

Network Modeling

Gonzalo Mateos

Dept. of ECE and Goergen Institute for Data Science

University of Rochester

gmateosb@ece.rochester.edu

<http://www.ece.rochester.edu/~gmateosb/>

Acknowledgments: E. Kolaczyk, F. La Rocca and A. Ribeiro

Facultad de Ingeniería, UdelaR

Montevideo, Uruguay

February 4, 2021

What is this lecture about?

- ▶ **Statistical graph models** are used for a variety of reasons:
 - 1) Mechanisms explaining properties observed on real-world networks
Ex: small-world effects, power-law degree distributions
 - 2) Testing for 'significance' of a characteristic $\eta(G)$ in a network graph
Ex: is the observed average degree unusual or anomalous?
 - 3) Assessment of factors potentially predictive of relational ties
Ex: are there reciprocity or transitivity effects in play?
- ▶ **Focus today on construction and use of models for network data**

- ▶ **Def:** A model for a network graph is a collection

$$\{P_\theta(G), G \in \mathcal{G} : \theta \in \Theta\}$$

- ▶ \mathcal{G} is an ensemble of possible graphs
 - ▶ $P_\theta(\cdot)$ is a probability distribution on \mathcal{G} (often write $P(\cdot)$)
 - ▶ Parameters θ ranging over values in parameter space Θ
- ▶ Richness of models derives from **how we specify $P_\theta(\cdot)$**
 - ⇒ Methods range from the simple to the complex

Model specification

- 1) Let $P(\cdot)$ be uniform on \mathcal{G} , add structural constraints to \mathcal{G}
Ex: Erdős-Renyi random graphs, generalized random graph models
 - 2) Induce $P(\cdot)$ via application of simple generative mechanisms
Ex: small world, preferential attachment, copying models
 - 3) Model structural features and their effect on G 's topology
Ex: exponential random graph models
 - 4) Model propensity towards establishing links via latent variables
Ex: stochastic block models, graphons, random dot product graphs
- Computational cost of associated inference algorithms relevant

Random graph models

Small-world models

Network-growth models

Exponential random graph models

Latent network models

Random dot product graphs

Classical random graph models

- ▶ Assign equal probability on all undirected graphs of given order and size
 - ▶ Specify collection \mathcal{G}_{N_v, N_e} of graphs $G(\mathcal{V}, \mathcal{E})$ with $|\mathcal{V}| = N_v$, $|\mathcal{E}| = N_e$
 - ▶ Assign $P(G) = \binom{N}{N_e}^{-1}$ to each $G \in \mathcal{G}_{N_v, N_e}$, where $N = |\mathcal{V}^{(2)}| = \binom{N_v}{2}$
- ▶ Most common variant is the **Erdős-Renyi random graph model** $G_{n,p}$
 - ⇒ Undirected graph on $N_v = n$ vertices
 - ⇒ Edge (u, v) present w.p. p , independent of other edges
- ▶ **Simulation**: simply draw $N = \binom{N_v}{2} \approx N_v^2/2$ i.i.d. $\text{Ber}(p)$ RVs
 - ▶ Inefficient when $p \sim N_v^{-1} \Rightarrow$ **sparse graph, most draws are 0**
 - ▶ Skip non-edges drawing $\text{Geo}(p)$ i.i.d. RVs, runs in $O(N_v + N_e)$ time

Properties of $G_{n,p}$

- ▶ $G_{n,p}$ is well-studied and tractable. **Noteworthy properties:**

P1) **Degree distribution** $P(d)$ is binomial with parameters $(n-1, p)$

- ▶ Large graphs have concentrated $P(d)$ with exponentially-decaying tails

P2) Phase transition on the **emergence of a giant component**

- ▶ If $np > 1$, $G_{n,p}$ has a giant component of size $O(n)$ w.h.p.
- ▶ If $np < 1$, $G_{n,p}$ has components of size only $O(\log n)$ w.h.p.



$np > 1$



$np < 1$

P3) **Small clustering coefficient** $O(n^{-1})$ and **short diameter** $O(\log n)$ w.h.p.

Generalized random graph models

- ▶ Recipe for generalization of Erdős-Renyi models
 - ⇒ Specify \mathcal{G} of fixed order N_v , possessing a desired characteristic
 - ⇒ Assign equal probability to each graph $G \in \mathcal{G}$
- ▶ Configuration model: fixed degree sequence $\{d_{(1)}, \dots, d_{(N_v)}\}$
 - ▶ Size fixed under this model, since $N_e = \bar{d}N_v/2 \Rightarrow \mathcal{G} \subset \mathcal{G}_{N_v, N_e}$
 - ▶ Equivalent to specifying model via conditional distribution on \mathcal{G}_{N_v, N_e}
- ▶ Configuration models useful as reference, i.e., 'null' models
 - Ex: compare observed G with $G' \in \mathcal{G}$ having power law $P(d)$
 - Ex: expected group-wise edge counts in **modularity** measure

Results on the configuration model

P1) Phase transition on the **emergence of a giant component**

- ▶ Condition depends on first two moments of given $P(d)$
- ▶ Giant component has size $O(N_v)$ as in $G_{N_v, p}$

M. Molloy and B. Reed, "A critical point for random graphs with a given degree sequence," *Random Struct. and Alg.*, vol. 6, pp. 161-180, 1995

P2) **Clustering coefficient vanishes** slower than in $G_{N_v, p}$

M. Newman et al, "Random graphs with arbitrary degree distributions and their applications", *Physical Rev. E*, vol. 64, p. 26,118, 2001

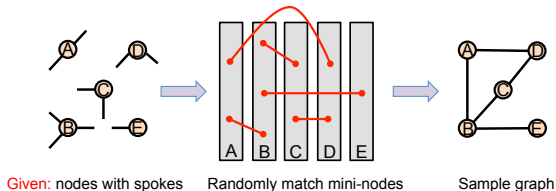
P3) Special case of given power-law degree distribution $P(d) \sim Cd^{-\alpha}$

- ▶ For $\alpha \in (2, 3)$, **short diameter** $O(\log N_v)$ as in $G_{N_v, p}$

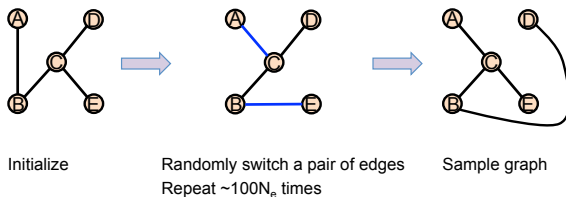
F. Chung and L. Lu, "The average distances in random graphs with given expected degrees," *PNAS*, vol. 99, pp. 15,879-15,882, 2002

Simulating generalized random graphs

▶ Matching algorithm



▶ Switching algorithm



Task 1: Model-based estimation in network graphs

- ▶ Consider a sample G^* of a population graph $G(\mathcal{V}, \mathcal{E})$
 - ⇒ Suppose a given characteristic $\eta(G)$ is of interest
 - ⇒ **Q:** Useful estimate $\hat{\eta} = \hat{\eta}(G^*)$ of $\eta(G)$?
- ▶ Statistical inference in sampling theory via **design-based methods**
 - ⇒ Only source of randomness is due to the sampling design
- ▶ Augment this perspective to include a **model-based component**
 - ▶ Assume G drawn uniformly from the collection \mathcal{G} , prior to sampling
- ▶ Inference on $\eta(G)$ should incorporate both randomness due to
 - ⇒ **Selection of G from \mathcal{G}** and **sampling G^* from G**

Directly modeling $\eta(G)$

- ▶ So far considered modeling G for model-based estimation of $\eta(G)$
⇒ Alternatively, one may **specify a model for $\eta(G)$ directly**

Example

- ▶ Estimate the power-law exponent $\eta(G) = \alpha$ from degree counts
- ▶ A power law implies the linear model $\log P(d) = C - \alpha \log d + \epsilon$
⇒ **Could use a model-based estimator such as least squares**
- ▶ Better form the MLE for the model $f(d; \alpha) = \frac{\alpha-1}{d_{\min}} \left(\frac{d}{d_{\min}}\right)^{-\alpha}$

$$\text{Hill estimator} \Rightarrow \hat{\alpha} = 1 + \left[\frac{1}{N_v} \sum_{i=1}^{N_v} \log \left(\frac{d_i}{d_{\min}} \right) \right]^{-1}$$

Task 2: Assessing significance in network graphs

- ▶ Consider a graph G^{obs} derived from observations
- ▶ **Q:** Is a structural characteristic $\eta(G^{obs})$ **significant**, i.e., unusual?
 - ⇒ Assessing significance requires a frame of reference, or null model
 - ⇒ Random graph models often used in setting up such comparisons
- ▶ Define collection \mathcal{G} , and compare $\eta(G^{obs})$ with values $\{\eta(G) : G \in \mathcal{G}\}$
 - ⇒ Formally, construct the reference distribution

$$P_{\eta, \mathcal{G}}(t) = \frac{|\{G \in \mathcal{G} : \eta(G) \leq t\}|}{|\mathcal{G}|}$$

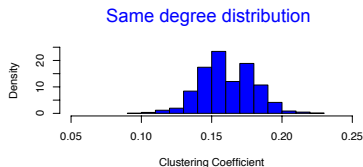
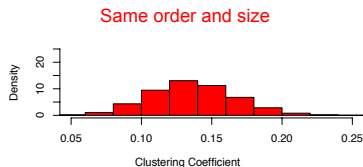
- ▶ If $\eta(G^{obs})$ found to be sufficiently unlikely under $P_{\eta, \mathcal{G}}(t)$
 - ⇒ Evidence against the null H_0 : G^{obs} is a uniform draw from \mathcal{G}

Example: Zachary's karate club

- ▶ **Zachary's karate club** has clustering coefficient $cl(G^{obs}) = 0.2257$
 - ⇒ Random graph models to assess whether the value is unusual
- ▶ Construct two 'comparable' abstract frames of reference
 - 1) Collection \mathcal{G}_1 of random graphs with same $N_v = 34$ and $N_e = 78$
 - 2) Add the constraint that \mathcal{G}_2 has the same degree distribution as G^{obs}
- ▶ $|\mathcal{G}_1| \approx 8.4 \times 10^{96}$ and $|\mathcal{G}_2|$ much smaller, but still large
 - ⇒ Enumerating \mathcal{G}_1 intractable to obtain $P_{\eta, \mathcal{G}_1}(t)$ exactly
- ▶ Instead **use simulations** to approximate both distributions
 - ⇒ Draw 10,000 uniform samples G from each \mathcal{G}_1 and \mathcal{G}_2
 - ⇒ Calculate $\eta(G) = cl(G)$ for each sample, plot histograms

Example: Zachary's karate club (cont.)

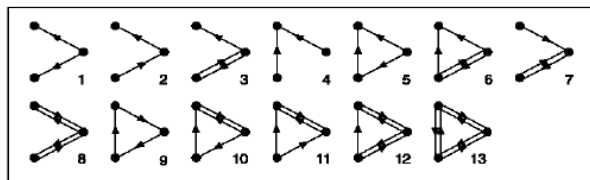
- ▶ Plot histograms to approximate the distributions



- ▶ Unlikely to see a value $cl(G^{obs}) = 0.2257$ under both graph models
Ex: only 3 out of 10,000 samples from \mathcal{G}_1 had $cl(G) > 0.2257$
- ▶ Strong evidence to reject G^{obs} obtained as sample from \mathcal{G}_1 or \mathcal{G}_2

Task 3: Detecting network motifs

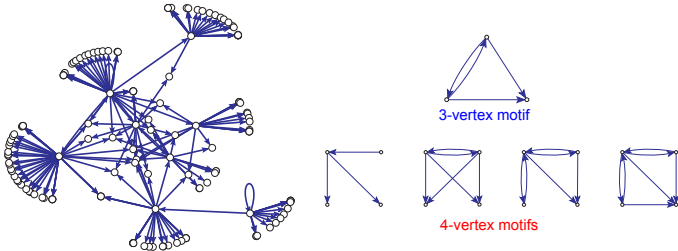
- ▶ Related use of random graph models is for detecting **network motifs**
 - ⇒ Find the simple 'building blocks' of a large complex network
- ▶ **Def:** Network motifs are small subgraphs occurring far more frequently in a given network than in comparable random graphs
- ▶ **Ex:** there are $L_3 = 13$ different connected 3-vertex subdigraphs



- ▶ Let N_i be the count in G of the i -th type k -vertex subgraph, $i = 1, \dots, L_k$
 - ⇒ Each value N_i can be compared to a suitable reference $P_{N_i, G}$
 - ⇒ Subgraphs for which N_i is extreme are declared as network motifs

Example: AIDS blog network

- ▶ **AIDS blog network** G^{obs} with $N_v = 146$ bloggers and $N_e = 183$ links
⇒ Examined evidence for motifs of size $k = 3$ and 4 vertices



- ▶ Simulated 10,000 digraphs using a switching algorithm
⇒ Fixed in- and out-degree sequences, mutual edges as in G^{obs}
⇒ Constructed approximate reference distributions $P_{N_i, \mathcal{G}}(t)$
- ▶ **Ex:** two bloggers with a mutual edge and a common 'authority'

Random graph models

Small-world models

Network-growth models

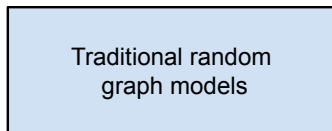
Exponential random graph models

Latent network models

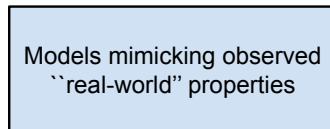
Random dot product graphs

Models for real-world networks

- ▶ Noteworthy innovation in 'modern' graph modeling



Transition



A “small” world?

