

Escalado Multidimensional. (Ej 2 Práctica 4)

$$Q = -\frac{1}{2} P D^{(2)} P.$$

Supongamos que $Q = (Px)(Px)'$

$$\begin{aligned} &= \tilde{X} \tilde{X}' \\ \xrightarrow{\text{descomp.}} &= U \Lambda U' \end{aligned}$$

espectral.

Q simétrica

y es semi-definida
positiva

($\lambda \geq 0$ $\forall \lambda$ valor
propio)

Siendo $U = (u_1 | u_2 | \dots | u_n)$

donde $\{u_1, u_2, \dots, u_n\}$ son vectores propios de Q .

los valores propios > 0 de $\tilde{X} \tilde{X}'$ y de $\tilde{X}' \tilde{X}$

coinciden.

$\tilde{X} \tilde{X}'$: $u_1, u_2, \dots, u_n \in \mathbb{R}^n$ vectores propios

$\tilde{X}' \tilde{X}$: loadings-
 $q_1, q_2, \dots, q_p \in \mathbb{R}^P$.

comp. principales: $z_1 = \tilde{x}_{q_1}, z_2 = \tilde{x}_{q_2}, \dots, z_p = \tilde{x}_{q_p} \in \mathbb{R}^n$

Si q_1 es vector propio de $\tilde{X}'\tilde{X}$
correspondiente a λ_1

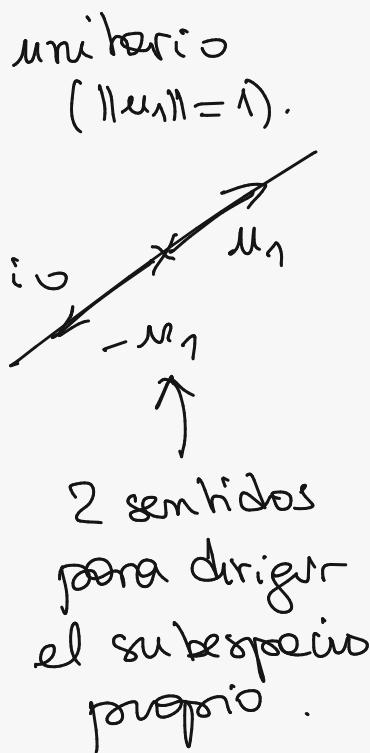
$$\boxed{\tilde{X}'\tilde{X} q_1 = \lambda_1 q_1}$$

$$\Rightarrow \tilde{X}\tilde{X}'(\tilde{X}q_1) = \tilde{X}(\lambda_1 q_1)$$

$$\Rightarrow \boxed{\tilde{X}\tilde{X}'(\tilde{X}q_1) = \lambda_1 \tilde{X}q_1.}$$

$\Rightarrow \tilde{X}q_1$ es vector propio de $\tilde{X}\tilde{X}' = Q$
correspondiente a λ_1

\hookrightarrow $\underbrace{\tilde{X}q_1}_{z_1} \parallel u_1$ unitario ($\|u_1\|=1$).
 $z_1 \leftarrow$ no unitario
 $\Rightarrow u_1 = \frac{z_1}{\sqrt{\lambda_1}}$



Cuando trabajamos en espacio multidimensional
lo que obtenemos son las coordenadas
de la proyección de los individuos en el
plano factorial.

$$\begin{aligned}
Q &= U \wedge U' \quad \wedge = \begin{pmatrix} \lambda_1 0 \\ 0 \lambda_2 \end{pmatrix} \\
&\stackrel{\text{simplifie}}{=} \left(\begin{array}{c|c} u_1 & u_2 \end{array} \right) \left(\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \left(\begin{array}{c|c} u_1 & u_2 \end{array} \right) \right)' \\
&= \left(\begin{array}{c|c} u_1 & u_2 \end{array} \right) \left(\begin{pmatrix} \sqrt{\lambda_1} & 0 \\ 0 & \sqrt{\lambda_2} \end{pmatrix} \left(\begin{pmatrix} \sqrt{\lambda_1} & 0 \\ 0 & \sqrt{\lambda_2} \end{pmatrix} \left(\begin{array}{c|c} u_1 & u_2 \end{array} \right) \right)' \right)' \\
&= \left(\begin{array}{c|c} \sqrt{\lambda_1} u_1 & \sqrt{\lambda_2} u_2 \end{array} \right) \left(\begin{array}{c|c} \sqrt{\lambda_1} u_1 & \sqrt{\lambda_2} u_2 \end{array} \right)' \\
&= \left(\begin{array}{c|c} z_1 & z_2 \end{array} \right) \left(\begin{array}{c|c} z_1 & z_2 \end{array} \right)' \\
&= z z'.
\end{aligned}$$

