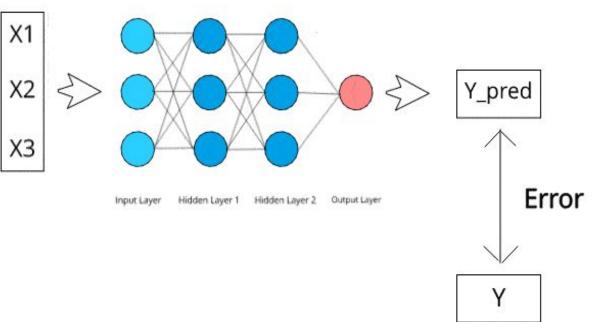


#### How do ANNs Learn?

ANNs learn by solving the **optimization problem** of reducing the error in terms of error, loss or cost function.

Back Propagation Algorithm:

It learns by example. If you submit to the algorithm the example of what you want the network to do, it changes the network's weights so that it can produce desired output for a particular input on finishing the training.

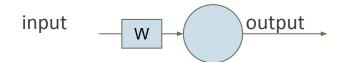


Objective: Learn the following data

Input	Desired output
0	0
1	2
2	4
3	6
4	8

output = 2 x input

- Error function: mean squared error (MSE)
- Neural network model: output = W x input (W represents the weight)



First step: Random weights initialization  $\rightarrow$  W = 3  $\rightarrow$  output = 3 x input

**Second step:** Get actual output → Forward propagate input

Input	Actual output
0	0
1	3
2	6
3	9
4	12

**Third step:** Get loss values  $\rightarrow$  loss = f(actual output, desired output) In our example f is mean squared error (MSE)

Input	Actual output	Desired output	Loss = Square error
0	0	0	0
1	3	2	1
2	6	4	4
3	9	6	9
4	12	8	16

Total loss is 30

Fourth step: Differentiation

In our numerical example: -1000.0 < W < 1000.0

We can move with steps of 0.0001

Optimization problem → finding W that minimizes loss

**Differentiation** allows us to address the problem

Remember  $\rightarrow$  the derivative of a function at a certain point, gives the rate or the speed of which this function is changing its values at this point

In order to see the effect of the derivative, we can ask ourselves the following question: how much the total error will change if we change the internal weight of the neural network with a certain small value  $\delta W=0.0001$ 

Loss with W=3.0001  $\rightarrow$  30.006

Loss with W=2.9999  $\rightarrow$  29.994

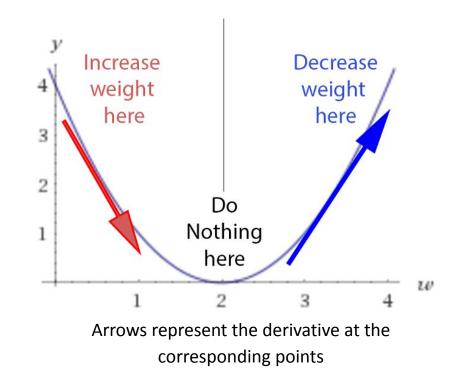
Fourth step: Differentiation

We could guess this rate by calculating directly the derivative of the loss function Here is what our loss function looks like:

If **W=2**, we have a loss of 0, since the neural network actual output fits perfectly the training set

If **W<2**, we have a positive loss function, but the derivative is negative, meaning that an increase of weight will decrease the loss function

If **W>2**, we have a positive loss, but the derivative is positive, meaning that any more increase in the weight, will increase the losses even more



Fifth step: Backpropagation

In this example, we used only one layer neural network

→ No backpropagation is needed!!!

In the case there are more layers, the process is the same but each layer (as the output layer with the loss function) requires to provide the function of its derivative.

Thus, we only need to keep a stack of the function calls during the forward pass and their parameters, in order to know the way back to back-propagate the errors using the derivatives of these functions. This can be done by de-stacking through the function calls. This technique is called auto-differentiation.