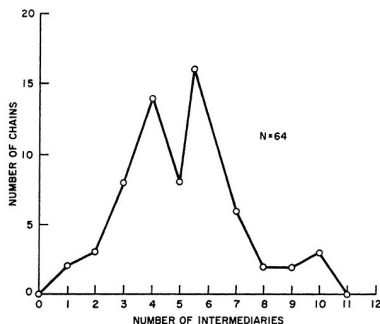
- ▶ **Six degrees of separation** popularized by a play [Guare'90]
 - ⇒ Short paths between us and everyone else on the planet
 - ⇒ Term relatively new, the concept has a long history
- ▶ Traced back to F. Karinthy in the 1920s
 - ⇒ 'Shrinking' modern world due to increased human connectedness
 - ⇒ **Challenge:** find someone whose distance from you is > 5
 - ⇒ Inspired by G. Marconi's Nobel prize speech in 1909
- ▶ First mathematical treatment [Kochen-Pool'50]
 - ⇒ Formally modeled the mechanics of social networks
 - ⇒ **But left 'degrees of separation' question unanswered**
- ▶ Chain of events led to a groundbreaking experiment [Milgram'67]

Milgram's experiment

- ▶ **Q1:** What is the typical geodesic distance between two people?
 - ⇒ Experiment on the global friendship (social) network
 - ⇒ Cannot measure in full, so need to probe explicitly
- ▶ **S. Milgram's ingenious small-world experiment in 1967**
 - ▶ 296 letters sent to people in Wichita, KS and Omaha, NE
 - ▶ Letters indicated a (unique) **contact** person in Boston, MA
 - ▶ Asked them to forward the letter to the contact, following **rules**
- ▶ **Def:** **friend** is someone known on a first-name basis
 - Rule 1:** If contact is a friend then send her the letter; else
 - Rule 2:** Relay to friend most-likely to be a contact's friend
- ▶ **Q2:** How many letters arrived? How long did they take?

Milgram's experimental results

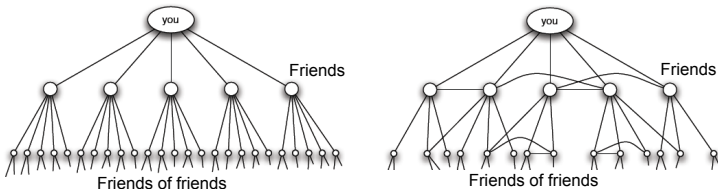
- ▶ 64 of 296 letter reached the destination, **average path length $\bar{\ell} = 6.2$**
⇒ Inspiring Guare's '6 degrees of separation'
- ▶ **Conclusion:** short paths connect arbitrary pairs of people



S. Milgram, "The small-world problem," *Psychology Today*, vol. 2, pp. 60-67, 1967

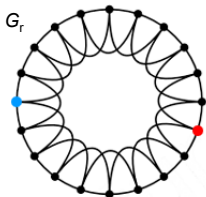
Moment to reflect

- ▶ Milgram demonstrated that short paths are in abundance
- ▶ **Q:** Is the small-world theory reasonable? Sure, e.g., assumes:
 - ▶ We have 100 friends, each of them has 100 **other** friends, ...
 - ▶ After 5 degrees we get 10^{10} friends > twice the Earth's population

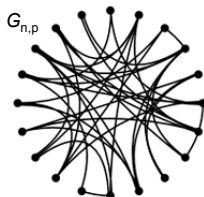


- ▶ Not a realistic model of social networks exhibiting:
 - ⇒ Homophily [Lazarfeld'54]
 - ⇒ Triadic closure [Rapoport'53]
- ▶ **Q:** How can networks be **highly-structured locally** and **globally small**?

Structure and randomness as extremes



High clustering and diameter



Low clustering and diameter

- ▶ **One-dimensional regular lattice** G_r on N_v vertices
 - ▶ Each node is connected to its $2r$ closest neighbors (r to each side)

Structure yields high clustering and high diameter

$$\text{cl}(G_r) = \frac{3r - 3}{4r - 2} \quad \text{and} \quad \text{diam}(G_r) = \frac{N_v}{2r}$$

- ▶ Other extreme is a **$G_{N_v,p}$ random graph** with $p = O(N_v^{-1})$
Randomness yields low clustering and low diameter

$$\text{cl}(G_{N_v,p}) = O(N_v^{-1}) \quad \text{and} \quad \text{diam}(G_{N_v,p}) = O(\log N_v)$$

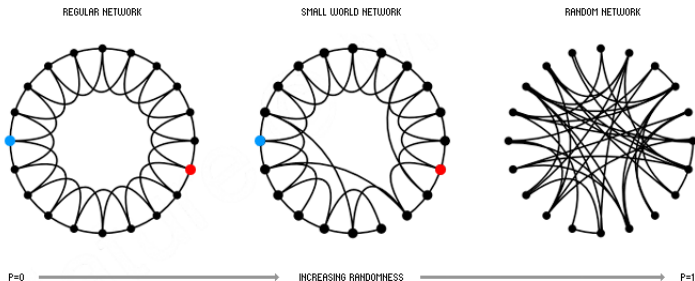
The Watts-Strogatz model

- ▶ **Small-world model**: blend of structure with little randomness

S1: Start with regular lattice that has desired clustering

S2: Introduce randomness to generate shortcuts in the graph

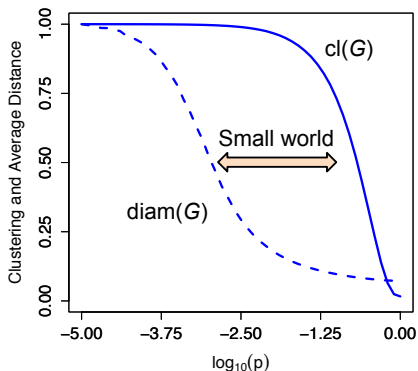
⇒ Each edge is randomly rewired with (small) probability p



- ▶ Rewiring interpolates between the **regular** and **random** extremes

Numerical results

- ▶ Simulate Watts-Strogatz model with $N_v = 1,000$ and $r = 6$
 - ▶ Rewiring probability p varied from 0 (lattice G_r) to 1 (random $G_{N_v,p}$)
 - ▶ Normalized $cl(G)$ and $diam(G)$ to maximum values ($p = 0$)



- ▶ Broad range of $p \in [10^{-3}, 10^{-1}]$ yields small $diam(G)$ and high $cl(G)$

- ▶ Structural properties of Watts-Strogatz model [Barrat-Weigt'00]

P1: Large N_v analysis of clustering coefficient

$$cl(G) \approx \frac{3r-3}{4r-2}(1-p^3) = cl(G_r)(1-p^3)$$

P2: Degree distribution concentrated around $2r$

- ▶ Small-world graph models of interest across disciplines
- ▶ Particularly relevant to 'communication' in a broad sense
 - ⇒ Spread of news, gossip, rumors
 - ⇒ Spread of natural diseases and epidemics
 - ⇒ Search of content in peer-to-peer networks

Roadmap

Random graph models

Small-world models

Network-growth models

Exponential random graph models

Latent network models

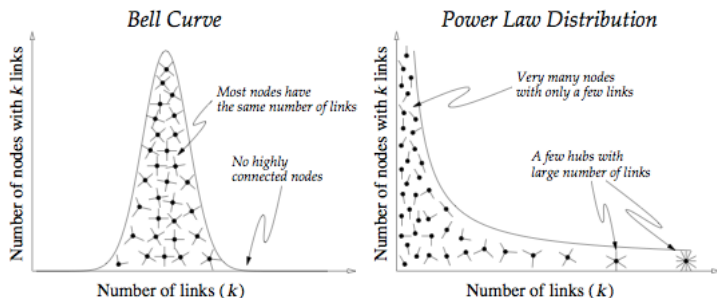
Random dot product graphs

Time-evolving networks

- ▶ Many networks **grow** or otherwise **evolve in time**
Ex: Web, scientific citations, Twitter, genome . . .
- ▶ **General approach to model construction mimicking network growth**
 - ▶ Specify simple mechanisms for network dynamics
 - ▶ Study emergent structural characteristics as time $t \rightarrow \infty$
- ▶ **Q:** Do these properties match observed ones in real-world networks?
- ▶ Two fundamental and popular classes of growth processes
 - ⇒ Preferential attachment models
 - ⇒ Copying models
- ▶ **Tenable mechanisms for popularity and gene duplication, respectively**

Popularity as a network phenomenon

- ▶ **Popularity** is a phenomenon characterized by extreme imbalances
 - ▶ How can we quantify these imbalances? Why do they arise?



- ▶ Basic **models of network behavior** can be very insightful
 - ⇒ Result of coupled decisions, correlated behavior in a population

Preferential attachment model

- ▶ Simple model for the creation of e.g., links among Web pages

- ▶ Vertices are created one at a time, denoted $1, \dots, N_v$
- ▶ When node j is created, it makes a single arc to i , $1 \leq i < j$
- ▶ Creation of (j, i) governed by a probabilistic rule:
 - ▶ With probability p , j links to i chosen uniformly at random
 - ▶ With probability $1 - p$, j links to i with probability $\propto d_i^{in}$

- ▶ The resulting graph is directed, each vertex has $d_v^{out} = 1$
- ▶ **Preferential attachment model** leads to “rich-gets-richer” dynamics
 - ⇒ Arcs formed preferentially to (currently) most popular nodes
 - ⇒ Prob. that i increases its popularity $\propto i$'s current popularity

Preferential attachment yields power laws

Theorem

The preferential attachment model gives rise to a power-law in-degree distribution with exponent $\alpha = 1 + \frac{1}{1-p}$, i.e.,

$$P(d^{in} = d) \propto d^{-(1 + \frac{1}{1-p})}$$

- ▶ **Key:** “ j links to i with probability $\propto d_i^{in}$ ” equivalent to **copying**, i.e., “ j chooses k uniformly at random, and links to i if $(k, i) \in E$ ”
- ▶ **Reflect:** Copy other’s decision vs. independent decisions in $G_{n,p}$
- ▶ As $p \rightarrow 0 \Rightarrow$ Copying more frequent \Rightarrow Smaller $\alpha \rightarrow 2$
 - ▶ **Intuitive:** more likely to see extremely popular pages (heavier tail)

Continuous approximation

- ▶ In-degree $d_i^{in}(t)$ of node i at time $t \geq i$ is a RV. Two facts
 - F1) Initial condition:** $d_i^{in}(i) = 0$ since node i just created at time $t = i$
 - F2) Dynamics of $d_i^{in}(t)$:** Probability that new node $t + 1 > i$ links to i is

$$P((t + 1, i) \in E) = p \times \frac{1}{t} + (1 - p) \times \frac{d_i^{in}(t)}{t}$$

- ▶ Will study a **deterministic, continuous approximation** to the model
 - ▶ Continuous time $t \in [0, N_v]$
 - ▶ Continuous degrees $x_i^{in}(t) : [i, N_v] \mapsto \mathbb{R}_+$ are deterministic
- ▶ Require in-degrees to satisfy the following **growth equation**

$$\frac{dx_i^{in}(t)}{dt} = \frac{p}{t} + \frac{(1 - p)x_i^{in}(t)}{t}, \quad x_i^{in}(i) = 0$$

Solving the differential equation

- ▶ Solve the first-order differential equation for $x_i^{in}(t)$ (let $q = 1 - p$)

$$\frac{dx_i^{in}}{dt} = \frac{p + qx_i^{in}}{t}$$

- ▶ Divide both sides by $p + qx_i^{in}(t)$ and integrate over t

$$\int \frac{1}{p + qx_i^{in}} \frac{dx_i^{in}}{dt} dt = \int \frac{1}{t} dt$$

- ▶ Solving the integrals, we obtain (c is a constant)

$$\ln(p + qx_i^{in}) = q \ln(t) + c$$

Solving the differential equation (cont.)