Obs: $Q = YY'$

Si $\tilde{Y} = YA$, A ortogonal. (A matriz de rotación).

$$A'A = AA' = I.$$

$$\begin{aligned}
 YY' &= (YA)(YA)' \\
 &= YAA'Y' \\
 &= YIY' \\
 &= YY' = Q.
 \end{aligned}$$

$$\begin{array}{c}
 x_{1j} \\
 x_{2j} \\
 \vdots \\
 \vdots \\
 x_{nj}
 \end{array}$$

↑
col. j

$$\tilde{x}_{ij} = \frac{x_{ij} - \bar{x}_j}{A_j}$$

$$\bar{x}_j = \frac{x_{1j} + x_{2j} + \dots + x_{nj}}{n}$$

$$(Desvio) A_j = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_{ij} - \bar{x}_j)^2}$$

$$R \text{ no max } \sigma_j \text{ pero } s_j = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_{ij} - \bar{x}_j)^2}$$

(desvio corregido)

Ejercicios 5 Práctico 4.

$$E = \{x_1, x_2, \dots, x_n\}.$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\begin{aligned} d_{n+1,i}^2 &= d^2(x_{n+1}, x_i) = \|x_{n+1} - x_i\|^2 \\ &\quad \text{individuo } n+1 \quad \text{individuo } i \\ &= \|x_{n+1}\|^2 + \|x_i\|^2 - 2 x_{n+1}' x_i \\ &= x_{n+1}' x_{n+1} + x_i' x_i - 2 x_{n+1}' x_i \end{aligned}$$

$$d = \begin{pmatrix} d_{n+1,1}^2 \\ \vdots \\ d_{n+1,n}^2 \end{pmatrix} = \|x_{n+1}\|^2 I_n + \begin{pmatrix} x_1' x_1 \\ x_2' x_2 \\ \vdots \\ x_n' x_n \end{pmatrix} - 2 X x_{n+1}$$

↑
vector
n dimensional
de 1's

$$\Rightarrow d = \|x_{n+1}\|^2 I_n + \underbrace{\text{diag}(Q)}_Q - 2 X x_{n+1}$$

Multiplico

$$\Rightarrow X' d = \|x_{n+1}\|^2 X' I_n + X' Q - 2 X' X x_{n+1}$$

$$\Rightarrow 2 X' X x_{n+1} = X' (Q - d) + \|x_{n+1}\|^2 \underbrace{X' I_n}_Q$$

$$\Rightarrow x_{n+1} = \frac{1}{2} (X' X)^{-1} X' (Q - d)$$

$$x_{n+1} = \frac{1}{2} \Lambda^{-1} X' (Q - d)$$

Recor der los fórmulas :

* contribución individuo x_i al eje v_k :

$$\frac{p_i c_{ik}^2}{\lambda_k}$$

$$c_{ik} = \langle x_i, v_k \rangle$$

$$x_{v_k} = z_k = \begin{pmatrix} c_{1k} \\ c_{2k} \\ \vdots \\ c_{nk} \end{pmatrix}, \|z_k\|^2 = \lambda_k$$

* contribución variable x_j al eje k :

$$\frac{d_{jk}^2}{\lambda_k} = a_{jk}^2$$

$$d_{jk} = \langle x_j, v_k \rangle$$

$$x_{v_k}^j = w_k = \begin{pmatrix} d_{1k} \\ d_{2k} \\ \vdots \\ d_{pk} \end{pmatrix}, \|w_k\|^2 = \lambda_k$$

* colinealidad individuo x_i sobre eje k :

$$\cos^2(\theta_{ik}) = \frac{p_i c_{ik}^2}{\|x_i\|^2}$$

* colinealidad variable x_j sobre eje k :

$$\cos^2(\theta_{jk}) = \frac{d_{jk}^2}{\|x_j\|^2}$$