

Initialmente $0 = \sigma_I + \sigma_P(0) + \sigma_2(0)$

$$\sigma_I(0) = -(\sigma_1(0) + \sigma_2(0))$$

$$\sigma_I(0) = 0$$

a) $\nabla \cdot \vec{J} = -\dot{\rho} \parallel \rightarrow g \nabla \cdot \vec{E} = -\dot{\rho}$
 $\vec{J} = g \vec{E}$

$$\Rightarrow g_1 (\vec{E}_1 \cdot \vec{n}) = -\dot{\sigma}_1 \quad \vec{E}_1 = \frac{\sigma_1}{\epsilon_1} \vec{e}$$

$$\frac{g_1}{\epsilon_1} \sigma_1 = -\dot{\sigma}_1$$

analogamente

$$\frac{g_2}{\epsilon_2} \sigma_2 = -\dot{\sigma}_2$$

$$\Rightarrow \sigma_1(t) = \sigma_1(0) e^{-\frac{g_1}{\epsilon_1} t} \quad \sigma_1(0) = \sigma_0$$

$$\sigma_2(t) = \sigma_2(0) e^{-\frac{g_2}{\epsilon_2} t} \quad \sigma_2(0) = -\sigma_0$$

$$\sigma_1(t) = \sigma_0 e^{-\frac{g_1}{\epsilon_1} t}$$

$$\sigma_2(t) = -\sigma_0 e^{-\frac{g_2}{\epsilon_2} t}$$

$$\sigma_I(t) = \sigma_0 \left(e^{-\frac{g_2}{\epsilon_2} t} - e^{-\frac{g_1}{\epsilon_1} t} \right)$$

$$E_{2n} - E_{1n} = \frac{\sigma_I}{\epsilon_0} = \frac{\sigma_L + \sigma_P}{\epsilon_0}$$

$$Q_L = D_{2n} - D_{1n} = \epsilon_2 E_{2n} - \epsilon_1 E_{1n}$$

$$\rightarrow (\epsilon_2 - \epsilon_1) E_{2n} - (\epsilon_0 - \epsilon_1) E_{1n} = \sigma_P$$

$$\sigma_P = \sigma_0 \left\{ \left(\frac{\epsilon_1 - \epsilon_0}{\epsilon_1} \right) e^{-\frac{g_1}{\epsilon_1} t} - \left(\frac{\epsilon_2 - \epsilon_0}{\epsilon_2} \right) e^{-\frac{g_2}{\epsilon_2} t} \right\}$$

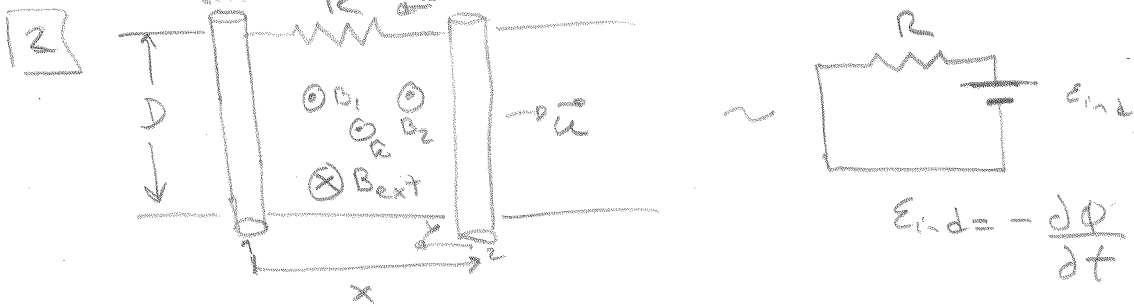
b) $\phi(L) - \phi(d) = - \int_d^L \vec{E}_2 \cdot d\vec{l}$

$$\phi(L) - \phi(d) = \frac{\sigma_0}{\epsilon_2} e^{-\frac{g_2}{\epsilon_2} t} (L-d) \quad (-)$$

$$\phi(d) = \frac{\sigma_0 (L-d)}{\epsilon_2} e^{-\frac{g_2}{\epsilon_2} t}$$

c) $\sigma_I(t) = \sigma_0 \left(e^{-\frac{g_2}{\epsilon_2} t} - e^{-\frac{g_1}{\epsilon_1} t} \right) = 0 \quad \forall t \Rightarrow$

$$\frac{g_2}{\epsilon_2} = \frac{g_1}{\epsilon_1}$$



$$\Phi = -B_{ext} D (x - 2a) + \phi_{ai}$$

$$\phi_{ai} = \int_a^{x-a} B_1 D dx + \int_a^{x-a} B_2 D dy$$

$$\vec{B}_1(x) = \frac{\mu_0 I}{2\pi} \frac{1}{x} \hat{k} ; \quad \vec{B}_2 = \frac{\mu_0 I}{2\pi} \frac{1}{y} \hat{k}$$

$$\Rightarrow \phi_{ai} = 2 \cdot \frac{\mu_0 I D}{2\pi} \int_a^{x-a} \frac{1}{x} dx = \frac{\mu_0 I D}{\pi} \ln\left(\frac{x-a}{a}\right)$$

$$I = \frac{\mathcal{E}_{ind}}{R} \quad \text{busca } I(t) \text{ cuando } \frac{dI}{dt} = 0$$

$$\Rightarrow R I(t) = B_{ext} D \dot{x} - \frac{\mu_0 I D}{\pi} \frac{\dot{x}}{x-a} \quad \dot{x} = u$$