- ▶ Exponentiating and letting $K = e^c$ we find

$$\ln(p + qx_i^{in}(t)) = q \ln(t) + c \Rightarrow x_i^{in}(t) = \frac{1}{q} (Kt^q - p)$$

- ▶ To determine the unknown constant K , use the initial condition

$$0 = x_i^{in}(i) = \frac{1}{q} (Ki^q - p) \Rightarrow K = \frac{p}{i^q}$$

- ▶ Hence, the deterministic approximation of $d_i^{in}(t)$ evolves as

$$x_i^{in}(t) = \frac{1}{q} \left(\frac{p}{i^q} \times t^q - p \right) = \frac{p}{q} \left[\left(\frac{t}{i} \right)^q - 1 \right]$$

Obtaining the degree distribution

- ▶ **Q:** At time t , what fraction $\bar{F}(d)$ of all nodes have in-degree $\geq d$?
Approximation: What fraction of all functions $x_i^{in}(t) \geq d$ by time t ?

$$x_i^{in}(t) = \frac{p}{q} \left[\left(\frac{t}{i} \right)^q - 1 \right] \geq d$$

- ▶ Can be rewritten in terms of i as

$$i \leq t \left[\left(\frac{q}{p} \right) d + 1 \right]^{-1/q}$$

- ▶ By time t there are exactly t nodes in the graph, so the fraction is

$$\bar{F}(d) = \left[\left(\frac{q}{p} \right) d + 1 \right]^{-1/q} = 1 - F(d)$$

Identifying the power law

- ▶ The degree distribution is given by the PDF $p(d)$
- ▶ Recall that the PDF, CDF and CCDF are related, namely

$$p(x) = \frac{dF(x)}{dx} = -\frac{d\bar{F}(x)}{dx}$$

- ▶ Differentiating $\bar{F}(d) = \left[\left(\frac{q}{p} \right) d + 1 \right]^{-1/q}$ yields

$$p(d) = \frac{1}{p} \left[\left(\frac{q}{p} \right) d + 1 \right]^{-(1+\frac{1}{q})}$$

- ▶ Showed $p(d) \propto d^{-(1+1/q)}$, a power law with exponent $\alpha = 1 + \frac{1}{1-p}$
 - ⇒ **Disclaimer:** Relied on heuristic arguments
 - ⇒ Rigorous, probabilistic analysis possible

The Barabási-Albert model

- ▶ **Barabási-Albert (BA) model** is for undirected graphs

- ▶ Initial graph $G_{BA}(0)$ of $N_v(0)$ vertices and $N_e(0)$ edges ($t = 0$)
- ▶ For $t = 1, 2, \dots$ current graph $G_{BA}(t-1)$ grows to $G_{BA}(t)$ by:
 - ▶ Adding a new vertex u of degree $d_u(t) = m \geq 1$
 - ▶ The new edges are incident to m different vertices in $G_{BA}(t-1)$
 - ▶ New vertex u is connected to $v \in \mathcal{V}(t-1)$ w.p.

$$P((u, v) \in \mathcal{E}(t)) = \frac{d_v(t-1)}{\sum_{v'} d_{v'}(t-1)}$$

- ▶ **Vertices connected to u preferentially towards higher degrees**
 $\Rightarrow G_{BA}(t)$ has $N_v(t) = N_v(0) + t$ and $N_e(t) = N_e(0) + tm$

A. Barabási and R. Albert, "Emergence of scaling in random networks," *Science*, vol. 286, pp. 509-512, 1999

Linearized chord diagram

- ▶ BA model ambiguous in how to select m vertices \propto to their degree
⇒ Joint distribution **not specified** by marginal on each vertex
- ▶ **Linearized chord diagram (LCD)** model removes ambiguities

- ▶ For $m = 1$, $G_{LCD}(0)$ consists of a vertex with a self-loop
- ▶ For $t = 1, 2, \dots$ graph $G_{LCD}(t-1)$ grows to $G_{LCD}(t)$ by:
 - ▶ Adding a new vertex v_t with an edge to $v_s \in \mathcal{V}(t)$
 - ▶ Vertex v_s , $1 \leq s \leq t$ is chosen w.p.

$$P(s = j) = \begin{cases} \frac{d_{v_j}(t-1)}{2t-1}, & \text{if } 1 \leq j \leq t-1, \\ \frac{1}{2t-1}, & \text{if } j = t \end{cases}$$

- ▶ For $m > 1$ simply run the above process m times for each t
 - ▶ Collapse all created vertices into a single one, retaining edges

A. Bollobás et al, "The degree sequence of a scale-free random graph process," *Random Struct. and Alg.*, vol. 18, pp. 279-290, 2001

Properties of the LCD model

- P1) The LCD model allows for **loops and multi-edges**, occurring rarely
- P2) $G_{LCD}(t)$ has **power-law degree distribution** with $\alpha = 3$, as $t \rightarrow \infty$
- P3) The BA model yields connected graphs if $G_{BA}(0)$ connected
 \Rightarrow Not true for the LCD model, but **$G_{LCD}(t)$ connected w.h.p.**
- P4) **Small-world behavior**

$$\text{diam}(G_{LCD}(t)) = \begin{cases} O(\log N_v(t)), & m = 1 \\ O\left(\frac{\log N_v(t)}{\log \log N_v(t)}\right), & m > 1 \end{cases}$$

- P5) **Unsatisfactory clustering**, since small for $m > 1$

$$\mathbb{E}[\text{cl}(G_{LCD}(t))] \approx \frac{m-1}{8} \frac{(\log N_v(t))^2}{N_v(t)}$$

\Rightarrow Marginally better than $O(N_v^{-1})$ in classical random graphs

Copying models

- ▶ **Copying** is another mechanism of fundamental interest
 - Ex: gene duplication to re-use information in organism's evolution
- ▶ Different from preferential attachment, but still results in power laws

- ▶ Initialize with a graph $G_C(0)$ ($t = 0$)
- ▶ For $t = 1, 2, \dots$ current graph $G_C(t - 1)$ grows to $G_C(t)$ by:
 - ▶ Adding a new vertex u
 - ▶ Choosing $v \in \mathcal{V}(t - 1)$ with uniform probability $\frac{1}{N_v(t-1)}$
 - ▶ Joining vertex u with v 's neighbors independently w.p. p

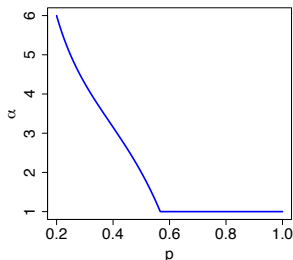
- ▶ Case $p = 1$ leads to **full duplication** of edges from an existing node

F. Chung et al, "Duplication models for biological networks," *Journal of Computational Biology*, vol. 10, pp. 677-687, 2003

Asymptotic degree distribution

- ▶ Degree distribution tends to a power law w.h.p. [Chung et al'03]
 - ⇒ Exponent α is the plotted solution to the equation

$$p(\alpha - 1) = 1 - p^{\alpha-1}$$



- ▶ Full duplication does not lead to power-law behavior; but does if
 - ⇒ Partial duplication performed a fraction $q \in (0, 1)$ of times

Fitting network growth models

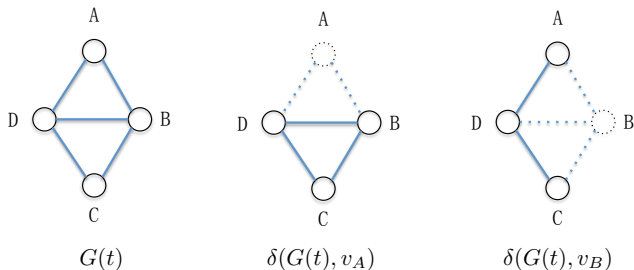
- ▶ Most common practical usage of network growth models is **predictive**
Goal: compare characteristics of G^{obs} and $G(t)$ from the models
- ▶ Little attempt to date to **fit network growth models to data**
 - ⇒ Expected due to simplicity of such models
 - ⇒ Still useful to estimate e.g., the duplication probability p
- ▶ To fit a model ideally would like to observe a sequence $\{G^{obs}(\tau)\}_{\tau=1}^t$
 - ⇒ Unfortunately, such **dynamic network data** is still fairly elusive
- ▶ **Q:** Can we fit a network growth model to a single snap-shot G^{obs} ?
- ▶ **A:** Yes, if we leverage the Markovianity of the growth process

Duplication-attachment models

- ▶ Similar to all network growth models described so far, suppose:
 - As1:** A single vertex is added to $G(t-1)$ to create $G(t)$; and
 - As2:** The manner in which it is added depends only on $G(t-1)$
- ▶ In other words, we assume $\{G(t)\}_{t=0}^{\infty}$ is a Markov chain
- ▶ Let graph $\delta(G(t), v)$ be obtained by deleting v and its edges from $G(t)$
- ▶ **Def:** vertex v is **removable** if $G(t)$ can be obtained from $\delta(G(t), v)$ via copying. If $G(t)$ has no removable vertices, we call it **irreducible**
- ▶ The class of **duplication-attachment (DA) models** satisfies:
 - (i) The initial graph $G(0)$ is irreducible; and
 - (ii) $P_{\theta}(G(t) \mid G(t-1)) > 0 \Leftrightarrow G(t)$ obtained by copying a vertex in $G(t-1)$

C. Wiuf et al, "A likelihood approach to analysis of network data," *PNAS*, vol. 103, pp. 7566-7570, 2006

Example: reducible graph



- ▶ Vertex v_A is removable (likewise v_C by symmetry)
 - ⇒ Obtain $G(t)$ from $\delta(G(t), v_a)$ by copying v_c
- ▶ This implies that $G(t)$ is reducible
 - ⇒ Notice though that v_B or v_D are not removable

MLE for DA model parameters

- ▶ Suppose that $G^{obs} = G(t)$ represents the observed network graph
- ▶ The likelihood for the parameter θ is **recursively** given by

$$\mathcal{L}(\theta; G(t)) = \frac{1}{t} \sum_{v \in \mathcal{R}_{G(t)}} P_{\theta}(G(t) | \delta(G(t), v)) \mathcal{L}(\theta; \delta(G(t), v))$$

$\Rightarrow \mathcal{R}_{G(t)}$ is the set of all removable nodes in $G(t)$

- ▶ The MLE for θ is thus defined as

$$\hat{\theta} = \arg \max_{\theta} \mathcal{L}(\theta; G(t))$$

\Rightarrow **Computing $\mathcal{L}(\theta; G(t))$ non-trivial**, even for modest-size graphs

- ▶ Monte Carlo methods to approximate $\mathcal{L}(\theta; G(t))$ [Wiuf et al'06]
 - \Rightarrow **Open issues**: vector θ , other growth models, scalability

Random graph models

Small-world models

Network-growth models

Exponential random graph models

Latent network models

Random dot product graphs

Statistical network graph models

- ▶ Good statistical network graph models should be [Robbins-Morris'07]:
 - ⇒ Estimable from and reasonably representative of the data
 - ⇒ Theoretically plausible about the underlying network effects
 - ⇒ Discriminative among competing effects to best explain the data
- ▶ Network-based versions of canonical statistical models
 - ⇒ Regression models - Exponential random graph models (ERGMs)
 - ⇒ Latent variable models - Latent network models
 - ⇒ Mixture models - Stochastic block models
- ▶ Focus here on ERGMs, also known as p^* models

G. Robbins et al., "An introduction to exponential random graph (p^*) models for social networks," *Social Networks*, vol. 29, pp. 173-191, 2007

- ▶ **Def:** discrete random vector $\mathbf{Z} \in \mathcal{Z}$ belongs to an **exponential family** if

$$P_{\theta}(\mathbf{Z} = \mathbf{z}) = \exp \left\{ \boldsymbol{\theta}^{\top} \mathbf{g}(\mathbf{z}) - \psi(\boldsymbol{\theta}) \right\}$$