Sixth step: Weight update

Thus as a general rule of weight updates is the delta rule:

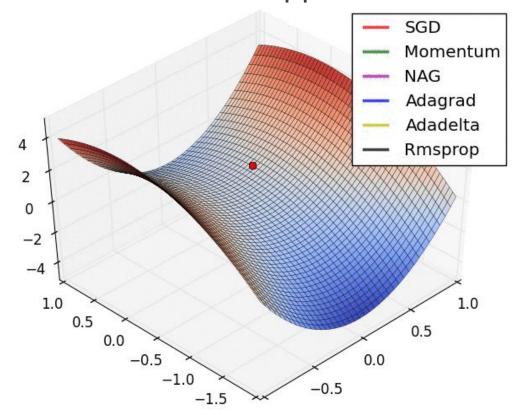
New weight = old weight - derivative x learning rate

If the **derivative rate is positive**, it means that an increase in weight will increase the error, thus the new weight should be smaller.

If the derivative rate is negative, it means that an increase in weight will decrease the error, thus we need to increase the weights.

If the **derivative** is **0**, it means that we are in a stable minimum. Thus, no update on the weights is needed -> we reached a stable state.

The importance of the optimization method applied



https://towardsdatascience.com/overview-of-various-optimizers-in-neural-networks-17c1be2df6d5

## **Deep Learning**

ANN results get better with

- more/better data
- bigger models
- more computation

#### **Deep Learning**

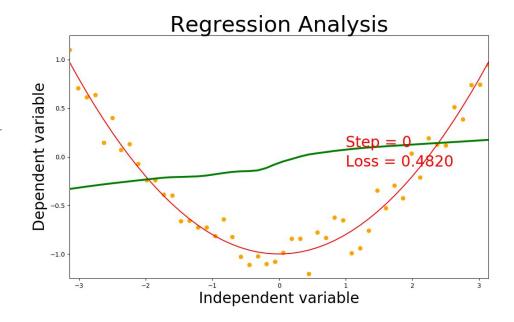
ANN results get better with

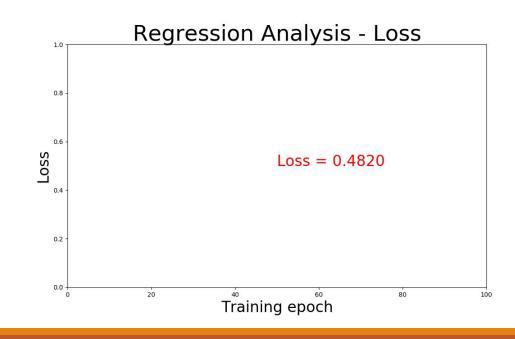
- more/better data
- bigger models
- more computation

#### **Example:**

Deep Learning for regression

https://drive.google.com/file/d/115dbtD8Zxs2I98t 0wSzvauEkie4IPI5P/view?usp=sharing



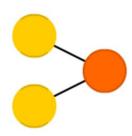


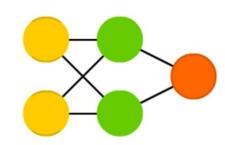
## **Artificial Neural Networks. Types**

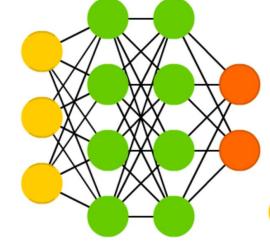
Perceptron (P)

Feed Forward (FF)

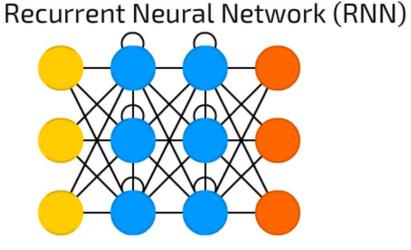
Deep Feed Forward (DFF)

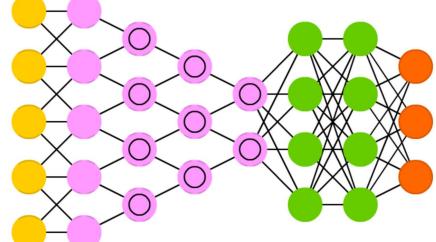






Deep Convolutional Network (DCN)





## Thanks!

# Comments?

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