$$I(t) = \frac{B_{ext} D u}{R + \frac{\mu_0 D u}{x-a}}$$

b) $P_v - P_r$ con P_r y P_v tomadas positivas

$$P_r = R I^2$$

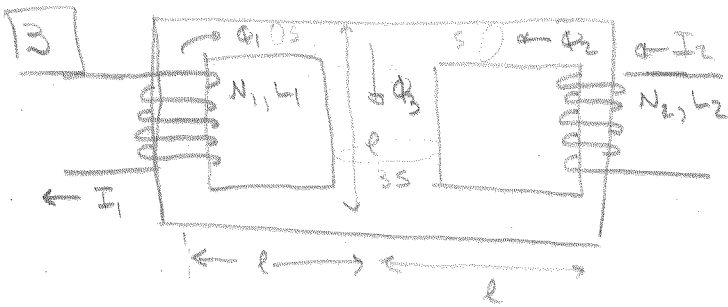
$$P_u = \vec{F}_{mag} \cdot \vec{u}$$

$$\vec{F}_{mag} = -B_{ext} D I \hat{u} + \frac{\mu_0 I^2 D}{2\pi} \frac{1}{x} \hat{u}$$

$$P_u = -B_{ext} D I u + \frac{\mu_0 I^2 D}{2\pi} \frac{1}{x} u$$

$$P_v - P_r = -R I^2 + B_{ext} D I v_0 - \frac{\mu_0 D v_0}{2\pi x} I^2$$

$$P_v - P_r = B D v_0 I - \left(\frac{\mu_0 D v_0}{2\pi x} + R \right) I^2$$



$$\mu_s = \frac{l}{\mu_0 \mu_r}$$

$$\phi_1 + \phi_2 = \phi_3$$

$$3\mu_s \phi_1 + \frac{\mu_s \phi_3}{3} = N_1 I_1$$

$$3\mu_s \phi_2 + \frac{\mu_s \phi_3}{3} = N_2 I_2$$

$$9\mu_s \phi_1 + \mu_s (\phi_1 + \phi_2) = 3N_1 I_1 \rightarrow \phi_2 = \frac{3N_1 I_1 - 10\mu_s \phi_1}{\mu_s}$$

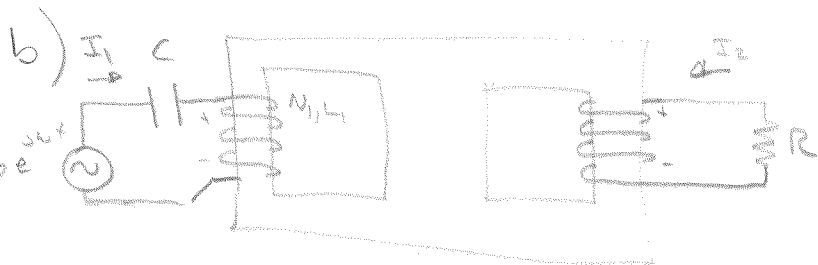
$$9\mu_s \phi_2 + \mu_s (\phi_1 + \phi_2) = 3N_2 I_2$$

$$\rightarrow 30N_1 I_1 - 100\mu_s \phi_1 + \mu_s \phi_2 = 3N_2 I_2$$

$$\phi_1 = \frac{10N_1 I_1 - N_2 I_2}{33\mu_s}$$

$$\phi_2 = \frac{10N_2 I_2 - N_1 I_1}{33\mu_s}$$

$$L_1 = \frac{d\phi_1}{dI_1} = \frac{10N_1^2}{33\mu_s} ; L_2 = \frac{10N_2^2}{33\mu_s} ; |M_{12}| = |M_{21}| = \frac{N_2 N_1}{33\mu_s}$$



$$V_0 - \frac{I_1}{j\omega C} = \frac{d\phi_1}{dt} \rightarrow V_0 - \frac{I_1}{j\omega C} = \frac{10N_1^2}{33\mu_s} I_1 j\omega - \frac{N_1 N_2}{33\mu_s} j\omega I_2$$

$$V_0 - \frac{I_1}{j\omega C} = L_1 I_1 j\omega - M j\omega I_2$$

$$-R I_2 = \frac{d\phi_2}{dt} \rightarrow -R I_2 = j\omega L_2 I_2 - M I_1 j\omega \rightarrow$$

$$V_o = \left(\frac{1}{j\omega C} + L_1 j\omega \right) I_1 - j\omega M I_2$$

$$I_1 = \left(\frac{R + j\omega L_2}{j\omega M} \right) I_2$$

$$V_o = \left(\frac{(1 - \omega^2 L_1 C)(j\omega L_2 + R) - j\omega M^2}{j\omega C} \right) I_2$$

$$V_o = \frac{((\omega^2 L_1 C - 1)(j\omega L_2 + R) + j\omega^3 M^2 C)}{\omega^2 M C} I_2$$

$$I_2 = \frac{V_o \omega^2 M C}{R(1 - \omega^2 L_1 C) + j(-\omega^3 L_1 L_2 C + \omega L_2 + \omega^3 M^2 C)}$$

$$|I_2| = \frac{V_o \omega^2 M C}{\left[R^2(1 - \omega^2 L_1 C)^2 + (\omega^3 M^2 C - \omega^3 L_1 L_2 C + \omega L_2)^2 \right]^{1/2}}$$

$$|V_R| = R |I_2|$$

$$|V_R| = \frac{V_o \omega^2 R M C}{\left[R^2(1 - \omega^2 L_1 C)^2 + (\omega^3(M^2 C - L_1 L_2 C) + \omega L_2)^2 \right]^{1/2}}$$