- ▶ $\boldsymbol{\theta} \in \mathbb{R}^p$ is a vector of parameters and $\mathbf{g} : \mathcal{Z} \mapsto \mathbb{R}^p$ is a function
 - ▶ $\psi(\boldsymbol{\theta})$ is a normalization term, ensuring $\sum_{\mathbf{z} \in \mathcal{Z}} P_{\theta}(\mathbf{z}) = 1$
 - ▶ **Ex:** Bernoulli, binomial, Poisson, geometric distributions
- ▶ For continuous exponential families, the pdf has an analogous form
 - Ex:** Gaussian, Pareto, chi-square distributions
- ▶ Exponential families share useful algebraic and geometric properties
 - ⇒ **Mathematically convenient for inference and simulation**

Exponential random graph model

- ▶ Let $G(\mathcal{V}, \mathcal{E})$ be a **random undirected graph**, with $A_{ij} := \mathbb{I}\{(i, j) \in \mathcal{E}\}$
 - ▶ Matrix $\mathbf{A} = [A_{ij}]$ is the random adjacency matrix, \mathbf{a} a realization
- ▶ An ERGM specifies in exponential family form the distribution of \mathbf{A} , i.e.,

$$P_{\theta}(\mathbf{A} = \mathbf{a}) = \left(\frac{1}{\kappa(\boldsymbol{\theta})} \right) \exp \left\{ \sum_H \theta_H g_H(\mathbf{a}) \right\}, \quad \text{where}$$

- (i) each H is a **configuration**, meaning a set of possible edges in G ;
- (ii) $g_H(\mathbf{a})$ is the **network statistic** corresponding to configuration H

$$g_H(\mathbf{a}) = \prod_{A_{ij} \in H} A_{ij} = \mathbb{I}\{H \text{ occurs in } \mathbf{a}\}$$

- (iii) $\theta_H \neq 0$ only if all edges in H are **conditionally dependent**; and
- (iv) $\kappa(\boldsymbol{\theta})$ is a normalization constant ensuring $\sum_{\mathbf{a}} P_{\theta}(\mathbf{a}) = 1$

- ▶ Graph order N_V is fixed and given, **only edges are random**
 - ⇒ Assumed unweighted, undirected edges. Extensions possible
- ▶ **ERGMs describe random graphs 'built-on' localized patterns**
 - ▶ These configurations are the structural characteristics of interest
 - ▶ **Ex:** Are there reciprocity effects? Add mutual arcs as configurations
 - ▶ **Ex:** Are there transitivity effects? Consider triangles
- ▶ (In)dependence is conditional on all other variables (edges) in G
 - ⇒ Control configurations relevant (i.e., $\theta_H \neq 0$) to the model
- ▶ **Well-specified dependence assumptions imply particular model classes**

A general framework for model construction

- ▶ In positing an ERGM for a network, one implicitly follows five steps
 - ⇒ Explicit choices connecting hypothesized theory to data analysis
 - Step 1:** Each edge (relational tie) is regarded as a random variable
 - Step 2:** A dependence hypothesis is proposed
 - Step 3:** Dependence hypothesis implies a particular form to the model
 - Step 4:** Simplification of parameters through e.g., homogeneity
 - Step 5:** Estimate and interpret model parameters

Example: Bernoulli random graphs

- ▶ Assume edges present independently of all other edges (e.g., in $G_{n,p}$)
⇒ Simplest possible (and unrealistic) dependence assumption
- ▶ For each (i, j) , we assume i_j independent of A_{uv} , for all $(u, v) \neq (i, j)$
⇒ $\theta_H = 0$ for all H involving two or more edges
- ▶ Edge configurations i.e., $g_H(\mathbf{a}) = A_{ij}$ relevant, and the ERGM becomes

$$P_{\theta}(\mathbf{A} = \mathbf{a}) = \left(\frac{1}{\kappa(\boldsymbol{\theta})} \right) \exp \left\{ \sum_{i,j} \theta_{ij} A_{ij} \right\}$$

- ▶ Specifies that edge (i, j) present independently, with probability

$$p_{ij} = \frac{\exp(\theta_{ij})}{1 + \exp(\theta_{ij})}$$

Constraints on parameters: homogeneity

- ▶ Too many parameters makes estimation infeasible from single \mathbf{a}
⇒ Under independence have N_V^2 parameters $\{\theta_{ij}\}$. **Reduction?**
- ▶ **Homogeneity** across all G , i.e., $\theta_{ij} = \theta$ for all (i, j) yields

$$P_{\theta}(\mathbf{A} = \mathbf{a}) = \left(\frac{1}{\kappa(\theta)} \right) \exp \{ \theta L(\mathbf{a}) \}$$

- ▶ Relevant statistic is the number of edges observed $L(\mathbf{a}) = \sum_{i,j} A_{ij}$
- ▶ **ERGM identical to $G_{n,p}$, where $p = \frac{\exp \theta}{1 + \exp \theta}$**

Ex: suppose we know a priori that vertices fall in two sets

- ▶ Can impose homogeneity on edges within and between sets, i.e.,

$$P_{\theta}(\mathbf{A} = \mathbf{a}) = \left(\frac{1}{\kappa(\theta)} \right) \exp \{ \theta_1 L_1(\mathbf{a}) + \theta_{12} L_{12}(\mathbf{a}) + \theta_2 L_2(\mathbf{a}) \}$$

Example: Markov random graphs

- ▶ **Markov dependence** notion for network graphs [Frank-Strauss'86]
 - ▶ Assumes two ties are dependent if they share a common node
 - ▶ Edge status A_{ij} dependent on any other edge involving i or j

Theorem

Under homogeneity, G is a Markov random graph if and only if

$$P_{\theta}(\mathbf{A} = \mathbf{a}) = \left(\frac{1}{\kappa(\theta)} \right) \exp \left\{ \sum_{k=1}^{N_v-1} \theta_k S_k(\mathbf{a}) + \theta_{\tau} T(\mathbf{a}) \right\}, \text{ where}$$

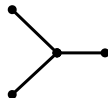
$S_k(\mathbf{a})$ is the number of k -stars, and $T(\mathbf{a})$ the number of triangles



1-star=edge



2-star



3-star



Triangle

- ▶ Including many higher-order terms challenges estimation
 - ⇒ High-order star effects often omitted, e.g., $\theta_k = 0$, $k \geq 4$
 - ⇒ But these models tend to fit real data poorly. **Dilemma?**
- ▶ **Idea:** Impose parametric form $\theta_k \propto (-1)^k \lambda^{2-k}$ [Snijders et al'06]
- ▶ Combine $S_k(\mathbf{a})$, $k \geq 2$ into a single **alternating k -star statistic**, i.e.,

$$\text{AKS}_\lambda(\mathbf{a}) = \sum_{k=2}^{N_v-1} (-1)^k \frac{S_k(\mathbf{a})}{\lambda^{k-2}}, \quad \lambda > 1$$

- ▶ Can show $\text{AKS}_\lambda(\mathbf{a}) \propto$ the **geometrically-weighted degree count**

$$\text{GWD}_\gamma(\mathbf{a}) = \sum_{d=0}^{N_v-1} e^{-\gamma d} N_d(\mathbf{a}), \quad \gamma > 0$$

⇒ $N_d(\mathbf{a})$ is the number of vertices with degree d

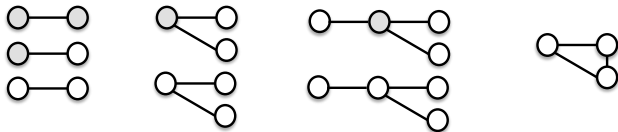
Incorporating vertex attributes

- ▶ Straightforward to incorporate vertex attributes to ERGMs
Ex: gender, seniority in organization, protein function
- ▶ Consider a realization \mathbf{x} of a random vector $\mathbf{X} \in \mathbb{R}^{N_v}$ defined on \mathcal{V}
- ▶ Specify an exponential family form for the **conditional distribution**

$$P_{\theta}(\mathbf{A} = \mathbf{a} \mid \mathbf{X} = \mathbf{x})$$

⇒ Will include additional statistics $g(\cdot)$ of \mathbf{a} and \mathbf{x}

- ▶ Ex: configurations for Markov, binary vertex attributes



- ▶ MLE for the parameter vector θ in an ERGM is

$$\hat{\theta} = \arg \max_{\theta} \left\{ \theta^{\top} \mathbf{g}(\mathbf{a}) - \psi(\theta) \right\}, \quad \text{where } \psi(\theta) := \log \kappa(\theta)$$

- ▶ Optimality condition yields

$$\mathbf{g}(\mathbf{a}) = \nabla \psi(\theta) |_{\theta=\hat{\theta}}$$

- ▶ Using also that $\mathbb{E}_{\theta}[\mathbf{g}(\mathbf{A})] = \nabla \psi(\theta)$, the MLE solves

$$\mathbb{E}_{\hat{\theta}}[\mathbf{g}(\mathbf{A})] = \mathbf{g}(\mathbf{a})$$

- ▶ Unfortunately $\psi(\theta)$ cannot be computed except for small graphs
 - ⇒ Involves a summation over $2^{\binom{N_v}{2}}$ values of \mathbf{a} for each θ
 - ⇒ Numerical methods needed to obtain approximate values of $\hat{\theta}$

Proof of $\mathbb{E}[g(\mathbf{A})] = \nabla\psi(\theta)$

- ▶ The pmf of \mathbf{A} is $P_\theta(\mathbf{A} = \mathbf{a}) = \exp\{\theta^\top \mathbf{g}(\mathbf{a}) - \psi(\theta)\}$, hence

$$\begin{aligned}\mathbb{E}_\theta[g(\mathbf{A})] &= \sum_{\mathbf{a}} g(\mathbf{a})P_\theta(\mathbf{A} = \mathbf{a}) \\ &= \sum_{\mathbf{a}} g(\mathbf{a}) \exp\{\theta^\top \mathbf{g}(\mathbf{a}) - \psi(\theta)\}\end{aligned}$$

- ▶ Recall $\psi(\theta) = \log \sum_{\mathbf{a}} \exp\{\theta^\top \mathbf{g}(\mathbf{a})\}$ and use the chain rule

$$\begin{aligned}\nabla\psi(\theta) &= \frac{\sum_{\mathbf{a}} g(\mathbf{a}) \exp\{\theta^\top \mathbf{g}(\mathbf{a})\}}{\sum_{\mathbf{a}} \exp\{\theta^\top \mathbf{g}(\mathbf{a})\}} = \frac{\sum_{\mathbf{a}} g(\mathbf{a}) \exp\{\theta^\top \mathbf{g}(\mathbf{a})\}}{\exp\psi(\theta)} \\ &= \sum_{\mathbf{a}} g(\mathbf{a}) \exp\{\theta^\top \mathbf{g}(\mathbf{a}) - \psi(\theta)\}\end{aligned}$$

- ▶ The red and blue sums are identical $\Rightarrow \mathbb{E}_\theta[g(\mathbf{A})] = \nabla\psi(\theta)$ follows

- ▶ **Idea:** for fixed θ_0 , maximize instead the **log-likelihood ratio**

$$r(\theta, \theta_0) = \ell(\theta) - \ell(\theta_0) = (\theta - \theta_0)^\top \mathbf{g}(\mathbf{a}) - [\psi(\theta) - \psi(\theta_0)]$$

- ▶ **Key identity:** will show that

$$\exp \{ \psi(\theta) - \psi(\theta_0) \} = \mathbb{E}_{\theta_0} [\exp \{ (\theta - \theta_0)^\top \mathbf{g}(\mathbf{A}) \}]$$

- ▶ **Markov chain Monte Carlo MLE algorithm to search over θ**

Step 1: draw samples $\mathbf{A}_1, \dots, \mathbf{A}_n$ from the ERGM under θ_0

Step 2: approximate the above $\mathbb{E}_{\theta_0}[\cdot]$ via sample averaging

Step 3: the logarithm of the result approximates $\psi(\theta) - \psi(\theta_0)$

Step 4: evaluate an \approx log-likelihood ratio $r(\theta, \theta_0)$

- ▶ For large n , the maximum value found approximates the MLE $\hat{\theta}$

Derivation of key identity

- ▶ Recall $\exp \psi(\boldsymbol{\theta}) = \sum_{\mathbf{a}} \exp \{ \boldsymbol{\theta}^\top \mathbf{g}(\mathbf{a}) \}$ to write

$$\exp \{ \psi(\boldsymbol{\theta}) - \psi(\boldsymbol{\theta}_0) \} = \frac{\sum_{\mathbf{a}} \exp \{ \boldsymbol{\theta}^\top \mathbf{g}(\mathbf{a}) \}}{\exp \psi(\boldsymbol{\theta}_0)}$$

- ▶ Multiplying and dividing by $\exp \{ \boldsymbol{\theta}_0^\top \mathbf{g}(\mathbf{a}) \} > 0$ yields

$$\begin{aligned} \exp \{ \psi(\boldsymbol{\theta}) - \psi(\boldsymbol{\theta}_0) \} &= \sum_{\mathbf{a}} \exp \{ (\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{g}(\mathbf{a}) \} \times \frac{\exp \{ \boldsymbol{\theta}_0^\top \mathbf{g}(\mathbf{a}) \}}{\exp \psi(\boldsymbol{\theta}_0)} \\ &= \sum_{\mathbf{a}} \exp \{ (\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{g}(\mathbf{a}) \} P_{\boldsymbol{\theta}_0}(\mathbf{A} = \mathbf{a}) \\ &= \mathbb{E}_{\boldsymbol{\theta}_0} [\exp \{ (\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{g}(\mathbf{A}) \}] \end{aligned}$$

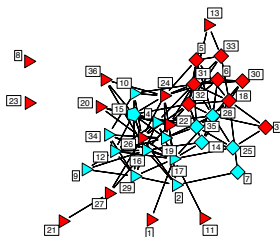
- ▶ Used $\exp \{ \boldsymbol{\theta}_0^\top \mathbf{g}(\mathbf{a}) - \psi(\boldsymbol{\theta}_0) \}$ is the exponential family pmf $P_{\boldsymbol{\theta}_0}(\mathbf{A} = \mathbf{a})$

Model goodness-of-fit

- ▶ **Best fit** chosen from a given class of models . . .
may not be a **good fit** to the data if **model class not rich enough**
- ▶ Assessing goodness-of-fit for ERGMs
 - Step 1:** simulate numerous random graphs from the fitted model
 - Step 2:** compare high-level characteristics with those of G^{obs}
Ex: distributions of degree, centrality, diameter
- ▶ If significant differences found in G^{obs} , conclude
 - ⇒ Systematic gap between specified model class and data
 - ⇒ **Lack of goodness-of-fit**
- ▶ **Take home:** model specification for ERGMs highly nontrivial
 - ⇒ Goodness-of-fit diagnostics can play key facilitating role

Example: Lawyer collaboration network

- ▶ Network G^{obs} of working relationships among lawyers [Lazega'01]
 - ▶ Nodes are $N_v = 36$ partners, edges indicate partners worked together



- ▶ Data includes various node-level attributes:
 - ▶ Seniority (node labels indicate rank ordering)
 - ▶ Office location (triangle, square or pentagon)
 - ▶ Type of practice, i.e., litigation (red) and corporate (cyan)
 - ▶ Gender (three partners are female labeled 27, 29 and 34)
- ▶ **Goal:** study cooperation among social actors in an organization

Modeling lawyer collaborations

- ▶ Assess **network effects** $S_1(\mathbf{a}) = N_e$ and alternating k -triangles statistic

$$\text{AKT}_\lambda(\mathbf{a}) = 3T_1(\mathbf{a}) + \sum_{k=2}^{N_v-2} (-1)^{k+1} \frac{T_k(\mathbf{a})}{\lambda^{k-1}}$$

⇒ $T_k(\mathbf{a})$ counts sets of k individual triangles sharing a common base

- ▶ Test the following set of **exogenous effects**:

$$h^{(1)}(\mathbf{x}_i, \mathbf{x}_j) = \text{seniority}_i + \text{seniority}_j, \quad h^{(2)}(\mathbf{x}_i, \mathbf{x}_j) = \text{practice}_i + \text{practice}_j$$

$$h^{(3)}(\mathbf{x}_i, \mathbf{x}_j) = \mathbb{I} \{ \text{practice}_i = \text{practice}_j \}, \quad h^{(4)}(\mathbf{x}_i, \mathbf{x}_j) = \mathbb{I} \{ \text{gender}_i = \text{gender}_j \}$$

$$h^{(5)}(\mathbf{x}_i, \mathbf{x}_j) = \mathbb{I} \{ \text{office}_i = \text{office}_j \}, \quad \mathbf{h}(\mathbf{x}_i, \mathbf{x}_j) := [h^{(1)}(\mathbf{x}_i, \mathbf{x}_j), \dots, h^{(5)}(\mathbf{x}_i, \mathbf{x}_j)]^T$$

- ▶ Resulting ERGM

$$\mathbb{P}_{\theta, \beta}(\mathbf{A} = \mathbf{a} | \mathbf{X} = \mathbf{x}) = \frac{1}{\kappa(\boldsymbol{\theta}, \boldsymbol{\beta})} \exp \left\{ \theta_1 S_1(\mathbf{a}) + \theta_2 \text{AKT}_\lambda(\mathbf{a}) + \boldsymbol{\beta}^T \mathbf{g}(\mathbf{a}, \mathbf{x}) \right\}$$

$$\mathbf{g}(\mathbf{a}, \mathbf{x}) = \sum_{i,j} A_{ij} \mathbf{h}(\mathbf{x}_i, \mathbf{x}_j)$$

Model fitting result

- ▶ Fitting results using the MCMC MLE approach

Parameter	Estimate	'Standard Error'
Density (θ_1)	-6.2073	0.5697
Alternating k -triangles (θ_2)	0.5909	0.0882
Seniority Main Effect (β_1)	0.0245	0.0064
Practice Main Effect (β_2)	0.3945	0.1103
Same Practice (β_3)	0.7721	0.1973
Same Gender (β_4)	0.7302	0.2495
Same Office (β_5)	1.1614	0.1952

⇒ Standard errors **heuristically** obtained via asymptotic theory

- ▶ Identified factors that may increase odds of cooperation

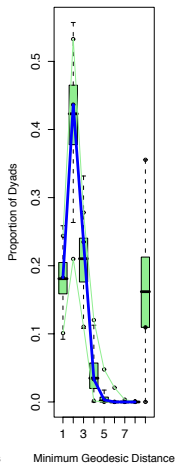
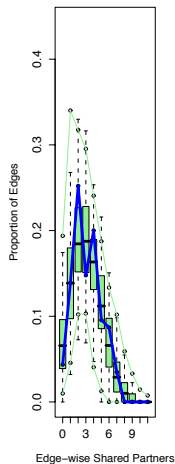
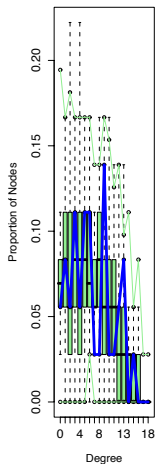
Ex: same practice, gender and office location double odds

- ▶ Strong evidence for transitivity effects since $\hat{\theta}_2 \gg \text{se}(\hat{\theta}_2)$

⇒ **Something beyond basic homophily explaining such effects**

Assessing goodness-of-fit

- ▶ Assess goodness-of-fit to G^{obs}
 - ▶ Sample from fitted ERGM
- ▶ Compared distributions of
 - ▶ Degree
 - ▶ Edge-wise shared partners
 - ▶ Geodesic distance
- ▶ Plots show good fit overall



Random graph models

Small-world models

Network-growth models

Exponential random graph models

Latent network models

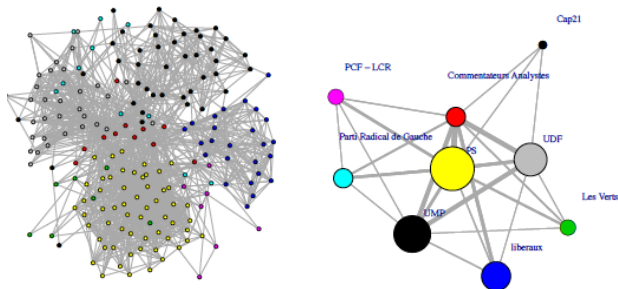
Random dot product graphs

Latent network models

- ▶ **Latent variables** widely used to model observed data
Ex: Hidden Markov models, factor analysis
- ▶ Basic idea permeated to statistical network analysis. Two types:
- ▶ **Latent class models**: unobserved class membership drives propensity towards establishing relational ties
- ▶ **Latent feature models**: relational ties more likely to form among vertices that are 'closer' in some latent space
- ▶ As of now latent network models come in many flavors. Focus here:
 - ⇒ **Stochastic block models (SBMs)**
 - ⇒ More general non-parametric analog based on **graphons**

Example: French political blogs

- ▶ **French political blog network** from October 2006 [Kolaczyk'17]
 - ⇒ Consists of $N_v = 192$ blogs linked by $N_e = 1431$ edges
 - ⇒ Colors indicate blog affiliation to a French political party



- ▶ Visual evidence of mixing of smaller subgraphs
 - ⇒ Different rates of connections among blogs (driven by party)
 - ⇒ Erdős-Renyi with fixed p cannot capture this structure

Stochastic block models

- ▶ **Stochastic block models** explicitly parameterize the notion of
 - ⇒ Groups, modules or communities $\mathcal{C}_1, \dots, \mathcal{C}_Q$
 - ⇒ Connection rates π_{qr} of vertices between/within groups

A generative model for an undirected random graph $G(\mathcal{V}, \mathcal{E})$

- ▶ Fix Q . Each vertex $i \in \mathcal{V}$ independently belongs to \mathcal{C}_q w.p. α_q

$$\boldsymbol{\alpha} = [\alpha_1, \dots, \alpha_Q]^\top, \quad \mathbf{1}^\top \boldsymbol{\alpha} = 1$$

- ▶ For vertices $i, j \in \mathcal{V}$, with $i \in \mathcal{C}_q$ and $j \in \mathcal{C}_r \Rightarrow (i, j) \in \mathcal{E}$ w.p. π_{qr}

P. W. Holland et al., "Stochastic block-models: First steps," *Social Networks*, vol. 5, pp. 109-137, 1983

Model specification and flexibility

- ▶ In other words, with $Z_{iq} = \mathbb{I}\{i \in C_q\}$ and $\mathbf{Z}_i = [Z_{i1}, \dots, Z_{iQ}]^\top$

$$\mathbf{Z}_i \stackrel{\text{i.i.d.}}{\sim} \text{Multinomial}(\mathbf{1}, \boldsymbol{\alpha}),$$

$$A_{ij} \mid \mathbf{Z}_i = \mathbf{z}_i, \mathbf{Z}_j = \mathbf{z}_j \sim \text{Bernoulli}(\pi_{\mathbf{z}_i, \mathbf{z}_j})$$

for $1 \leq i, j \leq N_v$, where $A_{ij} = A_{ji}$ and $A_{ii} \equiv 0$

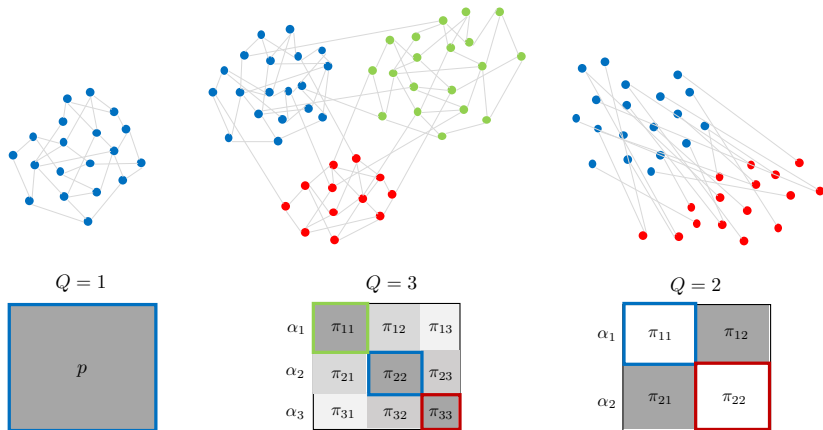
- ▶ **Parameters:** Q mixing weights α_q and Q^2 connection probs. π_{qr}
- ▶ Mixture of classical random graph models

$$P(A_{ij} = 1) = \sum_{1 \leq q, r \leq Q} \alpha_q \alpha_r \pi_{qr}$$

- ⇒ More flexible to capture the structure of observed networks
- ⇒ May face issues of identifiability [Allman et al'11]

- ▶ Emergence of giant component, size distribution of groups [Söderberg'03]

Model specification and flexibility (cont.)



► **Mixtures** of Erdős-Rényi models can be surprisingly flexible

Graphons and f -random graphs

- ▶ A **non-parametric variant of the SBM** can be defined as follows:

$$U_1, \dots, U_{N_v} \stackrel{\text{i.i.d.}}{\sim} \text{Uniform}[0, 1],$$
$$A_{ij} \mid U_i = u_i, U_j = u_j \sim \text{Bernoulli}(f(u_i, u_j))$$

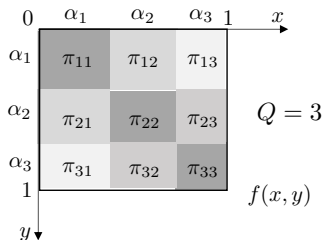
for $1 \leq i, j \leq N_v$, where $A_{ij} = A_{ji}$ and $A_{ii} \equiv 0$

- ▶ **Graphon**: symmetric, measurable function $f : [0, 1]^2 \mapsto [0, 1]$
⇒ Resulting graph G known as **f -random graph**
- ▶ Latent U_i randomly assigns vertex positions uniformly in $[0, 1]$
⇒ Graphon $f(u_i, u_j)$ specifies connection rate between i, j
- ▶ **SBM**: Latent \mathbf{Z}_i assigns memberships of vertices to one of Q groups
⇒ Probability π_{qr} defines linking rate between $i \in \mathcal{C}_q, j \in \mathcal{C}_r$

L. Lovász, “Large Networks and Graph Limits,” *AMS Colloquium Publications*, vol. 60, 2012

Example: SBM graphon

- ▶ The f -random graph model subsumes the parametric SBM. Recipe
 - Partition $[0, 1]$ into Q subintervals of lengths $\alpha_1, \dots, \alpha_Q$
 - Take the Cartesian product to partition $[0, 1]^2$ into Q^2 blocks
 - Define f to be piecewise constant on blocks, qr th block has height π_{qr}



- ▶ Can approximate measurable functions by piecewise-constant functions
 - \Rightarrow Approximate f -random graphs (in distribution) with an SBM
 - \Rightarrow Number of blocks Q required may be huge!

Example: Network generation

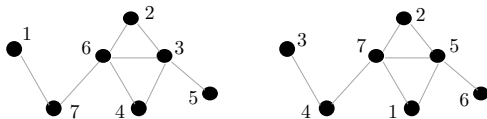
- ▶ Consider an f -random graph with $f(x, y) = \min(x, y)$ [Lovász'12]
 - ⇒ Left plot shows a gray-scale rendering of graphon f
- ▶ **Q:** How do generated graphs with $N_v = 40$ look like?



- ▶ Center plot depicts a realization of the adjacency matrix \mathbf{A}
 - ⇒ Given \mathbf{A} only, impossible to decipher how the graph was generated
- ▶ Sort vertices according to order statistics $U_{(1)}, \dots, U_{(40)}$ (right plot)
 - ⇒ Amenable to graphon estimation via non-parametric regression

Vertex exchangeability

- ▶ **Def:** a random array $\mathbf{A} = [A_{ij}]_{i,j \in \mathcal{V}}$ is vertex exchangeable if $\mathbf{A}_\sigma := [A_{\sigma(i)\sigma(j)}]_{i,j \in \mathcal{V}} \stackrel{D}{=} \mathbf{A}$ for every permutation $\sigma : \mathcal{V} \mapsto \mathcal{V}$



- ▶ Exchangeable models assign equal probability to isomorphic graphs
⇒ Means said models are most natural for **unlabeled graphs**
- ▶ Like SBMs, one can easily show **f -random graphs are exchangeable**
- ▶ Remarkably, **every exchangeable model is a mixture of f -random graphs**
⇒ Aldous-Hoover theorem extends de Finetti's result for sequences

D. J. Aldous, "Representations for partially exchangeable arrays of random variables," *Journal of Multivariate Analysis*, vol. 11, 1981

Every f -random graph is exchangeable

- ▶ The distribution of an f -random graph with N_v vertices is

$$P(\mathbf{A} = \mathbf{a}) = \int_{[0,1]^{N_v}} \prod_{1 \leq i \neq j \leq N_v} f(u_i, u_j)^{A_{ij}} (1 - f(u_i, u_j))^{1 - A_{ij}} du_1 \dots du_{N_v}$$

- ▶ For arbitrary permutation $\sigma : \mathcal{V} \mapsto \mathcal{V}$ and since the U_i are i.i.d. we have

$$\begin{aligned} P(\mathbf{A}_\sigma = \mathbf{a}_\sigma) &= \int_{[0,1]^{N_v}} \prod_{1 \leq i \neq j \leq N_v} f(u_i, u_j)^{A_{\sigma(i)\sigma(j)}} (1 - f(u_i, u_j))^{1 - A_{\sigma(i)\sigma(j)}} du_1 \dots du_{N_v} \\ &= \int_{[0,1]^{N_v}} \prod_{1 \leq i \neq j \leq N_v} f(u_{\sigma^{-1}(i)}, u_{\sigma^{-1}(j)})^{A_{ij}} (1 - f(u_{\sigma^{-1}(i)}, u_{\sigma^{-1}(j)}))^{1 - A_{ij}} \\ &\quad \times du_{\sigma^{-1}(1)} \dots du_{\sigma^{-1}(N_v)} \\ &= \int_{[0,1]^{N_v}} \prod_{1 \leq i \neq j \leq N_v} f(u_i, u_j)^{A_{ij}} (1 - f(u_i, u_j))^{1 - A_{ij}} du_1 \dots du_{N_v} \\ &= P(\mathbf{A} = \mathbf{a}) \end{aligned}$$

Identifiability issues

- ▶ Parametrization of f -random graphs is not unique \Rightarrow Non-identifiable

Ex: graphons $f(x, y)$ and $f(1 - x, 1 - y)$ yield the same model since

$$U \stackrel{D}{=} 1 - U \text{ for } U \sim \text{Uniform}[0, 1]$$

Ex: graphons $f(x, y)$ and $f(\phi(x), \phi(y))$ for measure-preserving ϕ , i.e.,

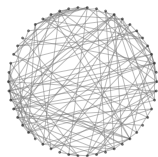
$$\phi : [0, 1] \mapsto [0, 1] \text{ for which } \phi(U) \sim \text{Uniform}[0, 1]$$

- ▶ Restrictions on the graphon f are often needed for statistical modeling
- ▶ **Def:** f is **strictly monotone** if $\exists \phi$ such that $\tilde{f}(x, y) = f(\phi(x), \phi(y))$ has a strictly increasing degree function $\tilde{g}(x) = \int_{[0,1]} \tilde{f}(x, y) dy$
 - \Rightarrow Restriction to \tilde{f} yields model identifiability [Bickel-Chen'09]

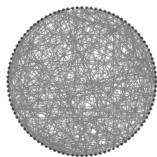
Graph limits

- ▶ Graph sequence $G_n(\mathcal{V}_n, \mathcal{E}_n)$ with growing number of nodes $N_v = n$
 - ▶ **Q:** When can we say $\{G_n\}_{n=1}^\infty$ converges to a limit?
 - ▶ **Q:** In what sense is convergence meaningful?
 - ▶ **Q:** What kind of object is this limit?
- ▶ **Spoiler:** If the sequence $\{G_n\}_{n=1}^\infty$ converges, the limit is a graphon f

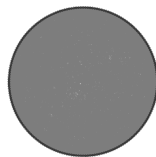
Ex: sequence of $G_{n,p}$ graphs as $n \rightarrow \infty$



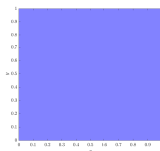
$n = 50$ nodes



$n = 100$ nodes



$n = 200$ nodes



Graphon
 $f(x, y) \equiv p$

Homomorphism density

- ▶ **Def:** **Homomorphisms** h are adjacency preserving maps from **motif** $F(\mathcal{V}', \mathcal{E}')$ into **graph** $G(\mathcal{V}, \mathcal{E})$

$$h : \mathcal{V}' \mapsto \mathcal{V} \text{ such that } (i, j) \in \mathcal{E}' \text{ implies } (h(i), h(j)) \in \mathcal{E}$$

- ▶ **Def:** **Homomorphism density** of **motif** F in **graph** G is

$$t(F, G) = \frac{\text{hom}(F, G)}{|\mathcal{V}|^{|\mathcal{V}'|}}$$

- ▶ $\text{hom}(F, G)$: number of **homomorphisms** between F and G
- ▶ $|\mathcal{V}|^{|\mathcal{V}'|}$: number of maps between vertices in F and G
- ▶ Relative measure of the number of ways in which F can be mapped to G

Convergence of graph sequences

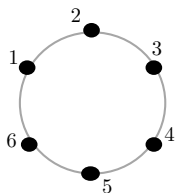
- ▶ **Def:** A sequence $\{G_n\}_{n=1}^{\infty}$ of graphs converges when for every motif F , the homomorphism density sequence $\{t(F, G_n)\}_{n=1}^{\infty}$ converges
- ▶ Noteworthy points about the definition
 - ▶ If the sequence becomes constant, then it converges
 - ▶ Sequence of isomorphic graphs trivially converges
 - ▶ Normalized densities converge, not number edges, triangles, ...
 - ▶ Result is for sequence of **dense** graphs, i.e., $|\mathcal{E}_n| = \Omega(n^2)$
- ▶ Answered the first two questions. Need to address the third
 - ⇒ The limit of a sequence of graphs is not necessarily a graph
 - ⇒ **Q:** What kind of object is this limit?

L. Lovász and B. Szegedy, "Limits of dense graph sequences,"
Journal of Combinatorial Theory, Series B, vol. 96, 2006

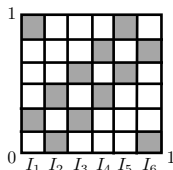
Induced graphon

- ▶ Every graph admits a graphon representation termed **induced graphon**
- ▶ Consider a graph $G(\mathcal{V}, \mathcal{E})$ with adjacency matrix \mathbf{A}
- ▶ Uniform partition of $[0, 1]$ in N_v subintervals $\Rightarrow I_i = [\frac{i-1}{N_v}, \frac{i}{N_v})$
- ▶ **Def:** The **induced graphon** f_G of G is

$$f_G(x, y) = \sum_{1 \leq i, j \leq N_v} A_{ij} \mathbb{I}\{x \in I_i\} \mathbb{I}\{y \in I_j\}$$



Cycle graph G with $N_v = 6$ nodes



Graphon f_G induced by the graph G

- ▶ **Claim:** Homomorphism density of motif F in graph G given by

$$t(F, G) = \int_{[0,1]^{|\mathcal{V}'|}} \prod_{(i,j) \in \mathcal{E}'} f_G(u_i, u_j) du_1 \dots du_{|\mathcal{V}'|}$$

⇒ Probability of F being mapped to an f_G -random graph

- ▶ This carries over to the limit. If the sequence $\{G_n\}_{n=1}^{\infty}$ converges, then

$$\lim_{n \rightarrow \infty} t(F, G_n) = \int_{[0,1]^{|\mathcal{V}'|}} \prod_{(i,j) \in \mathcal{E}'} f(u_i, u_j) du_1 \dots du_{|\mathcal{V}'|}$$

for some symmetric, measurable function $f : [0, 1]^2 \mapsto [0, 1]$

- ▶ We identify the **limiting object** – termed **graphon** – with f

Why is this useful at all?

Mathematical impact

- ▶ Bring to bear analysis tools in an otherwise purely combinatorial context

Statistical inference impact

- ▶ Large realizations become representative of the generative process
⇒ Infer the data-generation mechanism by examining the realization

Machine learning impact

- ▶ Study graph filters and GNNs in the limit of large number of nodes
⇒ **Transferability** e.g., using a trained model on a larger graph

L. Ruiz et al, "Graphon neural networks and the transferability of graph neural networks," *NeurIPS*, 2020

- ▶ Good statistical network graph models should be [Robbins-Morris'07]:
 - ⇒ Estimable from and reasonably representative of the data
 - ⇒ Theoretically plausible about the underlying network effects
- ▶ **Q:** How appropriate are latent network models? Are they plausible?
- ▶ **Q:** Can we approximate well an observed graph G^{obs} with an SBM?
 - ⇒ A variant of the Szemerédi regularity lemma useful here

C. Borgs et al, "Graph limits and parameter testing," *Symposium on Theory of Computing*, 2006

- ▶ Discussing approximation notions requires a **distance between graphs**
- ▶ **Def:** For graphs $G(\mathcal{V}, \mathcal{E})$ and $G'(\mathcal{V}', \mathcal{E}')$ with $|\mathcal{V}| = |\mathcal{V}'| = N_v$, the **cut distance** is given by

$$d_{\square}(G, G') = \frac{1}{N_v^2} \max_{\mathcal{S}, \mathcal{T} \in \{1, \dots, N_v\}} \left| \sum_{i \in \mathcal{S}} \sum_{j \in \mathcal{T}} (A_{ij} - A'_{ij}) \right|$$

⇒ One can show the quantity $d_{\square}(\cdot, \cdot)$ is a formal metric

- ▶ Defining and studying properties of graph distances is a timely topic

B. Bollobás and O. Riordan, "Sparse graphs: Metrics and random models," *Random Structures & Algorithms*, vol. 39, 2011

An approximation result

- ▶ Let $\mathcal{P} = \{\mathcal{V}_1, \dots, \mathcal{V}_Q\}$ partition the vertices \mathcal{V} of G into Q classes
- ▶ Define the complete graph G_P with vertex set \mathcal{V} and edge weights

$$w_{ij}(G_P) = \frac{1}{|\mathcal{V}_q||\mathcal{V}_r|} \sum_{u \in \mathcal{V}_q} \sum_{v \in \mathcal{V}_r} A_{uv}, \quad i \in \mathcal{V}_q, j \in \mathcal{V}_r$$

- ⇒ Expectation of a Q -class block model approximation to G
- ⇒ Probability an edge joins i, j is just $w_{ij}(G_P)$

Theorem: For every $\epsilon > 0$ and every graph $G(\mathcal{V}, \mathcal{E})$, there exists a partition \mathcal{P} of \mathcal{V} into $Q \leq 2 \frac{2}{\epsilon^2}$ classes such that $d_{\square}(G, G_P) \leq \epsilon$.

- ▶ Justifies the claim that **an SBM can approximate well an arbitrary graph**
 - ⇒ The upper bound on Q can be prohibitively large

What about f -random graphs?

- ▶ The f -random graph model is only appropriate for **dense networks**

Theorem: If a graph G is the restriction to vertices $\{1, \dots, N_v\}$ of an infinite exchangeable random graph, then it is either dense or empty.

Proof sketch: The expected proportion of edges in $G(\mathcal{V}, \mathcal{E})$ is

$$\varphi = \int_{[0,1]^2} f(u_1, u_2) du_1 du_2$$

⇒ If $\varphi = 0$ then $f = 0$ a.e. and G is empty. Sparse but boring

⇒ Else $\varphi > 0$ and (in expectation) $|\mathcal{E}| = \varphi \times \binom{N_v}{2} = \Omega(N_v^2)$

- ▶ Not great, but in practice main barrier is **vertex exchangeability**
 - ▶ Suitable for unlabeled graphs, yet in many graphs labels matter
 - ▶ Can incorporate vertex attributes as covariates [Sweet'15]

Estimating SBM parameters

- ▶ SBMs defined up to parameters $\{\alpha_q\}_{q=1}^Q$ and $\{\pi_{qr}\}_{1 \leq q, r \leq Q}$
- ▶ Conceptually useful to think about two sets of 'observations'
 - ⇒ Latent class labels: $\mathbf{Z} = \{\{Z_{iq}\}_{q=1}^Q\}_{i \in \mathcal{V}}$, where $Z_{iq} = \mathbb{I}\{i \in \mathcal{C}_q\}$
 - ⇒ Relational ties: $\mathbf{A} = [A_{ij}]$, where $A_{ij} = \mathbb{I}\{(i, j) \in \mathcal{E}\}$
- ▶ **But we only observe \mathbf{A}** , recall \mathbf{Z} are latent. Q assumed given
 - ⇒ Interest both in **parameter estimation** and in **vertex clustering**

Model-based community detection

Suppose G adheres to an SBM with Q classes. Predict class membership labels $\mathbf{Z} = \{\{Z_{iq}\}_{q=1}^Q\}_{i \in \mathcal{V}}$, given observations $\mathbf{A} = \mathbf{a}$.

Maximum likelihood estimation

- ▶ If we were to observe $\mathbf{A} = \mathbf{a}$ and $\mathbf{Z} = \mathbf{z}$, the log-likelihood would be

$$\ell(\mathbf{a}, \mathbf{z}; \boldsymbol{\theta}) = \sum_i \sum_q z_{iq} \log \alpha_q + \frac{1}{2} \sum_{i \neq j} \sum_{q \neq r} z_{iq} z_{jr} \log b(A_{ij}; \pi_{qr})$$

⇒ Defined $\boldsymbol{\theta} = \{\{\alpha_q\}, \{\pi_{qr}\}\}$ and $b(a; \pi) = \pi^a (1 - \pi)^{1-a}$

- ▶ But we do not. Instead have to work with the **observed data** likelihood

$$\ell(\mathbf{a}; \boldsymbol{\theta}) = \log \left(\sum_{\mathbf{z}} \exp \{ \ell(\mathbf{a}, \mathbf{z}; \boldsymbol{\theta}) \} \right)$$

⇒ Unfortunately, evaluation of $\ell(\mathbf{a}; \boldsymbol{\theta})$ is typically intractable

- ▶ Mixture model viewpoint suggests an **E-M procedure** [Snijders'97]
 - ⇒ Alternate between estimation of $\mathbb{E} [Z_{iq} \mid \mathbf{A} = \mathbf{a}]$ and $\boldsymbol{\theta}$
 - ⇒ Does not scale beyond $Q = 2$, $P(\mathbf{Z} \mid \mathbf{A} = \mathbf{a})$ expensive

- ▶ **Variational approach** to optimize a lower bound of $\ell(\mathbf{a}; \boldsymbol{\theta})$, namely

$$J(R_{\mathbf{a}}; \boldsymbol{\theta}) = \ell(\mathbf{a}; \boldsymbol{\theta}) - \text{KL}(R_{\mathbf{a}}(\mathbf{Z}), P(\mathbf{Z} | \mathbf{A} = \mathbf{a}))$$

- ▶ KL denotes de Kullback–Leibler divergence
 - ▶ $R_{\mathbf{a}}(\mathbf{Z})$ is a tractable approximation of $P(\mathbf{Z} | \mathbf{A} = \mathbf{a})$
- ▶ Mean field approximation to the conditional distribution

$$R_{\mathbf{a}}(\mathbf{Z}) = \prod_{i=1}^{N_v} h(\mathbf{Z}_i; \boldsymbol{\tau}_i)$$

- ▶ $h(\cdot; \boldsymbol{\tau}_i)$: multinomial pmf with parameter $\boldsymbol{\tau}_i = [\tau_{i1}, \dots, \tau_{iQ}]^T$

J. J. Daudin et al, "A mixture model for random graphs," *Stat. Comput.*, vol. 18, 2008

Alternating maximization algorithm

Proposition: Given θ , the optimal variational parameters $\{\hat{\tau}_i\} = \operatorname{argmax}_{\{\tau_i\}} J(R_a; \{\tau_i\}, \theta)$ satisfy the following fixed-point relation

$$\hat{\tau}_{iq} \propto \alpha_q \prod_{j \neq i} \prod_r b(A_{ij}; \pi_{qr})^{\hat{\tau}_{jr}}$$

Given $\{\tau_i\}$, the values of θ that maximize $J(R_a; \{\tau_i\}, \theta)$ are

$$\hat{\alpha}_q = \frac{1}{N_v} \sum_i \hat{\tau}_{iq}, \quad \hat{\pi}_{qr} = \sum_{i \neq j} \hat{\tau}_{iq} \hat{\tau}_{jr} A_{ij} / \sum_{i \neq j} \hat{\tau}_{iq} \hat{\tau}_{jr}$$

- ▶ Algorithm alternates between updates of θ and $\{\tau_i\}$ as follows

$$\theta[k+1] = \operatorname{argmax}_{\theta} J(R_a; \{\tau_i[k]\}, \theta)$$

$$\{\tau_i[k+1]\} = \operatorname{argmax}_{\{\tau_i\}} J(R_a; \{\tau_i\}, \theta[k+1])$$

- ▶ The sequence of J values is non-decreasing [Daudin et al'08]
- ▶ **Consistency results** available as $N_v \rightarrow \infty$, Q fixed [Celisse et al'12]

Choice of the number of classes

- ▶ Number of classes Q often unknown and should be estimated
 - ⇒ Use principles of Bayesian model selection
 - ⇒ Prior $g(\boldsymbol{\theta} \mid m_Q)$ on $\boldsymbol{\theta}$ given the SBM m_Q has Q classes
- ▶ Integrated Classification Likelihood (ICL) criterion yields

$$\begin{aligned} \text{ICL}(m_Q) = & \max_{\boldsymbol{\theta}} \log \mathcal{L}(\mathbf{a}, \hat{\mathbf{z}}(\boldsymbol{\theta}) \mid \boldsymbol{\theta}, m_Q) \\ & - \frac{Q(Q+1)}{4} \log \frac{N_v(N_v-1)}{2} - \frac{Q-1}{2} \log N_v \end{aligned}$$

- ▶ Asymptotic approximation of the complete-data integrated likelihood

$$\mathcal{L}(\mathbf{a}, \mathbf{z} \mid m_Q) = \int \mathcal{L}(\mathbf{a}, \mathbf{z} \mid \boldsymbol{\theta}, m_Q) g(\boldsymbol{\theta} \mid m_Q) d\boldsymbol{\theta}$$

- ▶ **Goal:** estimate graphon f from observed realization G^{obs}
- ▶ **Non-parametric regression** approaches estimate f given $\{A_{ij}, U_i, U_j\}_{i,j \in \mathcal{V}}$
⇒ Challenge is that the design points U_1, \dots, U_{N_v} are latent

SBM approximation

C. Gao et al, "Rate-optimal graphon estimation," *Annals of Statistics*, vol. 43, 2015

Histogram estimator (ordering and smoothing)

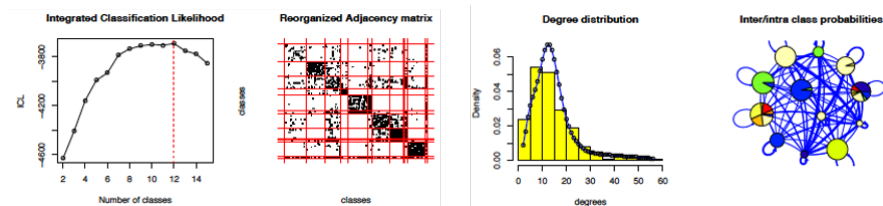
S. H. Chan and E. M. Airoldi, "A consistent histogram estimator for exchangeable graph models," *ICML*, 2014

Gaussian process model

P. Orbanz and D. M. Roy, "Bayesian models of graphs, arrays and other exchangeable random structures," *IEEE Trans. PAMI*, vol. 37, 2015

Assessing goodness-of-fit

- ▶ Goodness-of-fit diagnostics \Rightarrow mostly computational, visualization based
- ▶ Ex: French political blog network from October 2006 [Kolaczyk'17]
 \Rightarrow We fit an SBM using variational MLE (**mixer** in R)



- ▶ Optimal value $\hat{Q} = 12$, but $Q \in [8, 12]$ reasonable (9 political parties)
 \Rightarrow Permuted adjacency shows group structure (room for merging few)
- ▶ Relatively good fit of the degree distribution

Degree-corrected SBMs

- ▶ Communities with broad degree distributions

B. Karrer B and M. E. Newman, "Stochastic blockmodels and community structure in networks," *Physical Review E.*, vol. 83, 2011

Mixed-membership SBMs

- ▶ Nodes may belong only partially to more than one class

E. M. Airoldi, "Mixed membership stochastic blockmodels," *J. Machine Learning Research*, vol. 9, 2008

Hierarchical SBMs

- ▶ Hierarchical clustering meets SBMs

A. Clauset et al, "Hierarchical structure and the prediction of missing links in networks," *Nature*, vol. 453, 2008

Random graph models

Small-world models

Network-growth models

Exponential random graph models

Latent network models

Random dot product graphs

Random dot product graphs

- ▶ Consider a **latent space** $\mathcal{X}_d \subset \mathbb{R}^d$ such that for all

$$\mathbf{x}, \mathbf{y} \in \mathcal{X}_d \Rightarrow \mathbf{x}^\top \mathbf{y} \in [0, 1]$$

\Rightarrow Inner-product distribution $F : \mathcal{X}_d \mapsto [0, 1]$

- ▶ **Random dot product graphs** (RDPGs) are defined as follows:

$$\mathbf{x}_1, \dots, \mathbf{x}_{N_v} \stackrel{\text{i.i.d.}}{\sim} F,$$
$$A_{ij} \mid \mathbf{x}_i, \mathbf{x}_j \sim \text{Bernoulli}(\mathbf{x}_i^\top \mathbf{x}_j)$$

for $1 \leq i, j \leq N_v$, where $A_{ij} = A_{ji}$ and $A_{ii} \equiv 0$

- ▶ A particularly tractable **latent position random graph model**
 \Rightarrow Vertex positions $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_{N_v}]^\top \in \mathbb{R}^{N_v \times d}$

S. J. Young and E. R. Scheinerman, "Random dot product graph models for social networks," *WAW*, 2007

Connections to other models

- ▶ RDPGs encompass several other classic models for network graphs

Ex: Recover Erdős-Renyi $G_{N_v, p}$ graphs with $d = 1$ and $\mathcal{X}_d = \{\sqrt{p}\}$

Ex: Recover SBM random graphs by constructing F with pmf

$$P(\mathbf{X} = \mathbf{x}_q) = \alpha_q, \quad q = 1, \dots, Q$$

after selecting d and $\mathbf{x}_1, \dots, \mathbf{x}_Q$ such that $\pi_{qr} = \mathbf{x}_q^\top \mathbf{x}_r$

- ▶ Approximation results for SBMs justify the expressiveness of RDPGs
- ▶ RDPGs are special cases of latent position models [Hoff et al'02]

$$A_{ij} \mid \mathbf{x}_i, \mathbf{x}_j \sim \text{Bernoulli}(\kappa(\mathbf{x}_i, \mathbf{x}_j))$$

⇒ Approximate these accurately for large enough d [Tang et al'13]

Estimation of latent positions

- ▶ **Q:** Given G from an RDPG, find the 'best' $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_{N_v}]^\top$?
- ▶ MLE is well motivated but it is intractable for large N_v

$$\hat{\mathbf{X}}_{ML} = \underset{\mathbf{X}}{\operatorname{argmax}} \prod_{i < j} (\mathbf{x}_i^\top \mathbf{x}_j)^{A_{ij}} (1 - \mathbf{x}_i^\top \mathbf{x}_j)^{1 - A_{ij}}$$

- ▶ Instead, let $P_{ij} = P((i, j) \in \mathcal{E})$ and define $\mathbf{P} = [P_{ij}] \in [0, 1]^{N_v \times N_v}$
 - ⇒ The RDPG model specifies that $\mathbf{P} = \mathbf{X}\mathbf{X}^\top$
 - ⇒ **Key:** Observed \mathbf{A} is a noisy realization of \mathbf{P} ($\mathbb{E}[\mathbf{A}] = \mathbf{P}$)
- ▶ Suggests a **LS regression** approach to find \mathbf{X} s.t. $\mathbf{X}\mathbf{X}^\top \approx \mathbf{A}$

$$\hat{\mathbf{X}}_{LS} = \underset{\mathbf{X}}{\operatorname{argmin}} \|\mathbf{X}\mathbf{X}^\top - \mathbf{A}\|_F^2$$

Adjacency spectral embedding

- ▶ Since \mathbf{A} is real and symmetric, can decompose it as $\mathbf{A} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\top$
 - ▶ $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_{N_v}]$ is the orthogonal matrix of eigenvectors
 - ▶ $\mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_{N_v})$, with eigenvalues $\lambda_1 \geq \dots \geq \lambda_{N_v}$
- ▶ Define $\hat{\mathbf{\Lambda}} = \text{diag}(\lambda_1^+, \dots, \lambda_d^+)$ and $\hat{\mathbf{U}} = [\mathbf{u}_1, \dots, \mathbf{u}_d]$ ($\lambda^+ := \max(0, \lambda)$)
- ▶ Best rank- d , positive semi-definite (PSD) approximation of \mathbf{A} is $\hat{\mathbf{U}}\hat{\mathbf{\Lambda}}\hat{\mathbf{U}}^\top$
 \Rightarrow Adjacency spectral embedding (ASE) is $\hat{\mathbf{X}}_{LS} = \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}^{1/2}$ since

$$\mathbf{A} \approx \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}\hat{\mathbf{U}}^\top = \hat{\mathbf{U}}\hat{\mathbf{\Lambda}}^{1/2}\hat{\mathbf{\Lambda}}^{1/2}\hat{\mathbf{U}}^\top = \hat{\mathbf{X}}_{LS}\hat{\mathbf{X}}_{LS}^\top$$

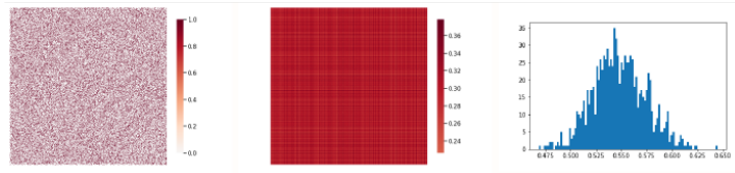
- ▶ **Q:** Is the solution unique? Nope, inner-products are rotation invariant

$$\mathbf{P} = \mathbf{X}\mathbf{W}(\mathbf{X}\mathbf{W})^\top = \mathbf{X}\mathbf{X}^\top, \quad \mathbf{W}\mathbf{W}^\top = \mathbf{I}_d$$

\Rightarrow RDPG embedding problem is identifiable modulo rotations

Embedding an Erdős-Renyi graph

- ▶ **Ex:** Erdős-Renyi graph $G_{1000,0.3}$, realization of \mathbf{A} (left)



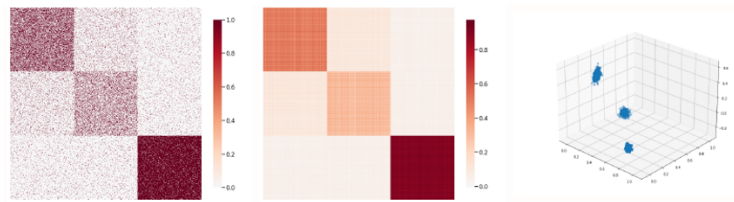
- ▶ For $d = 1$ we compute the ASE $\hat{\mathbf{x}}_{LS}$ and plot $\hat{\mathbf{x}}_{LS}\hat{\mathbf{x}}_{LS}^T$ (center)
 - ⇒ Approximates well the constant matrix $\mathbf{P} = 0.3 \times \mathbf{1}\mathbf{1}^T$
 - ⇒ Supported by histogram of entries in $\hat{\mathbf{x}}_{LS}$ (right, $\sqrt{p} = 0.547$)
- ▶ Consistency and limiting distribution results for ASEs available

A. Athreya et al., “Statistical inference on random dot product graphs: A survey,” *J. Mach. Learn. Res.*, vol. 18, pp. 1-92, 2018

Embedding an SBM graph

- ▶ **Ex:** SBM with $N_v = 1500$, $Q = 3$ and mixing parameters

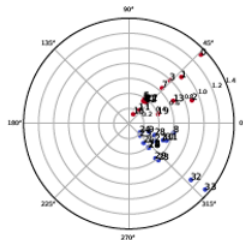
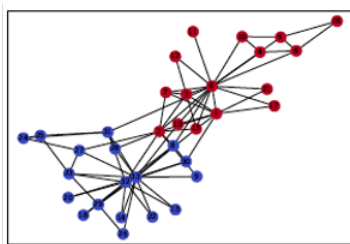
$$\boldsymbol{\alpha} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}, \quad \boldsymbol{\Pi} = \begin{bmatrix} 0.5 & 0.1 & 0.05 \\ 0.1 & 0.3 & 0.05 \\ 0.05 & 0.05 & 0.9 \end{bmatrix}$$



- ▶ Sample adjacency (left), $\hat{\mathbf{X}}_{LS}\hat{\mathbf{X}}_{LS}^T$ (center), rows of $\hat{\mathbf{X}}_{LS}$ (right)
- ▶ Use embeddings to bring to bear geometric methods of analysis

Interpretability of the embeddings

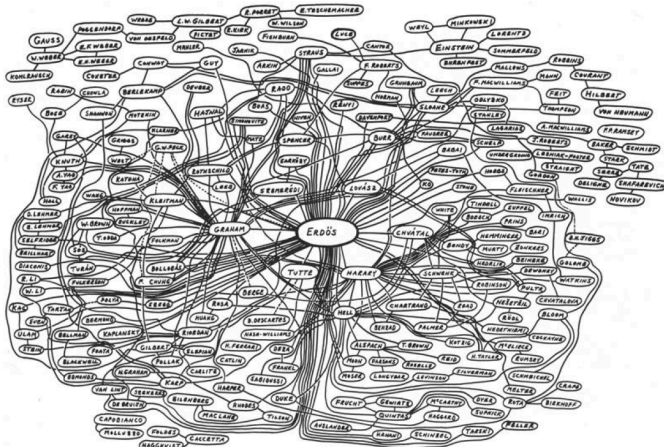
- ▶ **Ex:** Zachary's karate club graph with $N_v = 34$, $N_e = 78$ (left)



- ▶ Node embeddings (rows of $\hat{\mathbf{X}}_{LS}$) for $d = 2$ (right)
 - ▶ Club's administrator ($i = 0$) and instructor ($j = 33$) are orthogonal
- ▶ Interpretability of embeddings a valuable asset for RDPGs
 - ⇒ **Vector magnitudes** indicate how well connected nodes are
 - ⇒ **Vector angles** indicate positions in latent space

Mathematicians collaboration graph

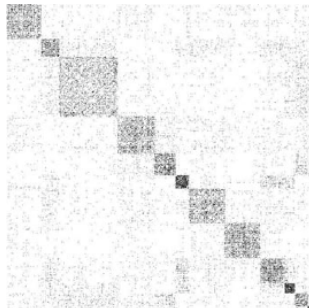
- ▶ Ex: Mathematics collaboration network centered at Paul Erdős



- ▶ Most mathematicians have an Erdős number of at most 4 or 5
⇒ Drawing created by R. Graham in 1979

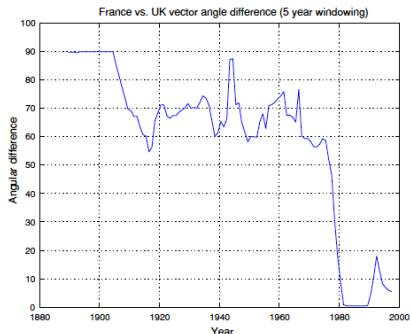
Mathematicians collaboration graph

- ▶ Coauthorship graph G , $N_v = 4301$ nodes with Erdős number ≤ 2
⇒ No discernible structure from the adjacency matrix \mathbf{A} (left)



- ▶ **Community structure revealed** after row-column permutation (right)
 - Obtained the ASE $\hat{\mathbf{X}}_{LS}$ for the mathematicians
 - Performed **angular k-means** on $\hat{\mathbf{X}}_{LS}$'s rows [Scheinerman-Tucker'10]

- ▶ **Ex:** Dynamic network G_t of **international relations among nations**
⇒ Nations $(i, j) \in \mathcal{E}_t$ if they have an alliance treaty during year t



- ▶ Track the angle between UK and France's ASE from 1890–1995
 - ▶ Orthogonal during the late 19th century
 - ▶ Came closer during the wars, retreat during Nazi invasion in WWII
 - ▶ Strong alignment starts in the 1970s in the run up to the EU

Closing remarks and extensions

- ▶ Neglected the constraint $[\hat{\mathbf{X}}_{LS}\hat{\mathbf{X}}_{LS}^T]_{ii} = 0$. Fix via iterative algorithm

E. R. Scheinerman and K. Tucker, "Modeling graphs using dot product representations," *Comput. Stat.*, vol. 25, pp. 1-16, 2010

- ▶ Assumed \mathbf{A} to be PSD. Extension known as **generalized RDPG**

P. Rubin-Delanchy et al, "A statistical interpretation of spectral embedding: The generalised random dot product graph," *arXiv:1709.05506 [stat.ML]*, 2017

- ▶ RDPG variants to model **weighted and directed graphs** possible

F. Larroca et al, "Change point detection in weighted and directed random dot product graphs," *ICASSP*, 2021

- ▶ Host of **applications** in testing, clustering, change-point detection, ...

- ▶ Network graph model
- ▶ Random graph models
- ▶ Configuration model
- ▶ Matching algorithm
- ▶ Switching algorithm
- ▶ Model-based estimation
- ▶ Assessing significance
- ▶ Reference distribution
- ▶ Network motif
- ▶ Small-world network
- ▶ Decentralized search
- ▶ Watts-Strogatz model
- ▶ Time-evolving network
- ▶ Network-growth models
- ▶ Preferential attachment
- ▶ Barabási-Albert model
- ▶ Copying models
- ▶ Exponential family
- ▶ Exponential random graph models
- ▶ Configurations
- ▶ Network statistic
- ▶ Homogeneity
- ▶ Markov random graphs